## Chap 2: Linear Regression

Least Squares Method, Multiple Regression and Distribution of  $\hat{\beta}$ 

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#### Outline

1 Least Squares Method

2 Multiple Regression

3 Distribution of  $\hat{\beta}$ 

## Simple Linear Regression

 $\bullet$  The data consists of  $(x_1,y_1),...,(x_N,y_N)$ 

$$y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$$

- $\beta_0$ : intercept
- $\beta_1$ : slope
- $\varepsilon_i$ : random error
- We obtain  $\beta_0$  and  $\beta_1$  via the least squares method.

## Least Squares Method

• sum of squares of the residuals, we minimize L of the squared distances L between  $(x_i,y_i)$  and  $(x_i,\beta_0+\beta_1x_i)$  over i=1,2,...,N.

$$L = \sum_{i=1}^N (y_i - \beta_0 - \beta_1 x_i)^2$$

• Then, by partially differentiating L by  $\beta_0, \beta_1$  and letting them be zero.

$$\begin{split} \frac{\partial L}{\partial \beta_0} &= -2\sum_{i=1}^N (y_i - \beta_0 - \beta_1 x_i) = 0 \\ \frac{\partial L}{\partial \beta_1} &= -2\sum_{i=1}^N (x_i (y_i - \beta_0 - \beta_1 x_i)) = 0 \end{split}$$

•  $\beta_0$  and  $\beta_1$  are regarded as constants when differentiating L by  $\beta_1$  and  $\beta_0$ .

#### Least Squares Method

• When  $\sum_{i=1}^{N}(x_i-\bar{x})^2\neq 0$ ,  $\hat{\beta}_0$ ,  $\hat{\beta}_1$  instead of  $\beta_0$ ,  $\beta_1$  which means that they are not the true values but rather estimates obtained from data.

$$\begin{split} \hat{\beta}_1 &= \frac{\sum_{i=1}^N (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^N (x_i - \bar{x})^2} \\ \hat{\beta}_0 &= \bar{y} - \hat{\beta}_1 \bar{x} \end{split}$$

• We center the data as follows,

$$\tilde{x}_1:=x_1-\bar{x},\cdots,\tilde{x}_N:=x_N-\bar{x},\tilde{y}_1:=y_1-\bar{y},\cdots,\tilde{y}_N:=y_N-\bar{y}$$

- Center the data results in a zero average.
- The formula for calculating the slope from the centralized data is as follows:

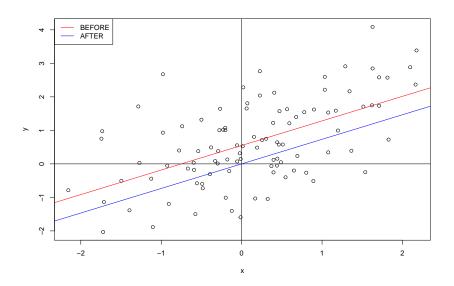
$$\hat{\beta}_1 = \frac{\sum_{i=1}^N \tilde{x}_i \tilde{y}_i}{\sum_{i=1}^N (\tilde{x}_i)^2}$$

#### Example

 The two lines l is obtained from the N pairs of data and the least squares method, and l' obtained by shifting l so that it goes through the origin.

```
min.sq=function(x,y){
  x.bar=mean(x);y.bar=mean(y)
  beta.1=sum((x-x.bar)*(y-y.bar))/sum((x-x.bar)^2);beta.0=y.bar-beta.1*x.bar
  return(list(a=beta.0,b=beta.1))
a=rnorm(1);b=rnorm(1);
N=100; x=rnorm(N); y=a*x+b+rnorm(N)
plot(x,y); abline(h=0); abline(v=0)
abline(min.sq(x,y)$a,min.sq(x,y)$b,col="red")
x=x-mean(x); y=y-mean(y)
abline(min.sq(x, y)a,min.sq(x, y)b,col="blue")
legend("topleft",c("BEFORE", "AFTER"),lty=1,col=c("red", "blue"))
```

## Example



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## Multiple Regression with Matrices

We formulate the least squares method for multiple regression with matrices.

$$\bullet \ L := \textstyle \sum_{i=1}^N (y_i - \beta_0 - \beta_1 x_i)^2,$$

$$L = \parallel y - X\beta \parallel^2 = (y - X\beta)^T (y - X\beta)$$

• If we define,

$$y := \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix}, X := \begin{bmatrix} 1 & x_{1,1} & \cdots & x_{1,p} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{N,1} & \cdots & x_{N,p} \end{bmatrix}, \beta := \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \end{bmatrix}$$

• Partial differentiation with L

$$\nabla L := \begin{bmatrix} \frac{\partial L}{\partial \beta_0} \\ \frac{\partial L}{\partial \beta_1} \end{bmatrix} = -2X^T (y - X\beta)$$

## Multiple Regression

• Set to zero to find the minimum value

$$-2X^T(y-X\beta) = \begin{bmatrix} -2\sum_{i=1}^N (y_i - \sum_{j=0}^p \beta_j x_{i,j}) \\ -2\sum_{i=1}^N x_{i,1} (y_i - \sum_{j=0}^p \beta_j x_{i,j}) \\ \vdots \\ -2\sum_{i=1}^N x_{i,p} (y_i - \sum_{j=0}^p \beta_j x_{i,j}) \end{bmatrix}$$

 $\bullet$  When a matrix  $X^TX$  is invertible, we have

$$\hat{\beta} = (X^TX)^{-1}X^Ty$$

## When $X^TX$ is irreversible

1. 
$$N$$

$$rank(X^TX) \leq rank(X) \leq min\{N,p+1\} = N < p+1$$

2. Two columns in X coincide.

$$X^TXz = 0 \Rightarrow z^TX^TX_Z = 0 \Rightarrow \parallel X_z \parallel^2 = 0 \Rightarrow X_z = 0$$

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# Distribution of $\hat{\beta}$

• y have been obtained from the covariates X multiplied by the (true) coefficients  $\beta$  plus some noise  $\epsilon$ .

$$y = X\beta + \epsilon$$

- The true  $\beta$  is unknown and different from the estimate  $\hat{\beta}$ .
- $\bullet$  We have estimated  $\hat{\beta}$  via the least squares method from the N pairs of data  $(x_1,y_1),\!\cdots,\!(x_N,y_N)\in R^p\ge R$

#### **Density function**

• We assume that each element  $\epsilon_1, \dots, \epsilon_N$  in the random variable  $\epsilon$  is independent of the others and Gaussian distribution with mean zero and variance  $\sigma^2$ .  $N(0, \sigma^2)$ 

$$f_i(\epsilon_i) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{\epsilon_i^2}{2\sigma^2}}$$

 $\bullet$  We may express the distributions of  $\epsilon_1, \cdots, \epsilon_N$  by

$$f(\epsilon) = \prod_{i=1}^{N} f_i(\epsilon_i) = \frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{\epsilon^T \epsilon}{2\sigma^2}}$$

This is  $N(0, \sigma^2 I)$ , I is a unit matrix of size N.

## Independent if and only if their covariance is zero

• For the proof,

$$\hat{\beta} = (X^TX)^{-1}X^T(X\beta + \epsilon) = \beta + (X^TX)^{-1}X^T\epsilon$$

• Since the average of  $\epsilon \in R^N$  is zero, the average of  $\epsilon$  multiplied from left by the constant matrix  $(X^TX)^{-1}X^T$  is zero.

$$E[\hat{\beta}] = \beta$$

 In general, we say that an estimate is unbiased if its average coincides with the true value.

# Covariance matrix of $\hat{\beta}$

- $V(\hat{\beta}_i) = E(\hat{\beta}_i \beta_i)^2, i = 0, 1, \dots, p$ , the covariance  $\sigma_{i,j} := E(\hat{\beta}_i \beta_i)(\hat{\beta}_j \beta_j)^T$  can be defined for each pair  $i \neq j$ .
- matrix consisting of  $\sigma_{i,j}$  in the *i*th row and *j*th column as to the covariance matrix of  $\hat{\beta}$ .

$$E\begin{bmatrix} (\hat{\beta}_0 - \beta_0)^2 & (\hat{\beta}_0 - \beta_0)(\hat{\beta}_1 - \beta_1) & \cdots & (\hat{\beta}_0 - \beta_0)(\hat{\beta}_p - \beta_p) \\ (\hat{\beta}_1 - \beta_1)(\hat{\beta}_0 - \beta_0) & (\hat{\beta}_1 - \beta_1)^2 & \cdots & (\hat{\beta}_1 - \beta_1)(\hat{\beta}_p - \beta_p) \\ \vdots & \vdots & \ddots & \vdots \\ (\hat{\beta}_p - \beta_p)(\hat{\beta}_0 - \beta_0) & (\hat{\beta}_p - \beta_p)(\hat{\beta}_1 - \beta_1) & \cdots & (\hat{\beta}_p - \beta_p)^2 \end{bmatrix}$$

# Covariance matrix of $\hat{\beta}$

$$\begin{split} E \begin{bmatrix} (\hat{\beta}_0 - \beta_0)^2 & (\hat{\beta}_0 - \beta_0)(\hat{\beta}_1 - \beta_1) & \cdots & (\hat{\beta}_0 - \beta_0)(\hat{\beta}_p - \beta_p) \\ (\hat{\beta}_1 - \beta_1)(\hat{\beta}_0 - \beta_0) & (\hat{\beta}_1 - \beta_1)^2 & \cdots & (\hat{\beta}_1 - \beta_1)(\hat{\beta}_p - \beta_p) \\ \vdots & \vdots & \ddots & \vdots \\ (\hat{\beta}_p - \beta_p)(\hat{\beta}_0 - \beta_0) & (\hat{\beta}_p - \beta_p)(\hat{\beta}_1 - \beta_1) & \cdots & (\hat{\beta}_p - \beta_p)^2 \end{bmatrix} \\ = E \begin{bmatrix} \hat{\beta}_0 - \beta_0 \\ \hat{\beta}_1 - \beta_1 \\ \vdots \\ \hat{\beta}_p - \beta_p \end{bmatrix} \begin{bmatrix} \hat{\beta}_0 - \beta_0, \hat{\beta}_1 - \beta_1, \cdots, \hat{\beta}_p - \beta_p \end{bmatrix} \\ = E(\hat{\beta} - \beta)(\hat{\beta} - \beta)^T = E(X^TX)^{-1}X^T\epsilon(X^TX)^{-1}X^T\epsilon^T \\ = (X^TX)^{-1}X^TE\epsilon\epsilon^TX(X^TX)^{-1} = \sigma^2(X^TX)^{-1} \end{split}$$

We have determined that the covariance matrix of  $\epsilon$  is  $E\epsilon\epsilon^T = \sigma^2 I$ .

$$\hat{\beta} \sim N(\beta, \sigma^2(X^TX)^{-1})$$

# 감사합니다