

On the feasibility for the system of quadratic equations

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- 1 The Power Flow feasibility problem
- 2 The algorithm
- 3 An example
- 4 Further plans

The problem

Power Flow Feasibility problem:

- ① Large-scale power grids
- ② Need to know if a regime is «normal», «safe»
- ③ Ohm's law \Rightarrow quadratic equations:

$$y_i = f_i(x) = x^T A_i x + 2b_i^T x$$

y (regime) known, x is not

- ④ Determine if $\exists x: y = f(x)$ (means «safe»)

The image $f(\mathbb{R}^n)$ must be examined

The solution

Given: the map $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$, $f_i(x) = x^T A_i x + 2b_i^T x$, $A_i^T = A_i$

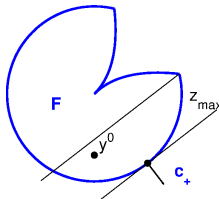
Proposed algorithm for examining $F = f(\mathbb{R}^n)$:

- **Input:** $y^0 \in F$, direction c_+ : $c_+ \cdot A > 0$
- **Output:** value z_{\max} s.t. the cut $Q(c_+, z_{\max}, F)$ is convex

Solution overview:

- 1 Discovering boundary nonconvexities $\{F_i\}$ close to y^0
- 2 Projecting to c_+ : (F_i, c_+)
- 3 Calculating $z_{\max} = \inf_i \inf_{y \in F_i} (c_+, y)$

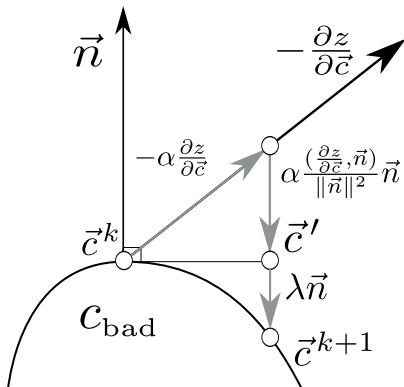
$Q(c_+, z, F) = \{y | (y - y^*, c_+) \in [0, z]\} \cap F$, y^* — touching point of hyperplane c_+



The solution

Infinite number of nonconvexities \Rightarrow

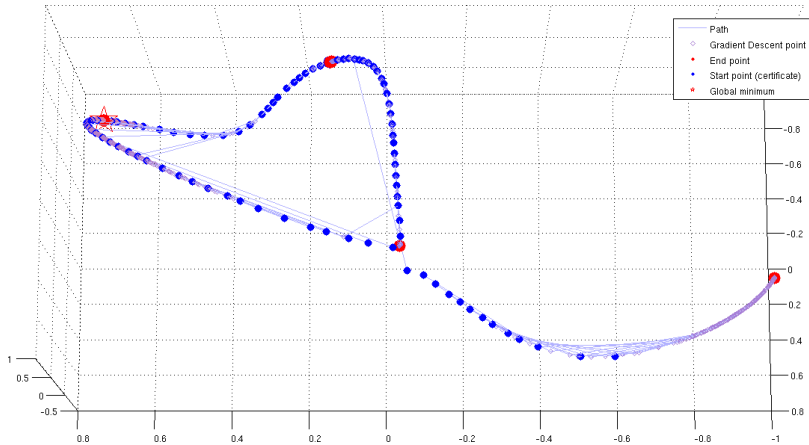
- 1 $z_{\max} = \inf_{c \in C_{\text{bad}}} z(c)$ — constrained optimization
- 2 Gradient projection method
- 3 Projection using $\vec{n} \perp C_{\text{bad}}$



Numerical experiment

An example: $f: \mathbb{R}^4 \rightarrow \mathbb{R}^4$. Looking for $z_{\max} = \inf_{c \in c_{\text{bad}}} z(c)$

- 4 local minima
- Global minimum found

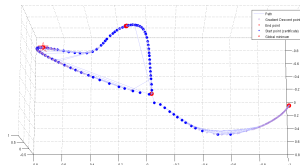
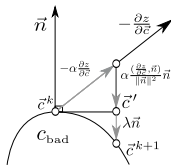
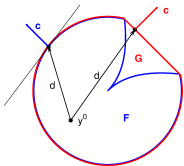
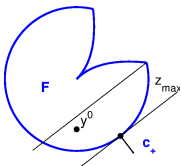


Summary

- 1 Power Flow feasibility
- 2 Algorithm cuts convex parts
- 3 Gradient projection method
- 4 Algorithm was tested on a number of maps f

Plan: practical application

- 1 \mathbb{C} case
- 2 Testing for higher dimensions



Thank you!
Questions?