Deep Learning을 이용한 개체명 분석

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구현

개체명 분석

개체명 분석

한국소비자보호원은 19일 시판중인 선물세트의 상당수가 과대 포장된

ORGANIZATION

DATE

Class 설계 (5개 Class)

√ OG : Organization

✓ DT : Date

✓ TI : Time

✓ LC : Location

✓ PS : Person

개체명 분석 데이터 (1)

- https://github.com/krikit/annie
- 2016년 한글 및 한국어 정보처리 학술대회 : "2016년 엑소브레인 V2.0 & 울산대학교 말뭉치"라는 명칭의 CD로 배포

아	B-LC
프	I-LC
가	I-LC
니	I-LC
스 탄	I-LC
탄	I-LC
의	0
	0
	0
헤	B-OG
즈	I-OG

• Train Data:./applications/sentiment_analysis/data/ner.n2n.txt

BIO Tagging scheme for Sequential Data

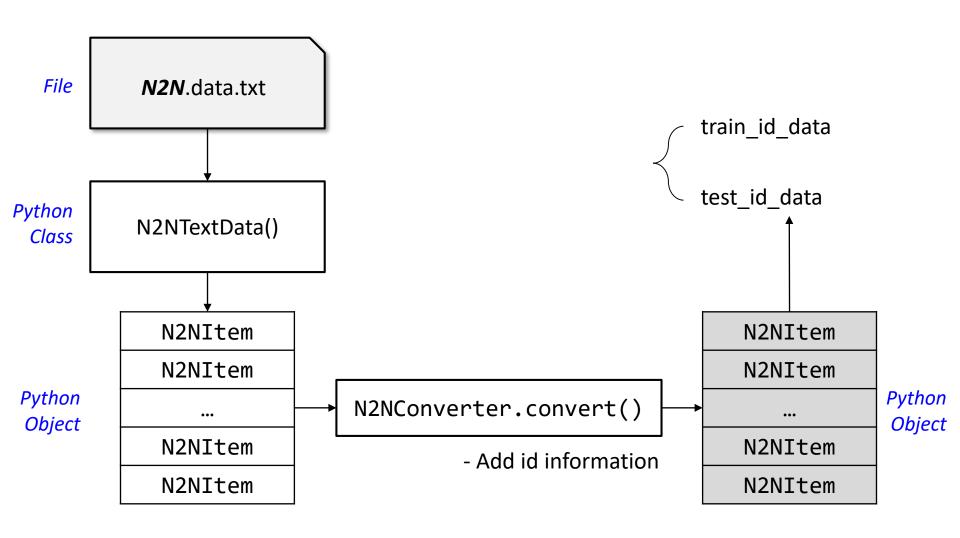
B-Tag	Beginning of the <i>tag</i>					
I-Tag	Inside of the <i>tag</i>					
0	Outside					

지	난	달		2	7	일	부	터		매	일		오	후		4	시	에
B-DT	I-DT	I-DT	I-DT	I-DT	I-DT	I-DT	0	0	0	B-DT	I-DT	0	B-TI	I-TI	I-TI	I-TI	I-TI	0

You can use other sequential tagging schems

- IO
- BMEWO
- BMEWO+
- BIOES
- ...

[N2N] Data Processing Flow



Code is available

https://github.com/hugman/deep_learning/tree/master/course/nlp

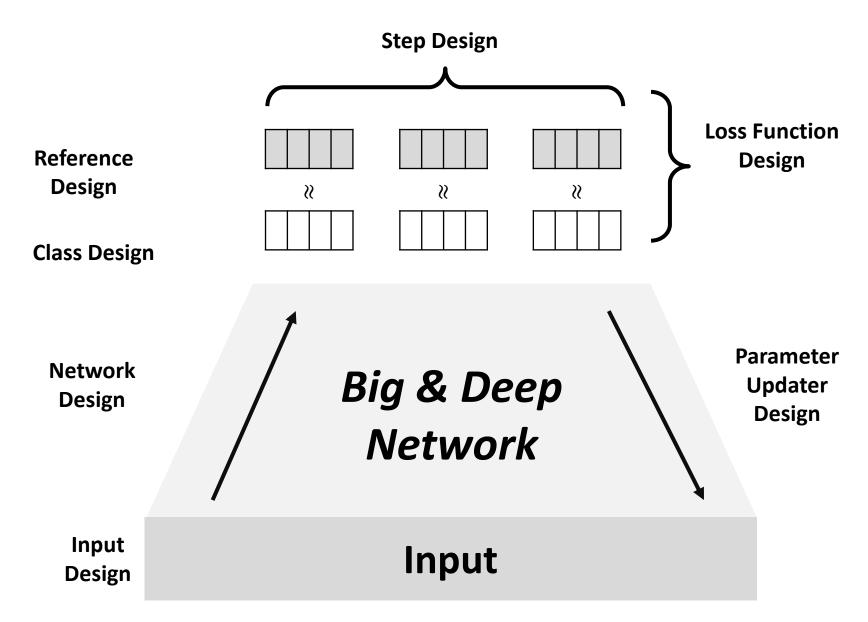
./applications./nanmed_entity_recognition/dataset : load_data()

```
# vocab loader
token_vocab_fn = os.path.join( os.path.dirname(__file__), 'data',
    'token.vocab.txt')
token_vocab = Vocab(token_vocab_fn, mode='token')
target_vocab_fn = os.path.join( os.path.dirname(__file__), 'data',
    'target.vocab.txt')
target_vocab = Vocab(target_vocab_fn, mode='target')

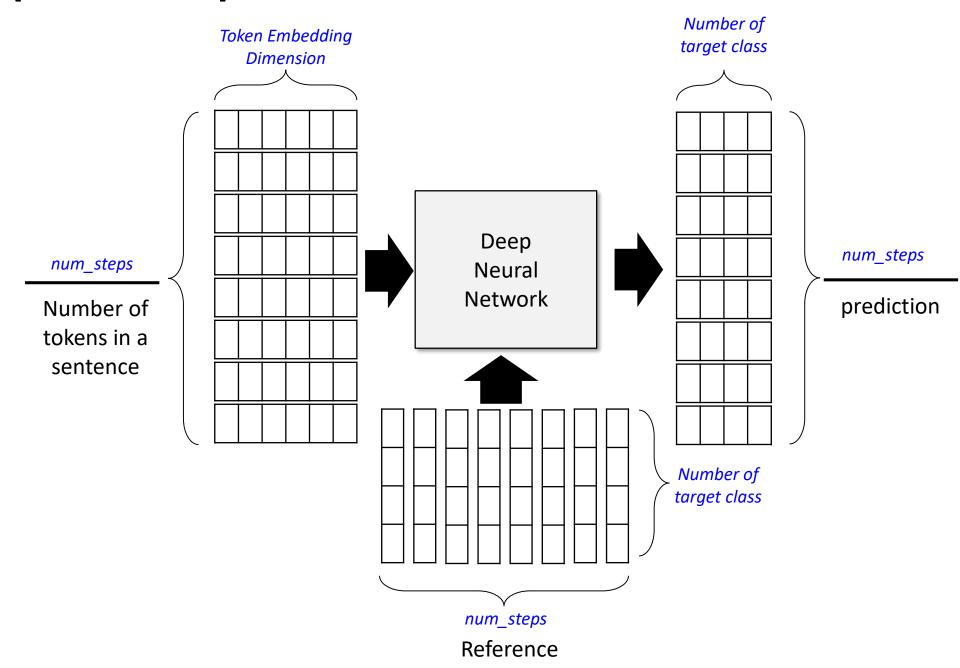
# load train data
train_data_fn = os.path.join( os.path.dirname(__file__), 'data', 'ner.n2n.txt')
train_txt_data = N2NTextData(train_data_fn)

# convert text data to id data
train_id_data = N2NConverter.convert(train_txt_data, target_vocab, token_vocab)
```

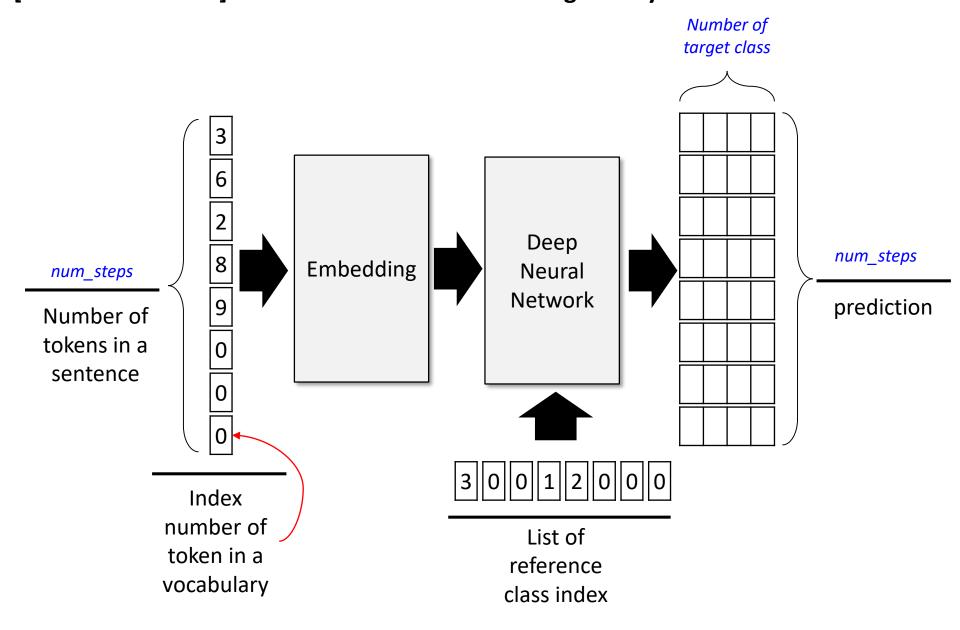
Building Block



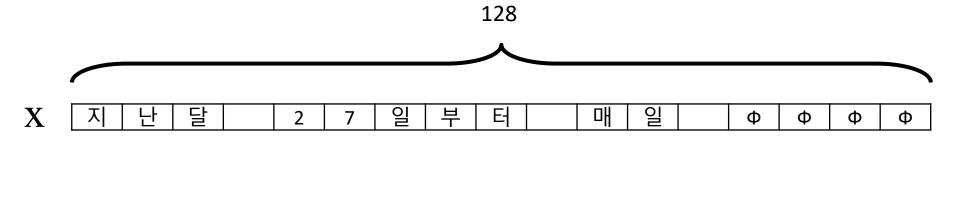
[N2N classification] DNN Interface



[N2N classification] DNN Interface with Embedding Library



Input Design



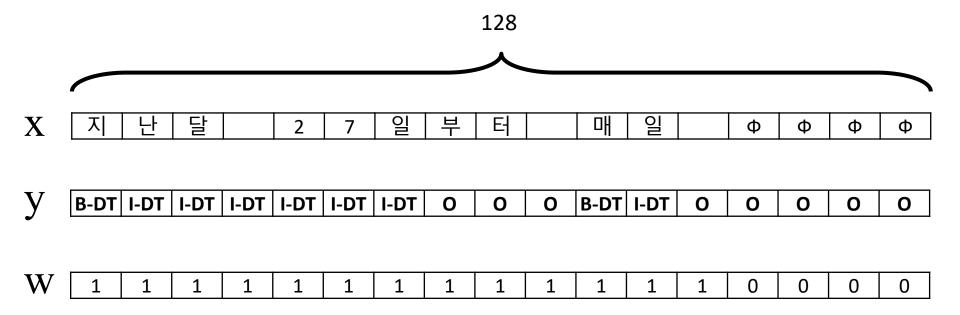
 Y
 B-DT
 I-DT
 I-DT
 I-DT
 I-DT
 I-DT
 O
 O
 B-DT
 I-DT
 O
 O

W

 Φ : padding symbol

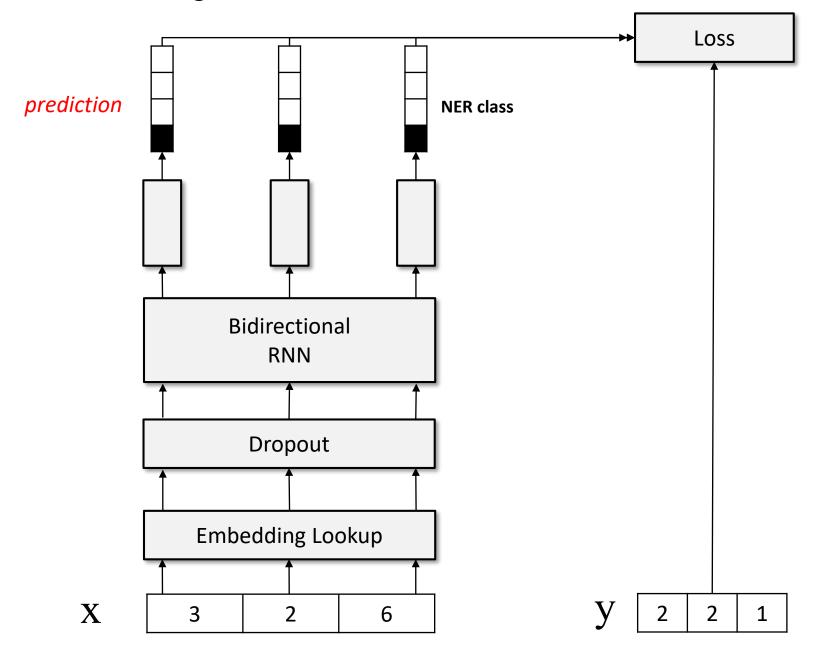
W: to mark padding positions

Tensorflow Interface Implementation

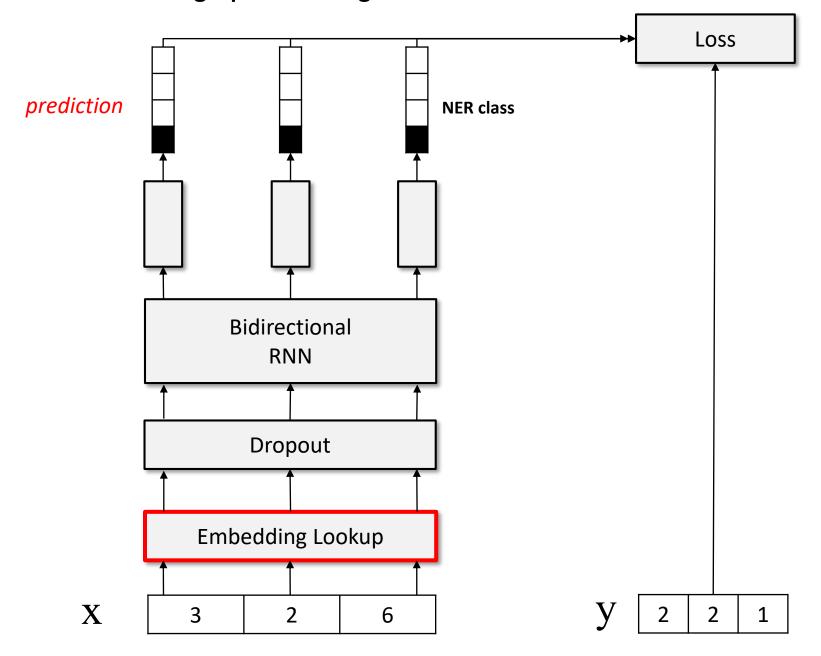


```
x = tf.placeholder(tf.int32, [None, hps.num_steps], name="pl_tokens")
y = tf.placeholder(tf.int32, [None, hps.num_steps], name="pl_target")
w = tf.placeholder(tf.int32, [None, hps.num_steps], name="pl_weight")
batch_size
```

Neural Network Design



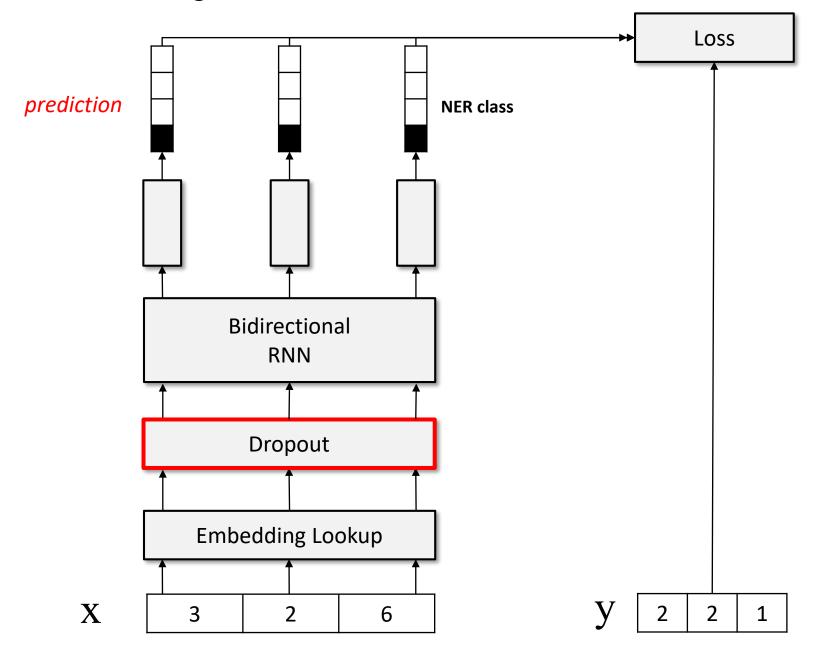
Neural Network Design | embedding



Tensorflow Implementation | Embedding

def _embedding(x)

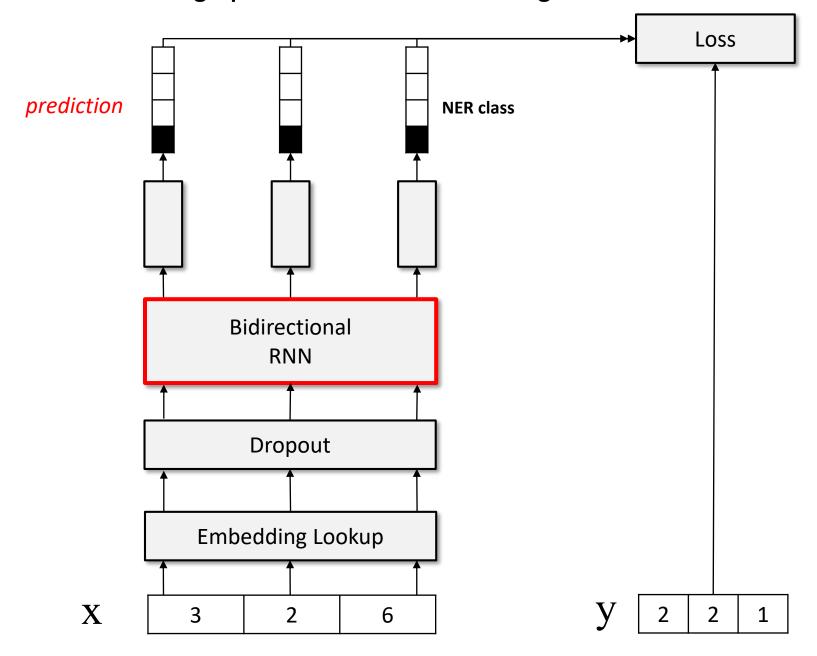
Neural Network Design



Tensorflow Implementation | Dropout

def _sequence_dropout(step_inputs, keep_prob)

Neural Network Design | BiRNN based N2N encoding



Tensorflow Implementation | RNN based N2N encoding | Exercise

def sequence_encoding_n2n(step_inputs, seq_length, cell_size)

```
Input : a list of <tf.Tensor shape=(?, 50), dtype=float32>
```

Return : a list of <tf.Tensor, shape=(?, 100)>

Keywords

tf.contrib.rnn.GRUCell

tf.nn.bidirectional_dynamic_rnn

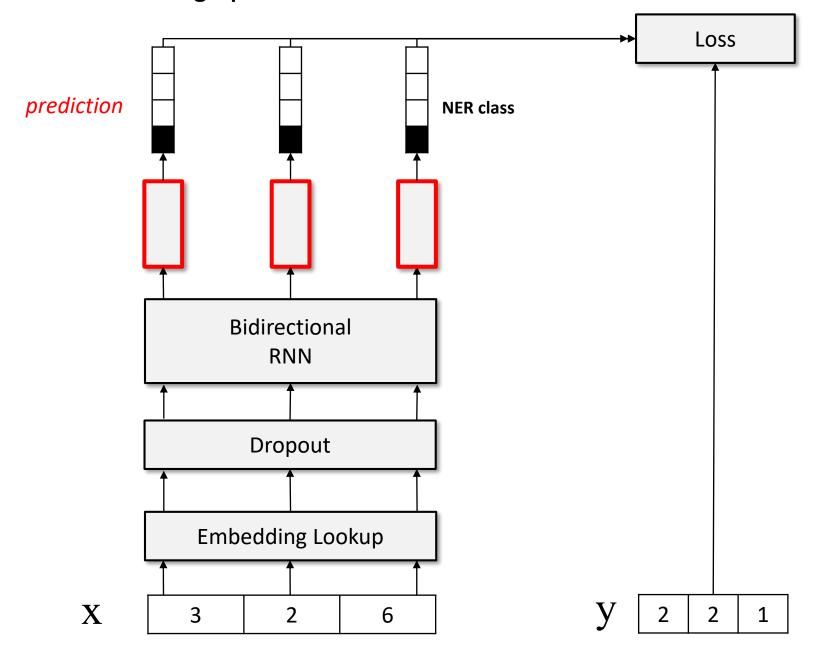
tf.stack

Tensorflow Implementation | RNN based N2N encoding

def sequence_encoding_n2n(step_inputs, seq_length, cell_size)

```
# birnn based N2N encoding
f rnn cell = tf.contrib.rnn.GRUCell(cell size, reuse=False)
b rnn cell = tf.contrib.rnn.GRUCell(cell_size, reuse=False)
inputs = tf.stack(step inputs, axis=1)
outputs, states, = tf.nn.bidirectional_dynamic_rnn(
                             f rnn cell,
                             b_rnn_cell,
                             _inputs,
                             sequence length=tf.cast(seq length, tf.int64),
                             time_major=False,
                             dtype=tf.float32,
                             scope='birnn',
output fw, output bw = outputs
states fw, states bw = states
output = tf.concat([output fw, output bw], 2)
step outputs = tf.unstack(output, axis=1)
final_state = tf.concat([states_fw, states_bw], 1)
return step_outputs
```

Neural Network Design | to class N2N



Tensorflow Implementation | to class | Exercise

def _to_class(step_inputs, num_class)

```
Input : a list of <tf.Tensor shape=(?, 200) dtype=float32>
```

Return : a list of <tf.Tensor, shape=(?, 11), dtype=float32)>

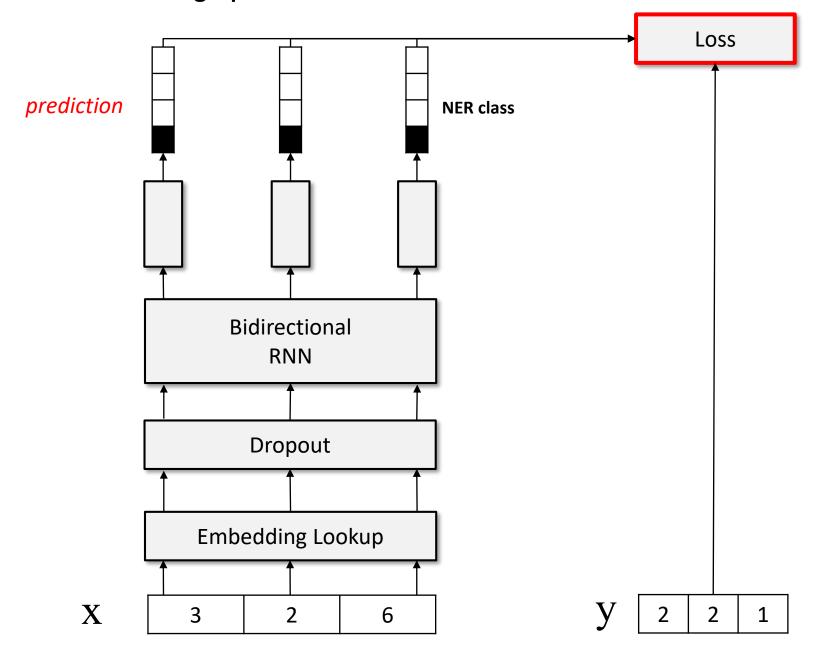
Keywords

tensorflow.contrib.layers.python.layers.linear

Tensorflow Implementation | to class

```
def _to_class(step_inputs, num_class)
 T = len(step_inputs)
 step output logits = []
 for t in range(T):
         # encoder to linear(map)
         out = step inputs[t]
         if t==0: out = linear(out, num_class, scope="Rnn2Target")
                  out = linear(out, num class, scope="Rnn2Target", reuse=True)
         step_output_logits.append(out)
 return step output logits
# output of the neural network
 # step preds and step out probs
 step out probs = []
 step out preds = []
 for _output in step_outputs:
         out probs = tf.nn.softmax( output)
         out pred = tf.argmax( out probs, 1)
         step out probs.append( out probs)
         step out preds.append( out pred)
 # stack for interface
 self.step out probs = tf.stack(step out probs, axis=1, name="step out probs")
 self.step_out_preds = tf.stack(step_out_preds, axis=1, name="step_out_preds")
```

Neural Network Design | Loss calculation



Tensorflow Implementation | sequencewise loss calculation | Exercise

def _loss(step_outputs, step_refs, weights)

```
Input step_outputs:
    a list of <tf.tensor, shape=(?, 11), dtype=float32>
Input step_refs:
    a list of <tf.tensor, shape=(?, 128), dtype=int32>
Return : tf.Tensor, shape=()
```

Keywords

tensorflow.contrib.seq2seq.sequence_loss

Tensorflow Implementation | sequencewise loss calculation

def _to_class_n2n(step_inputs, num_class)

from tensorflow.contrib.seq2seq import sequence_loss

Tensorflow Implementation | parameter update

optimizer settings

> train_op should be called outside of the network to update parameters

Training Process

training process

```
while not sv.should_stop():
        fetches = [model.global_step, model.loss, model.train_op]
        a_batch_data = next( train_data_set.iterator )
        y, x, w = a_batch_data
        fetched = sess.run(fetches, {
                                           model.x: x,
                                           model.y: y,
                                           model.w: w,
                                           model.keep_prob: hps.keep_prob,
        local_step += 1
        _global_step = fetched[0]
        loss = fetched[1]
```

감사합니다.

Lecture Blog: www.hugman.re.kr

Lecture Video: https://goo.gl/7NL5hV

Lecture Slides: https://goo.gl/6NfR1V

Code Share: https://github.com/hugman

Facebook: https://goo.gl/1RML3C

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