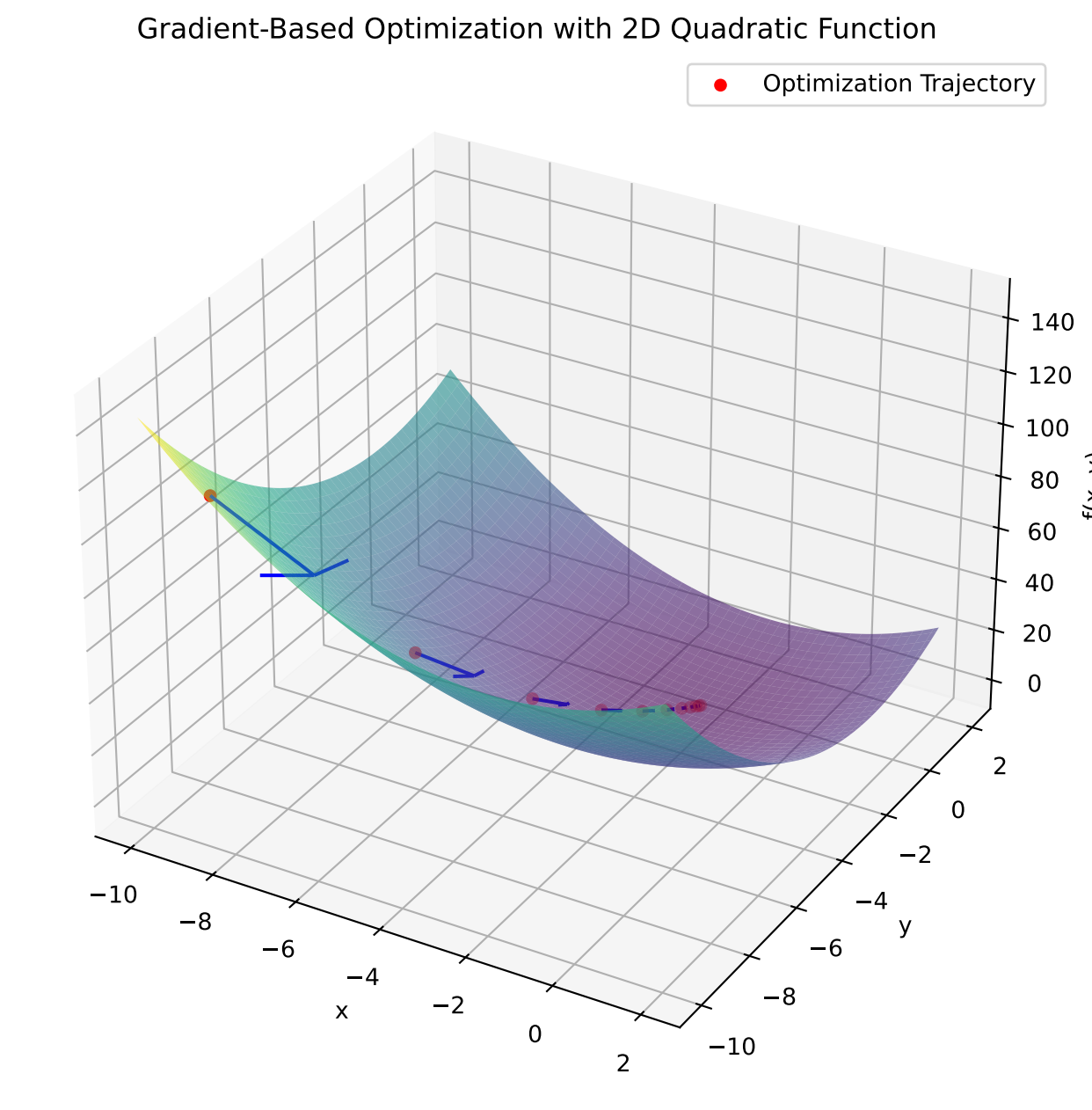
Gradient-Based Optimization with 2D Quadratic Function
Optimization Trajectory
140
120
100
80
60
40
20
0
−10
−8
−6
−4
−2
0
2
x
2
0
−2
−4
−6
−8
−10
y