Introduction to Sequential Parameter Optimization

Noise

• This notebook demonstrates how noisy functions can be handled with OCBA by Spot.

1 Example: Spot, OCBA, and the Noisy Sphere Function

```
import numpy as np
from math import inf
from spotPython.fun.objectivefunctions import analytical
from spotPython.spot import spot
from scipy.optimize import shgo
from scipy.optimize import direct
from scipy.optimize import differential_evolution
import matplotlib.pyplot as plt
```

The Objective Function: Noisy Sphere

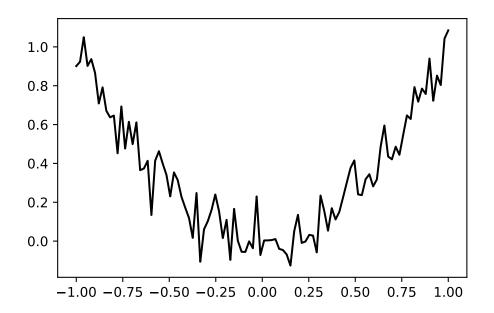
- The spotPython package provides several classes of objective functions.
- We will use an analytical objective function with noise, i.e., a function that can be described by a (closed) formula:

$$f(x) = x^2 + \epsilon$$

• Since sigma is set to 0.1, noise is added to the function:

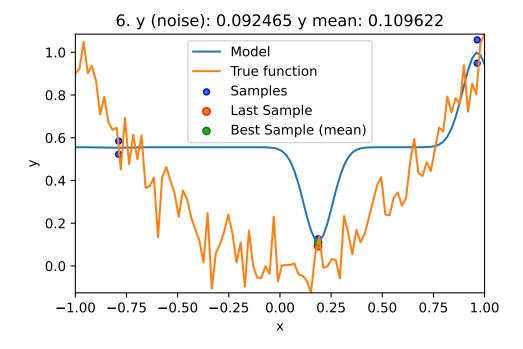
• A plot illustrates the noise:

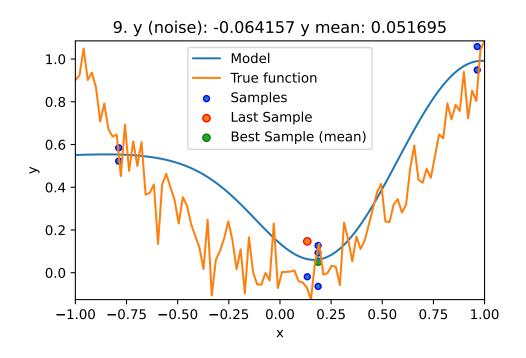
```
x = np.linspace(-1,1,100).reshape(-1,1)
y = fun(x, fun_control=fun_control)
plt.figure()
plt.plot(x,y, "k")
plt.show()
```

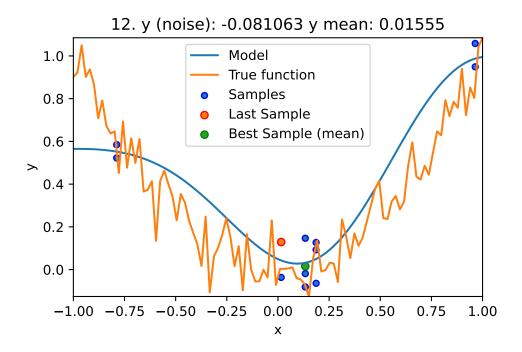


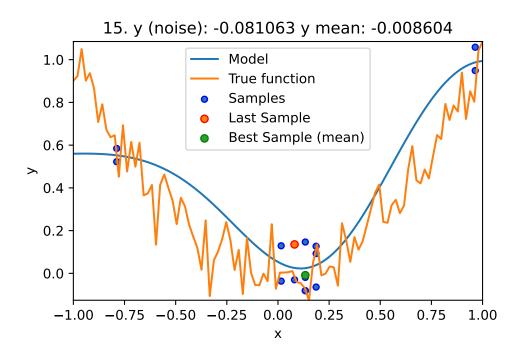
Spot is adopted as follows to cope with noisy functions:

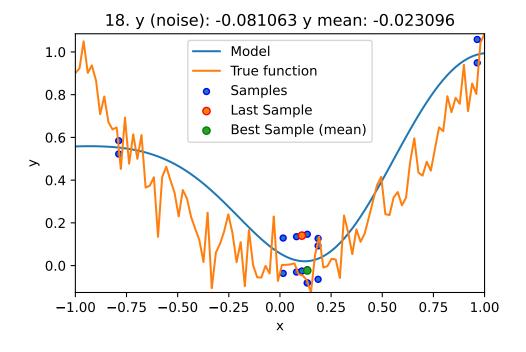
- 1. fun_repeats is set to a value larger than 1 (here: 2)
- 2. noise is set to true. Therefore, a nugget (Lambda) term is added to the correlation matrix
- 3. init size (of the design_control dictionary) is set to a value larger than 1 (here: 2)

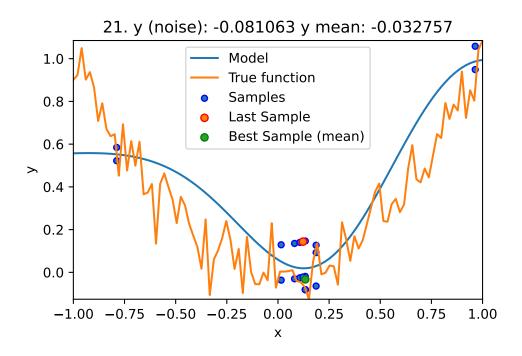


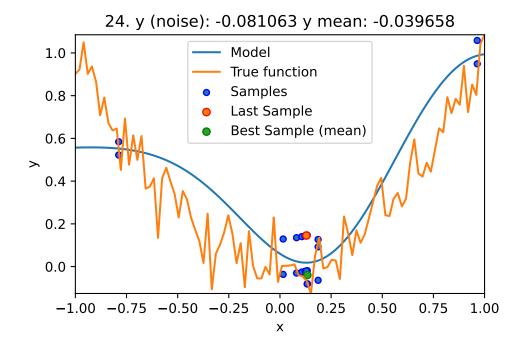


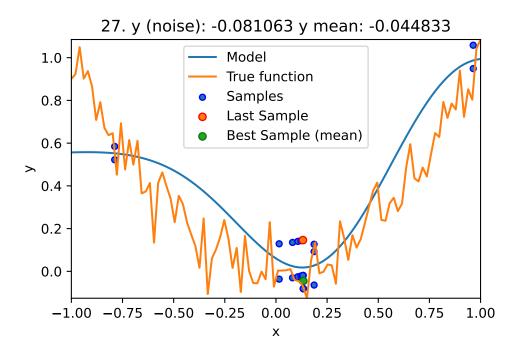


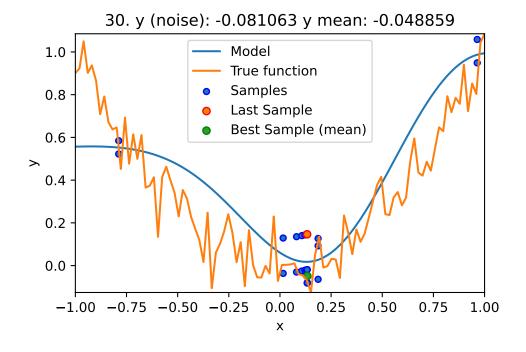


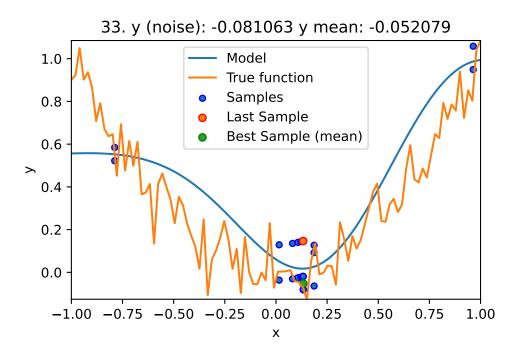


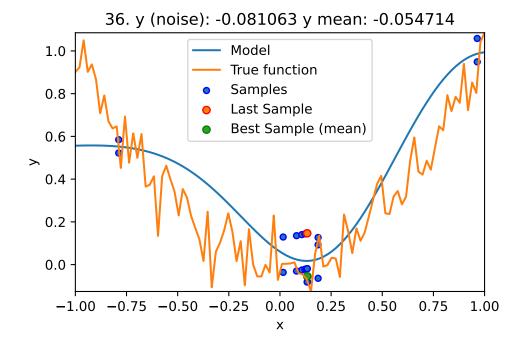


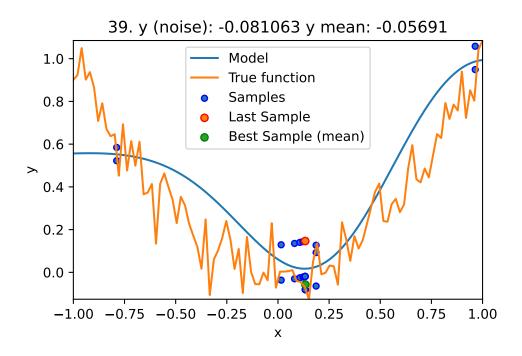


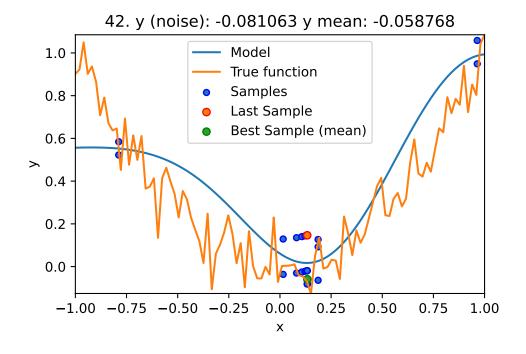


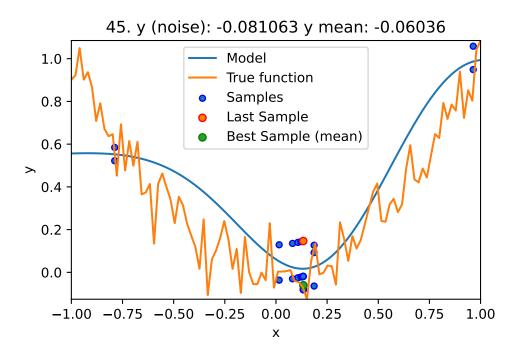


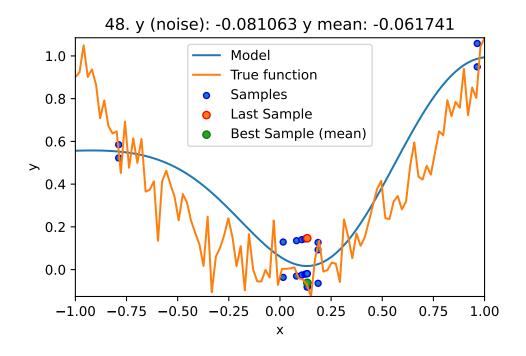


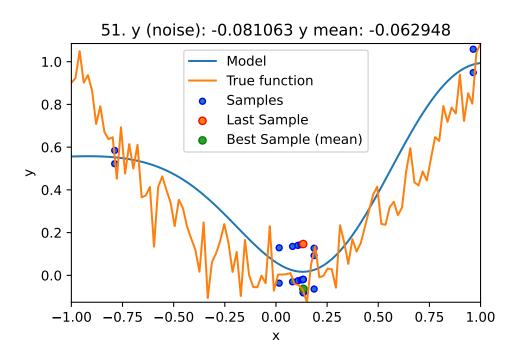












<spotPython.spot.spot.Spot at 0x1573e36a0>

Print the Results

```
spot_1_noisy.print_results()
```

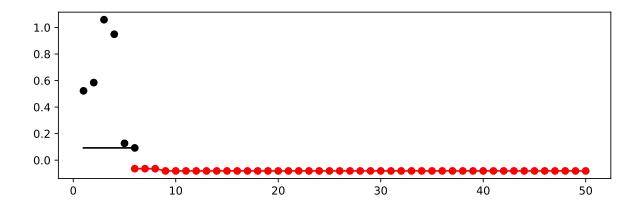
min y: -0.08106318979661208 x0: 0.1335999447536301

min mean y: -0.06294830660588041

x0: 0.1335999447536301

[['x0', 0.1335999447536301], ['x0', 0.1335999447536301]]

spot_1_noisy.plot_progress(log_y=False)



2 Noise and Surrogates: The Nugget Effect

2.1 The Noisy Sphere

The Data

• We prepare some data first:

```
import numpy as np
import spotPython
from spotPython.fun.objectivefunctions import analytical
from spotPython.spot import spot
from spotPython.design.spacefilling import spacefilling
from spotPython.build.kriging import Kriging
import matplotlib.pyplot as plt
gen = spacefilling(1)
rng = np.random.RandomState(1)
lower = np.array([-10])
upper = np.array([10])
fun = analytical().fun_sphere
fun_control = {"sigma": 2,
               "seed": 125}
X = gen.scipy_lhd(10, lower=lower, upper = upper)
y = fun(X, fun_control=fun_control)
X_{train} = X.reshape(-1,1)
y_train = y
```

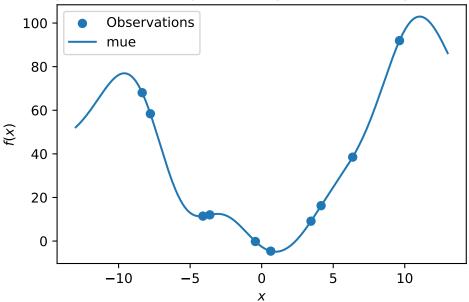
• A surrogate without nugget is fitted to these data:

```
S.fit(X_train, y_train)

X_axis = np.linspace(start=-13, stop=13, num=1000).reshape(-1, 1)
mean_prediction, std_prediction, ei = S.predict(X_axis, return_val="all")

plt.scatter(X_train, y_train, label="Observations")
plt.plot(X_axis, mean_prediction, label="mue")
plt.legend()
plt.xlabel("$x$")
plt.ylabel("$f(x)$")
_ = plt.title("Sphere: Gaussian process regression on noisy dataset")
```

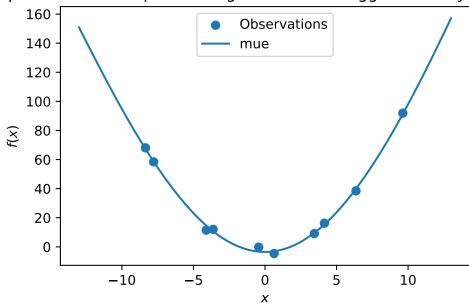
Sphere: Gaussian process regression on noisy dataset



• In comparison to the surrogate without nugget, we fit a surrogate with nugget to the data:

```
X_axis = np.linspace(start=-13, stop=13, num=1000).reshape(-1, 1)
mean_prediction, std_prediction, ei = S_nug.predict(X_axis, return_val="all")
plt.scatter(X_train, y_train, label="Observations")
plt.plot(X_axis, mean_prediction, label="mue")
plt.legend()
plt.xlabel("$x$")
plt.ylabel("$f(x)$")
_ = plt.title("Sphere: Gaussian process regression with nugget on noisy dataset")
```

Sphere: Gaussian process regression with nugget on noisy dataset



• The value of the nugget term can be extracted from the model as follows:

S.Lambda

S_nug.Lambda

9.088150066416743e-05

- We see:
 - the first model S has no nugget,
 - whereas the second model has a nugget value (Lambda) larger than zero.

Exercises

- Important:
 - Results from these exercises should be added to this document, i.e., you should submit an updated version of this notebook.
 - Please combine your results using this notebook.
 - Only one notebook from each group!
 - Presentation is based on this notebook. No additional slides are required!
 - spotPython version 0.16.11 (or greater) is required (see http://www.gm.fh-koeln.de/~bartz/site/download/)

Exercise 1

- Each team member should choose one of the following optimization algorithms.
- Please add your name to the section title!

1. Noisy fun_cubed

• Analyse the effect of noise on the fun_cubed function with the following settings:

2. fun_runge

• Analyse the effect of noise on the fun_runge function with the following settings:

```
lower = np.array([-10])
upper = np.array([10])
fun = analytical().fun_runge
```

3. fun_forrester

• Analyse the effect of noise on the fun_forrester function with the following settings:

4. fun_xsin

• Analyse the effect of noise on the fun_xsin function with the following settings:

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