

A probabilistic model for recursive factorized image features.

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Outline

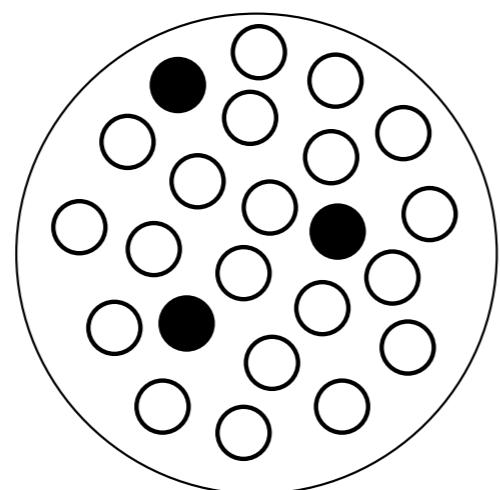
- Motivation:
 - * Distributed coding of local image features
 - * Hierarchical models
 - * Bayesian inference
- Our model: Recursive LDA
- Evaluation

Local Features

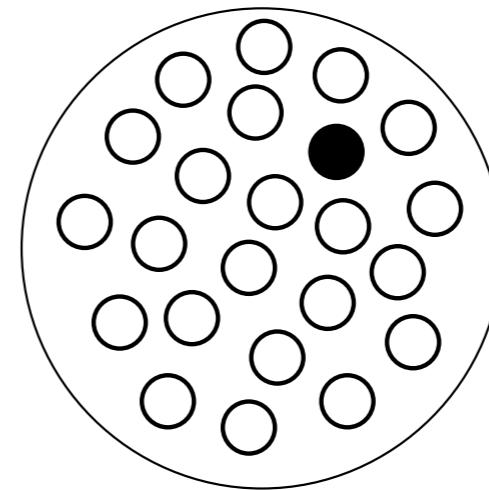
- Gradient energy histograms by orientation and grid position in local patches.
- Coded and used in bag-of-words or spatial model classifiers.

Feature Coding

- Traditionally vector quantized as *visual words*.
- But coding as mixture of components, such as in sparse coding, is empirically better.
(Yang et al. 2009)



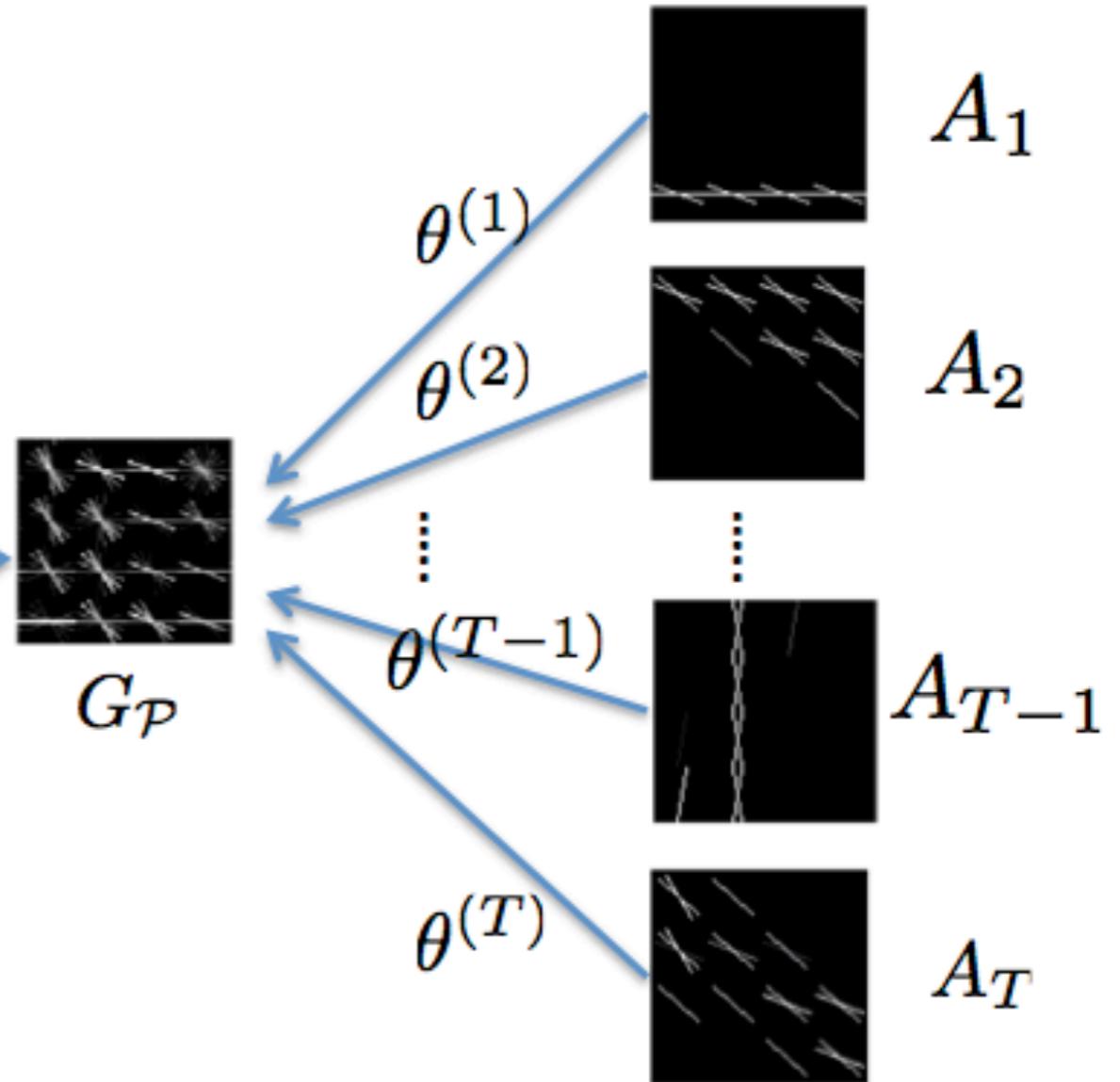
...



+ Decent combinatorial
capacity ($\sim N^K$)

- Low combinatorial
capacity (N)

Another motivation: additive image formation



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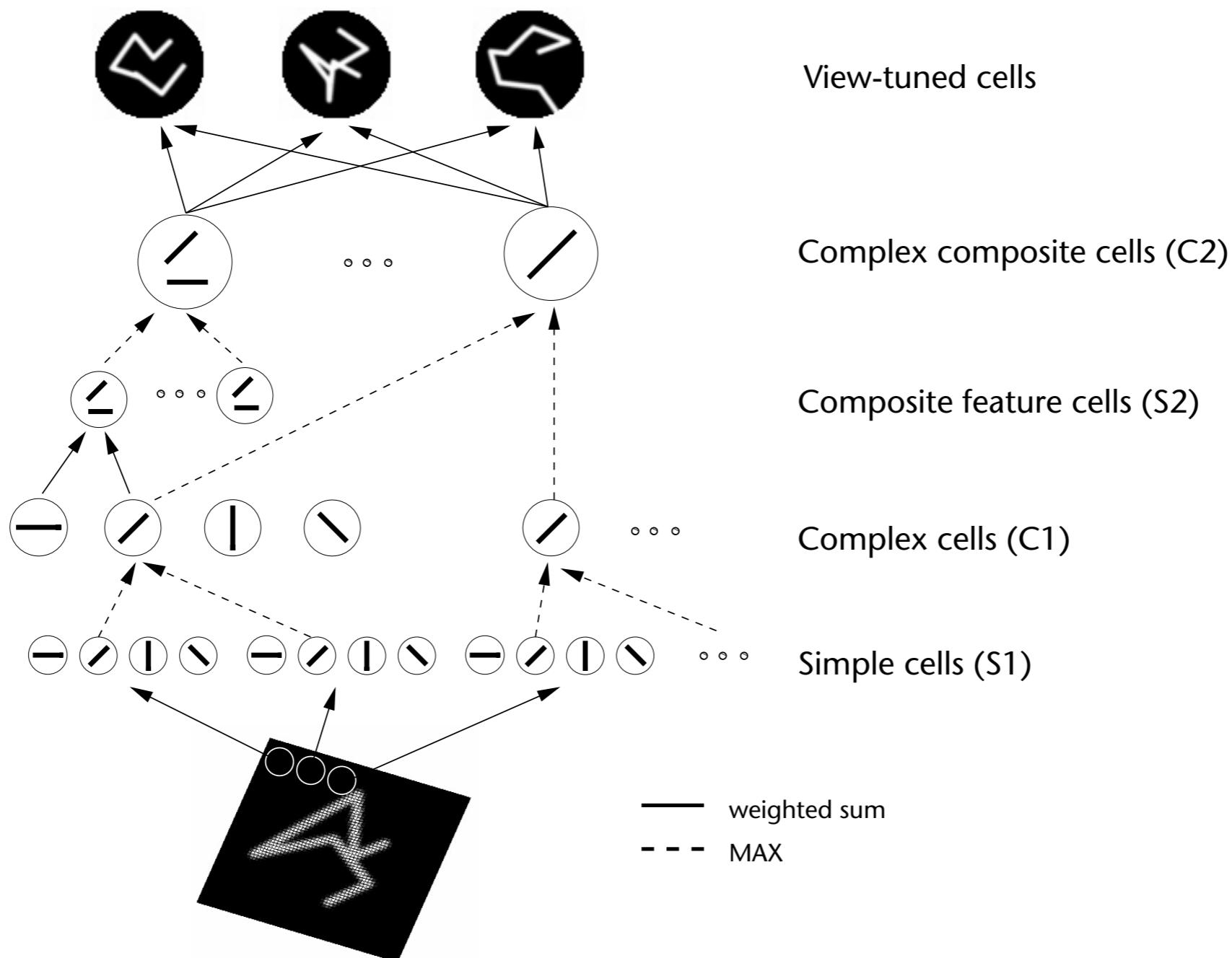
Hierarchies

- Biological evidence for increasing spatial support and complexity of visual pathway.
- Local features not robust to ambiguities.
Higher layers can help resolve.
- Efficient parametrization possible due to sharing of lower-layer components.

Past Work

- HMAX models (Riesenhuber and Poggio 1999, Mutch and Lowe 2008)
- Convolutional networks (Ranzato et al. 2007, Ahmed et al. 2009)
- Deep Belief Nets (Hinton 2007, Lee et al. 2009)
- Hyperfeatures (Agarwal and Triggs 2008)
- Fragment-based hierarchies (Ullman 2007)
- Stochastic grammars (Zhu and Mumford 2006)
- Compositional object representations (Fidler and Leonardis 2007, Zhu et al. 2008)

HMAX



Riesenhuber and Poggio. Hierarchical models of object recognition in cortex. *Nature Neuroscience* (1999).

Convolutional Deep Belief Nets

Stacked layers, each consisting of feature extraction, transformation, and pooling.

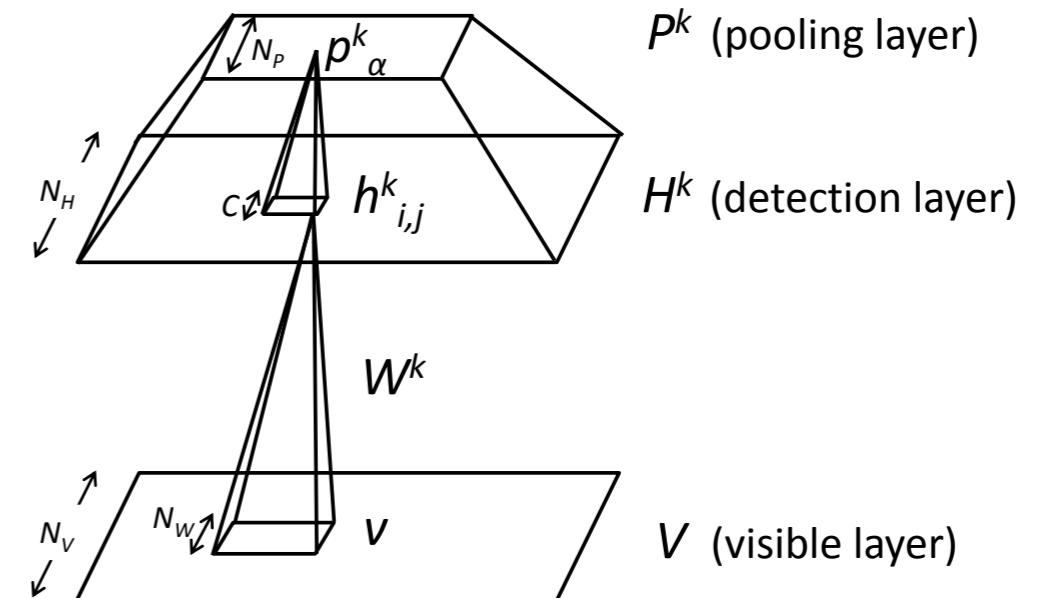
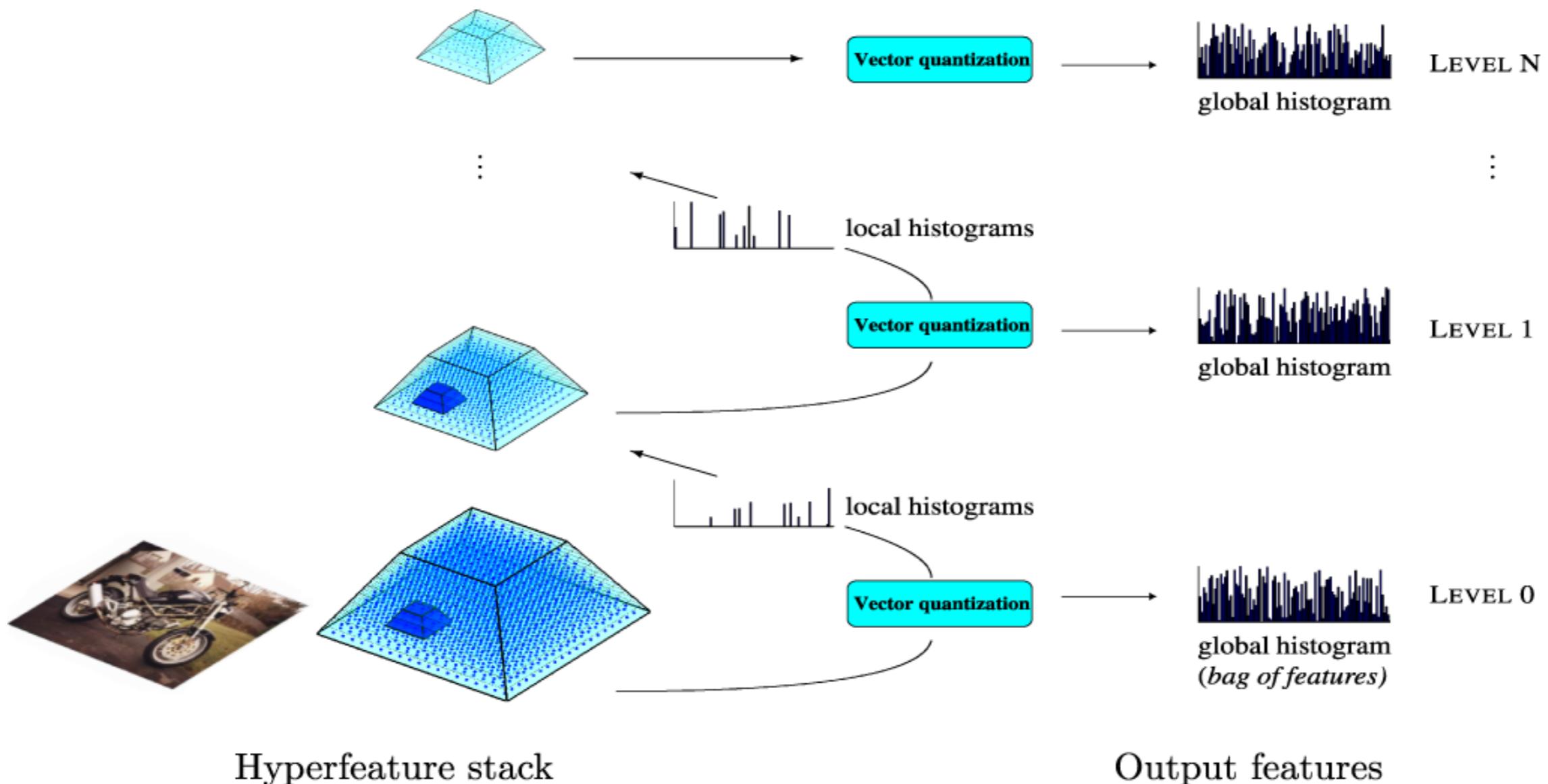


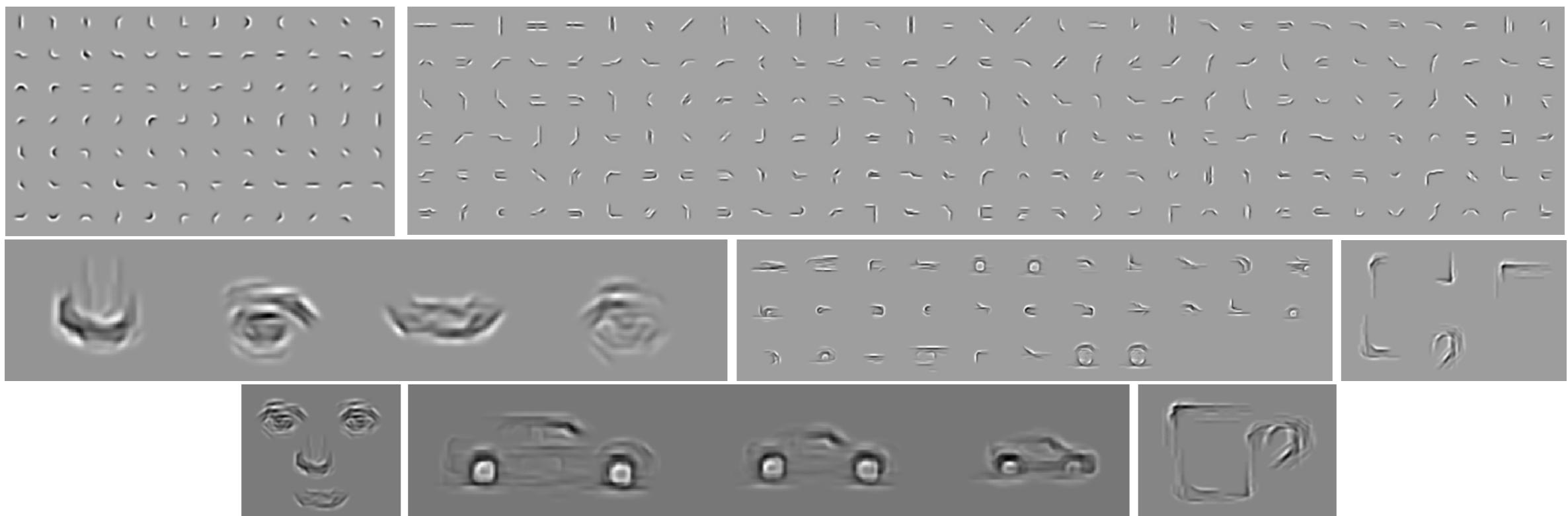
Figure 1. Convolutional RBM with probabilistic max-pooling. For simplicity, only group k of the detection layer and the pooling layer are shown. The basic CRBM corresponds to a simplified structure with only visible layer and detection (hidden) layer. See text for details.

Hyperfeatures



Agarwal and Triggs. Multilevel Image Coding with Hyperfeatures. International Journal of Computer Vision (2008).

Compositional Representations

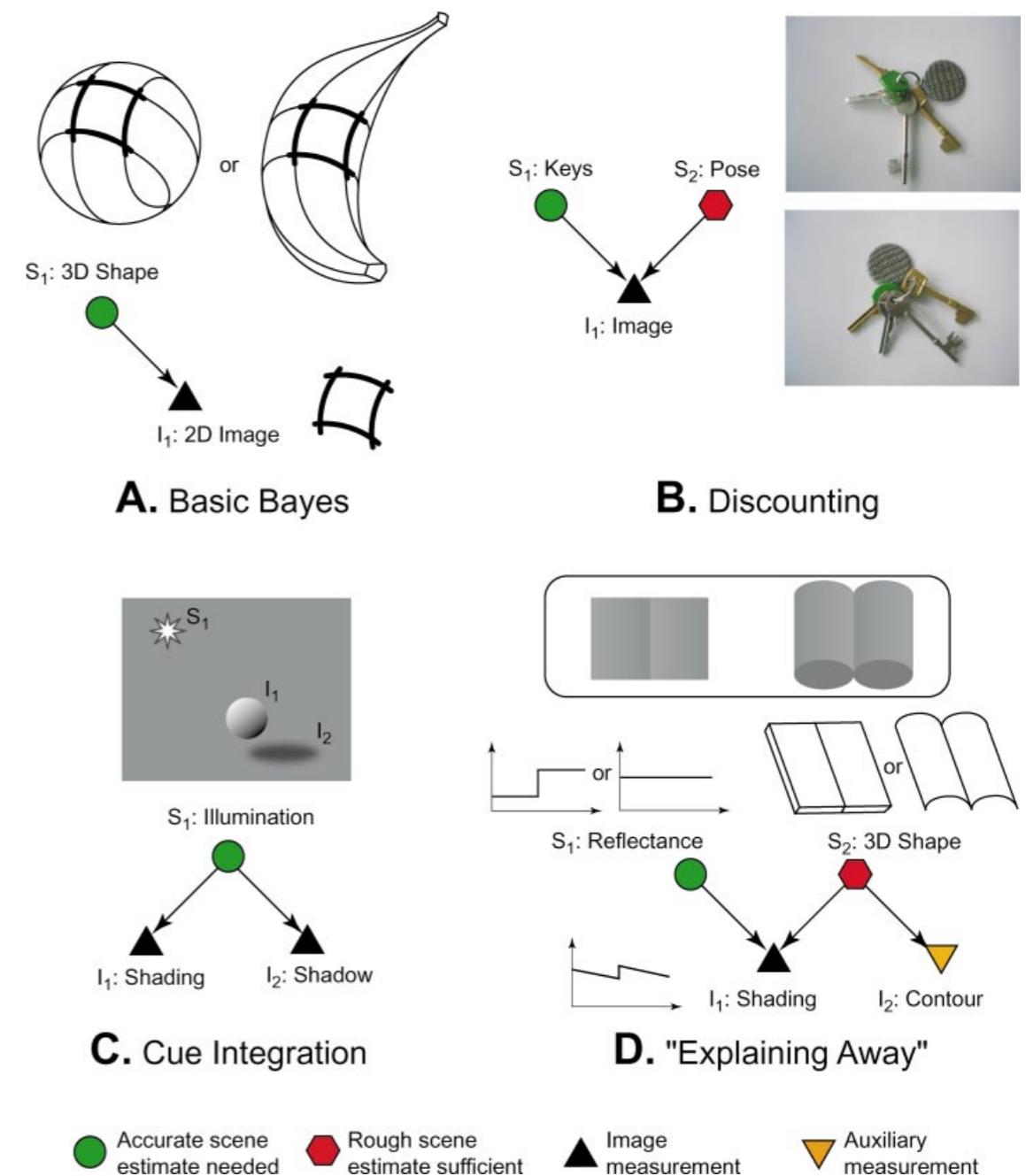
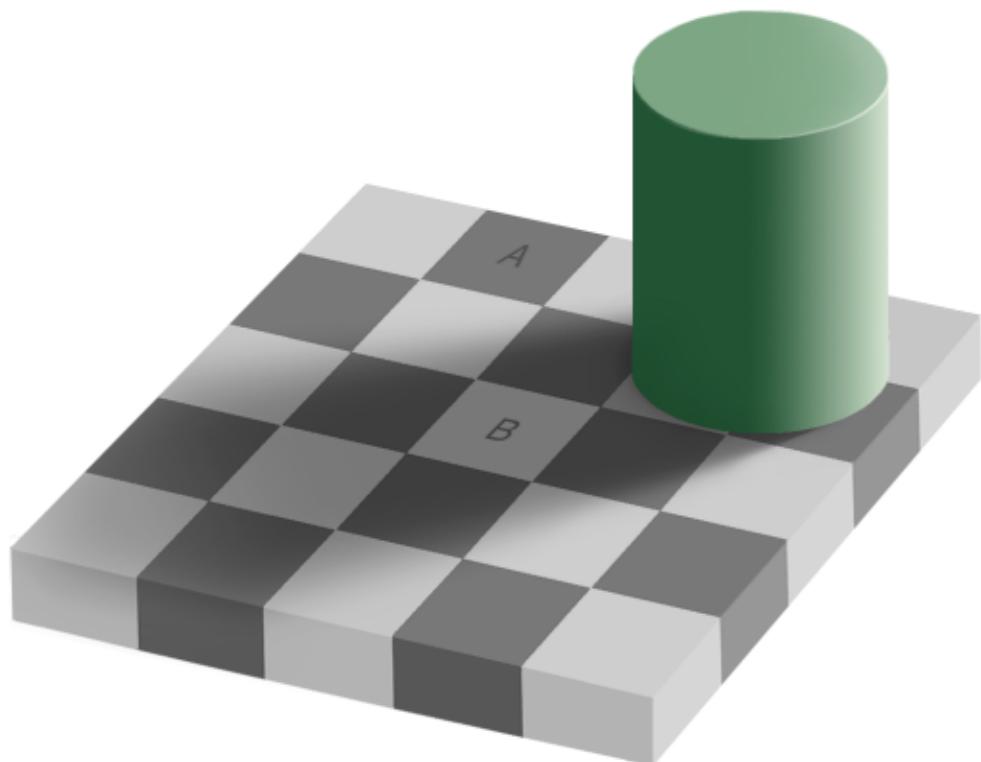


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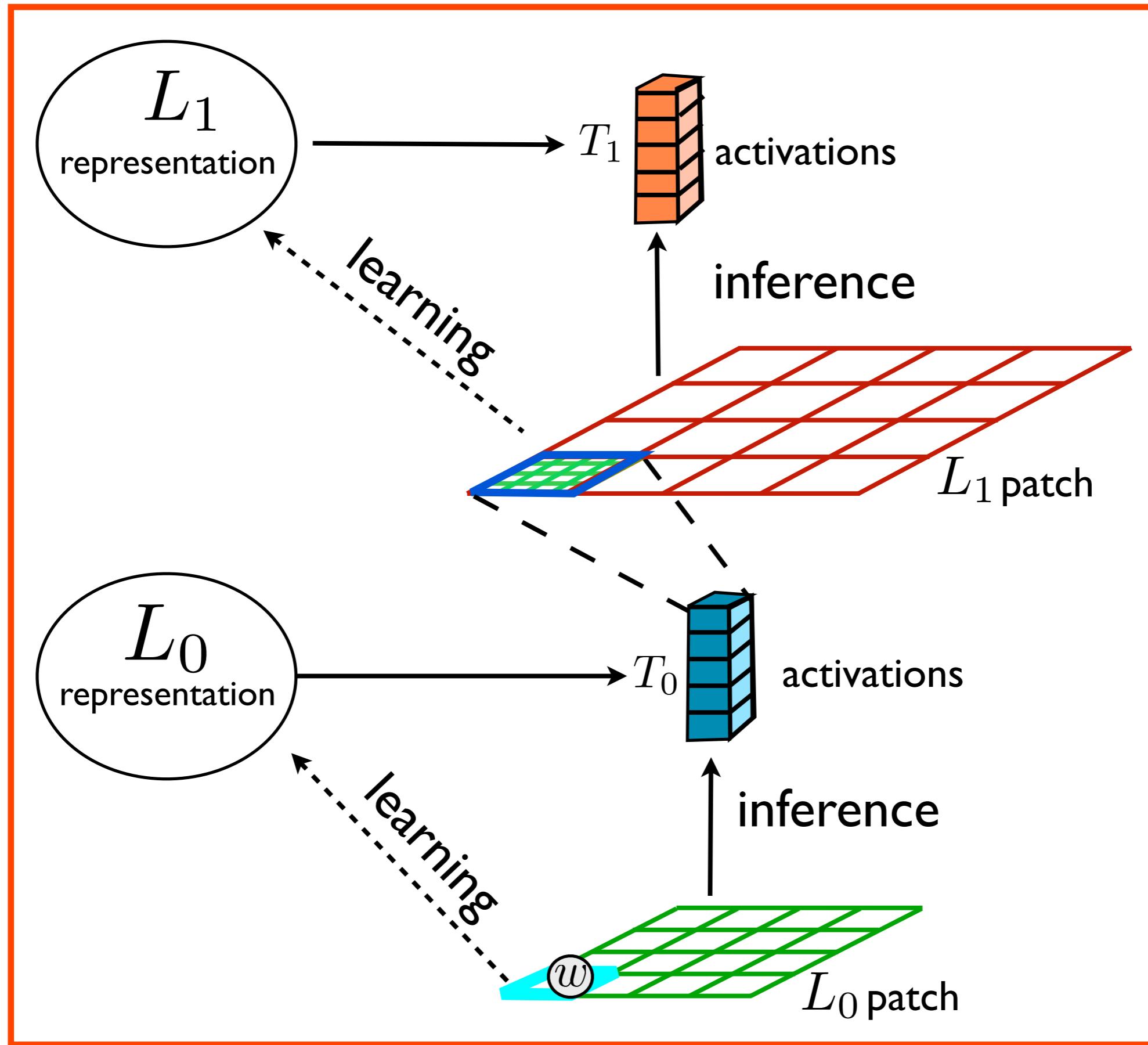
Bayesian inference

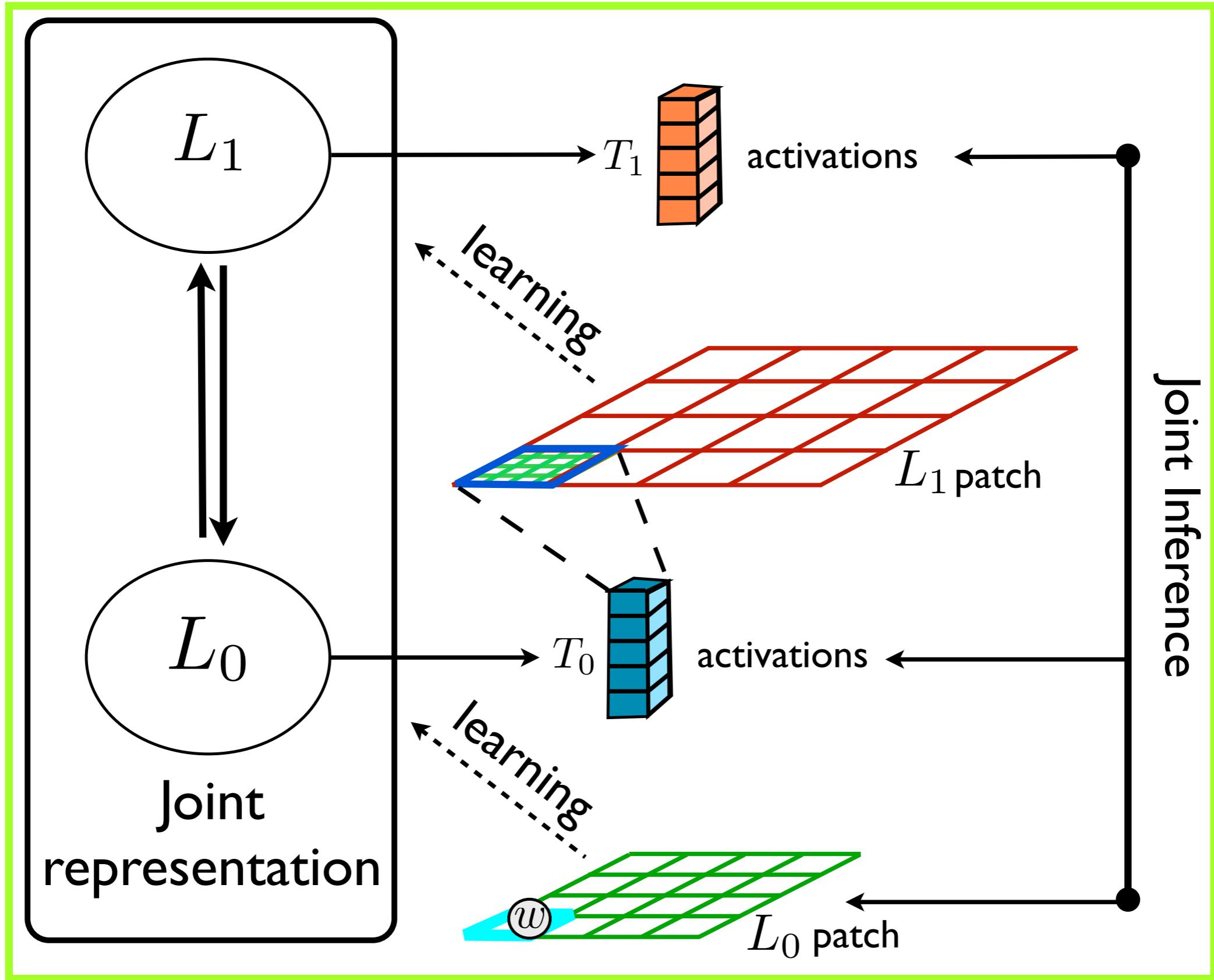
- The human visual cortex deals with inherently ambiguous data.
- Role of priors and inference (Lee and Mumford 2003).



Kersten et al. Object perception as Bayesian inference. Annual Reviews (2004)

- But most hierarchical approaches do both learning and inference only from the bottom-up.





What we would like

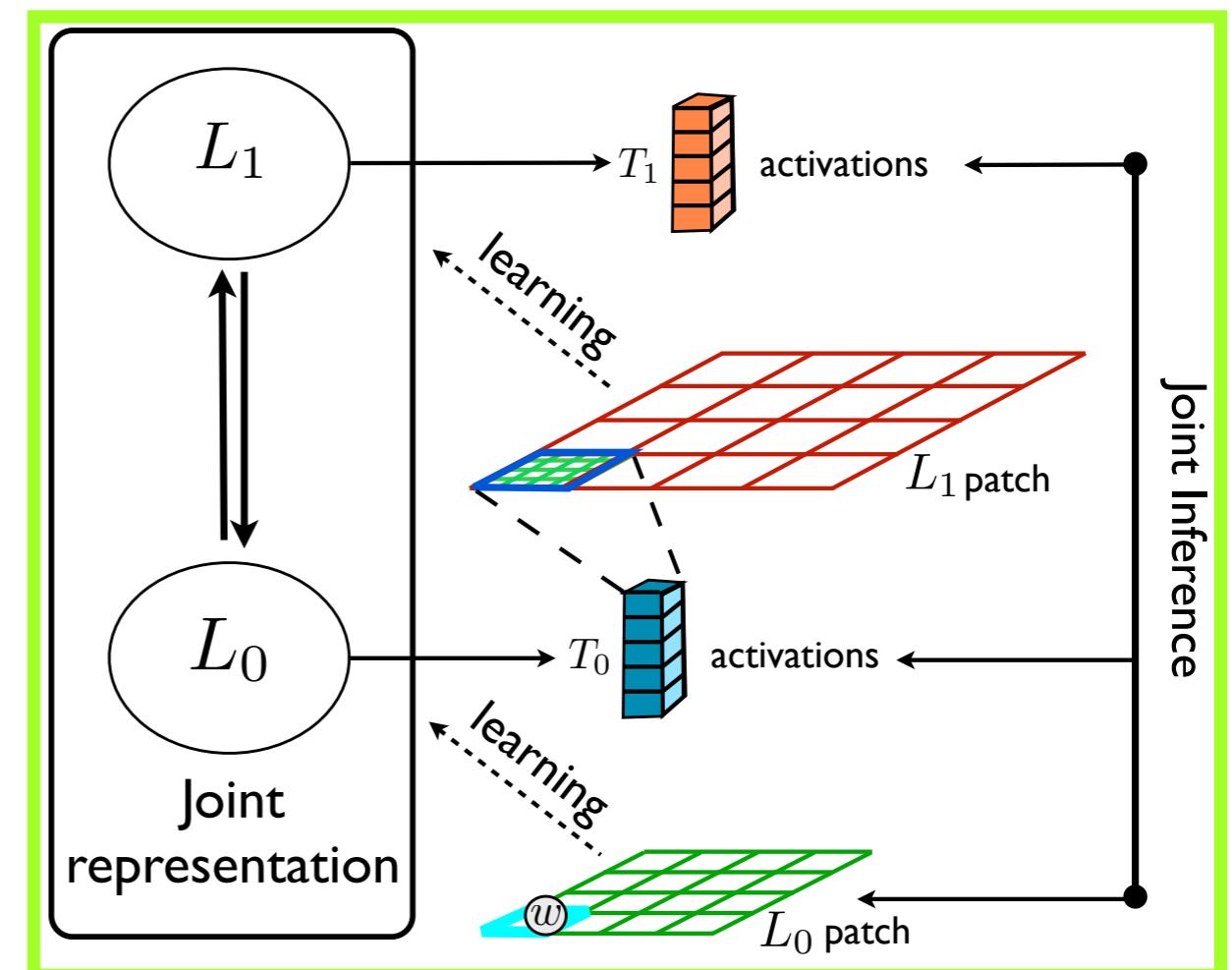
- Distributed coding of local features in a hierarchical model that would allow full inference.

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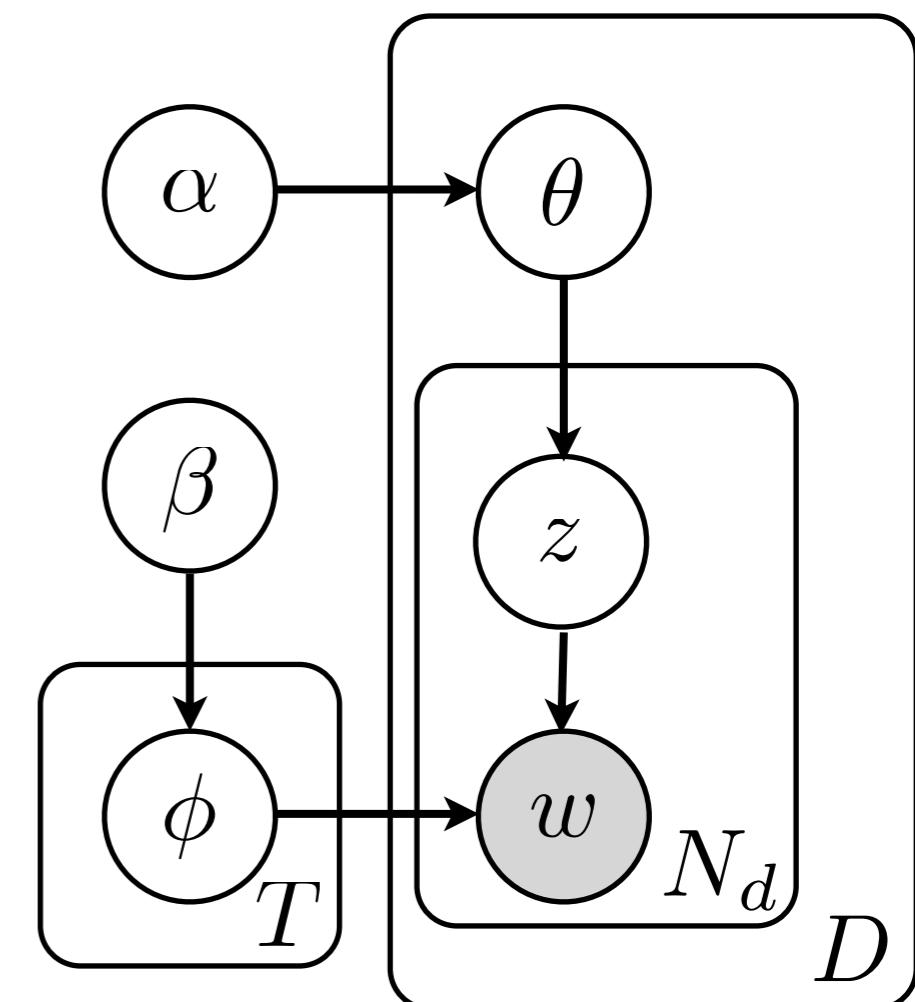
Our model: rLDA

- Based on Latent Dirichlet Allocation (LDA).
- Multiple layers, with increasing spatial support.
- Learns representation jointly across layers.



Latent Dirichlet Allocation

- Bayesian multinomial mixture model originally formulated for text analysis.



Latent Dirichlet Allocation

Corpus-wide, the multinomial distributions of words (topics) are sampled:

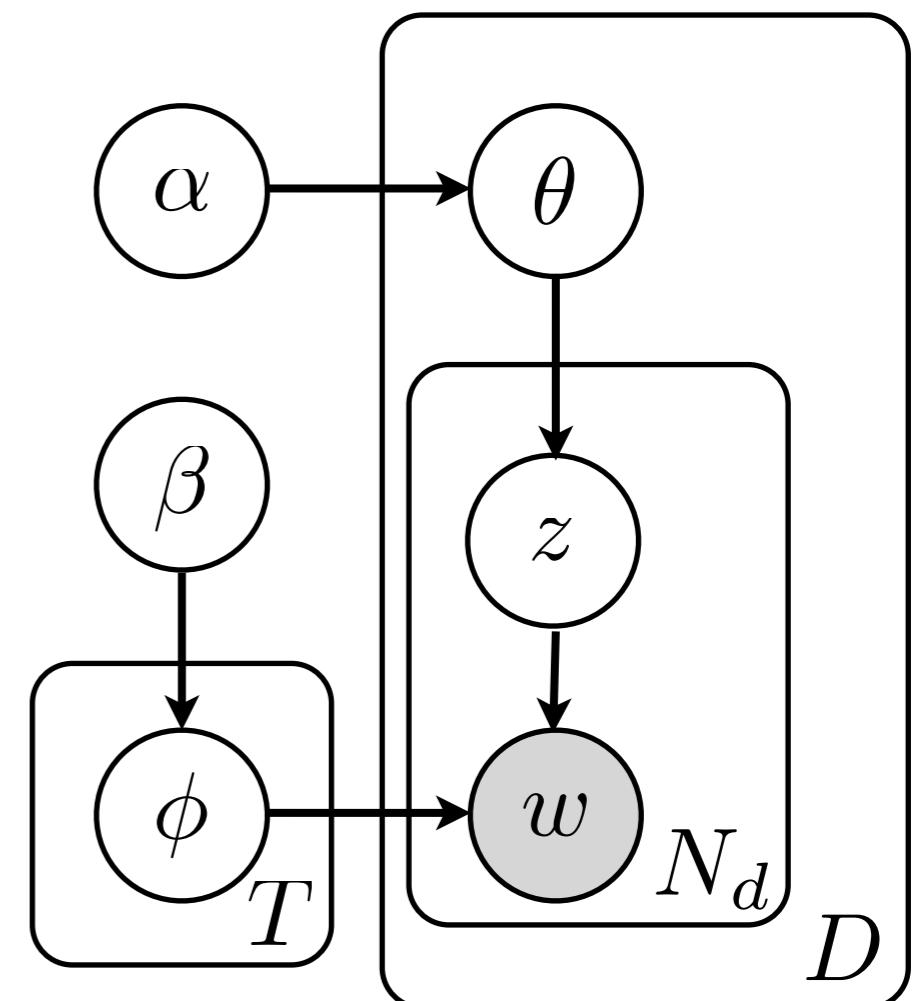
- $\phi \sim Dir(\beta)$

For each document, $d \in 1, \dots, D$, mixing proportions $\theta^{(d)}$ are sampled according to:

- $\theta^{(d)} \sim Dir(\alpha)$

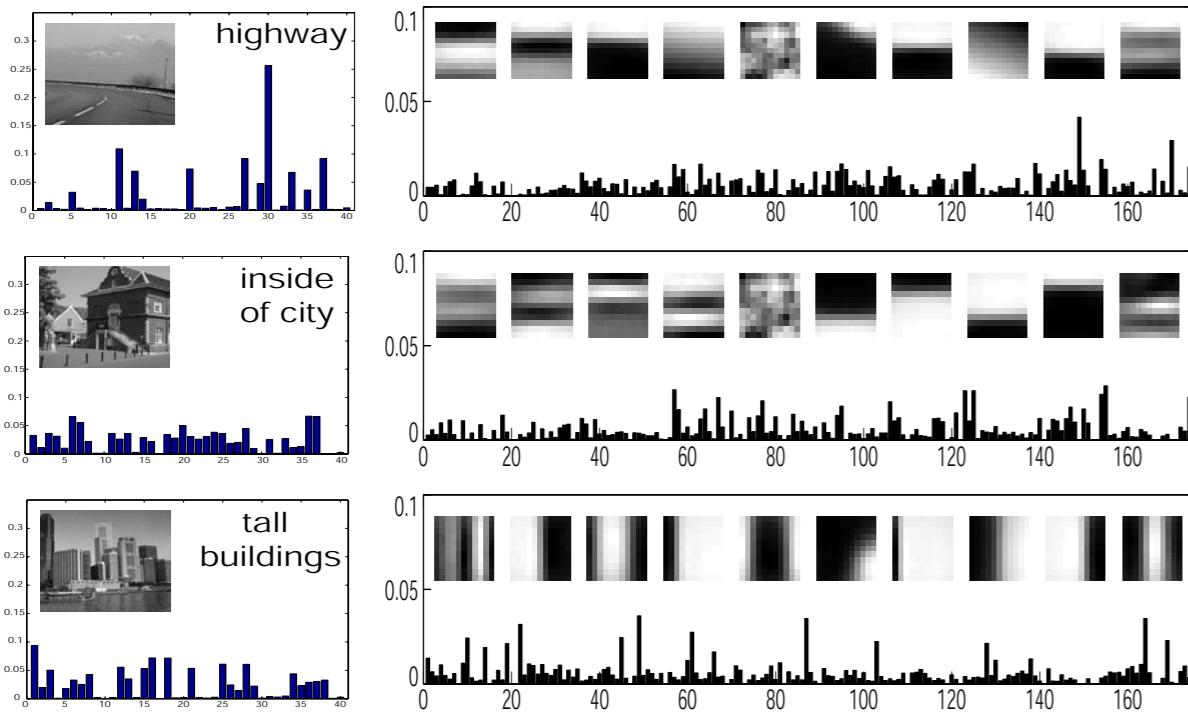
And N_d words w are sampled according to:

- $z \sim Mult(\theta^{(d)})$: sample topic given the document-topic mixing proportions
- $w \sim Mult(\phi^{(z)})$: sample word given the topic and the topic-word multinomials

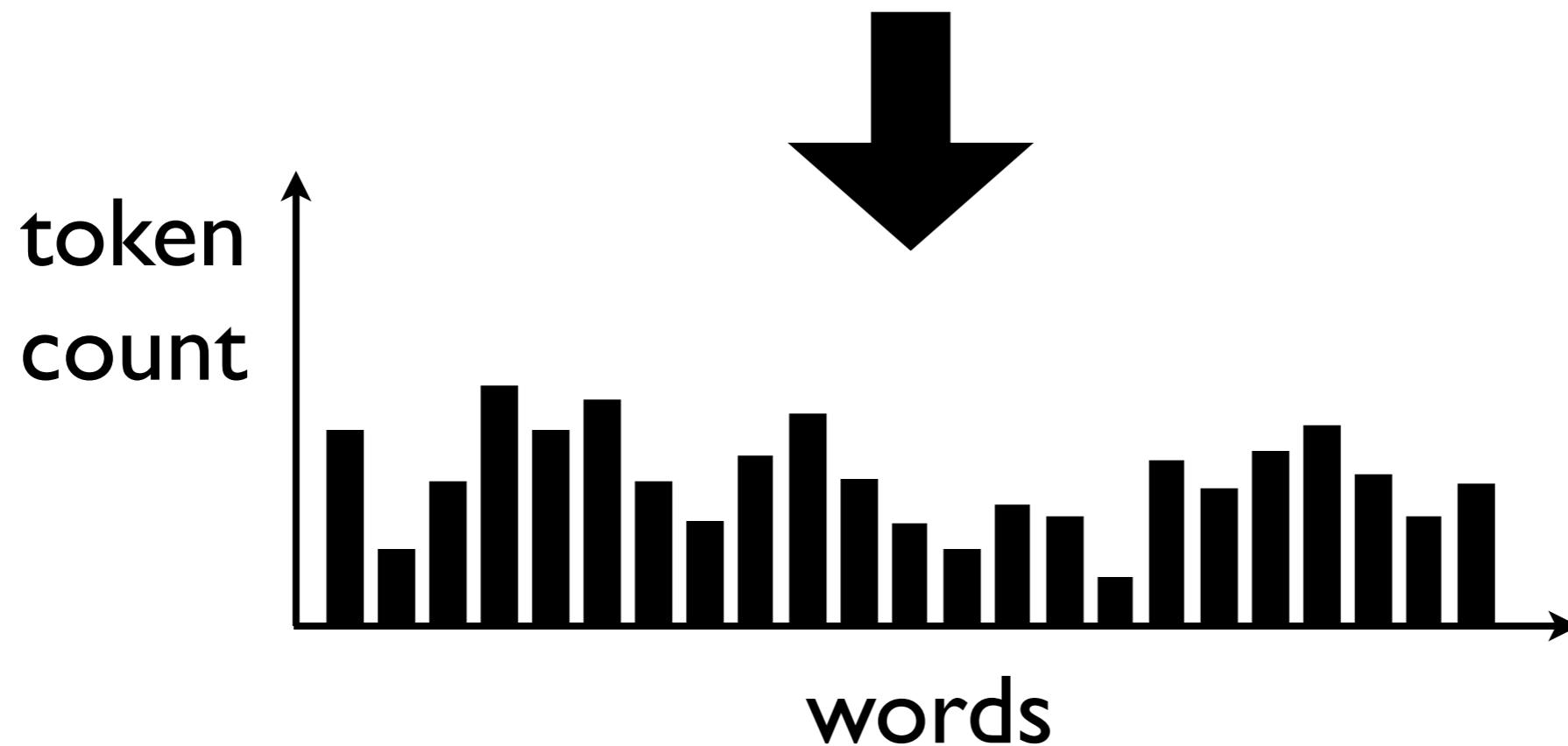
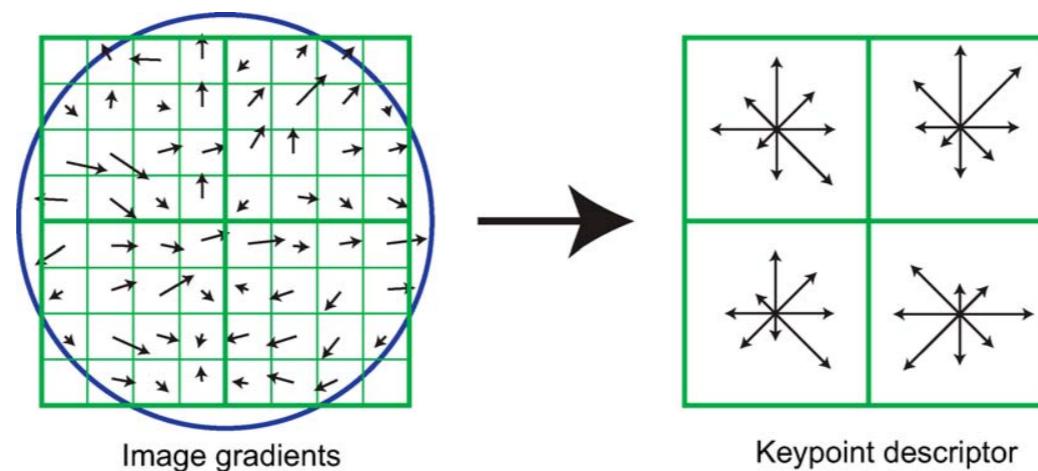


LDA in vision

- Past work has applied LDA to *visual words*, with topics being distributions over them.



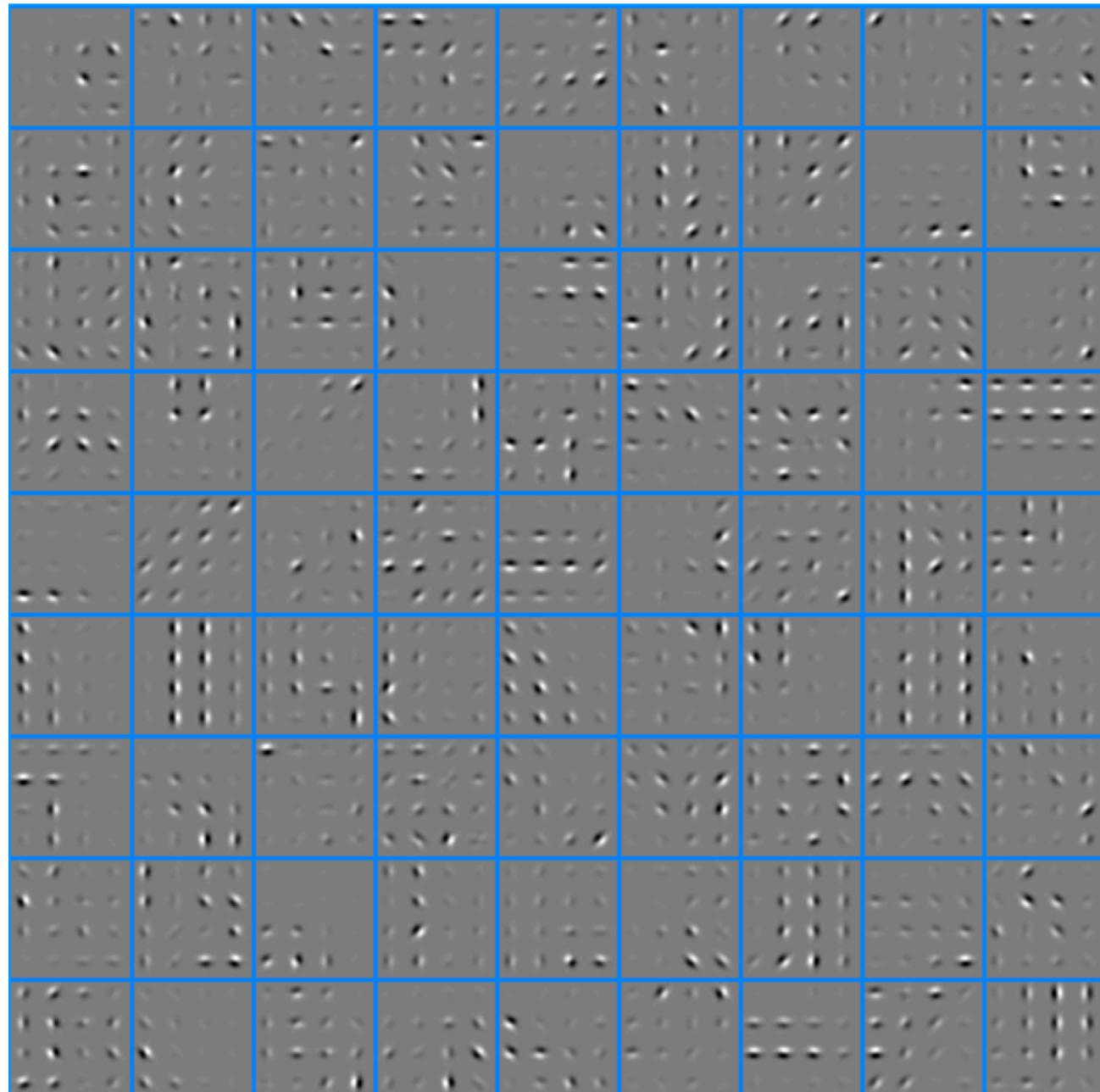
LDA-SIFT



How training works

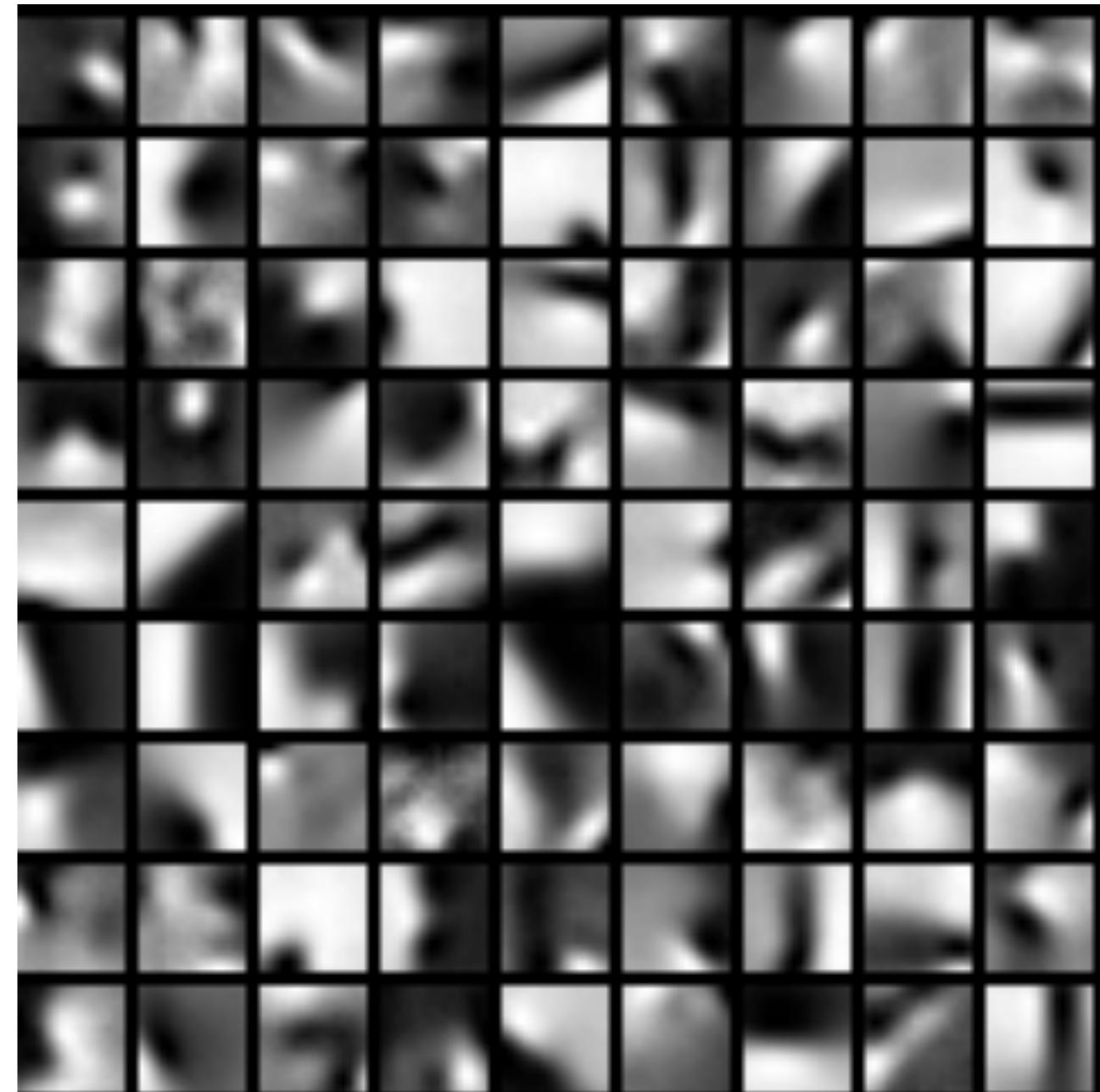
- (quantization, extracting patches, inference illustration)

Topics



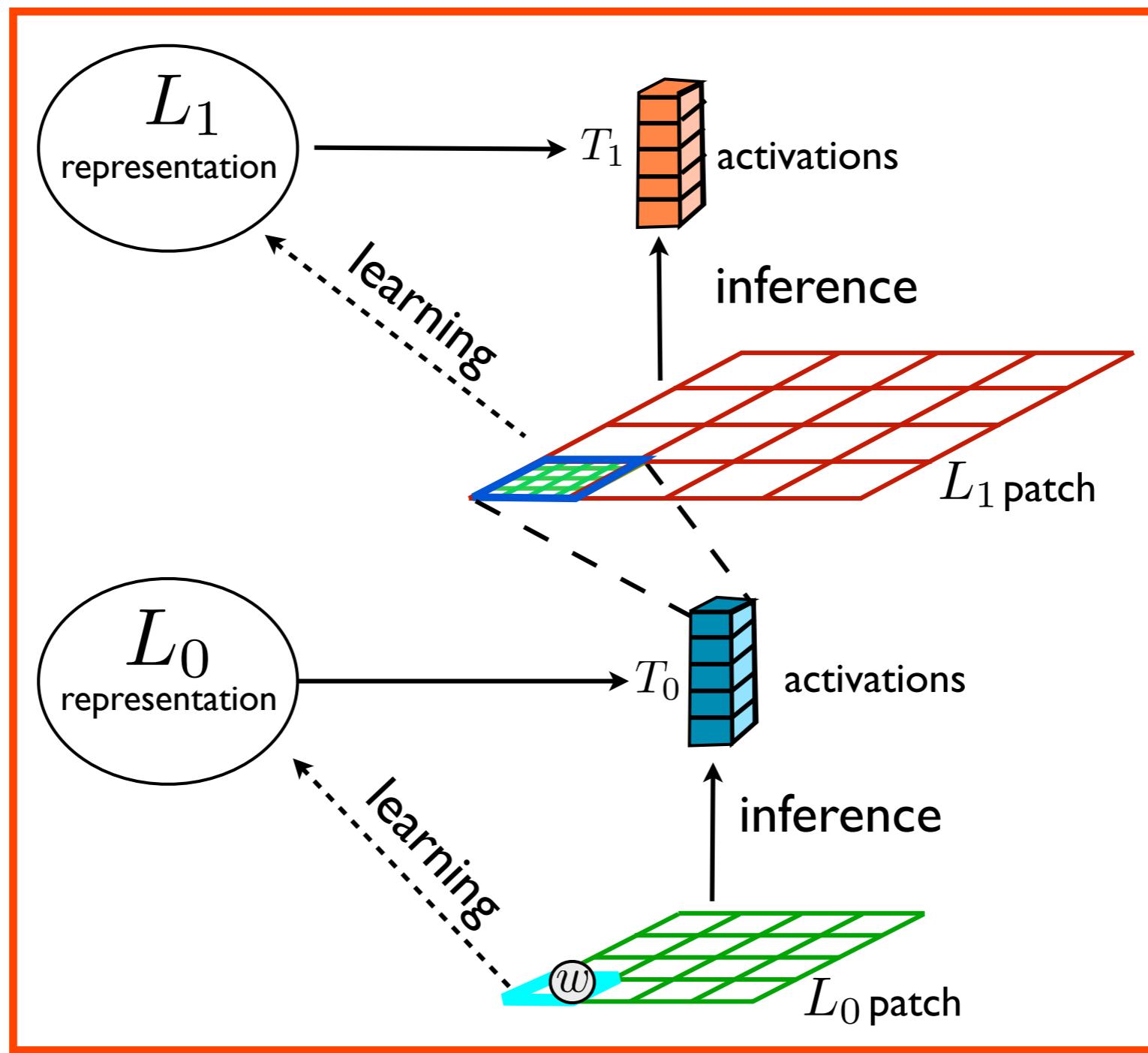
SIFT

(subset of 1024 topics)

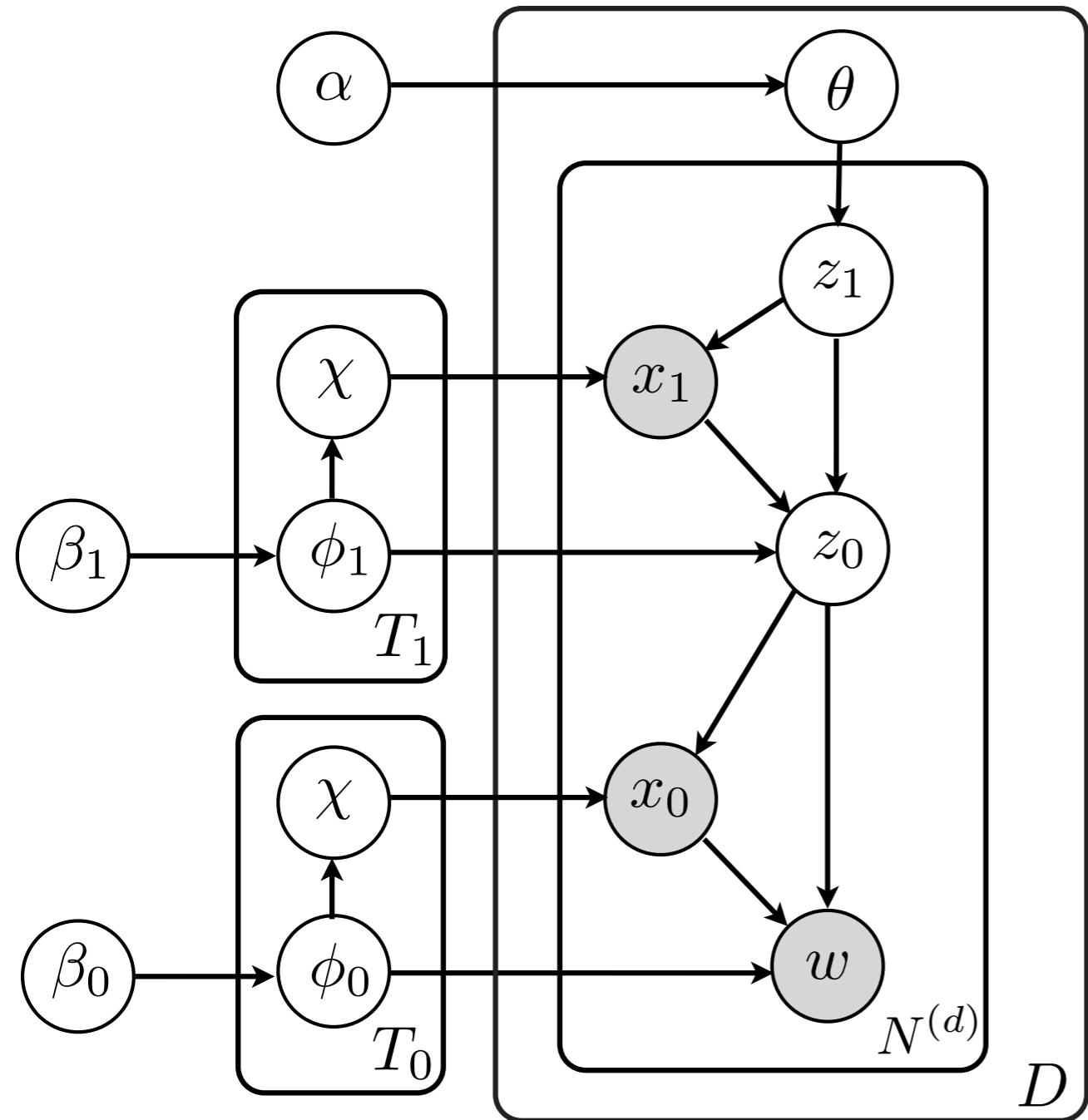


average image

Stacking two layers of LDA



Recursive LDA



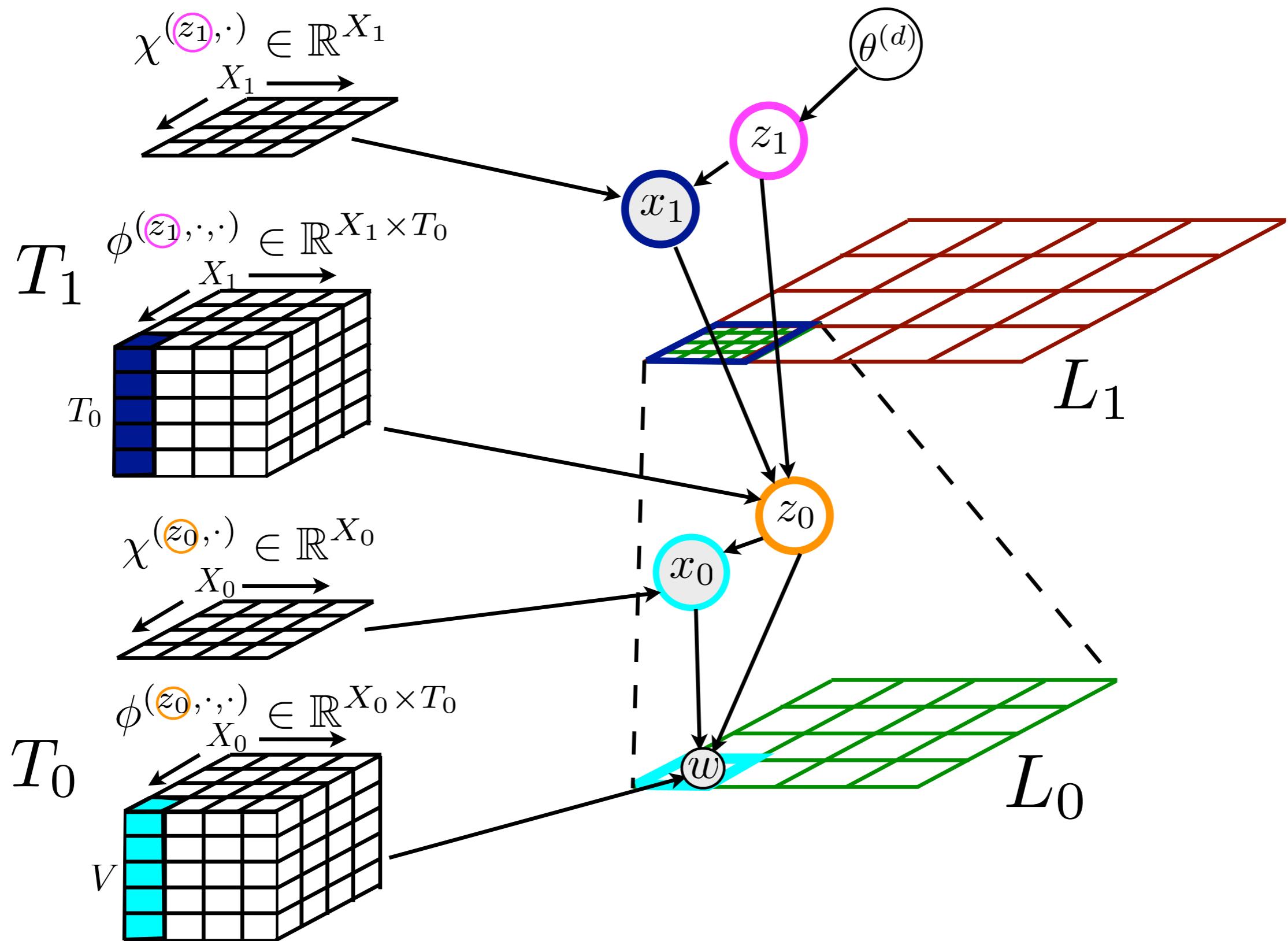
- $\phi_1 \sim \text{Dir}(\beta_1)$ and $\phi_0 \sim \text{Dir}(\beta_0)$: sample L_1 and L_0 multinomial parameters
- $\chi_1 \leftarrow \phi_1$ and $\chi_0 \leftarrow \phi_0$: compute spatial distributions from mixture distributions

For each document, $d \in \{1, \dots, D\}$ top level mixing proportions $\theta^{(d)}$ are sampled according to:

- $\theta^{(d)} \sim \text{Dir}(\alpha)$: sample top level mixing proportions

For each document d , $N^{(d)}$ words w are sampled according to:

- $z_1 \sim \text{Mult}(\theta^{(d)})$: sample L_1 mixture distribution
- $x_1 \sim \text{Mult}(\chi_1^{(z_1, \cdot)})$: sample spatial position on L_1 given z_1
- $z_0 \sim \text{Mult}(\phi_1^{(z_1, x_1, \cdot)})$: sample L_0 mixture distribution given z_1 and x_1 from L_1
- $x_0 \sim \text{Mult}(\chi_0^{(z_0, \cdot)})$: sample spatial position on L_0 given z_0
- $w \sim \text{Mult}(\phi_0^{(z_0, x_0, \cdot)})$: sample word given z_0 and x_0



Inference scheme

- Gibbs sampling: sequential updates of random variables with all others held constant.
- Linear topic response for initialization.

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Evaluation

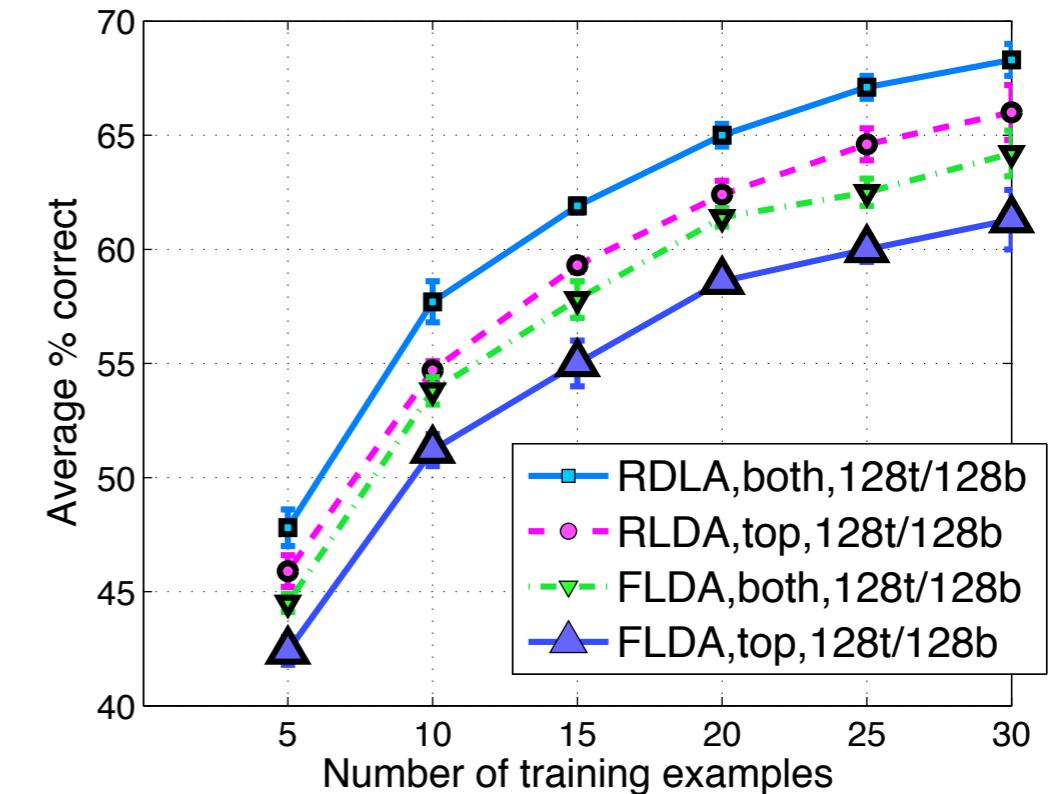
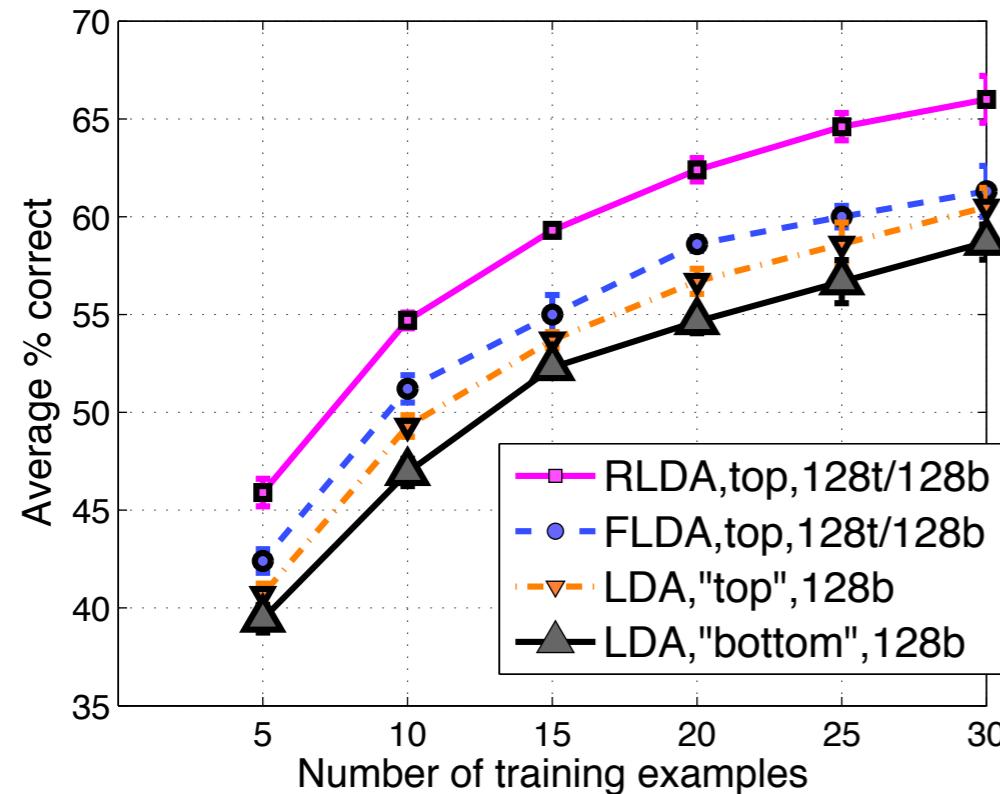
- 16px SIFT, extracted densely every 6px;
max value normalized to 100 tokens
- Three conditions:
 - * Single-layer LDA
 - * Feed-forward two-layer LDA (FLDA)
 - * Recursive two-layer LDA (RLDA)

RLDA > FLDA > LDA

Approach				Caltech-101	
	Model	Basis size	Layer(s) used	15	30
128-dim models	LDA	128	“bottom”	52.3 ± 0.5%	58.7 ± 1.1%
	RLDA	128t/128b	bottom	55.2 ± 0.3%	62.6 ± 0.9%
	LDA	128	“top”	53.7 ± 0.4%	60.5 ± 1.0%
	FLDA	128t/128b	top	55.4 ± 0.5%	61.3 ± 1.3%
	RLDA	128t/128b	top	59.3 ± 0.3%	66.0 ± 1.2%
	FLDA	128t/128b	both	57.8 ± 0.8%	64.2 ± 1.0%
	RLDA	128t/128b	both	61.9 ± 0.3%	68.3 ± 0.7%

- additional layer increases performance
- full inference increases performance

RLDA > FLDA > LDA



- additional layer increases performance
- full inference increases performance
- using both layers increases performance

RLDA vs. other hierarchies

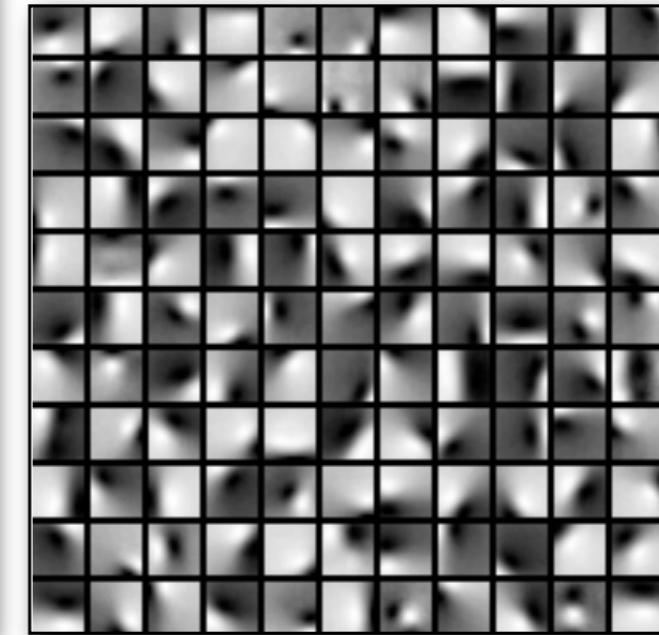
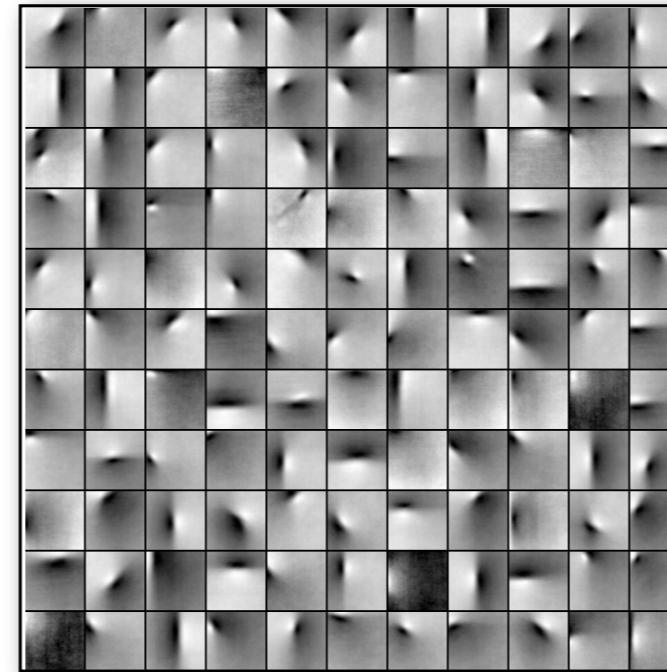
Approach		Caltech-101		
	Model	Layer(s) used	15	30
Our Model	RLDA (1024t/128b)	bottom	$56.6 \pm 0.8\%$	$62.7 \pm 0.5\%$
	RLDA (1024t/128b)	top	$66.7 \pm 0.9\%$	$72.6 \pm 1.2\%$
	RLDA (1024t/128b)	both	67.4 ± 0.5	$73.7 \pm 0.8\%$
Hierarchical Models	Sparse-HMAX [21]	top	51.0%	56.0%
	CNN [15]	bottom	–	$57.6 \pm 0.4\%$
	CNN [15]	top	–	$66.3 \pm 1.5\%$
	CNN + Transfer [2]	top	58.1%	67.2%
	CDBN [17]	bottom	$53.2 \pm 1.2\%$	$60.5 \pm 1.1\%$
	CDBN [17]	both	$57.7 \pm 1.5\%$	$65.4 \pm 0.4\%$
	Hierarchy-of-parts [8]	both	60.5%	66.5%
	Ommer and Buhmann [23]	top	–	$61.3 \pm 0.9\%$

RLDA vs. single-feature state-of-the-art

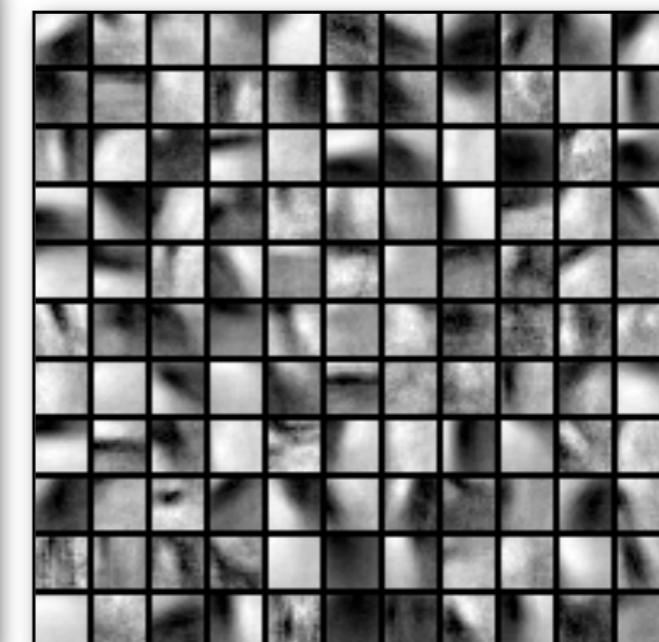
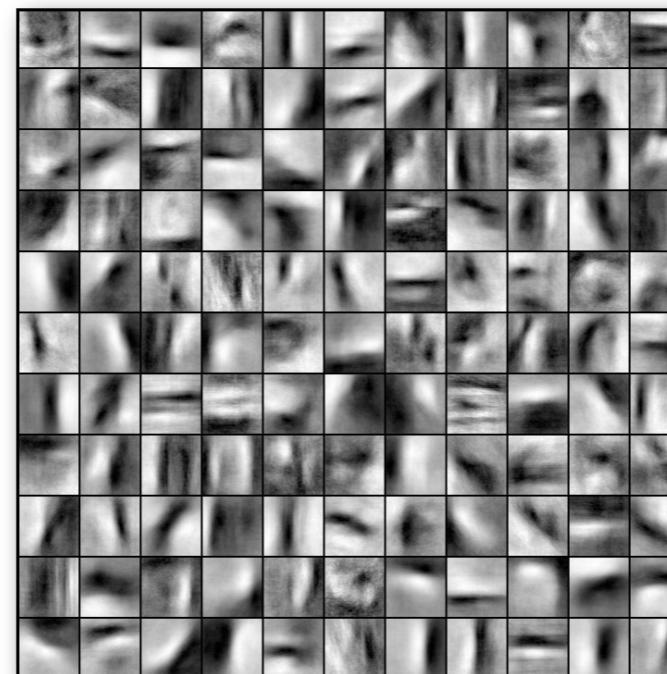
- RLDA: 73.7%
- Sparse-Coding Spatial Pyramid Matching: 73.2%
(Yang et al. CVPR 2009)
- SCSPM with “macrofeatures” and denser sampling:
75.7% (Bouerau et al. CVPR 2010)
- Locality-constrained Linear Coding: 73.4% (Wang et al. CVPR 2010)
- Saliency sampling + NBNN: 78.5% (Kanan and Cottrell, CVPR 2010)

Bottom and top layers

FLDA 128t/128b



RLDA 128t/128b



Top

Bottom

Conclusions

- Presented Bayesian hierarchical approach to modeling sparsely coded visual features of increasing complexity and spatial support.
- Showed value of full inference.

Future directions

- Extend hierarchy to object level.
- Direct discriminative component
- Non-parametrics
- Sparse Coding + LDA