

# **Documentation of the Sequential Parameter Optimization**

- This document describes the **Spot** features.

## Example: spot

```
import numpy as np
from math import inf
from spotPython.fun.objectivefunctions import analytical
from spotPython.spot import spot
from scipy.optimize import shgo
from scipy.optimize import direct
from scipy.optimize import differential_evolution
import matplotlib.pyplot as plt
```

## The Objective Function

- The `spotPython` package provides several classes of objective functions.
- We will use an analytical objective function, i.e., a function that can be described by a (closed) formula:

$$f(x) = x^2$$

```
fun = analytical().fun_sphere
```

```
x = np.linspace(-1,1,100).reshape(-1,1)
y = fun(x)
plt.figure()
plt.plot(x,y, "k")
plt.show()
```

```
spot_1 = spot.Spot(fun=fun,
                    lower = np.array([-10]),
                    upper = np.array([100]),
                    fun_evals = 7,
                    fun_repeats = 1,
                    max_time = inf,
                    noise = False,
                    tolerance_x = np.sqrt(np.spacing(1)),
                    var_type=["num"],
                    infill_criterion = "y",
```

```

n_points = 1,
seed=123,
log_level = 50,
show_models=True,
fun_control = {},
design_control={"init_size": 5,
               "repeats": 1},
surrogate_control={"noise": False,
                  "cod_type": "norm",
                  "min_theta": -4,
                  "max_theta": 3,
                  "n_theta": 1,
                  "model_optimizer": differential_evolution,
                  "model_fun_evals": 1000,
                  })

```

- `spot`'s `__init__` method sets the control parameters. There are two parameter groups:
  1. external parameters can be specified by the user
  2. internal parameters, which are handled by `spot`.

## External Parameters

external parameter	type	description	default	mandatory
<code>fun</code>	object	objective function		yes
<code>lower</code>	array	lower bound		yes
<code>upper</code>	array	upper bound		yes
<code>fun_evals</code>	int	number of function evaluations	15	no
<code>fun_evals</code>	int	number of function evaluations	15	no
<code>fun_control</code>	dict	noise etc.	<code>{}</code>	n
<code>max_time</code>	int	max run time budget	<code>inf</code>	no

external parameter	type	description	default	mandatory
<b>noise</b>	bool	if repeated evaluations of <b>fun</b> results in different values, then <b>noise</b> should be set to <b>True</b> .	<b>False</b>	no
<b>tolerance_x</b>	float	tolerance for new x solutions. Minimum distance of new solutions, generated by <b>suggest_new_X</b> , to already existing solutions. If zero (which is the default), every new solution is accepted.	0	no
<b>var_type</b>	list	list of type information, can be either <b>"num"</b> or <b>"factor"</b>	<b>["num"]</b>	no
<b>infill_criterion</b>	string	Can be <b>"y"</b> , <b>"s"</b> , <b>"y"</b> <b>"ei"</b> (negative expected improvement), or <b>"all"</b>	<b>"y"</b>	no
<b>n_points</b>	int	number of infill points	1	no

external parameter	type	description	default	mandatory
<b>seed</b>	int	initial seed. If <b>Spot.run()</b> is called twice, different results will be generated. To reproduce results, the <b>seed</b> can be used.	<b>123</b>	no

external parameter	type	description	default	mandatory
log_level	int	log level with the following settings: <b>NOTSET</b> (0), <b>DEBUG</b> (10: Detailed information, typically of interest only when diagnosing problems.), <b>INFO</b> (20: Confirmation that things are working as expected.), <b>WARNING</b> (30: An indication that something unexpected happened, or indicative of some problem in the near future (e.g. 'disk space low'). The software is still working as expected.), <b>ERROR</b> (40: Due to a more serious problem, the software has not been able to perform some function.), and <b>CRITICAL</b> (50: A serious error, indicating that the program itself may be unable to continue running.)	50	no

external parameter	type	description	default	mandatory
<code>show_models</code>	bool	Plot model. Currently only 1-dim functions are supported	<b>False</b>	no
<code>design</code>	object	experimental design	<b>None</b>	no
<code>design_control</code>	dict	control parameters	see below	no
<code>surrogate</code>		surrogate model	<b>kriging</b>	no
<code>surrogate_control</code>	dict	control parameters	see below	no
<code>optimizer</code>	object	optimizer	see below	no
<code>optimizer_control</code>	dict	control parameters	see below	no

- Besides these single parameters, the following parameter dictionaries can be specified by the user:

- `fun_control`
- `design_control`
- `surrogate_control`
- `optimizer_control`

## The `fun_control` Dictionary

external parameter	type	description	default	mandatory
<code>sigma</code>	float	noise: standard deviation	<b>0</b>	yes
<code>seed</code>	int	seed for rng	<b>124</b>	yes

## The `design_control` Dictionary

external parameter	type	description	default	mandatory
<code>init_size</code>	int	initial sample size	<b>10</b>	yes

external parameter	type	description	default	mandatory
repeats	int	number of repeats of the initial sammples	1	yes

## The surrogate\_control Dictionary

external parameter	type	description	default	mandatory
noise				
model_optimizer	object	optimizer	differential_evolution	
model_fun_evals				
min_theta			-3.	
max_theta			3.	
n_theta			1	
n_p			1	
optim_p			False	
cod_type			"norm"	
var_type				
use_cod_y	bool		False	

## The optimizer\_control Dictionary

external parameter	type	description	default	mandatory
max_iter	int	max number of iterations. Note: these are the cheap evaluations on the surrogate.	1000	no



## Run

```
spot_1.run()
```

## Print the Results

```
spot_1.print_results()
```

## Show the Progress

```
spot_1.plot_progress()
```

## Visualize the Surrogate

- The plot method of the kriging surrogate is used.
- Note: the plot uses the interval defined by the ranges of the natural variables.

```
spot_1.surrogate.plot()
```

## 1. Init: Build Initial Design

```
from spotPython.design.spacefilling import spacefilling
from spotPython.build.kriging import Kriging
from spotPython.fun.objectivefunctions import analytical
gen = spacefilling(2)
rng = np.random.RandomState(1)
lower = np.array([-5,-0])
upper = np.array([10,15])
fun = analytical().fun_branin
fun_control = {"sigma": 0,
               "seed": 123}

X = gen.scipy_lhd(10, lower=lower, upper = upper)
```

```
print(X)
y = fun(X, fun_control=fun_control)
print(y)
```

## Replicability

- Seed

```
gen = spacefilling(2, seed=123)
X0 = gen.scipy_lhd(3)
gen = spacefilling(2, seed=345)
X1 = gen.scipy_lhd(3)
X2 = gen.scipy_lhd(3)
gen = spacefilling(2, seed=123)
X3 = gen.scipy_lhd(3)
X0, X1, X2, X3
```

## Surrogates

### A Simple Predictor

The code below shows how to use a simple model for prediction.

- Assume that only two (very costly) measurements are available:
  1.  $f(0) = 0.5$
  2.  $f(2) = 2.5$
- We are interested in the value at  $x_0 = 1$ , i.e.,  $f(x_0 = 1)$ , but cannot run an additional, third experiment.

```
from sklearn import linear_model
X = np.array([[0], [2]])
y = np.array([0.5, 2.5])
S_lm = linear_model.LinearRegression()
S_lm = S_lm.fit(X, y)
X0 = np.array([[1]])
y0 = S_lm.predict(X0)
print(y0)
```

- Central Idea:
  - Evaluation of the surrogate model  $S_{lm}$  is much cheaper (or / and much faster) than running the real-world experiment  $f$ .

## Demo/Test: Objective Function Fails

- SPOT expects `np.nan` values from failed objective function values.
- These are handled.
- Note: SPOT's counter considers only successful executions of the objective function.

```
import numpy as np
from spotPython.fun.objectivefunctions import analytical
from spotPython.spot import spot
import numpy as np
from math import inf
# number of initial points:
ni = 20
# number of points
n = 30

fun = analytical().fun_random_error
lower = np.array([-1])
upper = np.array([1])
design_control={"init_size": ni}

spot_1 = spot.Spot(fun=fun,
                   lower = lower,
                   upper= upper,
                   fun_evals = n,
                   show_progress=False,
                   design_control=design_control,)
spot_1.run()
# To check whether the run was successfully completed,
# we compare the number of evaluated points to the specified
# number of points.
assert spot_1.y.shape[0] == n
```