

9/13/10

ميرزا

$$a) x(t) = e^{-\xi t} u(-t) + e^{-\alpha t} u(t) (e^{\alpha J t} - e^{\beta J t}) - 1$$

$$x(t) = e^{-\xi t} u(t) + \frac{1}{r_J} e^{-t(\alpha - \beta J)} u(t) - \frac{1}{r_J} e^{-t(\alpha + \beta J)} u(t)$$

$$x(s) = \frac{-1}{s + \xi} + \frac{1}{r_J} + \frac{1}{s - \alpha - \beta J} + \frac{1}{r_J} + \frac{1}{s - \alpha + \beta J}$$

$$\operatorname{Re}\{s\} < -\xi \quad \operatorname{Re}\{s\} > -\alpha \quad \operatorname{Re}\{s\} > -\alpha$$

$$\text{استان} \Rightarrow \alpha < \operatorname{Re}\{s\} < -\xi$$

$$x(s) = \frac{\alpha}{(s + \alpha J)^2 + r_0} + \frac{-1}{s + \xi}$$

$$b) x(s) = \int_0^1 t e^{-st} dt + \int_1^r (r-t) e^{-st} dt$$

$$\Rightarrow \frac{e^{-rs} - r e^{-s}}{s^2} + 1 \quad R_{\alpha} = R - \{0\}$$

$$c) X(s) = \int_{-\infty}^{\infty} \left(\sum_{n=0}^{\infty} e^{-nt} \delta(t-nt) \right) e^{-st} dt$$

$$= \sum_{n=0}^{\infty} e^{-nt} \int_{-\infty}^{\infty} \delta(t-nt) e^{-st} dt$$

$$= \sum_{n=0}^{\infty} e^{-n(1+s)} \Rightarrow \frac{1}{1-e^{-(1+s)}} \quad \text{ROC} \rightarrow -1$$

$$d) -\frac{d}{ds} X(s) = t e^{-t} \rightarrow (t u(t))$$

$$\frac{1}{s+1}, \text{Re}\{s\} > -1 \rightarrow (e^{-t} u(t))$$

$$\frac{1}{2} \left(\frac{1}{s-1+j} + \frac{1}{s-1-j} \right) = \frac{s}{s^2+4} \quad \text{ROC} \rightarrow \text{Re}\{s\} > 0$$

$$t u(t) \rightarrow -\frac{d}{ds} \frac{1}{s} = \frac{1}{s^2} \quad \text{ROC} \rightarrow \text{Re}\{s\} > 0$$

$$X(s) = \frac{1}{s-1} + \frac{1}{s+1} + \frac{s}{s^2+4} \quad \text{ROC} \rightarrow \text{Re}\{s\} > 0$$

$$X(s) = \frac{s+0}{(s+2)(s-4)} = \frac{A}{s+2} + \frac{B}{s-4} \quad -2$$

$$\Rightarrow \begin{cases} A+B=1 \\ 2B-4A=0 \end{cases} \Rightarrow A = -\frac{1}{3}, B = \frac{4}{3}$$

$$X(s) = -\frac{1}{3} \left(\frac{1}{s+2} \right) + \frac{4}{3} \left(\frac{1}{s-4} \right)$$

① If $\text{ROC} < -2$ $x(t) = -\frac{1}{3} e^{-2t} u(-t) + \frac{4}{3} e^{4t} u(-t)$

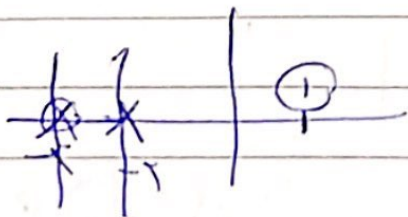
② If $-2 < \text{ROC} < 4$ $x(t) = -\frac{1}{3} e^{-2t} u(t) + \frac{4}{3} e^{4t} u(-t)$

③ If $\text{ROC} > 4$ $x(t) = -\frac{1}{3} e^{-2t} u(t) + \frac{4}{3} e^{4t} u(t)$

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نست

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۱ مقرر و دو قطب

در دو حالت فعلی

۱- بین دو قطب

۲- $-2 < 4$

$$\frac{A}{s+r} + \frac{B}{s+r} \quad A = -r \quad B = \xi$$

$$H(s) = \frac{-r}{s+r} + \frac{\xi}{s+r} \Rightarrow x(t) = r e^{-rt} u(t) - \xi e^{-rt} u(t)$$

$$\text{ROC} < -r$$

$$b) \frac{A}{s+r} + \frac{B}{s+r} + \frac{C}{s+1} \rightarrow H(s) = \frac{1}{(s+r)} - \frac{r}{s+r} - \frac{s}{s+1}$$

$$h(t) = -1 \cdot e^{-rt} u(-t) - r e^{-rt} u(t) + s e^{-t} u(t)$$

$$c) \frac{As+B}{s+r} + \frac{C}{s+r} \quad \text{سم على} \rightarrow \text{سم على}$$

$$\text{Re}\{s\} \rightarrow -r$$

$$\Rightarrow (As+B)(s+r) + C(s+r) = s^2 + 1$$

$$\Rightarrow A=1 \quad C=-1 \quad B=r$$

$$\frac{s+r}{s+r} - \frac{1}{s+r}$$

$$1 + (s) = \frac{s+2}{s+2} + \frac{-1}{s+2} = 1 + \frac{0}{s+2} + \frac{-1}{s+2}$$

$$\Rightarrow \delta(t) + 2e^{-2t} u(t) - 1e^{-2t} u(t)$$

d) R_{cc} با R_{cs} جز $R_{cs} > -1$

$$H(s) = \frac{s^2 - s + 1 + 3s - 3s}{s^2 + 5s + 1} = 1 - \frac{3s}{s^2 + 5s + 1}$$

$$= 1 - \frac{3s}{(s+1)^2} = 1 - \frac{-3}{s+1} + \frac{3}{(s+1)^2}$$

$$\Rightarrow h(t) = \delta(t) - 3e^{-t} u(t) + 3te^{-t} u(t)$$

۴- الف) برای تمام قطب ها، $\sigma_p < 0$ است و سیستم پایدار است.
ب) $\sigma_p < 0$ است و سیستم پایدار است.

$$H(s) = Y(s)$$

$$X(s)$$

$$\{ \delta(t) \} = 1$$

$$\Rightarrow H(s) = Y(s)$$

$$s^2 H(s) + \varepsilon s H(s) + k H(s) = 1$$

$$\Rightarrow 1 + \varepsilon s = \frac{1}{s^2 + \varepsilon s + k}$$

$$\frac{c}{a} > 0 \Rightarrow \frac{b}{a} < 0$$

$$\Rightarrow k > 0$$

المعنى هو ان $k > 0$ هو شرط الاستقرار

$$y(t) = x(t) * h(t)$$

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$$\Rightarrow H(s) = \frac{1}{s^2 + \varepsilon s + k}$$

$$x(t) = u(t) \Rightarrow x(s) = \frac{1}{s}$$

$$Y(s) = \frac{1}{s} \cdot \frac{1}{s^2 + \varepsilon s + k} \Rightarrow \frac{A}{s} + \frac{B}{s + r} + \frac{C}{s + 1}$$

$$A = \frac{1}{(s + r)(s + 1)} \Big|_{s=0} \Rightarrow A = \frac{1}{r}$$

$$B = \frac{1}{s} \quad \text{و} \quad C = -\frac{1}{r}$$

$$Y(s) = \frac{1}{r} \cdot \frac{1}{s} - \frac{1}{r} \cdot \frac{1}{s + r} + \frac{1}{r} \cdot \frac{1}{s + 1}$$

$$y(t) = \frac{1}{r} u(t) - \frac{1}{r} e^{-rt} u(t) + \frac{1}{r} e^{-t} u(t)$$

ALVAND

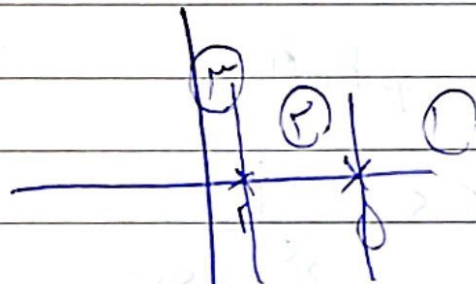
$$x(t) \rightarrow \hat{x}(t) \rightarrow y(t) = h(t)$$

(2) - 0

$$s \{ H(s) - v s H(s) \} = 1 \quad H(s) = \frac{1}{s}$$

$$H(s) = \frac{1}{(s-1)(s-2)} = \frac{A}{s-1} + \frac{B}{s-2}$$

$$A = -1 \quad B = 1$$



① علی و نا پایدار

② غیر علی و نا پایدار

③ ضد علی و پایدار

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$$h(t) = 1e^{1t} u(t) - 1e^{2t} u(t) \quad \text{ROC} < 1 \quad (1)$$

$$\text{ROC} > 2 \quad (2)$$

ALVAND

$$h(t) = -1e^{1t} u(t) + 1e^{2t} u(t)$$

$$\gamma < \text{Re } s < 0 \quad \mu$$

$$h(t) = -\gamma e^{\gamma t} u(t) - \gamma e^{\delta t} u(-t)$$