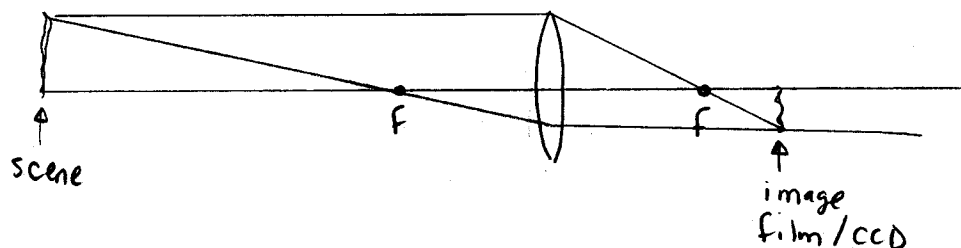


Camera

Place film/CCD at the image focus



- Questions:
- (1) Location of film/CCD.
 - (2) How do you change the picture size?
 - (3) How big is the picture?
 - (4) What is the field of view of the camera?

(1) use the thin lens equation

$$\frac{1}{s_o} + \frac{1}{s_i} = \frac{1}{f}$$

For a normal camera $f \sim 50\text{mm}$
Typical $s_o > f$

Let's say $0.5\text{m} < s_o < 30\text{m}$

$$\frac{1}{s_i} = \frac{1}{f} - \frac{1}{s_o}$$

$$s_i = \frac{s_o f}{s_o - f}$$

$$55.6\text{mm} < s_i < 50.08\text{mm}$$

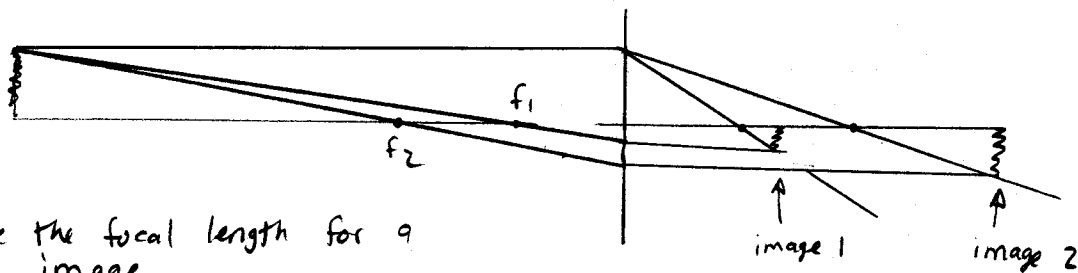
about a 6 mm shift in the film
This is the camera focus
Usually camera auto-focuses
This is moving the lenses relative to the film/CCD

More motion is needed when s_o is close to f

What happens if $s_o < f$?

s_i is negative and you get a virtual image.
Can't put the film at the correct location.

(2) How do you change the picture size (zoom)?



Increase the focal length for a bigger image

Wide angle
Normal
Telephoto

$24\text{mm} < f < 35\text{mm}$
 $\sim 50\text{mm}$
 $80\text{mm} < f < 300\text{mm}$

← This is why telephoto lenses are really long

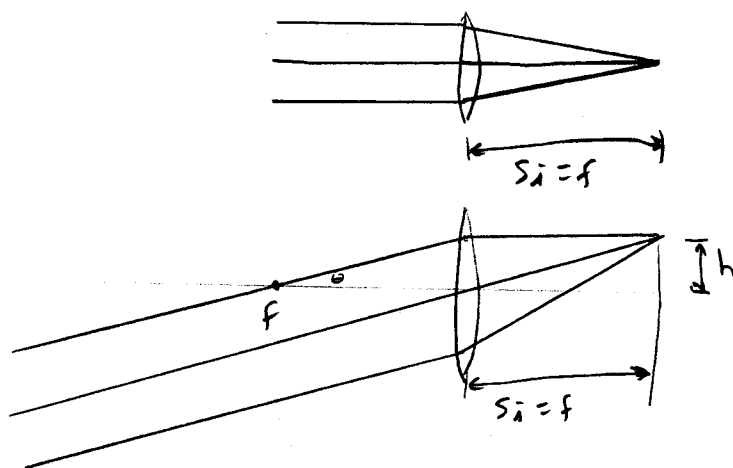
(3) and (4)

What is the magnification?
 $S_o = 1\text{m}$

$f = 50\text{mm}$

$$M = \frac{h_i}{h_o} = \frac{S_i}{S_o} = \frac{f}{S_o - f} = 52.6 \times 10^{-3}$$

This standard magnification equation is not actually the best way
Since $S_o \gg f$ we will treat the object points as plane wave with different incident angles



$$\tan \theta = \frac{h}{f}$$

$$\theta = \frac{h}{f}$$

$$h = f\theta$$

A particular point on the film/ccd corresponds to a specific incident angle.

There is a cone of angles for each pixel
A cone for the entire CCD array

The Fov of the camera is

$$H = f\theta$$

$$\theta = \frac{H}{f}$$

where H is the size of Film/CCD

The resolution of a CCD is essentially the Fov of a particular pixel.

$$\theta_{\text{pixel}} = \frac{h}{f}$$

so the larger f is the smaller the angular content of a single pixel

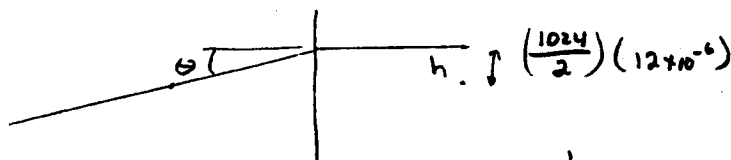
In class example

There are 2 optical imagers on the Cassini spacecraft.

Both use a 1024×1024 CCD with $12\mu\text{m}$ pixels
This is approximately a $\frac{1}{2}$ inch wide CCD

The 2 imagers are
Narrow angle camera (NAC) $f = 2\text{m}$
Wide angle camera (WAC) $f = 0.2\text{m}$

What is the total FOV for both imagers in degrees?



$$\tan \theta = \frac{h}{f}$$

$$\theta \approx \frac{h}{f}$$

$$\theta \approx \frac{(512)(12 \times 10^{-6})}{2}$$

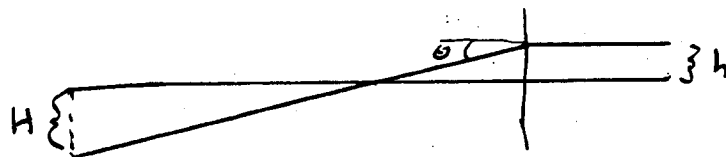
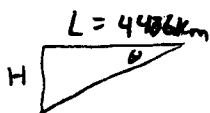
$$\theta \approx 0.00307, 0.00307 \text{ rad}$$

$$\pm \theta \approx 0.176^\circ, 0.176^\circ$$

$$\text{FOV} = 0.35^\circ, 0.35^\circ$$

What is the resolution at a distance of 4486 km using the NAC camera?

For a single pixel $h = 12\mu\text{m}$



$$\theta = \frac{h}{f} = \frac{12 \times 10^{-6}}{2} = \frac{H}{4486}$$

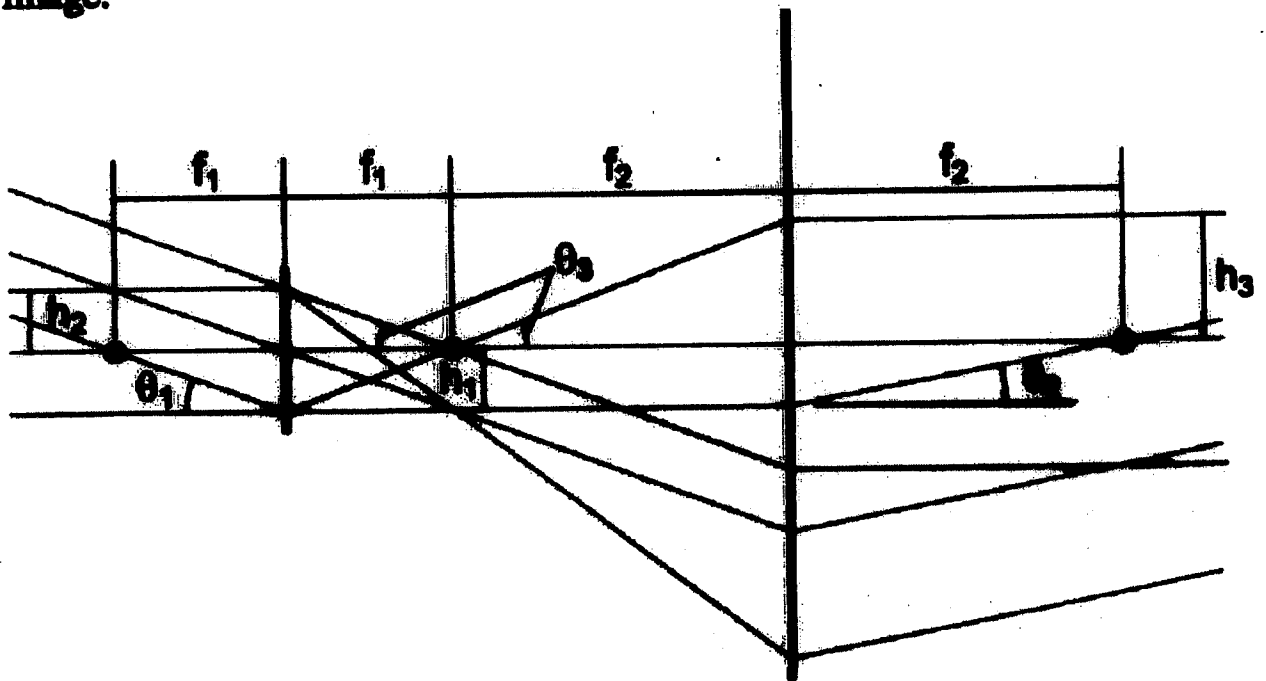
$$H = \left(\frac{12 \times 10^{-6}}{2} \right) (4486 \times 10^3)$$

$$H = 26.9 \text{ m}$$

see cassini picture

Afocal (Beam Expander)

Called an afocal since neither the input nor output comes to an image.



Beam Expansion

$$\tan(\theta_3) = \frac{h_2}{f_1} \approx \theta_3$$

$$\tan(\theta_3) = \frac{h_2}{f_2} \approx \theta_3$$

$$\frac{h_3}{h_2} = \frac{f_2}{f_1}$$

Angle

$$\frac{h_1}{f_1} = \theta_1$$

$$\theta_2 = \frac{h_1}{f_2}$$

$$\frac{\theta_2}{\theta_1} = \frac{f_1}{f_2}$$

Cannon Powershot G7

3648 x 2736 pixels

7.18 mm x 5.32 mm

Wide angle lens $f = 35\text{mm}$

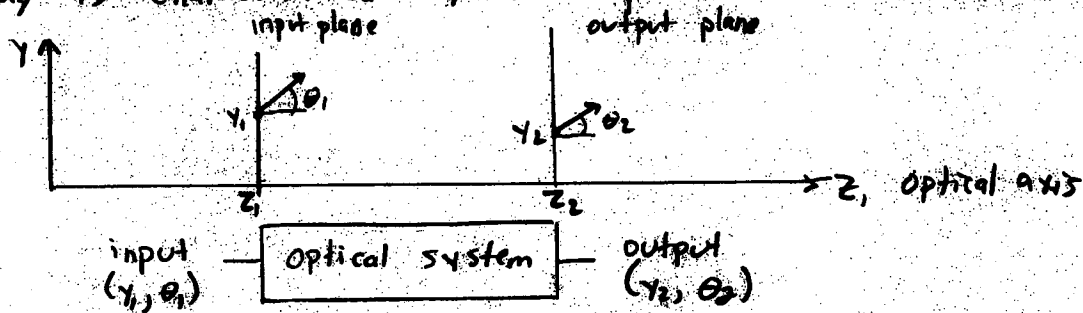
Telephoto lens $f = 210\text{mm}$

Normal focus range 50cm

Macro focus range 1cm

F2.8 - F4.8 aperture

In a homogeneous material rays travel in straight lines.
A ray is characterized by its position and direction.



An optical system is a set of optical components that change the position and direction of rays.

In the paraxial approximation, when all angles are sufficiently small so that $\sin \theta \approx \theta$, the relationship between (y_1, θ_1) and (y_2, θ_2) is linear.

$$\begin{aligned} y_2 &= A y_1 + B \theta_1 \\ \theta_2 &= C y_1 + D \theta_1 \end{aligned}$$

$$\begin{bmatrix} y_2 \\ \theta_2 \end{bmatrix} = \underbrace{\begin{bmatrix} A & B \\ C & D \end{bmatrix}}_M \begin{bmatrix} y_1 \\ \theta_1 \end{bmatrix}$$

The matrix M characterizes the optical system.

This analysis technique is called "Matrix Optics" or "ABCD Matrices".

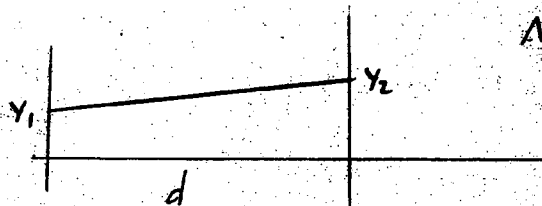
Let's calculate the ABCD matrices for some simple optical components.

Free Space Propagation

rays travel in straight lines

$$\begin{aligned} y_2 &= y_1 + \theta_1 d \\ \theta_2 &= \theta_1 \end{aligned}$$

$$M = \begin{bmatrix} 1 & d \\ 0 & 1 \end{bmatrix}$$



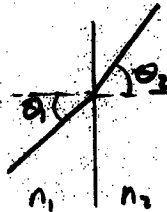
Refraction at a Planar Boundary

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

$$n_1 \theta_1 \approx n_2 \theta_2$$

$$y_2 = y_1$$

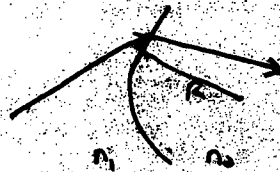
$$\theta_2 = \frac{n_1}{n_2} \theta_1 \quad M = \begin{bmatrix} 1 & 0 \\ 0 & \frac{n_1}{n_2} \end{bmatrix}$$

Refraction at a Spherical Boundary

$$y_2 = y_1$$

$$\theta_2 \approx \frac{n_1}{n_2} \theta_1 - \frac{n_2 - n_1}{n_2 R} y_1$$

$$M = \begin{bmatrix} 1 & 0 \\ -\frac{n_2 - n_1}{n_2 R} & \frac{n_1}{n_2} \end{bmatrix}$$

Transmission through a Thin Lens

$$y_2 = y_1$$

$$\theta_2 = \theta_1 - \frac{y}{f} \quad M = \begin{bmatrix} 1 & 0 \\ -\frac{1}{f} & 1 \end{bmatrix}$$

Reflection from a Planar Mirror

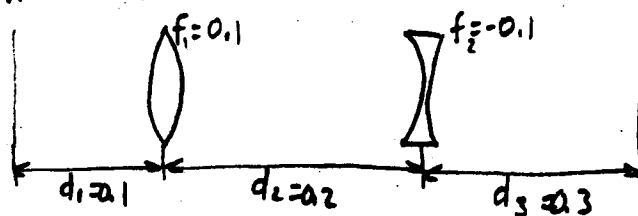
$$y_2 = y_1$$

$$\theta_2 = \theta_1 \quad M = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Reflection from a Spherical Mirror

$$M = \begin{bmatrix} 1 & 0 \\ \frac{2}{R} & 1 \end{bmatrix}$$

Multiple elements are analyzed by multiplying all of the matrices for the individual elements.



$$M = \begin{bmatrix} 1 & d_1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -\frac{1}{f_1} & 1 \end{bmatrix} \begin{bmatrix} 1 & d_2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -\frac{1}{f_2} & 1 \end{bmatrix} \begin{bmatrix} 1 & d_3 \\ 0 & 1 \end{bmatrix}$$

if the initial ray is $y_1 = 0$
 $\theta_1 = 1^\circ = 0.0174$

$$\begin{bmatrix} y_2 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 1 & .1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -10 & 1 \end{bmatrix} \begin{bmatrix} 1 & .2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 10 & 1 \end{bmatrix} \begin{bmatrix} 1 & .3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ .0174 \end{bmatrix} = \begin{bmatrix} 0.007 \\ -1.1218 \end{bmatrix}$$

Can use this technique to perform a simple ray trace through an arbitrary system.