

# SVD-AE: Simple Autoencoders for Collaborative Filtering



Seoyoung Hong<sup>1</sup>, Jeongwan Choi<sup>2</sup>, Yeon-Chang Lee<sup>3</sup>, Srikanth Kumar<sup>4</sup>, Noseong Park<sup>5</sup>

<sup>1</sup>Boeing Korea Engineering & Technology Center <sup>2</sup>Yonsei University

<sup>3</sup>UNIST <sup>4</sup>Georgia Institute of Technology <sup>5</sup>KAIST <sup>2</sup>jeongwan.choi@yonsei.ac.kr



## Motivation: Achieving Optimal Balance in Recommendation Systems

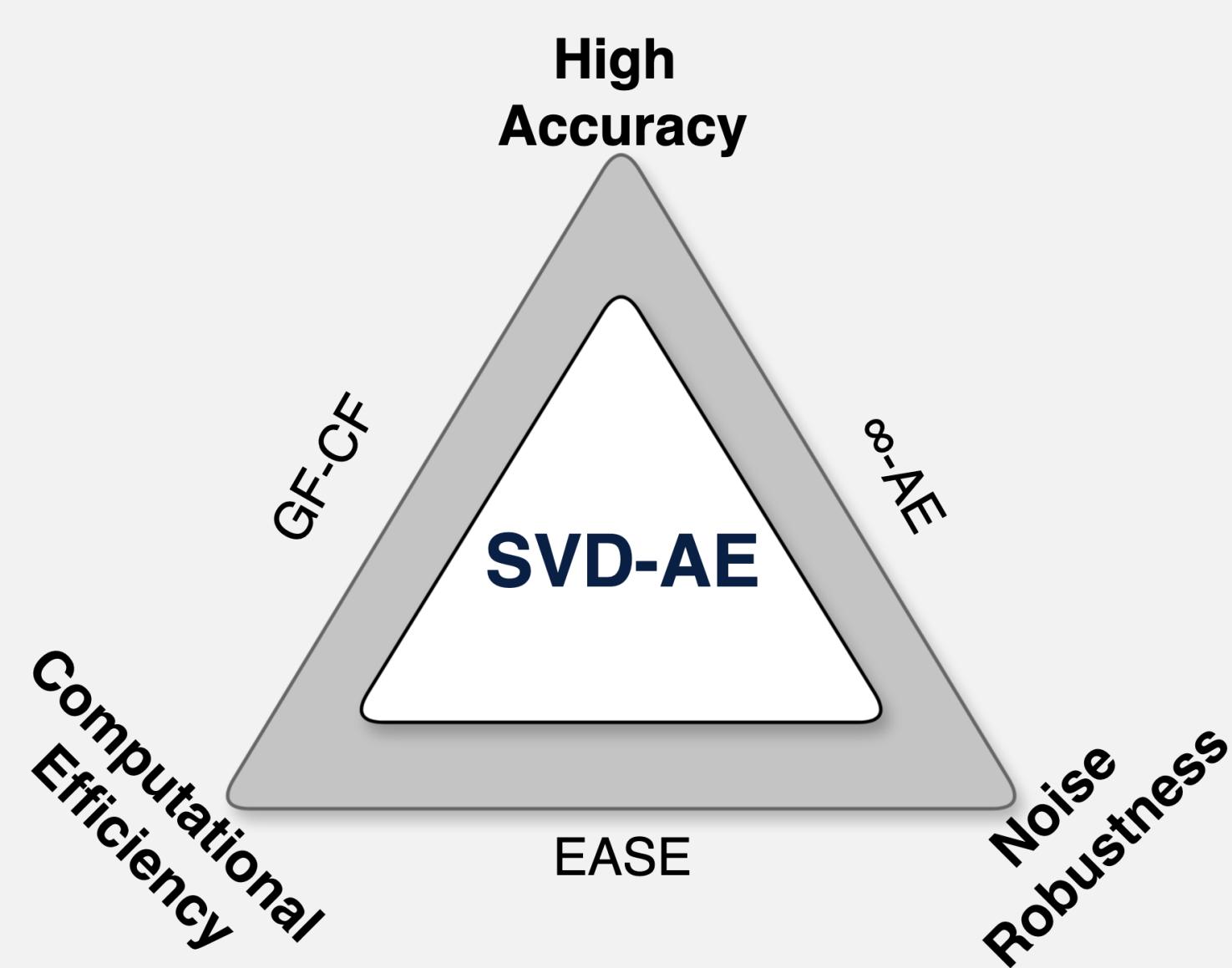


Figure 1: The best overall balance between 3 goals.

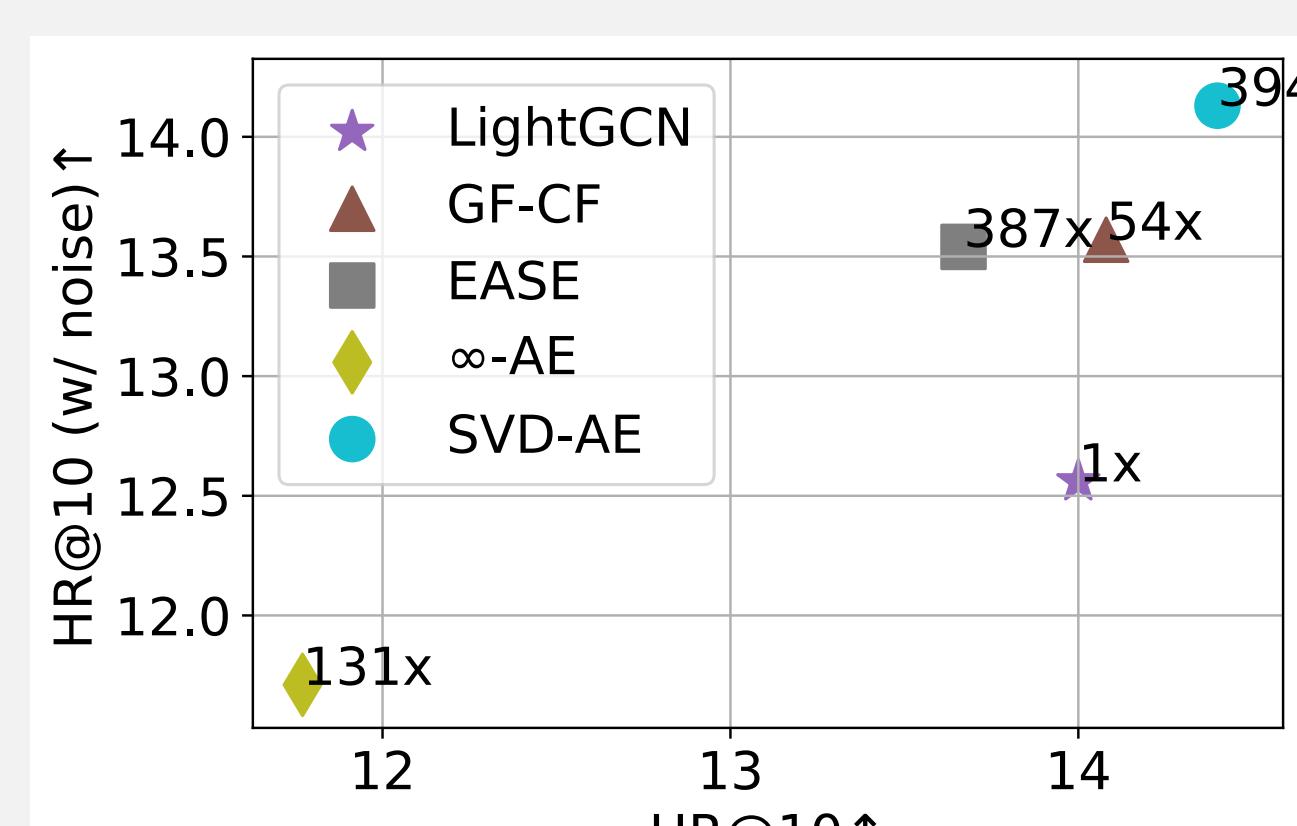


Figure 2: The accuracy, robustness, and computation time of various methods on Gowalla.

	GF-CF [1]	EASE [2]	∞-AE [3]	SVD-AE
Closed-form Solution	✓	✓	✓	✓
Autoencoder-based	✗	✓	✓	✓
Using SVD	✓	✗	✗	✓
Using Neural Networks	✗	✗	✓	✗

Table 1: Comparison of existing lightweight methods and our SVD-AE.

## Performance Comparison

Dataset	Measure	LightGCN	GF-CF	MultVAE	EASE	∞-AE	SVD-AE
Gowalla	HR@10	14.00	14.08	11.88	13.67	11.77	<b>14.40</b>
	HR@100	37.40	<b>38.84</b>	33.56	35.74	34.20	37.34
	NDCG@10	13.77	13.50	11.30	13.15	10.84	<b>13.94</b>
	NDCG@100	21.04	<b>21.25</b>	18.11	20.08	17.97	21.15
	PSP@10	2.26	2.47	2.09	2.31	2.02	<b>2.48</b>
Yelp2018	HR@10	4.32	4.87	4.31	4.65	4.62	<b>4.90</b>
	HR@100	19.01	<b>20.86</b>	18.75	17.74	18.33	19.79
	NDCG@10	4.19	4.66	4.10	4.55	4.48	<b>4.74</b>
	NDCG@100	9.57	<b>10.53</b>	9.37	9.54	10.22	10.22
	PSP@10	0.39	0.44	0.43	0.42	0.43	<b>0.45</b>
ML-1M	HR@10	29.07	30.81	27.86	30.43	31.15	<b>31.79</b>
	HR@100	57.62	59.10	57.67	57.74	<b>60.75</b>	59.33
	NDCG@10	30.30	32.37	28.44	31.90	32.27	<b>33.55</b>
	NDCG@100	39.95	42.00	39.34	40.95	42.54	<b>42.57</b>
	PSP@10	3.01	3.17	3.13	3.16	<b>3.22</b>	3.22
ML-10M	HR@10	34.79	35.10	34.20	36.30	35.83	<b>36.76</b>
	HR@100	64.11	64.23	64.55	64.78	64.48	<b>64.80</b>
	NDCG@10	35.60	36.02	34.48	37.63	36.93	<b>37.75</b>
	NDCG@100	46.14	45.71	45.23	46.74	46.27	<b>46.97</b>
	PSP@10	4.69	4.73	4.82	4.76	4.74	<b>4.93</b>

Table 2: Performance evaluation of overall performance among SVD-AE and baselines

## Generalized Linear Autoencoder for Recommender Systems

- The objective function of linear autoencoder is:

$$\min_{\hat{\mathbf{R}}} \|\mathbf{R} - \hat{\mathbf{R}}\|_F^2, \text{ s.t. } \mathcal{C}, \quad (1)$$

- $\mathbf{R} \in \{0, 1\}^{|U| \times |I|}$  is the given user-item interaction matrix
- $\hat{\mathbf{R}} \in \{0, 1\}^{|U| \times |I|}$  is the reconstructed interaction matrix

- EASE uses ridge regression with a regularization term:

$$\min_{\mathbf{B}} \|\mathbf{R} - \mathbf{RB}\|_F^2 + \lambda \cdot \|\mathbf{B}\|_F^2, \text{ s.t.} \text{diag}(\mathbf{B}) = 0, \quad (2)$$

- $\infty$ -AE uses Kernelized Ridge Regression:

$$\arg\min_{[\alpha_j]_{j=1}^{|U|}} \sum_{u \in U} \|\mathbf{R}_u - f(\mathbf{R}_u|\alpha)\|_2^2 + \lambda \cdot \|f\|_{\mathcal{H}}^2. \quad (3)$$

- Closed-form solutions for optimal  $\hat{\mathbf{R}}$  in different methods:

$$\hat{\mathbf{R}} = \begin{cases} \mathbf{R} \cdot (\mathbf{I} - \hat{\mathbf{P}} \cdot \text{diagMat}(\tilde{\mathbf{I}} \oslash \text{diag}(\hat{\mathbf{P}}))) & (\text{EASE}), \\ \mathbf{K} \cdot (\mathbf{K} + \lambda \mathbf{I})^{-1} \cdot \mathbf{R} & (\infty\text{-AE}), \\ \tilde{\mathbf{R}} \cdot \mathbf{V} \tilde{\Sigma}^+ \mathbf{Q}^T \mathbf{R} & (\text{SVD-AE}), \end{cases} \quad (4)$$

- $\hat{\mathbf{P}} = (\mathbf{R}^T \mathbf{R} + \lambda \mathbf{I})^{-1}$ .

- $\tilde{\mathbf{R}} = \mathbf{D}_U^{-\frac{1}{2}} \mathbf{R} \mathbf{D}_I^{-\frac{1}{2}}$  is a normalized adjacency matrix.

## The Presence of Noise

- $\mathbf{R}$  often contains noisy interactions that don't reflect true user preferences.
- EASE and  $\infty$ -AE use  $\lambda$  to prevent overfitting to noisy rating matrix.
- Smaller  $\lambda$  minimizes MSE but doesn't guarantee better performance.

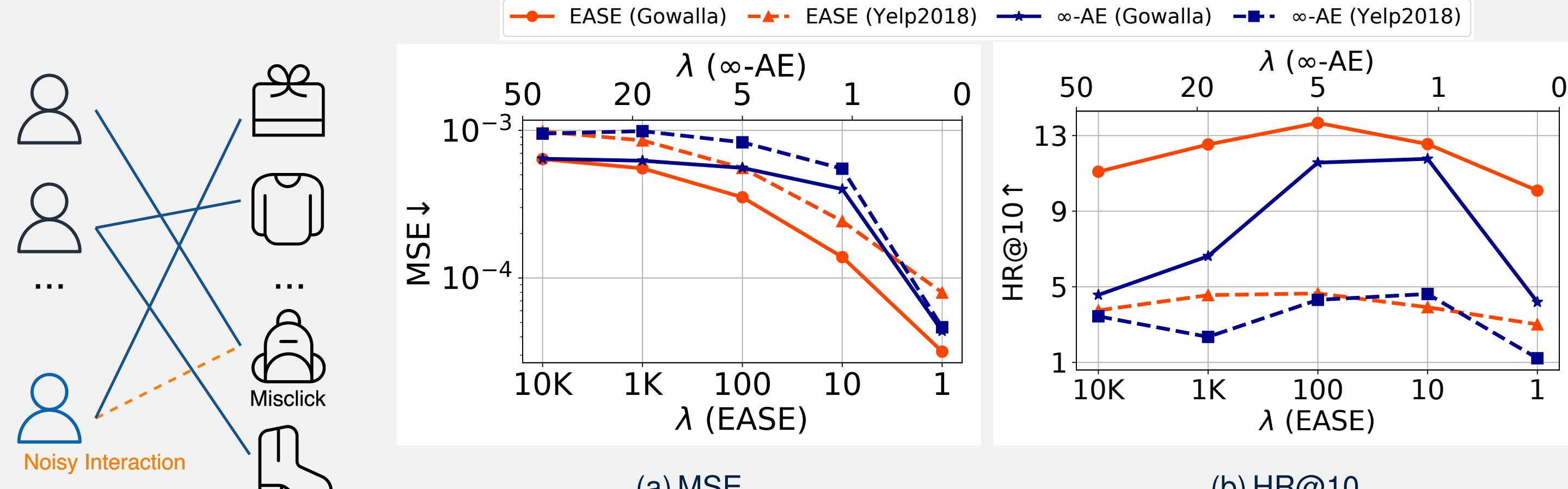


Figure 3: The performance comparison with different regularization parameters.

## SVD-AE Method

- SVD-AE solves a ridge regression-like problem:

$$\min_{\mathbf{B}} \|\mathbf{R} - \tilde{\mathbf{R}}\|_F^2 \quad (5)$$

- The regularization term is implicitly handled by truncated SVD.

- Novel closed-form solution:

$$\mathbf{B} = \tilde{\mathbf{R}}^+ \mathbf{R} = \mathbf{V} \tilde{\Sigma}^+ \mathbf{Q}^T \mathbf{R}, \quad (6)$$

- Let  $\tilde{\mathbf{R}} = \mathbf{Q} \Sigma \mathbf{V}^T$  be the SVD of  $\tilde{\mathbf{R}}$ , then we can get the pseudo-inverse of  $\tilde{\mathbf{R}}$ ,  $\tilde{\mathbf{R}}^+$ .
- $\mathbf{Q} \in \mathbb{R}^{|U| \times m}$  and  $\mathbf{V} \in \mathbb{R}^{|I| \times m}$  are top- $m$  singular vectors
- $\tilde{\Sigma}^+$  contains inverse of top- $m$  singular values of  $\tilde{\mathbf{R}}$
- $m = \lfloor \gamma \times \min(|U|, |I|) \rfloor$ , where  $\gamma = 0.04$  is optimal for all datasets

- Low-rank Inductive Bias in SVD-AE:

- Reduces noise (smaller singular values).

- Speeds up calculations for large, sparse matrices.

## References

- [1] Yifei Shen, Yongji Wu, Yao Zhang, Caihua Shan, Jun Zhang, B Khaled Letaief, and Dongsheng Li. How powerful is graph convolution for recommendation? In *CIKM*, 2021.
- [2] Harald Steck. Embarrassingly shallow autoencoders for sparse data. In *TheWebConf*, 2019.
- [3] Noveen Sachdeva, Mehak Preet Dhaliwal, Carole-Jean Wu, and Julian McAuley. Infinite recommendation networks: A data-centric approach. In *NeurIPS*, 2022.

