

Revision: 5.63

Date:2023.5





Features:

Item	Description		
	Chip	M10050	
	Receiver type	GPS L1 C/A, QZSS L1 C/A/S,BDS B1I/B1C, Galileo	
Electrical	Receiver type	E1B/C,SBAS L1 C/A: WAAS, EGNOS, MSAS, GAGAN	
Characteristic	Default position system	GPS, BDS, GALILEO	
	Augmentation system	SBAS, QZSS	
	Channel	N/A	
	Tracking & Navigation	-166dBm	
Sensitivity	Reacquisition	-160dBm	
Sensitivity	Cold start	-148dBm	
	Hot Start	-160dBm	
	Horizontal position	2.0m CEP	
	Velocity	0.05m/s	
Accuracy	Dynamic heading	0.3 deg	
	Time mules	RMS 30ns	
	Time pulse	99% 60ns	
	Cold start	27s	
Acquisition	Hot start	1s	
	Aided start	1s	
	Baud rate	4800bps - 921600bps,default 38400bps	
	Level	TTL level	
	Protocol Protocol	NMEA,UBX	
	NMEA messages	RMC,VTG,GGA,GSA,GSV,GLL	
Data Output	Update rate	0.25Hz-18Hz,default 1Hz	
	FLASH	With FLASH, the configuration can be changed, and the	
		power will not be lost	
	Frequency of time pulse		
	signal Altitude	1s, and the high level lasts for 100ms 80,000m	
Operational	Velocity	500m/s	
Limits			
_	Dynamics	<4g	
Power	Voltage	DC 3.6V-5.5V, typical: 5.0V	
Consumption	Current	15mA/5.0V	
Physical	Dimension	22*20*6mm	
Specications	Weight	5.3g	
	Connector	1.00mm 4pins connector	
Temperature	Operating	-40 °C ~ +85°C	



	Storage	-40°C ~ +105°C
		TX LED: blue. The data output, TX LED flashing
LED	Built-in LED	PPS LED: red. PPS LED not bright when GPS not fixed,
		flashing when fixed

Pin Description:



PIN	Name	I/O	Description
1	GND	G	Ground
2	TX	0	Serial Data Output.
3	RX	I	Serial Data Input.
4	VCC	I	DC 3.6V - 5.5V supply input, Typical: 5.0V

Indicator light:

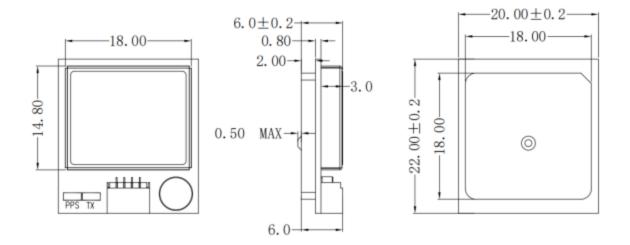
- 1. The blue light, the TX light, and the blue light flashes when power on, indicating that there is data output.
- 2. The red light, the PPS light, does not light up if it is not positioned; after 3D positioning, it starts to flash.

Rear view of the module:





Dimensions:



Data output protocol

Joint Mode Protocol Header - GN GPS Mode Protocol Header-GP GLONASS Mode Protocol Header-GL Beidou mode protocol header - GB or BD

Unlocated:

\$GNRMC,,V,,,,,,,,,N,V*37 \$GNVTG,,,,,,,,,,,*56 \$GNGGA,,,,,0,00,99.99,,99.99,99,99,99,1*33 \$GNGSA,A,1,,,,,,,,,,99.99,99,99,99,99,3*31 \$GNGSA,A,1,,,,,,,,,,99.99,99,99,99,99,4*36 \$GNGSA,A,1,,,,,,,,,,99.99,99,99,99,99,5*37 \$GPGSV,1,1,00,0*65 \$GAGSV,1,1,00,0*74 \$GBGSV,1,1,00,0*77 \$GQGSV,1,1,00,0*64 \$GNGLL,,,V,N*7A

Positioned:

\$GNRMC,054411.00,A,2243.08151,N,11401.10827,E,0.008,,230423,,,A,V*1E \$GNVTG,,T,,M,0.008,N,0.016,K,A*32 \$GNGGA,054411.00,2243.08151,N,11401.10827,E,1,12,0.56,93.2,M,-2.7,M,,*64 \$GNGSA,A,3,30,03,14,06,07,17,01,19,,,,1.15,0.56,1.00,1*0D \$GNGSA,A,3,30,13,15,34,27,02,,,,,,1.15,0.56,1.00,3*01 \$GNGSA,A,3,27,28,30,01,02,03,37,38,40,,,,1.15,0.56,1.00,4*04 \$GNGSA,A,3,02,07,03,04,,,,,,,1.15,0.56,1.00,5*00



\$GPGSV,3,1,12,01,27,034,37,03,44,087,39,06,38,241,42,07,15,180,35,1*64

\$GPGSV,3,2,12,14,78,359,45,17,43,333,38,19,28,303,39,30,34,212,39,1*6C

\$GPGSV,3,3,12,39,29,252,33,40,20,257,40,41,46,237,44,50,60,149,39,1*65

\$GPGSV,1,1,01,11,00,228,,0*5C

\$GAGSV,2,1,06,02,30,136,38,13,23,238,40,15,68,289,42,27,37,324,30,7*7E

\$GAGSV,2,2,06,30,83,091,42,34,41,026,41,7*70

\$GBGSV,3,1,11,01,47,123,36,02,46,234,37,03,63,189,38,04,,,31,1*49

\$GBGSV,3,2,11,05,..34,27,52,351,44,28,24,046,37,30,31,283,40,1*46

\$GBGSV,3,3,11,37,43,178,40,38,70,172,40,40,57,034,39,1*48

\$GQGSV,1,1,04,02,63,125,42,03,59,044,39,04,38,131,38,07,60,149,36,1*6C

\$GNGLL,2243.08151,N,11401.10827,E,054411.00,A,A*71

 $\label{lem:sepse} $$xxGGA, time, lat, NS, Ion, EW, quality, numSV, HDOP, alt, altUnit, sep, sepUnit, diffAge, diffStation*cs < CR > < LF >$

Example:

\$GPGGA,092725.00,4717.11399,N,00833.91590,E,1,08,1.01,499.6,M,48.0,M,.*5B

Field	Name	Unit	Format	Example	Description
No.					
0	xxGGA	-	string	\$GPGGA	GGA Message ID (xx = current Talker ID, see
					NMEA Talker IDs table)
1	time	-	hhmmss.ss	092725.00	UTC time, see note on UTC representation
2	lat	-	ddmm.	4717.11399	Latitude (degrees & minutes), see format
			mmmmm		description
3	NS	-	character	N	North/South indicator
4	lon	-	dddmm.	00833.91590	Longitude (degrees & minutes), see format
			mmmmm		description
5	EW	-	character	E	East/West indicator
6	quality	-	digit	1	Quality indicator for position fix, see position
					fix flags description Flags in NMEA 4.10 and
					above
7	numSV	-	numeric	08	Number of satellites used (range: 0-12)
8	HDOP	-	numeric	1.01	Horizontal Dilution of Precision
9	alt	m	numeric	499.6	Altitude above mean sea level
Field	Name	Unit	Format	Example	Description
No.					
10	altUnit	-	character	М	Altitude units: M (meters, fixed field)
11	sep	m	numeric	48.0	Geoid separation: difference between
					ellipsoid
					and mean sea level
12	sepUnit	-	character	М	Geoid separation units: M (meters, fixed
					field)
13	diffAge	s	numeric	-	Age of differential corrections (null when
					DGPS is not used)
		•	•	•	



14	diffStat	-	numeric	-	ID of station providing differential corrections
	ion				(null when DGPS is not used)
15	cs	-	hexadecim	*5B	Checksum
			al		
16	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed

\$xxGLL,lat,NS,lon,EW,time,status,posMode*cs<CR><LF> Example:

\$GPGLL,4717.11364,N,00833.91565,E,092321.00,A,A*60

Field	Name	Unit	Format	Example	Description
No.					
0	xxGLL	-	string	\$GPGLL	GLL Message ID (xx = current Talker ID, see
					NMEA Talker IDs table)
1	lat	-	ddmm.	4717.11364	Latitude (degrees & minutes), see format
			mmmmm		description
2	NS	-	character	Ν	North/South indicator
3	lon	-	dddmm.	00833.91565	Longitude (degrees & minutes), see format
			mmmmm		description
4	EW	-	character	E	East/West indicator
5	time	-	hhmmss.ss	092321.00	UTC time, see note on UTC representation
6	status	-	character	Α	Data validity status, see position fix flags
					description
7	posMode	-	character	Α	Positioning mode, see position fix flags
					description (only available in NMEA 2.3 and
					later)
Field	Name	Unit	Format	Example	Description
No.					
8	cs	-	hexadecimal	*60	Checksum
9	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed

 $xxGSA, opMode, navMode{, svid}, PDOP, HDOP, VDOP, systemId*cs < CR > < LF > Example:$

\$GPGSA,A,3,23,29,07,08,09,18,26,28,,,,,1.94,1.18,1.54,1*0D

Field	Name	Unit	Format	Example	Description
No.					
0	xxGSA	-	string	\$GPGSA	GSA Message ID (xx = current Talker ID, see
					NMEA Talker IDs table)
1	opMode	-	character	A	Operation mode:
					M = Manually set to operate in 2D or 3D mode
					A = Automatically switching between 2D or 3D
					mode



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2	navMode	t	digit	3	Navigation mode, see position fix flags
					description
Start o	of repeated b	lock ((12 times)		
3 +	svid	-	numeric	29	Satellite number
1*N					
End o	f repeated bl	ock			
15	PDOP	-	numeric	1.94	Position dilution of precision
16	HDOP	-	numeric	1.18	Horizontal dilution of precision
17	VDOP	-	numeric	1.54	Vertical dilution of precision
18	systemId	-	numeric	1	NMEA defined GNSS System ID, see Signal
					dentifiers table (only available in NMEA 4.10
					and later)
19	cs	-	hexadecimal	*0D	Checksum
20	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed

\$xxGSV,numMsg,msgNum,numSV{,svid,elv,az,cno},signalld*cs<CR><LF>

Example:

\$GPGSV,3,1,09,09,,,17,10,,,40,12,,,49,13,,,35,1*6F \$GPGSV,3,2,09,15,,,44,17,,,45,19,,,44,24,,,50,1*64

\$GPGSV,3,3,09,25,,,40,1*6E

\$GPGSV,1,1,03,12,,,42,24,,,47,32,,,37,5*66

\$GAGSV,1,1,00,2*76

Field	Name	Unit	Format	Example	Description
No.					
0	xxGSV	-	string	\$GPGSV	GSV Message ID (xx = GSV Talker ID, see
					NMEA Talker IDs table). Talker ID GN shall not
					be used
1	numMsg	-	digit	3	Number of messages, total number of GSV
					messages being output (range: 1-9)
2	msgNum	-	digit	1	Number of this message (range: 1-numMsg)
3	numSV	-	numeric	10	Number of known satellites in view regarding
					both the talker ID and the signalld
Start o	of repeated I	block	(14 times)		
4 +	svid	-	numeric	23	Satellite ID
4*N					
5 +	elv	deg	numeric	38	Elevation (range: 0-90)
4*N					
6 +	az	deg	numeric	230	Azimuth (range: 0-359)
4*N					
7 +	cno	dB	numeric	44	Signal strength (C/N0, range: 0-99), null when
4*N		Hz			not tracking
End of	frepeated b	lock			
Field	Name	Unit	Format	Example	Description



No.					
5	signalld	-	numeric	0	NMEA defined GNSS Signal ID, see Signal
16				l	Identifiers table (only available in NMEA 4.10 and later)
6	cs	-	hexadecimal	*7F	Checksum
16					
7	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed
16					

xxRMC, time, status, lat, NS, lon, EW, spd, cog, date, mv, mvEW, posMode, navStatus*cs<CR><LF>Example:

\$GPRMC,083559.00,A,4717.11437,N,00833.91522,E,0.004,77.52,091202,,,A,V*57

Field	Name	Unit	Format	Example	Description
No.					
0	xxRMC	-	string	\$GPRMC	RMC Message ID (xx = current Talker ID, see
					NMEA Talker IDs table)
1	time	-	hhmmss.ss	083559.00	UTC time, see note on UTC representation
2	status	-	character	A	Data validity status, see position fix flags
					description
3	lat	-	ddmm.	4717.11437	Latitude (degrees & minutes), see format
			mmmmm		description
4	NS	-	character	N	North/South indicator
5	lon	-	dddmm.	00833.91522	Longitude (degrees & minutes), see format
			mmmmm		description
6	EW	-	character	E	East/West indicator
7	spd	kno	numeric	0.004	Speed over ground
		ts			
8	cog	deg	numeric	77.52	Course over ground
		ree s			
Field	Name	Unit	Format	Example	Description
No.					
9	date	-	ddmmyy	091202	Date in day, month, year format, see note on
					UTC representation
10	mν	deg	numeric	-	Magnetic variation value. Only supported in
		ree s			ADR 4.10 and later
11	mvEW	-	character	-	Magnetic variation E/W indicator. Only
					supported in ADR 4.10 and later
12	posMode	-	character	Α	Mode Indicator, see position fix flags
					description (only available in NMEA 2.3 and
					later)



13	navStatu	-	character	V	Navigational status indicator: V (Equipment is
	s				not providing navigational status information,
					fixed field, only available in NMEA 4.10 and
					ater)
14	cs	-	hexadecimal	*57	Checksum
15	<cr><l< td=""><td>-</td><td>character</td><td>-</td><td>Carriage return and line feed</td></l<></cr>	-	character	-	Carriage return and line feed
	F>				

\$xxVTG, cogt, cogtUnit, cogm, cogmUnit, sogn, sognUnit, sogk, sogkUnit, posMode*cs < CR > < LF >

Example:

\$GPV Field	Name	Unit	Format	Example	Description		
No.	Name	Unit	Format	Example	Description		
0	xxVTG	-	atrin a	\$GPVTG	VTG Message ID (xx = current Talker ID, see		
U	XXVIG	Ī	string	\$GPVIG			
	<u> </u>	ļ. —		77.50	NMEA Talker IDs table)		
1	cogt	deg	numeric	77.52	Course over ground (true)		
		ree					
		s					
2	cogtUnit	}	character	Т	Course over ground units: T (degrees true,		
					fixed field)		
3	cogm	deg	numeric	-	Course over ground (magnetic). Only		
		re e			supported in ADR 4.10 and above		
		s					
4	cogmUnit	-	character	M	Course over ground units: M (degrees		
					magnetic, fixed field)		
5	sogn	kno	numeric	0.004	Speed over ground		
		ts					
6	sognUnit	-	character	N	Speed over ground units: N (knots, fixed field)		
Field	Name	Unit	Format	Example	Description		
No.							
7	sogk	km/	numeric	0.008	Speed over ground		
		h					
8	sogkUnit	-	character	K	Speed over ground units: K (kilometers per		
					hour, fixed field)		
9	posMode - character A Mode		Mode Indicator, see position fix flags				
					description (only available in NMEA 2.3 and		
					later)		
10	cs	-	hexadecimal	*06	Checksum		
11	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed		

Flags in NMEA 4.10 and above

NMEA Message	GLL, RMC	GGA	GLL, VTG	RMC, GNS



Field	status	quality	posMode	posMode
No position fix (at power-up, after losing satellite lock)	V	0	N	N
GNSS fix, but user limits exceeded	V	0	N	N
Dead reckoning fix, but user limits exceeded	V	6	Е	E
Dead reckoning fix	Α	6	Е	E
RTK float	Α	5	D	F
RTK fixed	Α	4	D	R
2D GNSS fix	Α	1/2	A/D	A/D
3D GNSS fix	Α	1/2	A/D	A/D
Combined GNSS/dead reckoning fix	Α	1/2	A/D	A/D
	See below (1)	See below(2)	See below(3)	See below(3)

- (1) Possible values for status: V = Data invalid, A = Data valid
- (2) Possible values for quality: 0 = No fix, 1 = Autonomous GNSS fix, 2 = Differential GNSS fix, 4 = RTK fixed, 5 = RTK float, 6 = Estimated/Dead reckoning fix
- (3) Possible values for posMode: N = No fix, E = Estimated/Dead reckoning fix, A = Autonomous GNSS fix, D = Differential GNSS fix, F = RTK float, R = RTK fixed