Chapter 2.

Divide-and-Conquer

Foundations of Algorithms, 5th Ed. Richard E. Neapolitan

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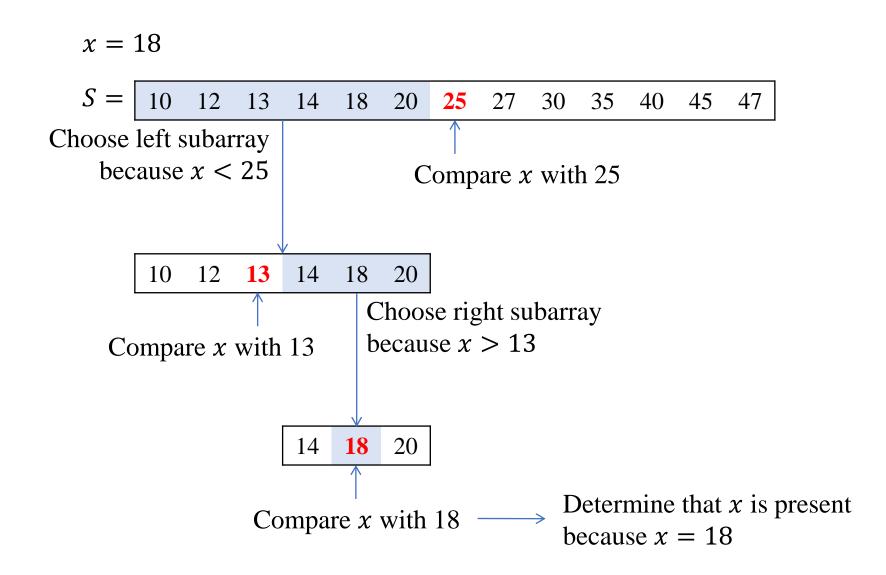


- The Divide-and-Conquer Approach
 - divides an instance of a problem into two or more smaller instances.
 - The divided smaller instances are also instances of the problem.
 - If they are *still too large* to be solved readily,
 - they can be divided into *still smaller instances*.
 - If solutions to them can be obtained readily,
 - these smaller solutions can be *combined* into the original solution.
 - It is a *top-down approach*, that is,
 - the solution to a *top-level instance* of a problem is obtained
 - by *going down* and *obtaining solutions* to smaller instances.





- The steps of Binary Search:
 - If *x* equals the middle item, then quit. Otherwise:
 - 1. Divide the array into two subarrays about half as large.
 - If x is *smaller* than the *middle* item, choose the *left* subarray.
 - If x is *larger* than the *middle* item, choose the *right* subarray.
 - **2.** Conquer (solve) the subarray
 - by determining whether *x* is in that subarray.
 - Unless the subarray is sufficiently small, use *recursion* to do this.
 - 3. *Obtain* the solution to the array from the solution to the subarray.





ALGORITHM 2.1: Binary Search (Recursive)

```
int binsearch2(int low, int high) {
    int mid;
    if (low > high)
        return 0;
    else {
        mid = (low + high) / 2;
        if (x == S[mid])
            return mid;
        else if (x < S[mid])</pre>
            return binsearch2(low, mid - 1);
        else // x > S[mid]
            return binsearch2(mid + 1, high);
```





- Implementing the *Recursive* Binary Search:
 - Note that n, S, and x are not parameters to the function binsearch 2.
 - Only the variables whose values can change in the recursive calls
 - are made parameters to recursive routines.
 - Hence, define *n*, *S*, and *x* as *global variables*.
 - Then, our *top-level call* to the function *binsearch* 2 and the output would be:

```
// global variables
int n, x;
int n, x;
vector<int> S;
lo 12 13 14 18 20 25 27 30 35 40 45 47
18

location = binsearch2(1, n);
[Output]
5
```





- Time Complexity Analysis (*Worst-Case*)
 - Basic Operation: the *comparison* of x with S[mid].
 - Input Size: *n*, the *number of items* in the array.
 - Note that the worst-case can occur
 - when x is larger than all items in the list.
 - Assume that *n* is a power of 2.
 - If n = 1, then W(n) = W(1) = 1.
 - If n > 1, then $W(n) = W\left(\frac{n}{2}\right) + 1$ Comparisons in recursive call top level



- Time Complexity Analysis (Worst-Case)
 - The recurrence equation:
 - -W(1) = 1, for n = 1,
 - W(n) = W(n/2) + 1, for n > 1 and n is a power of 2.
 - This recurrence is solved to:
 - $W(n) = \lg n + 1 \in \Theta(\lg n)$. (Refer to Example B.1 in Appendix B)
 - If *n* is not restricted to being a power of 2, then
 - $W(n) = |\lg n| + 1 \in \Theta(\lg n)$. (Refer to Exercise 2.1.4)





Mergesort:

- Two-way merging
 - combines *two sorted arrays* into *one sorted array*.
- We can sort an array
 - by *repeatedly* apply the *two-way merging* procedure.
- *Divide* it into two subarrays, *sort* the two arrays, and
 - *merge* them to produce the sorted array.

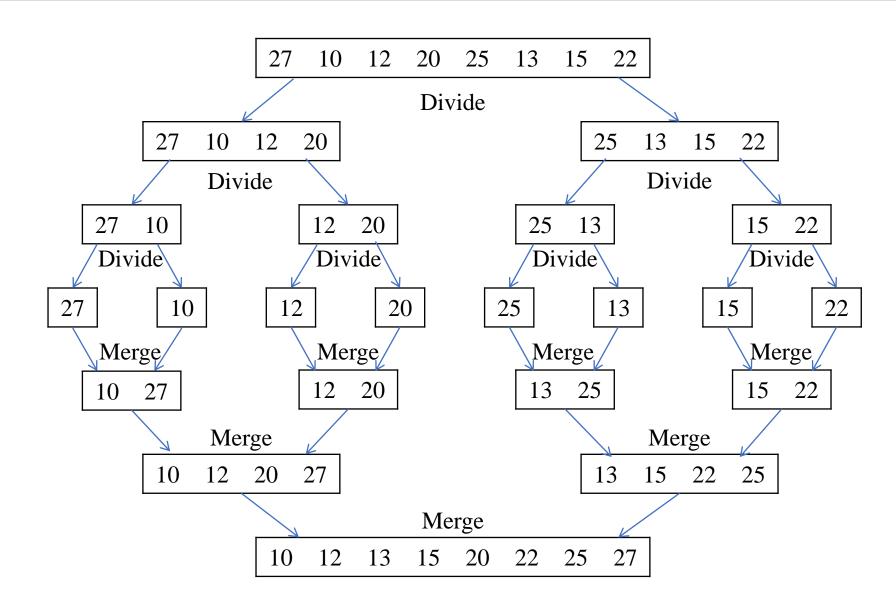




- The steps of Mergesort
 - 1. **Divide** the array into two subarrays each with n/2 items.
 - 2. Conquer (solve) each subarray by sorting it.
 - Unless the array is sufficiently small, use *recursion* to do this.
 - **3.** Combine the solutions to the subarrays
 - by *merging* them into a single sorted array.











> 2.2 Mergesort

ALGORITHM 2.2: Mergesort

```
void mergesort(int n, vector<int>& S)
    if (n > 1) {
        int h = n / 2, m = n - h;
        vector<int> U(h + 1), V(m + 1);
        // copy S[1] through S[h] to U[1] through U[h]
        for (int i = 1; i <= h; i++)
            U[i] = S[i];
        // copy S[h+1] through S[n] to V[1] through V[m]
        for (int i = h + 1; i <= n; i++)
            V[i - h] = S[i];
        mergesort(h, U);
        mergesort(m, V);
        merge(h, m, U, V, S);
```



ALGORITHM 2.3: Merge

```
void merge(int h, int m, vector<int>& U, vector<int>& V, vector<int>& S)
    int i = 1, j = 1, k = 1;
    while (i \le h \&\& j \le m)
        S[k++] = (U[i] < V[j]) ? U[i++] : V[j++];
    if (i > h)
        // copy V[j] through V[m] to S[k] through S[h+m]
        while (j \ll m)
            S[k++] = V[j++];
    else // j > m
        // copy U[i] through U[h] to S[k] through S[h+m]
        while (i <= h)
            S[k++] = U[i++];
```



• Merging two arrays U and V into one array S.

15 20 <mark>27</mark>





- Time Complexity of *Merge* (Worst-Case)
 - Basic Operation: the *comparison* of U[i] with V[j].
 - Input Size: *h* and *m*, the *number of items* in each of the two input arrays.
 - The *worst-case* occurs when the while-loop is exited,
 - one of two indices (i) has reached its exit point (h + 1),
 - whereas the other index (j) has reached m (1 less than its exit point).
 - Therefore,
 - W(h, m) = h + m 1.



- Time Complexity of Mergesort (Worst-Case)
 - Basic Operation: the *comparison* that takes place in *merge*.
 - Input Size: *n*, the *number of items* in the array *S*.
 - The total number of comparisons is the sum of
 - the number of comparison in the recursive call to *mergesort*.

$$W(n) = W(h) + W(m) + h + m - 1$$
 $\uparrow \qquad \uparrow \qquad \uparrow$

Time to sort U Time to sort V Time to merge



- Time Complexity of Mergesort (Worst-Case)
 - In the case where n is a power of 2.
 - Establish the recurrence relation:
 - $h = \lfloor n/2 \rfloor = n/2$, m = n h = n/2, h + m = n.
 - W(1) = 0, for n = 1,
 - W(n) = 2W(n/2) + n 1, for n > 1, n is a power of 2.
 - Therefore,
 - $W(n) = n \lg n (n-1) \in \Theta(n \lg n)$ (Example B.19 in Appendix B)
 - In the case where *n* is *not* a power of 2.
 - $W(n) = W(\lfloor n/2 \rfloor) + W(\lfloor n/2 \rfloor) + n 1$
 - W(n) ∈ $\Theta(n \lg n)$ by Theorem B.4 (Example B.25 in Appendix B.4)



- How about the Space Complexity?
 - An *in-place sort* is a sorting algorithm that
 - does not use any *extra space* beyond that needed to store the input.
 - Algorithm 2.2 is not an in-place sort,
 - because it uses extra arrays *U* and *V* besides the input array *S*.
 - The total number of extra array items created is about

$$S(n) = n(1 + \frac{1}{2} + \frac{1}{4} + \cdots) = 2n$$

- It is *possible* to *reduce* the *amount of extra space*
 - to *only one array* containing *n* items.



ALGORITHM 2.4: Mergesort 2

```
void mergesort2(int low, int high)
    if (low < high) {</pre>
        int mid = (low + high) / 2;
        mergesort2(low, mid);
        mergesort2(mid + 1, high);
        merge2(low, mid, high);
```

```
// global varaibles mergesort2(1, n);
int n;
vector<int> S;
```





> 2.2 Mergesort

ALGORITHM 2.5: Merge 2

```
void merge2(int low, int mid, int high) {
    int i = low, j = mid + 1, k = 0;
    vector<int> U(high - low + 1);
    while (i <= mid && j <= high)
        U[k++] = (S[i] < S[j]) ? S[i++] : S[j++];
    if (i > mid)
        // move S[j] through S[high] to U[k] through U[high]
        while (j <= high)</pre>
            U[k++] = S[j++];
    else // j > high
        // move S[i] through S[mid] to U[k] through U[high]
        while (i <= mid)</pre>
            U[k++] = S[i++];
    // move U[0] through U[high-low+1] to S[low] through S[high]
    for (int t = low; t <= high; t++)
        S[t] = U[t - low];
```



2.3 The Divide-and-Conquer Approach

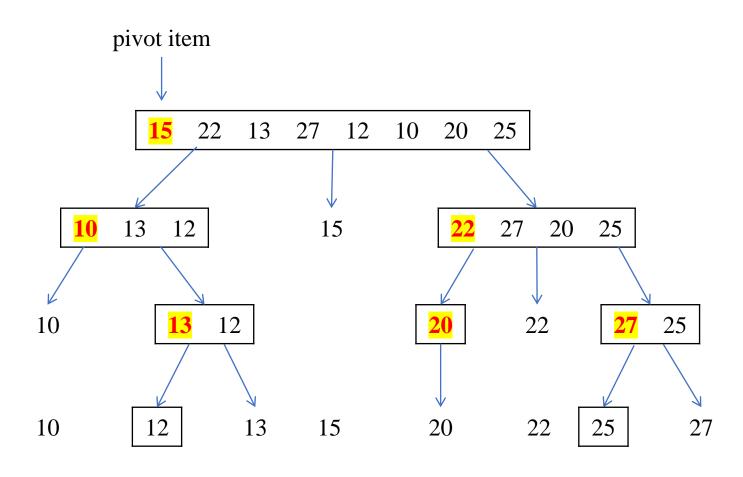
- The *Design Strategy* of the Divide-and-Conquer:
 - 1. Divide an instance of a problem into one or more smaller instances.
 - **2.** Conquer (solve) each of the smaller instances.
 - Unless a smaller instance is sufficiently small, use *recursion* to do this.
 - 3. *If necessary*, **combine** the solutions to the smaller instances
 - to obtain the solution to the original instance.



Quicksort

- is an *in-place* sorting algorithm developed by Hoare (1962).
- is similar to Mergesort in that
 - it divides the array into *two partitions*
 - and then sorting each partition recursively.
- However, the array is partitioned
 - by placing all items *smaller* than some *pivot item before* that item
 - and all items *larger* than the *pivot item after* it.
 - the *pivot item* can be *any* item,
 - for convenience, we will simply make it the first one.









ALGORITHM 2.6: Quicksort

```
void quicksort(int low, int high)
{
   int pivotpoint;

   if (low < high) {
      partition(low, high, pivotpoint);
      quicksort(low, pivotpoint - 1);
      quicksort(pivotpoint + 1, high);
   }
}</pre>
```

```
// global variables quicksort(1, n);
int n;
vector<int> S;
```





ALGORITHM 2.7: Partition

```
void partition(int low, int high, int& pivotpoint)
    int pivotitem = S[low];
    int j = low;
    for (int i = low + 1; i <= high; i++)
        if (S[i] < pivotitem) {</pre>
            j++;
            swap(S[i], S[j]);
    pivotpoint = j;
    swap(S[low], S[pivotpoint]);
```



| <i>S</i> [1] | <i>S</i> [2] | <i>S</i> [3] | <i>S</i> [4] | <i>S</i> [5] | <i>S</i> [6] | <i>S</i> [7] | <i>S</i> [8] |
|--------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|
| 15 | 22 | 13 | 27 | 12 | 10 | 20 | 25 |
| | | | | | | | |
| 15 | 22 | 13 | 27 | 12 | 10 | 20 | 25 |
| j | i | | | | | | |
| 15 | 22 | 13 | 27 | 12 | 10 | 20 | 25 |
| | j | i | | | | | |
| 15 | 13 | 22 | 27 | 12 | 10 | 20 | 25 |
| | j | | i | | | | |

| 15 | 13 | 22 | 27 | 12 | 10 | 20 | 25 |
|----|----|-----------|----|----|----|----|----|
| | | \dot{j} | | i | | | |
| 15 | 13 | 12 | 27 | 22 | 10 | 20 | 25 |
| | | | j | | i | | |
| 15 | 13 | 12 | 10 | 22 | 27 | 20 | 25 |
| | | | j | | | i | |
| 15 | 13 | 12 | 10 | 22 | 27 | 20 | 25 |
| | | | j | | | | i |
| 10 | 13 | 12 | 15 | 22 | 27 | 20 | 25 |
| | | | | | | | |

pivotpoint



- Time Complexity of *Partition* (Every-Case)
 - Basic Operation: the *comparison* of S[i] with *pivotitem*.
 - Input Size: n = high low + 1, the *number of items* in the subarray.
 - Since every item except the first is compared,
 - -T(n) = n 1.



- Time Complexity of *Quicksort* (Worst-Case)
 - Basic Operation: the *comparison* of S[i] with *pivotitem* in partition.
 - Input Size: *n*, the *number of items* in the array *S*.
 - Note that the *worst-case* occurs
 - when the array is *already sorted* in non-decreasing order.
 - If the array is already sorted,
 - no items are less than the first item (pivot item) in the array.
 - Therefore,

$$T(n) = T(0) + T(n-1) + n-1$$
 \uparrow
 \uparrow
 \uparrow
Time to sort
 $left$ subarray
 $right$ subarray
 $right$ subarray
 \uparrow



- Time Complexity of Quicksort (Worst-Case)
 - recurrence equation:
 - T(0) = 1, for n = 0,
 - $T(n) \le \frac{n(n-1)}{2}$, for n > 0.
 - the *worst-case* time complexity is:
 - $W(n) = \frac{n(n-1)}{2}$ ∈ $\Theta(n^2)$. (Example B.16 in Appendix B)



- Time Complexity of *Quicksort* (*Average-Case*)
 - Now assume that the value of *pivotpoint* returned by *partition*
 - is *equally likely* to be *any* of the numbers from 1 through *n*.
 - In this case, the average-case time complexity is given:

$$A(n) = \sum_{p=1}^{n} \frac{1}{n} [A(p-1) + A(n-p)] + n - 1$$
Probability that pivotpoint is p

Average time to sort subarray when pivotpoint is p

Time to partition

- The *approximate* solution to this recurrence is given:
 - $-A(n) \approx (n+1)2 \ln n = (n+1)2 \ln 2 (\lg n) \approx 1.38(n+1) \lg n \in \Theta(n \lg n)$



- The Analysis of *Recursive Algorithms*:
 - is not as straightforward as it is for *iterative* algorithms.
 - However, it is not difficult to represent
 - the time complexity of a recursive algorithm
 - by a recurrence equation.
 - Fortunately, there exist a simple method
 - to solve the recurrence equations with a certain type.
 - called as *The Master Theorem*.



- Theorem B.5 (Master Theorem)
 - Suppose that a complexity function T(n) satisfies:
 - $T(n) = aT(\frac{n}{b}) + cn^k, \text{ for } n > 1, n \text{ is a power of } b,$
 - T(1) = d, for n = 1.
 - where $b \ge 2$ and $k \ge 0$ are constant integers,
 - and a, c, and d are constants such that a > 0, c > 0, and $d \ge 0$.
 - Then,
 - $T(n) \in \Theta(n^k)$, if $a < b^k$.
 - $T(n) \in \Theta(n^k \lg n)$, if $a = b^k$.
 - $T(n) \in \Theta(n^{\log_b a}), \text{ if } a > b^k.$



- Examples of Applying the Master Theorem:
 - Example B.26:
 - $T(n) = 8T(n/4) + 5n^2$, for n > 1, n is a power of 4.
 - T(1) = 3
 - Then, $T(n) \in \Theta(n^2)$, since $a = 8 < b^k = 4^2$.
 - Example B.27:
 - $T(n) = 9T(n/3) + 5n^{1}$, for n > 1, n is a power of 3.
 - -T(1) = 7
 - Then, $T(n) \in \Theta(n^{\log_3 9}) = \Theta(n^2)$, since $a = 9 > b^k = 3^1$.



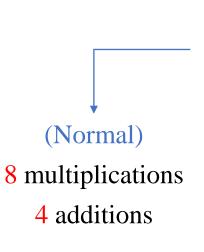
- Examples of Applying the Master Theorem:
 - Example B.28:
 - $T(n) = 8T(n/2) + 5n^3$, for n > 64, n is a power of 2.
 - T(64) = 200
 - Then, $T(n) \in \Theta(n^3 \lg n)$, since $a = 8 = b^k = 2^3$.
 - The Analysis of the Algorithm 2.2 (*Mergesort*)
 - -W(n) = 2W(n/2) + n 1, for n > 1, n is a power of 2.
 - W(1) = 0
 - Then, $W(n) \in \Theta(n \lg n)$, since $a = 2 = b^k = 2^1$.



2.5 Strassen's Matrix Multiplication Algorithm

- Matrix Multiplication Algorithm
 - Recall that Algorithm 1.4 multiplies two matrices
 - strictly according to the definition of matrix multiplication.
 - time complexity: $T(n) = n^3 \in \Theta(n^3)$.
 - Is it possible to design an efficient algorithm
 - whose time complexity is better than $\Theta(n^3)$?
 - Strassen published an algorithm (in 1969)
 - whose time complexity is better than cubic
 - in terms of both *multiplication* and *additions/subtractions*.





$$\begin{bmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}$$

$$m_1 = (a_{11} + a_{22})(b_{11} + b_{22})$$

$$m_2 = (a_{21} + a_{22})b_{11}$$

$$m_3 = a_{11}(b_{12} - b_{22})$$

$$m_4 = a_{22}(b_{21} - b_{11})$$

$$m_5 = (a_{11} + a_{12})b_{22}$$

$$m_6 = (a_{21} - a_{11})(b_{11} + b_{12})$$

$$m_7 = (a_{12} - a_{22})(b_{21} + b_{22})$$

(Strassen's)

7 multiplications

18 additions/subtractions

$$C = \begin{bmatrix} m_1 + m_4 - m_5 + m_7 & m_3 + m_5 \\ m_2 + m_4 & m_1 + m_3 - m_2 + m_6 \end{bmatrix} -$$



- Pertaining the Strassen's Method to Larger Matrices
 - that are each *divided* into *four submatrices*.

$$\begin{bmatrix} C_{11} & C_{12} \\ \vdots & \vdots & C_{21} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ \vdots & \vdots & \vdots \\ A_{21} & A_{22} \end{bmatrix} \times \begin{bmatrix} B_{11} & B_{12} \\ \vdots & \vdots & \vdots \\ B_{21} & B_{22} \end{bmatrix}$$

$$M_1 = (A_{11} + A_{22})(B_{11} + B_{22})$$

$$M_2 = (A_{21} + A_{22})B_{11}$$

$$C = \begin{bmatrix} M_1 + M_4 - M_5 + M_7 & M_3 + M_5 \\ M_2 + M_4 & M_1 + M_3 - M_2 + M_6 \end{bmatrix}$$



$$\begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 0 & 1 & 2 & 3 \\ 4 & 5 & 6 & 7 \end{bmatrix} \times \begin{bmatrix} 8 & 9 & 1 & 2 \\ 3 & 4 & 5 & 6 \\ 0 & 7 & 8 & 9 & 1 \\ 2 & 3 & 4 & 5 \end{bmatrix}$$

$$M_1 = (A_{11} + A_{22})(B_{11} + B_{22}) = \begin{bmatrix} 3 & 5 \\ 11 & 13 \end{bmatrix} \times \begin{bmatrix} 17 & 10 \\ 7 & 9 \end{bmatrix} = \begin{bmatrix} 86 & 75 \\ 278 & 227 \end{bmatrix}$$

$$M_2 = (A_{21} + A_{22})B_{11} = \begin{bmatrix} 11 & 4 \\ 10 & 12 \end{bmatrix} \times \begin{bmatrix} 8 & 9 \\ 4 & 4 \end{bmatrix} = \begin{bmatrix} 100 & 115 \\ 116 & 138 \end{bmatrix}$$

$$M_3 =$$

$$M_4 =$$

$$M_5 =$$

$$M_6 =$$

$$C = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} 43 & 53 & 54 & 37 \\ 123 & 149 & 130 & 93 \\ 95 & 110 & 44 & 41 \\ 103 & 125 & 111 & 79 \end{bmatrix}$$

$$M_7 =$$





ALGORITHM 2.8: Strassen (*pseudo-code*)

```
void strassen(int n, matrix_t A, matrix_t B, matrix_t& C) {
    if (n <= threshold) {</pre>
        compute C = A * B using the standard algorithm;
    else {
        partition A into four submatrices A11, A12, A21, A22;
        partition B into four submatrices B11, B12, B21, B22;
        compute C = A * B using Strassen's method;
            // example recursive call:
            // strassen(n/2, A11 + A22, B11 + B22, M1);
```





```
typedef vector<vector<int>> matrix t;
const int threshold = 1;
void print_matrix(int n, matrix_t M);
void resize(int n, matrix t& mat);
void madd(int n, matrix_t A, matrix_t B, matrix_t& C);
void msub(int n, matrix_t A, matrix_t B, matrix_t& C);
void mmult(int n, matrix_t A, matrix_t B, matrix_t &C);
void partition(int m, matrix_t M,
               matrix t& M11, matrix t& M12, matrix t& M21, matrix t& M22);
void combine(int m, matrix_t& M,
               matrix t M11, matrix t M12, matrix t M21, matrix t M22);
void strassen(int n, matrix_t A, matrix_t B, matrix_t &C);
```



```
matrix t A11, A12, A21, A22;
matrix t B11, B12, B21, B22;
matrix t C11, C12, C21, C22;
matrix_t M1, M2, M3, M4, M5, M6, M7;
matrix t L, R;
int m = n / 2;
resize(m, A11); resize(m, A12); resize(m, A21); resize(m, A22);
resize(m, B11); resize(m, B12); resize(m, B21); resize(m, B22);
resize(m, C11); resize(m, C12); resize(m, C21); resize(m, C22);
resize(m, C11); resize(m, C12); resize(m, C21); resize(m, C22);
resize(m, M1); resize(m, M2); resize(m, M3); resize(m, M4); resize(m, M5);
resize(m, M6); resize(m, M7); resize(m, L); resize(m, R);
```





```
void strassen(int n, matrix_t A, matrix_t B, matrix_t &C) {
    if (n <= threshold) {</pre>
        mmult(n, A, B, C);
    else {
        // Define local variables here.
        partition(m, A, A11, A12, A21, A22);
        partition(m, B, B11, B12, B21, B22);
        // Implement Strassen's Method Here.
        combine(m, C, C11, C12, C21, C22);
```



| $m_1 = (a_{11} + a_{22})(b_{11} + b_{22})$ | <pre>madd(m, A11, A22, L); madd(m, B11, B22, R); strassen(m, L, R, M1);</pre> |
|--|---|
| $m_2 = (a_{21} + a_{22})b_{11}$ | <pre>madd(m, A21, A22, L); strassen(m, L, B11, M2);</pre> |
| $m_3 = a_{11}(b_{12} - b_{22})$ | <pre>msub(m, B12, B22, R); strassen(m, A11, R, M3);</pre> |
| $m_4 = a_{22}(b_{21} - b_{11})$ | <pre>msub(m, B21, B11, R); strassen(m, A22, R, M4);</pre> |
| $m_5 = (a_{11} + a_{12})b_{22}$ | <pre>madd(m, A11, A12, L); strassen(m, L, B22, M5);</pre> |
| | |





| $C_{11} = m_1 + m_4 - m_5 + m_7$ | <pre>madd(m, msub(m, madd(m,</pre> | L, | M5, | R); |
|--|------------------------------------|-------|-------|--------------------|
| $C_{12} = m_3 + m_5$ | <pre>madd(m,</pre> | М3, | M5, | C12); |
| $C_{21} = m_2 + m_4$ | <pre>madd(m,</pre> | М2, | M4, | C21); |
| $C_{22} = m_1 + m_3 - m_2 + m_6$ | <pre>madd(m, msub(m, madd(m,</pre> | L, | M2, | R); |
| $C = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}$ | combine | (m, (| C, Cí | 11, C12, C21, C22) |



- Time Complexity of *Strassen's* (*multiplications*)
 - Basic Operation: one *elementary multiplication*.
 - Input Size: *n*, the *number of rows and columns* in the matrices.
 - For simplicity,
 - we keep dividing until n = 1 (threshold = 1).
 - Then, we can establish the recurrence:
 - T(n) = 7T(n/2), for n > 1, n is a power of 2.
 - -T(1)=1.



- Time Complexity of *Strassen's* (*multiplications*)
 - The recurrence is solved in Example B.2 in Appendix B:

$$T(n) = n^{\lg 7} \approx n^{2.81} \in \Theta(n^{2.81}).$$

$$T(n) = 7 \times T\left(\frac{n}{2}\right)$$

$$= 7^{2} \times T\left(\frac{n}{2^{2}}\right)$$

$$= \cdots$$

$$= 7^{k} \times T\left(\frac{n}{2^{k}}\right)$$

$$= 7^{k} \times T(1)$$

$$= 7^{k}$$

$$= 7^{k}$$

$$= 7^{k} \times T(1)$$

$$= 7^{k}$$

$$= 7^{k}$$

$$= 7^{k} \times T(1)$$

• We can also apply the *Master Theorem*.



- Time Complexity of *Strassen's* (additions/subtractions)
 - Basic Operation: one *elementary addition* or *subtraction*.
 - Input Size: *n*, the *number of rows and columns* in the matrices.
 - Again, for simplicity, we keep dividing until n = 1.
 - Then, we can establish the recurrence:
 - $T(n) = 7T(\frac{n}{2}) + 18(\frac{n}{2})^2$, for n > 1, n is a power of 2.
 - T(1) = 0.
 - The recurrence is solved in Example B.20 in Appendix B:
 - $T(n) = 6n^{\lg 7} 6n^2 \in \Theta(n^{2.81})$
 - We can also apply the Master Theorem.



Comparing two algorithms:

| | Standard Algorithm | Strassen's Algorithm | |
|------------------------|--------------------|----------------------|--|
| Multiplications | n^3 | $n^{2.81}$ | |
| Additions/Subtractions | $n^3 - n^2$ | $6n^{2.81} - 6n^2$ | |

- What happen if n is not a power of 2?
 - Simply, *fill 0s to the matrices* to make the dimension a power of 2.



- How fast can we multiply two matrices?
 - There are some variants of Strassen's algorithm.
 - Some of them has more efficient complexity, to say, $\Theta(n^{2.38})$.
 - It is *provable* that the complexity requires at least $\Omega(n^2)$.
 - This is a *lower bound* of matrix multiplication *problem*.
 - Is it *possible* to design an efficient algorithm with $\Theta(n^2)$?
 - No one has ever developed an algorithm for it.
 - *No one* has ever *proved* that it is *not possible*.



- Representation of Large Integers
 - Suppose that we need to do arithmetic operations on large integers
 - whose size *exceeds* the computer's *hardware capability*.
 - A straightforward way to represent a large integer is
 - to use an array of integers,
 - in which each array slot stores only one digit.

```
5 4 3 1 2 7
S[5] S[4] S[3] S[2] S[1] S[0]
```



- Data Type and Linear-Time Operations:
 - To represent both positive and negative integers
 - we need *only* reserve the *high-order* array slot for the *sign*.
 - 0 for positive, 1 for negative.
 - For convenience,
 - we assume that all the large integers are positive.

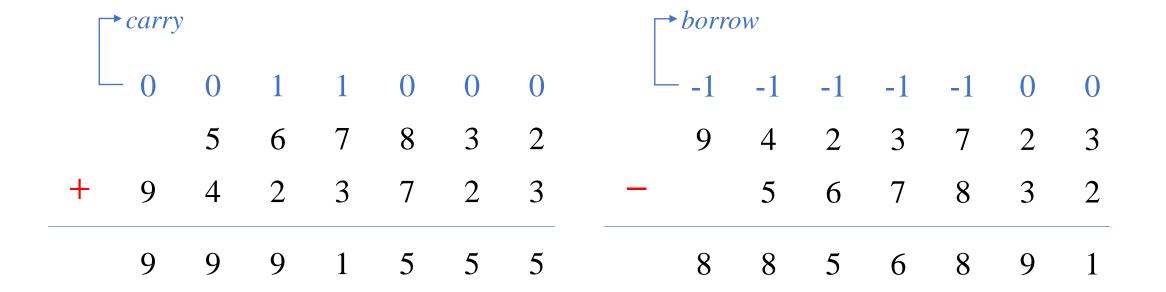
```
typedef vector<int> LargeInteger;
const int threshold = 1;
```



- Data Type and Linear-Time Operations:
 - Write linear-time algorithms for
 - addition & subtraction.
 - powered by exponent: $u \times 10^m$
 - divided by exponent: u divide 10^m
 - returns the *quotient* in integer division.
 - remainder by exponent: $u \operatorname{rem} 10^{m}$
 - return the remainder.



Addition & Subtraction





```
void roundup_carry(LargeInteger& v) {
    int carry = 0;
    for (int i = 0; i < v.size(); i++) {
        v[i] += carry;
        carry = v[i] / 10;
        v[i] = v[i] \% 10;
    if (carry != 0)
        v.push back(carry);
```





```
void ladd(LargeInteger a, LargeInteger b, LargeInteger& c) {
    c.resize(max(a.size(), b.size()));
    fill(c.begin(), c.end(), 0);
    for (int i = 0; i < c.size(); i++) {
        if (i < a.size()) c[i] += a[i];
        if (i < b.size()) c[i] += b[i];
    }
    roundup_carry(c);
}</pre>
```





- Multiplication of Large Integers:
 - A simple algorithm for multiplying large integers
 - has a *quadratic* time complexity: $\Theta(n^2)$.

| | | 1 | 2 | 3 |
|---|---|----|----|----|
| × | | | 4 | 5 |
| | | 5 | 10 | 15 |
| + | 4 | 8 | 12 | |
| | 4 | 13 | 22 | 15 |
| | 5 | 5 | 3 | 5 |





```
void lmult(LargeInteger a, LargeInteger b, LargeInteger& c) {
    c.resize(a.size() + b.size() - 1);
    fill(c.begin(), c.end(), 0);
    for (int i = 0; i < a.size(); i++)
        for (int j = 0; j < b.size(); j++)
        c[i + j] += a[i] * b[j];
    roundup_carry(c);
}</pre>
```



Operations with Exponents: Power, Divide, and Remainder

$$u = 567,832, m = 3$$

$$u \times 10^m$$

$$u = 567832000$$

$$u$$
 divide 10^m

$$u = 567832$$

$$u = 567832$$



```
void pow_by_exp(LargeInteger u, int m, LargeInteger &v) {
    if (u.size() == 0)
        v.resize(0);
    else {
        v.resize(u.size() + m);
        fill(v.begin(), v.end(), 0);
        copy(u.begin(), u.end(), v.begin() + m);
    }
}
```



```
void rem_by_exp(LargeInteger u, int m, LargeInteger &v) {
    if (u.size() == 0)
        v.resize(0);
    else {
        // Note that u.size() can be smaller than m.
        int k = m < u.size() ? m : u.size();</pre>
        v.resize(k);
        copy(u.begin(), u.begin() + k, v.begin());
        remove_leading_zeros(v);
```



- Designing an *Efficient* Multiplication Algorithm:
 - based on the Divide-and-Conquer approach
 - to *split* an *n*-digit integer into two integers of *approximately n/2* digits.

$$567,832 = 567 \times 10^{3} + 832$$

$$6 \text{ digits} \qquad 3 \text{ digits} \qquad 3 \text{ digits}$$

$$9,423,723 = 9,423 \times 10^{3} + 723$$

$$7 \text{ digits} \qquad 4 \text{ digits} \qquad 3 \text{ digits}$$

$$u = x \times 10^{m} + y$$

$$n \text{ digits} \qquad [n/2] \text{ digits} \qquad [n/2] \text{ digits}$$

The exponent m of 10 is given by $m = \lfloor n/2 \rfloor$



```
u = x \times 10^m + y
v = w \times 10^m + z
uv = (x \times 10^m + y)(w \times 10^m + z)
    = xw \times 10^{2m} + (xz + wy) \times 10^{m} + yz
567,832 \times 9,423,723 = (567 \times 10^3 + 832)(9,423 \times 10^3 + 723)
    = 567 \times 9,423 \times 10^{6} + (567 \times 723 + 9,423 \times 832) \times 10^{3} + 832 \times 723
    = 5,351,091,478,536
```



ALGORITHM 2.9: Large Integer Multiplication

```
large integer prod(large integer u, large integer v)
    large integer x, y, w, z;
    int n, m;
    n = maximum(number of digits in u, number of digits in v);
    if (u == 0 | | v == 0)
         return 0;
    else if (n <= threshold)</pre>
         return u × v obtained in the usual way;
    else {
         m = n / 2;
         x = u \text{ divide } 10^m; y = u \text{ rem } 10^m;
         w = v \operatorname{divide} 10^{m}; z = v \operatorname{rem} 10^{m};
         return prod(x, w) \times 10^{2m} + (prod(x, z) + prod(w, y)) \times 10^m + prod(y, z);
```



```
void prod(LargeInteger u, LargeInteger v, LargeInteger &r) {
    LargeInteger x, y, w, z;
    LargeInteger t1, t2, t3, t4, t5, t6, t7, t8;
    int n = max(u.size(), v.size());
    if (u.size() == 0 || v.size() == 0)
        r.resize(0);
    else if (n <= threshold)</pre>
        lmult(u, v, r);
    else {
        int m = n / 2;
        div_by_exp(u, m, x); rem_by_exp(u, m, y);
        div_by_exp(v, m, w); rem_by_exp(v, m, z);
        // t2 <- prod(x,w) * 10^(2*m)
        prod(x, w, t1); pow_by_exp(t1, 2 * m, t2);
        // t6 <- (prod(x,z)+prod(w,y)) * 10^m
        prod(x, z, t3); prod(w, y, t4); ladd(t3, t4, t5); pow_by_exp(t5, m, t6);
        // r < - t2 + t6 + prod(y, z)
        prod(y, z, t7); ladd(t2, t6, t8); ladd(t8, t7, r);
```





- Time Complexity of Algorithm 2.9 (*Worst-Case*)
 - Basic Operation: the *manipulation of one decimal digit* in a large integer
 - when adding, subtracting, or doing pow, div, and rem operations.
 - Input Size: *n*, the *number of digits* in each of the two integers.
 - The worst-case occurs when
 - both integers have *no digits equal to 0*,
 - because the recursion ends if and only if *threshold* is passed.
 - For simplicity, suppose that n is a power of 2.





- Time Complexity of Algorithm 2.9 (Worst-Case)
 - The operations of addition, subtraction, power, divide, and remainder
 - have linear time-complexities in terms of n, because m = n/2.
 - We can establish the recurrence equation:
 - W(n) = 4W(n/2) + cn, for n > s, n is a power of 2.
 - where *c* is a positive constant.
 - W(s) = 0, for $n \le s$.
 - Therefore,
 - $W(n) \in \Theta(n^{\log_2 4}) = \Theta(n^2)$. (Example B.25 in Appendix B)
 - We can apply the *Master Theorem*.



- What's happen?
 - Algorithm 2.9 is still quadratic: $\Theta(n^2)$
 - The algorithm does *four multiplications*
 - on integers with *half* as many digits as the original integers.
 - We should *reduce* the number of these multiplications.
 - to obtain an algorithm that is better than quadratic.



$$u = x \times 10^{m} + y$$

$$v = w \times 10^{m} + z$$

$$uv = xw \times 10^{2m} + (xz + wy) \times 10^{m} + yz$$

$$r = (x + y)(w + z) = xw + (xz + yw) + yz$$

$$(xz + yw) = r - (xw + yz)$$

$$uv = xw \times 10^{2m} + ((x + y)(w + z) - (xw + yz)) \times 10^{m} + yz$$
three multiplications





ALGORITHM 2.10: Large Integer Multiplication 2

```
large_integer prod2(large_integer u, large_integer v)
    large_integer x, y, w, z, r, p, q;
    int n, m;
    n = maximum(number of digits in u, number of digits in v);
    if (u == 0 | | v == 0)
         return 0;
    else if (n <= threshold)</pre>
         return u × v obtained in the usual way;
    else {
         m = n / 2;
         x = u \text{ divide } 10^m; y = u \text{ rem } 10^m;
         w = v \text{ divide } 10^m; z = v \text{ rem } 10^m;
         r = prod2(x + y, w + z);
         p = prod2(x, w);
         q = prod2(y, z);
         return p \times 10^{2m} + (r - p - q) \times 10^{m} + q;
```



```
typedef long long largeint;
const int threshold = 1;
largeint karatsuba(largeint u, largeint v) {
    largeint x, y, w, z, p, q, r;
    int n = max(digits(u), digits(v));
    if (u == 0 || v == 0)
        return 0;
    else if (n <= threshold)</pre>
        return u * v;
    else {
        int m = n / 2;
        x = div by exp(u, m); y = rem by exp(u, m);
        w = div_by_exp(v, m); z = rem_by_exp(v, m);
        r = karatsuba(x + y, w + z);
        p = karatsuba(x, w);
        q = karatsuba(y, z);
        return pow_by_exp(p, 2*m) + pow_by_exp(r-p-q, m) + q;
```



- Time Complexity of Algorithm 2.10 (Worst-Case)
 - If n is a power of 2, then x, y, w, and z all have n/2 digits.

$$-\frac{n}{2}$$
 <= digits in $x + y \le \frac{n}{2} + 1$.

$$-\frac{n}{2} \le \text{digits in } w + z \le \frac{n}{2} + 1.$$

| n | х | у | x + y | Number of Digits in $x + y$ |
|---|------|------|--------|-----------------------------|
| 4 | 10 | 10 | 20 | 2 = n/2 |
| 4 | 99 | 99 | 198 | 3 = n/2 + 1 |
| 8 | 1000 | 1000 | 2000 | 4 = n/2 |
| 8 | 9999 | 9999 | 19,998 | 5 = n/2 + 1 |



- Time Complexity of Algorithm 2.10 (Worst-Case)
 - The input sizes for the given function calls:
 - prod2(x + y, w + z): $\frac{n}{2} \le \text{input size} \le \frac{n}{2} + 1$.
 - prod2(x, w): input size = $\frac{n}{2}$
 - prod2(y, z): input size = $\frac{n}{2}$
 - Therefore, W(n) satisfies
 - $-3W(\frac{n}{2}) + cn \le W(n) \le 3W(\frac{n}{2} + 1) + cn$, for n > s, n is a power of 2.
 - W(s) = 0, for $n \le s$.



- Time Complexity of Algorithm 2.10 (Worst-Case)
 - Owing to the left inequality in the recurrence and the Master Theorem:
 - $W(n) \in \Omega(n^{\log_2 3})$.
 - We can also show that
 - W(n) ∈ $O(n^{\log_2 3})$. (Refer to the textbook)
 - Therefore, combining these two results,
 - $W(n) \in \Theta(n^{\log_2 3})$.



- The Effect of *Threshold* Value
 - Recursion requires
 - a fair amount of overhead in terms of computer time.
 - Consider the problem of sorting only eight keys:
 - Which is the faster in terms of the *execution* time?
 - Recursive Mergesort: $\Theta(n \lg n)$ or Exchange Sort: $\Theta(n^2)$.
 - We need to develop a method that *determines for what value of n*
 - it is at least as fast to call an alternative algorithm as it is
 - to divide the instance further.



- Finding an *Optimal Threshold*:
 - An *optimal threshold value* of *n* is
 - an instance size such that for any smaller instance
 - it would be at least as fast to call the other algorithm as
 - it would be to divide the instance further,
 - and for any larger instance size
 - it would be faster to divide the instance again.





- Example: Mergesort & Exchange Sort
 - Recurrence of Mergesort (worst-case)
 - $W(n) = 2W(n/2) + 32n \mu s, W(1) = 0 \mu s$
 - Mergesort takes $W(n) = 32n \lg n \mu s$, where Exchange Sort takes $\frac{n(n-1)}{2} \mu s$.
 - Solving the inequality $\frac{n(n-1)}{2} < 32n \lg n$, the solution is n < 591.
 - Is it optimal to call Exchange Sort when n < 591
 - and to call Mergesort otherwise?
 - Note that this analysis is *incorrect*.
 - It only tells us that if we use Mergesort and keep dividing until n = 1,
 - then Exchange Sort is better for n < 591.



- The *Optimal Threshold* for Mergesort & Exchange Sort:
 - Suppose we modify Mergesort so that
 - Exchange Sort is called when $n \leq t$ for some threshold t.

•
$$W(n) = \begin{cases} \frac{n(n-1)}{2} \mu s, & \text{for } n \leq t \\ W\left(\left[\frac{n}{2}\right]\right) + W\left(\left[\frac{n}{2}\right]\right) + 32n \mu s, & \text{for } n > t \end{cases}$$

$$-W\left(\left\lfloor \frac{t}{2}\right\rfloor\right) + W\left(\left\lceil \frac{t}{2}\right\rceil\right) + 32t = \frac{t(t-1)}{2}$$

- Solving this equation, we can obtain t = 128. (Refer to the textbook)
- Therefore, we have
 - an optimal threshold value of 128.



2.8 When not to Use Divide-and-Conquer

- Avoid the Divide-and-Conquer in the following two cases:
 - 1. An instance of size n is divided into
 - two or more instances each almost size n.
 - It leads to an *exponential-time* algorithm.
 - 2. An instance of size n is divided into
 - almost *n* instances of size n/c, where *c* is a constant.
 - It leads to $n^{\Theta(\lg n)}$ algorithm.
 - Consider the following problems:
 - nth Fibonacci Term: Algorithm 1.6 (Recursive), 1.7 (Iterative)
 - Towers of Hanoi: *intrinsically* exponential algorithm.

Any Questions?

