

Q1

Let $n' = n/2 = 2^{k-1}$, and h_{ij} = ith row \wedge jth column entry of H_{k-1} . Let the first n' entry of v as v_1 and the later n' entries as v_2 . Then,

$$H_k v = \begin{bmatrix} \sum_{i=1}^{n'} h_{1i} v_i + \sum_{i=1}^{n'} h_{1i} v_{i+n'} \\ \sum_{i=1}^{n'} h_{2i} v_i + \sum_{i=1}^{n'} h_{2i} v_{i+n'} \\ \vdots \\ \sum_{i=1}^{n'} h_{n'i} v_i + \sum_{i=1}^{n'} h_{n'i} v_{i+n'} \\ \sum_{i=1}^{n'} h_{1i} v_i - \sum_{i=1}^{n'} h_{1i} v_{i+n'} \\ \sum_{i=1}^{n'} h_{2i} v_i - \sum_{i=1}^{n'} h_{2i} v_{i+n'} \\ \vdots \\ \sum_{i=1}^{n'} h_{n'i} v_i - \sum_{i=1}^{n'} h_{n'i} v_{i+n'} \end{bmatrix} = \begin{bmatrix} H_{k-1} v_1 \\ H_{k-1} v_1 \end{bmatrix} + \begin{bmatrix} H_{k-1} v_2 \\ -H_{k-1} v_2 \end{bmatrix} \quad (1)$$

We claim that the following algorithm, which uses the above equation, calculates the desired matrix-vector product runs in $\theta(n \log n)$ operations.

We first recursively compute $H_{k-1} v_1$ and $H_{k-1} v_2$ (which are of size $n' = n/2$).

Extending $H_{k-1} v_1$ by adding itself to create $\begin{bmatrix} H_{k-1} v_1 \\ H_{k-1} v_1 \end{bmatrix}$ takes constant operation.

Extending $H_{k-1} v_2$ by adding itself multiplied by -1 to create $\begin{bmatrix} H_{k-1} v_2 \\ -H_{k-1} v_2 \end{bmatrix}$ takes $\theta(n/2) \in \theta(n)$ operation.

Thus, the total time complexity of this algorithm is given by recurrence relation $T(n) = 2T(n/2) + \theta(n)$, which solves to $\theta(n \log n)$ by master theorem.

Q2

In this question, we assume that:

- Computing $n/3$ takes $O(1)$ time for all $n \in \mathbb{N}$.
- Shifting bits (multiplication by a power of 2) takes $O(n)$ time.
- Addition and subtraction takes $O(n)$ time.

(a)

Let $m = n/3$ (we ignore ceiling), $x = a_2 2^{2m} + a_1 2^m + a_0$ then we compute the following.

Define

- $p(B) = a_2 B^2 + a_1 B + a_0$
- $P(B) = (p(B))^2 = c_4 B^4 + c_3 B^3 + c_2 B^2 + c_1 B + c_0$ for some $c_4, c_3, c_2, c_1, c_0 \in \mathbb{R}$
Note that $c_4 = a_2^2$ and $c_0 = a_0^2$

and let

- $r_0 = a_0^2$
- $r_1 = (a_2 + a_1 + a_0)^2 = (p(1))^2 = P(1)$
- $r_2 = (a_2 - a_1 + a_0)^2 = (p(-1))^2 = P(-1)$
- $r_3 = (4a_2 + 2a_1 + a_0)^2 = (p(2))^2 = P(2)$
- $r_4 = a_2^2$

Thus,

$$\begin{bmatrix} 0 & 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 16 & 8 & 4 & 2 & 1 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} c_4 \\ c_3 \\ c_2 \\ c_1 \\ c_0 \end{bmatrix} = \begin{bmatrix} r_0 \\ r_1 \\ r_2 \\ r_3 \\ r_4 \end{bmatrix}$$

Let H be the matrix above, then

$$H^{-1} \begin{bmatrix} r_0 \\ r_1 \\ r_2 \\ r_3 \\ r_4 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 1 \\ \frac{1}{2} & -\frac{1}{2} & -\frac{1}{6} & \frac{1}{6} & -2 \\ -1 & \frac{1}{2} & \frac{1}{2} & 0 & -1 \\ -\frac{1}{2} & 1 & -\frac{1}{3} & -\frac{1}{6} & 2 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} r_0 \\ r_1 \\ r_2 \\ r_3 \\ r_4 \end{bmatrix} = \begin{bmatrix} c_4 \\ c_3 \\ c_2 \\ c_1 \\ c_0 \end{bmatrix} = \begin{bmatrix} r_4 \\ \frac{1}{2}r_0 - \frac{1}{2}r_1 - \frac{1}{6}r_2 + \frac{1}{6}r_3 - 2r_4 \\ -r_0 + \frac{1}{2}r_1 + \frac{1}{2}r_2 - r_4 \\ -\frac{1}{2}r_0 + r_1 - \frac{1}{3}r_2 - \frac{1}{6}r_3 + 2r_4 \\ r_0 \end{bmatrix}$$

Thus, all the coefficient can be computed using dividing by 3, bit shifting, and addition and subtraction, which in combination takes $O(n)$ time. Since

$$x^2 = (a_2 2^{2m} + a_1 2^m + a_0)^2 = c_4 2^{4m} + c_3 2^{3m} + c_2 2^{2m} + c_1 2^{1m} + c_0 = P(2^m)$$

with additional shifting and addition operation, we can compute x^2 that takes $5T(n/3) + O(n) \in O(n^{\log_3 5})$

(b)

Let $m = n/3$ (we ignore ceiling), $A = a_22^{2m} + a_12^m + a_0$, $B = b_22^{2m} + b_12^m + b_0$ then we compute the following.

Define

- $p(X) = a_2X^2 + a_1X + a_0$
- $q(X) = b_2X^2 + b_1X + b_0$
- $P(X) = p(X)q(X) = c_4X^4 + c_3X^3 + c_2X^2 + c_1X + c_0$ for some $c_4, c_3, c_2, c_1, c_0 \in \mathbb{R}$
Note that $c_4 = a_2b_2$ and $c_0 = a_0b_0$

and let

- $r_0 = a_0b_0 = c_0$
- $r_1 = (a_2 + a_1 + a_0)(b_2 + b_1 + b_0) = p(1)q(1) = P(1)$
- $r_2 = (a_2 - a_1 + a_0)(b_2 - b_1 + b_0) = p(-1)q(-1) = P(-1)$
- $r_3 = (4a_2 + 2a_1 + a_0)(4b_2 + 2b_1 + b_0) = p(2)q(2) = P(2)$
- $r_4 = a_2b_2 = c_4$

Using the same matrix operation, we can derive coefficients, Since

$$AB = (a_22^{2m} + a_12^m + a_0)(b_22^{2m} + b_12^m + b_0) = P(2^m) = c_42^{4m} + c_32^{3m} + c_22^{2m} + c_12^{1m} + c_0$$

we can compute the multiplication in $O(n^{\log_3 5})$ due to the same reasoning as part(a).

Q3

Algorithm 1 3 Split Huffman Encoding

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1: function HUFFMAN( $S$ )           ▷  $F$  is the priority queue of (frequency, letter) where frequency is key
2:   if size of  $S \leq 3$            ▷ Base case returns correct encoding when size  $\leq 3$ 
3:     return a single node tree if  $|S| = 1$ .
4:     return a tree with two leaves if  $|S| = 2$ .
5:     return a tree with three leaves if  $|S| = 3$ .
6:   end if

7:   If the size of  $S$  is even pad  $S$  with a dummy character with frequency = 0.

8:    $x, y, z \leftarrow$  three smallest frequency elements in  $S$ .
9:   Let  $w := xyz'$ 
10:  Let  $f_w := f_x + f_y + f_z$ 
11:  Push  $(f_w, w)$  to  $S$            ▷ Create input with smaller size for recursive call
12:   $H \leftarrow \text{Huffman}(S)$ .

13:  Find the node  $w^*$  in  $H$  that corresponds to  $w$ .
14:  Add branches as children of  $w^*$ .           ▷ This assigns encoding to branches.
15:  return  $H$ 

16: end function

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Time Complexity

The base case takes $O(1)$ time. For the recursive case, popping the three or two smallest elements takes $O(\log n)$ time. All operations before the recursive call take $O(1)$ time, and all operations after the recursive call take $O(1)$ time (e.g., the tree is implemented using direct access table). Since branching by factor of 3 will reduce the time complexity more than by branching factor of 2, The time complexity of this algorithm is given by the recurrence relation $T(n) \leq T(n-1) + O(\log n)$ = recurrence relation of original Huffman algorithm. From lecture, original Huffman algorithm takes $O(n \log n)$, thus, $T(n) \in O(n \log n)$.

Correctness

(Lemma 1) In an optimal ternary tree that is not a single node tree, every node other than the root must have a sibling, because if otherwise, replacing the parent of a single child with its child gives tree with lower total length, contradicting that the original tree was optimal.

(Lemma 2) The optimal ternary tree T is a full ternary tree if it has odd number of leaves ≥ 3 . Suppose for contradiction that it is not. Then there is at least one node that has binary branching, let v be the deepest such node. If v is not a parent of two leaves, by moving a non-child leaf of the subtree rooted at v as the child of v we can find a tree with lower loss than T . If v is a parent of two leaves, there are two cases. If there is another binary branching at node u , moving a child of v as a child of u and replacing v with its remaining child makes a lower cost tree. If there no other binary branching, then the tree cannot have odd number of leaves, since for each node from v to root, it give rise to $3_1^{k_1} + 3_2^{k_2}$ leaves for some k_1, k_2 , and this number must be even.

(Lemma 3) In optimal ternary tree, the three lowest frequency nodes x, y, z (in this order) must be the three deepest node (in that order). Suppose for contradiction that it is not. Let $p \in x, y, z$ then there exists at least one q such that q is more frequent than p but located deeper than p . swapping p and q leads to a tree with lower total length, which is a contradiction.

Proof.

As the base case, when the size of $|S| \leq 3$ the algorithm outputs optimal tree.

In any other cases the algorithm ensure that $|S|$ is odd at line 7.

Assume as IH that algorithm outputs optimal tree when size of input is less than $k \in \mathbb{N}^{\geq 3}$.

Let S be an input of size k . Let H be the output of the algorithm given S . Let S' be the S after operations at line 8 to 11. Then the recursive call at line 12 returns the optimal tree, H' over S' by IH.

Let f_w be the sum of frequencies of x, y, z . We know that total loss of S , $loss(H) = f_w + loss(H')$ (using the same reasoning as KT p.174 but using three frequencies instead of two).

Suppose for contradiction H is not optimal. Then there exists an optimal tree T over S , and thus $loss(H) > loss(T)$. Because T is optimal, the three lowest frequency nodes appear as siblings at the deepest level of T . (by lemma 2 and 3). Let T' be a tree after removing the three lowest frequency nodes from T . Similarly as above, T' is a optimal tree over S' and we can show that $loss(T) = f_w + loss(T')$ by using the same reasoning as above.

By IH, $loss(H') \leq loss(T')$. However, then $loss(H) = f_w + loss(H') \leq f_w + loss(T') = loss(T)$, which is a contradiction. \square

Q4

Algorithm 2 Maximize Profit

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1: function MAXIMIZEPROFIT( $E$ )                                 $\triangleright$   $E$  is the priority queue of  $(g_i, t_i)$  where  $t_i$  is the key
2:    $schedule \leftarrow []$ ;  $time \leftarrow 0$ 
3:   while  $E$  is not empty do
4:      $Q \leftarrow$  Max-Heap of  $(g_i, t_i)$  where the key is  $g_i$ 
5:      $(g_i, t_i) \leftarrow \mathbf{Dequeue}(E)$ 
6:     while  $E$  is not empty and  $time \leq t_i < time + 1$  do
7:       Enqueue  $(g_i, t_i)$  to  $Q$  and update  $(g_i, t_i)$  with the output of Dequeue( $E$ )
8:     end while
9:     If  $t_i$  of the last tuple is within  $[time, time + 1)$  Enqueue  $(g_i, t_i)$  to  $Q$ 
10:    Else Enqueue  $(g_i, t_i)$  to  $E$                                  $\triangleright$  enqueue the tuple back to  $E$  if it is out of the range
11:    If  $Q$  is not empty Add Max( $Q$ ) to  $schedule$ 
12:     $time \leftarrow time + 1$ 
13:  end while
14:  return  $schedule$ 
15: end function

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Time Complexity

If we had to build priority queue, this takes $O(n)$ time. Every operation other than enqueueing or dequeuing takes constant time.

Let j_i be the number of iterations of inner while loop at i th iteration of the outer while loop. At least j_i number of tuples are removed from E at i th iteration. Suppose that the outer loop iterates k times in total. Then the outer while loop stops when $\sum_{i=1}^k j_i = n$. The total number of enqueueing and dequeuing at i th iteration is $2 + 2j_i$. Thus, total number of enqueueing and dequeuing of the algorithm is $\sum_{i=1}^k 2 + 2j_i = 2k + 2n$.

k can exceed n iff inner loop does not iterate for many iteration of the outer loop. However, because the time gets incremented at each iteration of the outer loop, $2k + 2n \in O(\max(\max(t_i)_{i=1}^n, n))$. Let $m = \max(\max(t_i)_{i=1}^n, n)$, then the algorithm takes $O(m \log n)$ time.

Correctness

We define optimality as maximizing the sum of profit.

For each $t \in \mathbb{N}$, define $P(t)$ as: at the end of t th iteration of the outer loop, the algorithm have the optimal solution ($schedule$) among all the events i where $t_i \in [0, t)$

For the base case $t = 0$, the empty array $schedule$ is the optimal solution in $[0, 0)$.

Let $t \in \mathbb{N}^+$ and assume $P(t-1)$ holds. By IH, $schedule$ is the optimal solution in the time interval $[0, t-1)$.

Since *time* increases by 1 at the end of every iteration of the outer loop, $time = t - 1$ during the t th iteration of the outer loop. If E is empty at the beginning of t th iteration of the outer loop, then the function returns, and all the events have critical time within the range $[0, t - 1)$. Thus the algorithm outputs the optimal solution within $[0, t)$.

Suppose that E is not empty and the outer loop is executed

(Case 1) E becomes empty before the inner loop gets executed.

If $t_i \in [t - 1, t)$, then the last item in E is added to schedule, and result in schedule with maximum benefit among all the events with critical time within $[0, t)$.

If $t_i \notin [t - 1, t)$ then it is trivial to show $P(t)$.

(Case 2) E is non-empty right before the inner loop, but loop does not iterate.

Then the only event (g_i, t_i) dequeued at line 5 is not added to schedule since $t_i \notin [0, t)$ and iteration ends. Note that t_i cannot be less than $t - 1$ because in that case it would have dequeued in the previous iteration. All the events following it will have critical value of at least t_i , and hence will not be in $[0, t)$. Thus all the events in $[0, t)$ is equivalent to all the events in $[0, t - 1)$, and schedule has optimal solution among all the tasks whose critical time is within $[0, t)$.

(Case 2) If E is non empty and the inner loop iterates at least once.

Then the inner loop adds all the events to Q if their critical time is within $[0, t)$. Because every event takes one unit of time and we can do only one task in Q , choosing the event with maximum profit gives the optimal solution among all the tasks in the interval $[0, t)$.

Thus in any case, at the end of t th iteration, the algorithm have the optimal solution (*schedule*) among all the events i where $t_i \in [0, t)$

Let $t_{max} = \lceil \max_{i=1}^n t_i \rceil + 1$ then by $P(t_{max})$, the algorithm outputs the optimal solution among all the events in E .