

Parameterized intractability: the W-hierarchy

Serge Gaspers

Contents

1	Parameterized Complexity Theory	1
1.1	Parameterized reductions	2
1.2	Parameterized complexity classes	2
2	Case study	4
3	Further Reading	4

1 Parameterized Complexity Theory

Main Parameterized Complexity Classes

n : instance size

k : parameter

P: class of problems that can be solved in $n^{O(1)}$ time

FPT: class of parameterized problems that can be solved in $f(k) \cdot n^{O(1)}$ time

W[·]: parameterized intractability classes

XP: class of parameterized problems that can be solved in $f(k) \cdot n^{g(k)}$ time (“polynomial when k is a constant”)

$$P \subseteq \text{FPT} \subseteq W[1] \subseteq W[2] \cdots \subseteq W[P] \subseteq \text{XP}$$

Note: We assume that f is *computable* and *non-decreasing*.

Polynomial-time reductions for parameterized problems?

A *vertex cover* in a graph $G = (V, E)$ is a subset of vertices $S \subseteq V$ such that every edge of G has an endpoint in S .

VERTEX COVER

Input: Graph G , integer k

Parameter: k

Question: Does G have a vertex cover of size k ?

An *independent set* in a graph $G = (V, E)$ is a subset of vertices $S \subseteq V$ such that there is no edge $uv \in E$ with $u, v \in S$.

INDEPENDENT SET

Input: Graph G , integer k

Parameter: k

Question: Does G have an independent set of size k ?

- We know: $\text{INDEPENDENT SET} \leq_P \text{VERTEX COVER}$
- However: $\text{VERTEX COVER} \in \text{FPT}$ but INDEPENDENT SET is not known to be in FPT

We will need another type of reductions

- Issue with polynomial-time reductions: parameter can change arbitrarily.
- We will want the reduction to produce an instance where the parameter is bounded by a function of the parameter of the original instance.
- Also: we can allow the reduction to take FPT time instead of only polynomial time.

1.1 Parameterized reductions

Parameterized reduction

Definition 1. A *parameterized reduction* from a parameterized decision problem Π_1 to a parameterized decision problem Π_2 is an algorithm, which, for any instance I of Π_1 with parameter k produces an instance I' of Π_2 with parameter k' such that

- I is a YES-instance for $\Pi_1 \Leftrightarrow I'$ is a YES-instance for Π_2 ,
- there exists a computable function g such that $k' \leq g(k)$, and
- there exists a computable function f such that the running time of the algorithm is $f(k) \cdot |I|^{O(1)}$.

If there exists a parameterized reduction from Π_1 to Π_2 , we write $\Pi_1 \leq_{\text{FPT}} \Pi_2$.

Note: We can assume that f and g are non-decreasing.

New FPT algorithms via reductions

Lemma 2. If Π_1, Π_2 are parameterized decision problems such that $\Pi_1 \leq_{\text{FPT}} \Pi_2$, then $\Pi_2 \in \text{FPT}$ implies $\Pi_1 \in \text{FPT}$.

Proof sketch. To obtain an FPT algorithm for Π_1 , perform the reduction and then use an FPT algorithm for Π_2 on the resulting instance. \square

1.2 Parameterized complexity classes

Boolean Circuits

Definition 3. A *Boolean circuit* is a directed acyclic graph with the nodes labeled as follows:

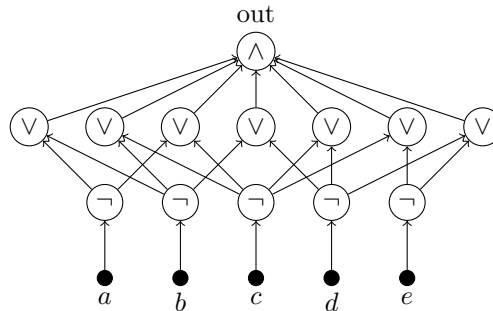
- every node of in-degree 0 is an *input node*,
- every node with in-degree 1 is a *negation node* (\neg), and
- every node with in-degree ≥ 2 is either an *AND-node* (\wedge) or an *OR-node* (\vee).

Moreover, exactly one node with out-degree 0 is also labeled the *output node*.

The *depth* of the circuit is the maximum length of a directed path from an input node to the output node.

The *weft* of the circuit is the maximum number of nodes with in-degree ≥ 3 on a directed path from an input node to the output node.

Example



A depth-3, weft-1 Boolean circuit with inputs a, b, c, d, e .

Weighted Circuit Satisfiability

Given an assignment of Boolean values to the input gates, the circuit determines Boolean values at each node in the obvious way.

If the value of the output node is 1 for an input assignment, we say that this assignment *satisfies* the circuit.

The *weight* of an assignment is its number of 1s.

WEIGHTED CIRCUIT SATISFIABILITY (WCS)

Input: A Boolean circuit C , an integer k
 Parameter: k
 Question: Is there an assignment with weight k that satisfies C ?

Exercise: Show that WEIGHTED CIRCUIT SATISFIABILITY \in XP.

WCS for special circuits

Definition 4. The class of circuits $\mathcal{C}_{t,d}$ contains the circuits with weft $\leq t$ and depth $\leq d$.

For any class of circuits \mathcal{C} , we can define the following problem.

WCS[\mathcal{C}]

Input: A Boolean circuit $C \in \mathcal{C}$, an integer k
 Parameter: k
 Question: Is there an assignment with weight k that satisfies C ?

W classes

Definition 5 (W-hierarchy). Let $t \in \{1, 2, \dots\}$. A parameterized problem Π is in the parameterized complexity class $W[t]$ if there exists a parameterized reduction from Π to $WCS[\mathcal{C}_{t,d}]$ for some constant $d \geq 1$.

Independent Set and Dominating Set

Theorem 6. INDEPENDENT SET $\in W[1]$.

Theorem 7. DOMINATING SET $\in W[2]$.

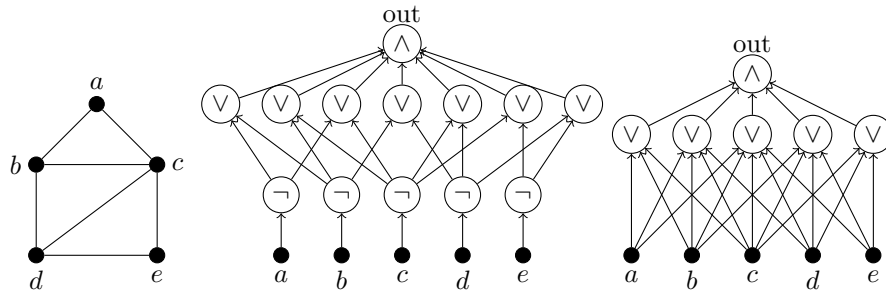
Recall: A *dominating set* of a graph $G = (V, E)$ is a set of vertices $S \subseteq V$ such that $N_G[S] = V$.

DOMINATING SET

Input: A graph $G = (V, E)$ and an integer k
 Parameter: k
 Question: Does G have a dominating set of size at most k ?

“Proof” by picture

Parameterized reductions from INDEPENDENT SET to $WCS[\mathcal{C}_{1,3}]$ and from DOMINATING SET to $WCS[\mathcal{C}_{2,2}]$.



Setting an input node to 1 corresponds to adding the corresponding vertex to the independent set / dominating set.

W-hardness

Definition 8. Let $t \in \{1, 2, \dots\}$. A parameterized decision problem Π is $W[t]$ -hard if for every parameterized decision problem Π' in $W[t]$, there is a parameterized reduction from Π' to Π . Π is $W[t]$ -complete if $\Pi \in W[t]$ and Π is $W[t]$ -hard.

Theorem 9 ((Downey and Fellows, 1995b)). INDEPENDENT SET is $W[1]$ -complete.

Theorem 10 ((Downey and Fellows, 1995a)). DOMINATING SET is $W[2]$ -complete.

Proving W-hardness

To show that a parameterized decision problem Π is $W[t]$ -hard:

- Select a $W[t]$ -hard problem Π'
- Show that $\Pi' \leq_{\text{FPT}} \Pi$ by designing a parameterized reduction from Π' to Π
 - Design an algorithm, that, for any instance I' of Π' with parameter k' , produces an equivalent instance I of Π with parameter k
 - Show that k is upper bounded by a function of k'
 - Show that there exists a function f such that the running time of the algorithm is $f(k') \cdot |I'|^{O(1)}$

2 Case study

Clique

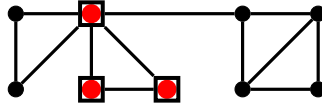
A *clique* in a graph $G = (V, E)$ is a subset of its vertices $S \subseteq V$ such that every two vertices from S are adjacent in G .

CLIQUE

Input: Graph $G = (V, E)$, integer k

Parameter: k

Question: Does G have a clique of size k ?



- We will show that CLIQUE is $W[1]$ -hard by a parameterized reduction from INDEPENDENT SET.

Lemma 11. INDEPENDENT SET \leq_{FPT} CLIQUE.

Proof. Given any instance $(G = (V, E), k)$ for INDEPENDENT SET, we need to describe an FPT algorithm that constructs an equivalent instance (G', k') for CLIQUE such that $k' \leq g(k)$ for some computable function g .

Construction. Set $k' \leftarrow k$ and $G' \leftarrow \overline{G} = (V, \{uv : u, v \in V, u \neq v, uv \notin E\})$.

Equivalence. We need to show that (G, k) is a YES-instance for INDEPENDENT SET if and only if (G', k') is a YES-instance for CLIQUE.

(\Rightarrow) : Let S be an independent set of size k in G . For every two vertices $u, v \in S$, we have that $uv \notin E$. Therefore, $uv \in E(\overline{G})$ for every two vertices in S . We conclude that S is a clique of size k in \overline{G} .

(\Leftarrow) : Let S be a clique of size k in \overline{G} . By a similar argument, S is an independent set of size k in G .

Parameter. $k' \leq k$.

Running time. The construction can clearly be done in FPT time, and even in polynomial time. □

Corollary 12. CLIQUE is $W[1]$ -hard

3 Further Reading

- Chapter 13, *Fixed-parameter Intractability* in (Cygan et al., 2015)
- Chapter 13, *Parameterized Complexity Theory* in (Niedermeier, 2006)
- Elements of Chapters 20–23 in (Downey and Fellows, 2013)

References

- Marek Cygan, Fedor V. Fomin, Łukasz Kowalik, Daniel Lokshantov, Dániel Marx, Marcin Pilipczuk, Michał Pilipczuk, and Saket Saurabh (2015). *Parameterized Algorithms*. Springer. DOI: 10.1007/978-3-319-21275-3.
- Rodney G. Downey and Michael R. Fellows (1995a). “Fixed-Parameter Tractability and Completeness I: Basic Results”. In: *SIAM Journal on Computing* 24.4, pp. 873–921.
- (1995b). “Fixed-Parameter Tractability and Completeness II: On Completeness for $W[1]$ ”. In: *Theoretical Computer Science* 141.1&2, pp. 109–131.
- (2013). *Fundamentals of Parameterized Complexity*. Springer. DOI: 10.1007/978-1-4471-5559-1.
- Rolf Niedermeier (2006). *Invitation to Fixed Parameter Algorithms*. Oxford University Press. DOI: 10.1093/ACPROF:OSO/9780198566076.001.0001.