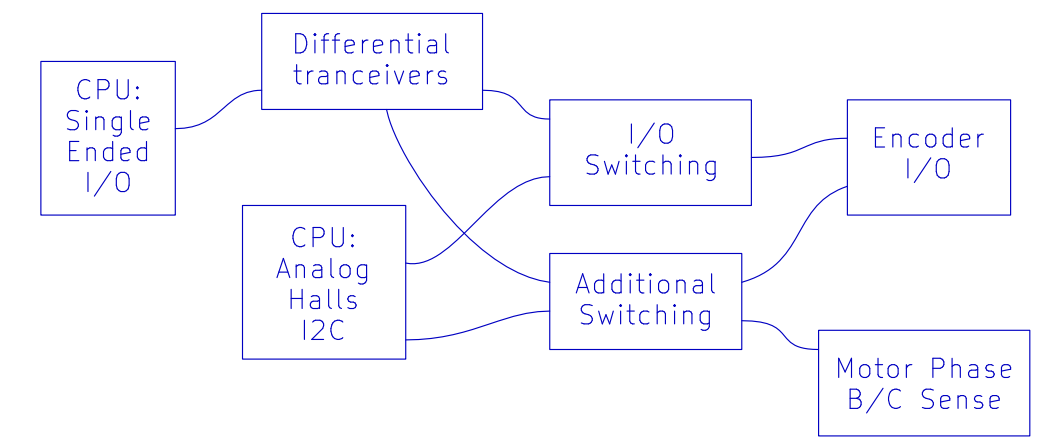


53V input maximum run voltage
 20 Amp max continuous current draw (roughly, depends on thermals)
 50 Amp peak per motor absolute maximum

CONSIDER THERMISTOR VOLTAGE IF MOTOR HALLS RUN AT 5V
 (or punt!?)

Changelog:
 July 16 2024
 Change low side pullups to
 pulldowns so that low side
 FET is on by default.

Encoder Supports:
 Single Ended I2C
 Hall Sensors
 Differential or Single Ended SPI
 Differential or Single Ended Quadrature with Index
 Dual Channel Analog



SEE ALSO CA-135556 PART WHICH IS SIMILAR BUT HAS SWAPPED RXD AND TXD

