

Power flow feasibility problem

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The problem

- ① Large-scale power grids
- ② Need to know if a regime of the grid is «normal», «safe»
- ③ Ohm's law \Rightarrow quadratic equations:

$$y_i = f_i(x) = x^T A_i x + 2b_i^T x$$

y (regime) known, x is not

- ④ Need to determine if $\exists x: y = f(x)$ (means «safe»)

This problem is known as Power Flow Feasibility problem.
To solve it, the image $f(\mathbb{R}^n)$ must be examined

The solution

Given: the map $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$, $f_i(x) = x^T A_i x + 2b_i^T x$, $A_i^T = A_i$

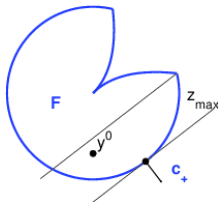
Proposed algorithm for examining $F = f(\mathbb{R}^n)$:

- **Input:** $y^0 \in F$, direction c_+ : $c_+ \cdot A > 0$
- **Output:** value z_{\max} s.t. the cut $Q(c_+, z_{\max}, F)$ is convex

Solution overview:

- 1 Discovering boundary nonconvexities $\{F_i\}$ close to y^0
- 2 Projecting to c_+ : (F_i, c_+)
- 3 Calculating $z_{\max} = \inf_i \inf_{y \in F_i} (c_+, y)$

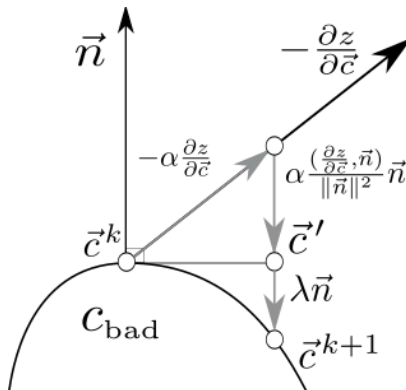
$Q(c_+, z, F) = \{y \mid (y - y^*, c_+) \in [0, z]\} \cap F$, y^* — touching point of hyperplane c_+



The solution

Solution in details:

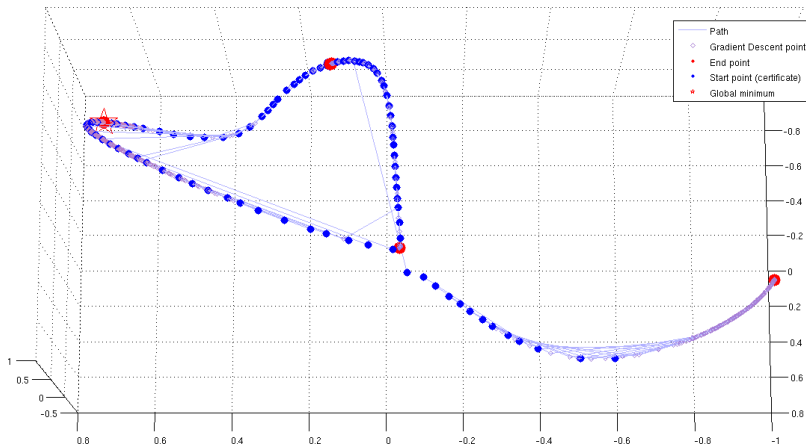
- 1 Rewrite $z_{\max} = \inf_{c_{\text{bad}}} z(c)$ — constrained optimization task
- 2 Using the Gradient projection method
- 3 Special technique for projection using geometry of c_{bad}



Numerical experiment

An example: $f: \mathbb{R}^4 \rightarrow \mathbb{R}^4$

- 4 local minima
- Global minimum found



Algorithm for examining the set of «safe» regimes was proposed:

- ① Can determine if the whole subset is «safe» at one run
- ② Cuts convex parts of the image F
- ③ General case when the set of nonconvexities is a continuum was considered
- ④ Algorithm was tested on a number of maps f

Plan:

- ① \mathbb{C} case
- ② Testing for higher dimensions

