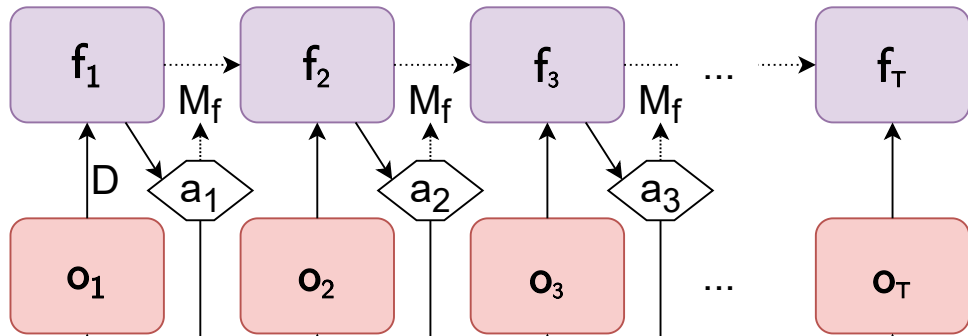


Inferred
feature
dynamics



Seen
observation
dynamics

True latent
environment
state dynamics
(unknown)

