

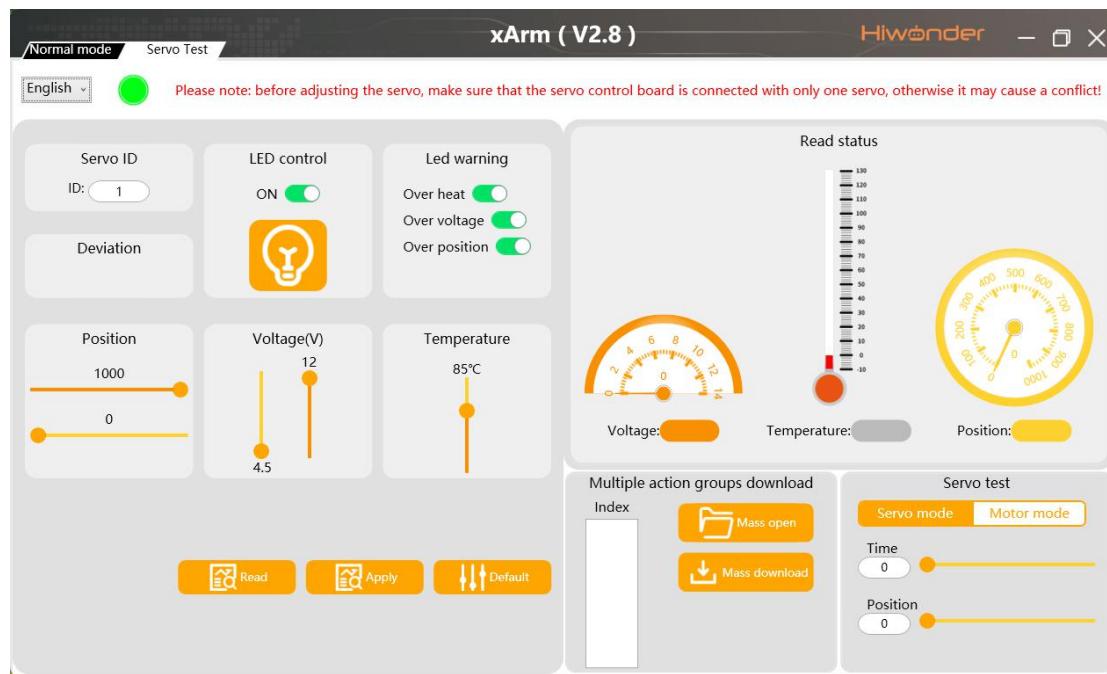
Lesson 6 Action Group Download

1.Preface

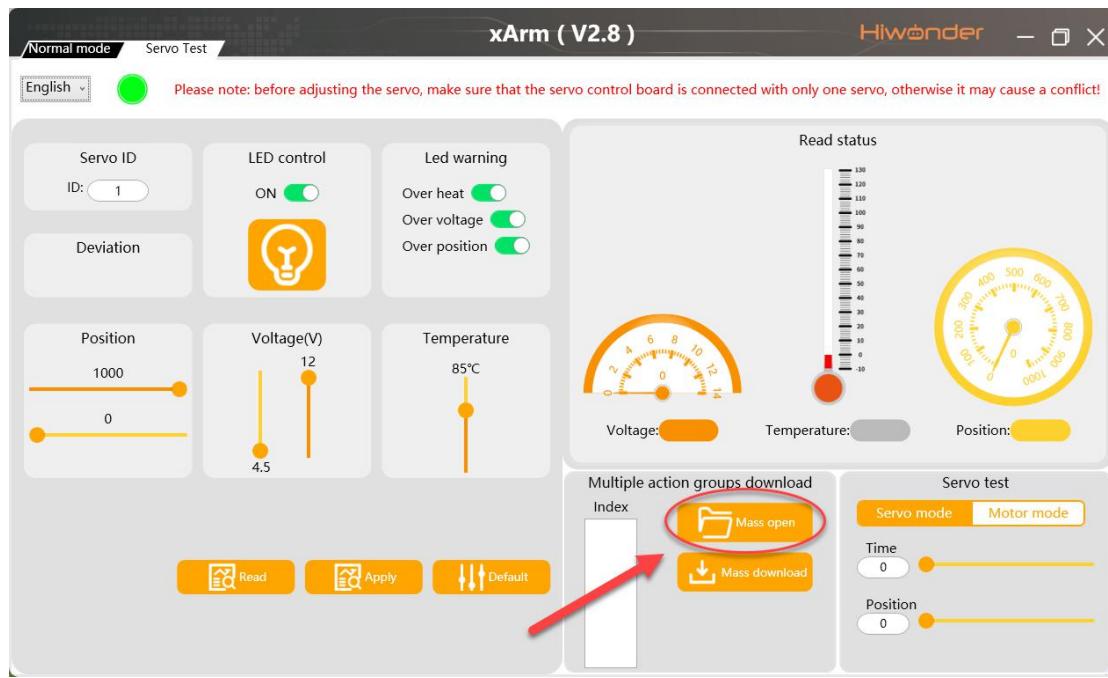
The robot arm like a human arm, the limbs need "muscle memory" to perform their move function. Therefore, the action group needs to be download to controller to perform the action.

2.Download Method

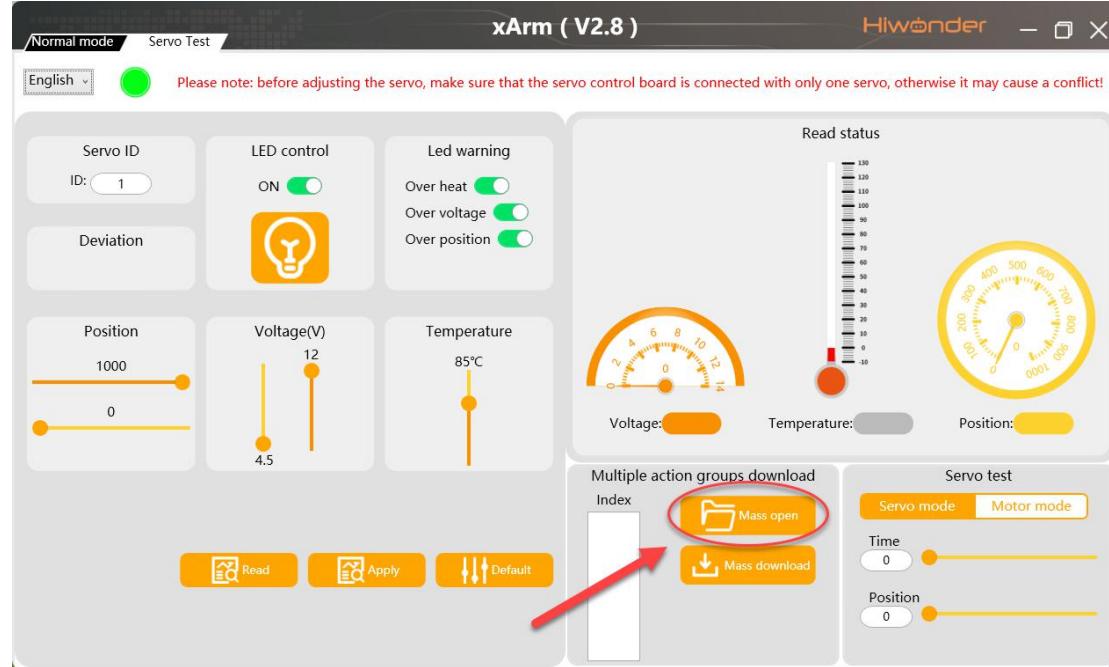
- 1) Connect robot arm and computer, and turn on PC software.
- 2) Click "Servo Test "to switch debug mode on PC interface.



- 3) Click "Mass download " button, and select "Action Group "file in the pop-up prompt file.



- 4) Open the file and select (From No.0- Initial Action to No.11-Omin-directional Rotational Detection Grip) all action groups. Then click "Open" button.



- 5) Wait for a while, after all the action groups are added, the imported action group serial number will be displayed in the list, and then click the "Mass download" button.



6) Next, the "Mass download" button will appear download progress prompt. Each time a file is successfully download. The robot arm will emit a "beep" sound reminder. After waiting for the download progress prompt to disappear, all files are download to the controller.

