$$\begin{split} & \frac{T_{av}}{C_{c}} = \frac{C}{v}, \quad T_{o} = \frac{C_{o}}{V_{o}}, \quad dT = \frac{dT}{d\rho} \begin{vmatrix} d\rho + \frac{1}{2} \frac{d^{2}T}{d\rho^{2}} \end{vmatrix} d\rho^{2} + \cdots \qquad \frac{dT}{T} = \frac{T - T_{o}}{T_{o}} \\ & \frac{C - C_{o}}{C_{o}} = \alpha_{o} \delta + \alpha_{o} \delta^{2} \rightarrow C = C_{o}(\alpha_{o} \delta + \alpha_{o} \delta^{2}) + C_{o} = \rightarrow \frac{dC}{d\delta} = C_{o}(\alpha_{o} + 2\alpha_{o} \delta) \\ & \frac{\delta V}{V} = \frac{\delta}{\rho^{2}} \rightarrow \frac{dV}{d\rho} = \frac{V}{\rho^{2}}, \quad \frac{d^{2}V}{d\rho^{2}} = \frac{V}{\rho^{2}} \frac{1}{\rho^{2}} \frac{1}{\rho^{2}} \frac{V}{\rho^{2}} \frac{1}{\rho^{2}} \frac{V}{\rho^{2}} \frac{1}{\rho^{2}} \frac{V}{\rho^{2}} \frac$$