# Sergia VOLODIN (Sergei)

☑ sergia-ch.github.io / Wehntalerstrasse 20, 8057 Zürich, Switzerland ☑ Birth date: 3rd of October 1994 (27 years), Russian 🛁



#### **ABSTRACT**

\$ Sergia: artsy recently graduated software engineer and young scientist with interests in open-source democratic and consensual technology with experience in research and development in industry, academia and startups. Looking for an inclusive and diverse team where we all share and discuss what is in our heart, to create something honest, awesome, and balanced to give people what they need.

#### **EDUCATION**

EPFL Swiss Federal Institute of Technology in Lausanne (EPFL) 

Master's

Lausanne, Switzerland

Sep 2017 – Apr 2021

- Master's degree in Computer Science, GPA: 5.67/6
- Minor in Computational Neurosciences
- Research Assistant position (2017–2019)
- Thesis "CauseOccam: Learning Interpretable Abstract Representations in Reinforcement Learning Environments via Model Sparsity"

Moscow Institute of Physics and Technology 

Moscow, Russia

Bachelor's degree in Applied Mathematics, GPA: 4.84/5

# SKILLS

Relevant courses: Machine Learning, Software Engineering, Unsupervised and Reinforcement Learning, Convex Optimization, Distributed Algorithms, Algorithms, Random graph theory, Functional Programming, Set Theory, Random Processes, Functional Analysis, Biological modeling of neural networks, Complexity theory, Learning theory, Neuroscience: behavior and cognition, Neuroprosthetics, Theory and methods for Reinforcement Learning, Optimization for Machine Learning, Computer Vision

Scientific programming: Keras, TensorFlow, PyTorch, ray/tune/rllib, tf-agents, scikit-learn, Brian 2, MATLAB, Mathematica, R

Programming languages: Python, C/C++, Java, TypeScript, Scala, nasm, C#, AVR C++ Frameworks: Qt/QML, Django, Android Studio, OpenGL/GLSL, Unity 3D, Blender, React.js

Environment: Git, LATEX, Bash, Debian/Ubuntu Linux

Scientific skills: experimental sections of research papers, working on theoretical problems, scientific presentation, data analysis

Software development: agile software development (Scrum), CI/CD, debugging, design patterns, concurrent and distributed systems, TCP/IP networking, AVR microcontrollers, Arduino platform, team and project management in small startups

Languages: ■ English: 🗹 TOEFL iBT 113/120, 🖳 French: A1, 🛏 Russian: native

# RESEARCH EXPERIENCE

EPFL, Laboratory for Computational Neuroscience Lausanne, Switzerland

Master's Thesis student
Oct 2020 – Apr 2021

- Designed  $\square$  an algorithm with Python 3, Pytorch and ray based on the  $\square$  "Consciousness Prior" proposal that finds a simple causal model of an RL environment in the general case from pixels. The project is a continuation of my Google Research internship (see below)
- The algorithm works on benchmarks, see my thesis 🗗 "CauseOccam: Learning Interpretable Abstract Representations in Reinforcement Learning Environments via Model Sparsity"
- The work includes theoretical results on abstraction learning as well as a code base with tests and documentation
- The thesis defended on the 21st of April 2021 with Adam Gleave (Berkeley/DeepMind) as an external expert

Berkeley, CA, United States (remote due to COVID-19, from Zurich, Switzerland )

Summer Intern

Berkeley, CA, United States (remote due to COVID-19, from Zurich, Switzerland )

June 2020 – Sep 2020

- Designed better defenses against adversarial policies in Multi-Agent Reinforcement Learning via alternating training of opponents using Python 3, Tensorflow, ray, rllib.
- Ran hyperparameter sweeps on multiple machines with ray and rllib
- Converted legacy code using stable baselines and Tensorflow 1.0 to rllib and Tensorflow 2.0
- Results published as a blog post 🗗 "Defending against Adversarial Policies in Reinforcement Learning with Alternating Training" on the Effective Altruism forum

|    | Google Research ■ Software Engineering Int  Mountain View, CA, United States Nov 2019 – Feb 20  |       |  |
|----|---|-------|--|
| •  | Designed an algorithm to uncover a linear Causal Model of a Reinforcement Learning environment using interventions  | 020   |  |
|    | with Python 3, Tensorflow, tf-agents, and analyzed the effect of interventions on the quality of exploration  |       |  |
| •  | Used TensorFlow and tf-agents to conduct the experiments with large hyperparameter sweeps  Results 🗗 published as an ICLR CLDM workshop paper   |       |  |
|    | EPFL, Distributed Computing Laboratory 🖾  |       |  |
| •  | Lausanne, Switzerland Sep 2018 – Oct 20 Investigated fault tolerance of a neural network using Taylor approximation   | )19   |  |
| •  | Introduced the <i>continuous limit</i> to  bound the error, and compared to the Neural Tangent Kernel limit case Conducted  experiments to test the theory using <b>Keras</b> including the <b>implementation</b> of custom layers and regularizers   |       |  |
|    | EPFL, Computer-Human Interaction in Learning and Instruction laboratory   |       |  |
| •  | Lausanne, Switzerland  Created  a library QML-AR for seamless augmented reality using OpenCV, Qt/C++ and Qt/QML with competitive performance on Android and small visual negative impact  | )18   |  |
| •  | Designed an  activity for kids for learning math using AR, tested the application in a classroom setting, analyzed the obtained data  |       |  |
|    | Skolkovo Institute of Science and Technology, Center for Energy Systems — Research Int  | ern   |  |
| •  | Moscow, Russia  Sep 2016 – Jul 20 Characterized using numerical optimization and theoretically the structure of the set of boundary non-convexities of an   |       |  |
|    | image of a quadratic map in case the number of non-convexities is infinite  |       |  |
| •  | Designed and implemented the Convexity Analysis of Quadratic Maps library using MATLAB which gives approximate solutions to a number of problems involving quadratic maps   |       |  |
| Ρl | PUBLICATIONS  |       |  |
|    | Lê-Nguyên Hoang, Louis Faucon, Aidan Jungo, Sergei Volodin, Dalia Papuc, Orfeas Liossatos, Ben Crulis, Mariame Tighanimine, Isabela C stantin, Anastasiia Kucherenko, Alexandre Maurer, Felix Grimberg, Vlad Nitu, Chris Vossen, Sébastien Rouault, El-Mahdi El-Mhamdi.  Tonesol: A quest for a large, secure and trustworthy database of reliable human judgments, 2021. Code for the platform (backend, ML, fronter experiments, part of data analysis, writing   | our-  |  |
|    | ICLR Sergei Volodin, Nevan Wichers, Jeremy Nixon.  Resolving Spurious Correlations in Causal Models of Environments via Intervention 2020. Topic choice, experiments, theory, writing.  ICLR CLDM workshop 2020.  | ons,  |  |
|    | El-M. El-Mhamdi, R. Guerraoui, A. Kucharavy, S. Volodin. The Probabilistic Fault Tolerance of Neural Networks in the Continuous Lin 2019. Experiments, theory, writing.   | mit,  |  |
|    | A. Dymarsky, E. Gryazina, S. Volodin, B. Polyak.  Geometry of quadratic maps via convex relaxation, 2018. Exp-s, theory, writing.   |       |  |
|    | A. Petrov, S. Volodin 🗹 Janibekov's effect and the laws of mechanics. Doklady Akademii Nauk, 2013. Graphics for the article, experiments, year of my BSc  | first |  |
| W  | VORK EXPERIENCE   |       |  |
| _  |   |       |  |
|    | ☐ Fave For Fans ☐ Software Engin  |       |  |
| •  | Platform dedicated to passionate fans, Zürich, Switzerland Responsible for the backend development with microservices on Cloudflare Workers with TypeScript, an ArangoDB-based database, automatic data schema validation, and CI/CD with integration tests. First full-time engineer at the  | J22   |  |
|    | company.  |       |  |
| •  | Proposing and discussing ways to create more ethical and democratic social media sharing mechanisms, organizing voting in the team to discuss proposals ("mini  Stakeholder Capitalism")  |       |  |
| •  | Research into ways of obtaining data from third-party services with privacy guarantees Conducted analysis of the database to create better ranking results  |       |  |
|    |   | eer   |  |
|    | Startup designing better recommender systems, Lausanne, Switzerland May 2020 – May 2020 |       |  |
| •  | Co-founded a startup working on contributor-driven collaborative recommender systems  |       |  |
| •  | Responsible for 🗹 back-end engineering using Django, and Machine Learning engineering with TensorFlow, the API server   |       |  |
| •  | Responsible as well for system administration (Debian), (partially) front-end development with React.js and parts of algorithm design   |       |  |
| •  | Co-authored 🗗 the paper with our results  |       |  |
|    |   |       |  |

- Created a startup selling software and hardware for real-world escape room games which allows to speed up the
  construction and reduce maintenance costs
- Responsible for back-end software engineering with C++/Python, servers administration, sales and customer support
- · Managed a team of two web developers until a successful launch of the web interface
- Sold more than forty solutions which are currently running in different countries across the globe and provided remote support

ITBrat Software Engineer

Algorithmic trading startup, Moscow, Russia Jul 2015 – Feb 2016

- Developed algorithmic trading application from initial discussion with the team to deployment and supporting in C++
- · Added low-level user-space networking to the project which allowed to decrease latency and increase profit
- Responsible for the performance of the code

#### **RESEARCH INTERESTS**

Artificial Intelligence, Machine Learning, Artificial Intelligence Safety/Ethics, Causal Reasoning, Adversarial policies, Mathematical Optimization, Robotics, Consciousness research

### **SCHOLARSHIPS**

- 🗹 Research Scholars, a paid Research Assistant position, Swiss Federal Institute of Technology in Lausanne (EPFL), 2017 2019
- Abramov Fund's scholarship for excellent grades, 2014

#### **PROJECTS**

Safe Proximal Policy Optimization

EPFL EE-618 course project, advised by Dr. Kamalaruban Parameswaran and Prof. Volkan Cevher, Lausanne, Switzerland [2019]

- Added a projection step to the Proximal Policy Optimization algorithm to comply with requirements of Constrained Markov Decision Processes
- Implemented code in Tensorflow and tested it in simple environments
- Presented the project at the RLSS 2019 summer school (Lille, France)

Quadcopter drone from scratch project

\*\*Russia → 2012 – 2014

- Poveloped  $\mathbb{Z}$  an algorithm in C++ for stabilization of a quadcopter drone from scratch using AVR microcontrollers, IMU sensors and PID regulators
- Co-managed the project consisting of 2-5 developers
- Conducted the analysis of launches to improve flying quality
- Results were published as a 🕜 popular science article (in Russian)

#### **CONFERENCES AND SUMMER SCHOOLS**

- Machine Learning Summer School, 2020 (virtual due to COVID-19), poster presenter
- Reinforcement Learning Summer School, 2019 (Lille, France), poster presenter, selected to receive financial help
- Data science summer school, 2019 (Paris, France), poster presenter
- QtDay 2019 (Firenze, Italy), speaker, one hour session on qml-ar
- 💶 🗹 P.A.I.S.S. Al Summer School, INRIA Grenoble, 2018, participant in tutorials given by top experts; 🗹 selected to receive financial aid
- Information Technologies and Systems (Saint-Petersburg, Repino, 2016), speaker, poster presenter

# **COMPETITIONS**

- Google HashCode Qualification round coding contest, top 6% (team EPFL\_Noobs), managed the team, developed algorithms and did the coding, 2019
- ightharpoonup Deep Reinforcement Learning for Atari games, managed the team and developed an 🗗 evolutionary algorithm with an autoencoder, MIPT, Moscow, Russia, 2017

### **INTERESTS**

Music, Dancing, Running (1/2 marathon 2018), Snowboarding, Swimming, Philosophy, DIY, Activism

## **VOLUNTEERING**

| Better Russia  Community of pro-democracy Russians, Zurich, Switzerland  Making posters for the demonstrations, organizing voting on important decisions among members, brainstorming on the situation to find a way forward   | 2022     |
|--|----------|
| Effective Altruism Lausanne  Local  EA community, Lausanne, Switzerland  Co-founding the group,  introduction workshop speaker, running a  discussion group on Al safety and theory, newsletter management and writing, Facebook events announcements, managing open discussions | 2019     |
| Artificial Intelligence Governance Forum  Al governance conference, Geneva, Switzerland (2019), virtual due to COVID-19 (2020)  Time-keeping, technical support, small tutorial on neural networks   | <br>2020 |
| Technical help for presenters, badge check   | 2019     |
| Anti-corruption foundation (A. Navalny)  A  non-profit aimed at investigating corruption, Moscow, Russia  Conveyed the results of the investigations by talking to people on the streets as a volunteer  | 2017     |