

## Lesson 5 Offline Run Learning

### 1. Project Outcome

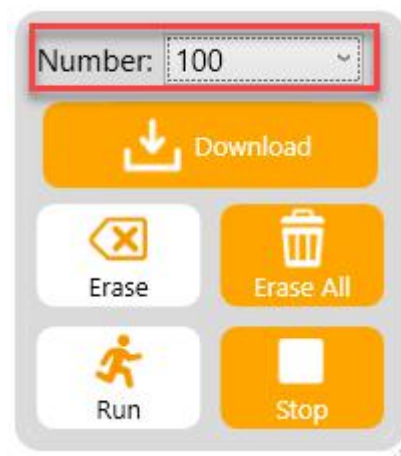
Control the robotic arm by pressing offline running button instead of the software control.

### 2. Complete Program

**Step1:** Connect computer and robotic arm controller by USB wire, and turn on PC software.

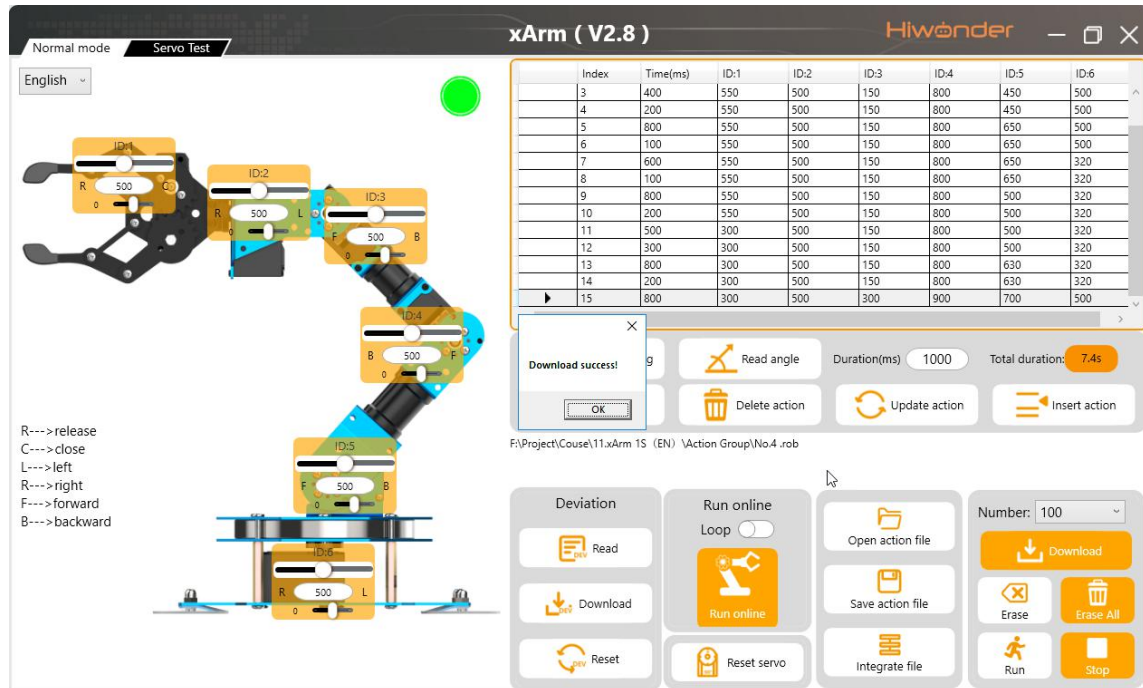
**Step 2:** Open a action group file arbitrarily ("5. Appendix -> Action Group File"), such as "No. 4-Show Action 2".

**Step3:** Set the action group number to 100 and then click on "Download" button. If wanna run offline, you should download it into No. 100 Action group because No.100 operation group is set to run offline by default.



**Step 4:** After action group download is complete, the PC software interface will pop up a prompt box indicating that download is successful. Click the "OK"

button to close the prompt box to complete.



**Step 5:** Turn on power, and then press the **【Run】** button on the controller to run the No.100 action group offline. Long press button for 3 seconds, the action group will be executed repeatedly.

