# Parameterized intractability: the W-hierarchy

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## 1 Parameterized Complexity Theory

### Main Parameterized Complexity Classes

n: instance sizek: parameter

P: class of problems that can be solved in  $n^{O(1)}$  time

FPT: class of parameterized problems that can be solved in  $f(k) \cdot n^{O(1)}$  time

W[·]: parameterized intractability classes

XP: class of parameterized problems that can be solved in  $f(k) \cdot n^{g(k)}$  time ("polynomial when k is a constant")

$$P \subseteq FPT \subseteq W[1] \subseteq W[2] \cdots \subseteq W[P] \subseteq XP$$

**Note**: We assume that f is *computable* and *non-decreasing*.

## Polynomial-time reductions for parameterized problems?

A vertex cover in a graph G = (V, E) is a subset of vertices  $S \subseteq V$  such that every edge of G has an endpoint in S.

Vertex Cover

Input: Graph G, integer k

Parameter: k

Question: Does G have a vertex cover of size k?

An independent set in a graph G = (V, E) is a subset of vertices  $S \subseteq V$  such that there is no edge  $uv \in E$  with  $u, v \in S$ .

INDEPENDENT SET

Input: Graph G, integer k

Parameter: k

Question: Does G have an independent set of size k?

- We know: Independent Set  $\leq_{\mathbb{P}}$  Vertex Cover
- However: Vertex Cover ∈ FPT but Independent Set is not known to be in FPT

#### We will need another type of reductions

- Issue with polynomial-time reductions: parameter can change arbitrarily.
- We will want the reduction to produce an instance where the parameter is bounded by a function of the parameter of the original instance.
- Also: we can allow the reduction to take FPT time instead of only polynomial time.

#### 1.1 Parameterized reductions

#### Parameterized reduction

**Definition 1.** A parameterized reduction from a parameterized decision problem  $\Pi_1$  to a parameterized decision problem  $\Pi_2$  is an algorithm, which, for any instance I of  $\Pi_1$  with parameter k produces an instance I' of  $\Pi_2$  with parameter k' such that

- I is a YES-instance for  $\Pi_1 \Leftrightarrow I'$  is a YES-instance for  $\Pi_2$ ,
- there exists a computable function g such that  $k' \leq g(k)$ , and
- there exists a computable function f such that the running time of the algorithm is  $f(k) \cdot |I|^{O(1)}$ .

If there exists a parameterized reduction from  $\Pi_1$  to  $\Pi_2$ , we write  $\Pi_1 \leq_{\text{FPT}} \Pi_2$ .

**Note**: We can assume that f and g are non-decreasing.

#### New FPT algorithms via reductions

**Lemma 2.** If  $\Pi_1, \Pi_2$  are parameterized decision problems such that  $\Pi_1 \leq_{\mathrm{FPT}} \Pi_2$ , then  $\Pi_2 \in \mathrm{FPT}$  implies  $\Pi_1 \in \mathrm{FPT}$ .

*Proof sketch.* To obtain an FPT algorithm for  $\Pi_1$ , perform the reduction and then use an FPT algorithm for  $\Pi_2$  on the resulting instance.

## 1.2 Parameterized complexity classes

#### **Boolean Circuits**

**Definition 3.** A Boolean circuit is a directed acyclic graph with the nodes labeled as follows:

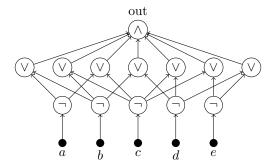
- every node of in-degree 0 is an input node,
- every node with in-degree 1 is a negation node  $(\neg)$ , and
- every node with in-degree  $\geq 2$  is either an AND-node ( $\wedge$ ) or an OR-node ( $\vee$ ).

Moreover, exactly one node with out-degree 0 is also labeled the *output node*.

The depth of the circuit is the maximum length of a directed path from an input node to the output node.

The weft of the circuit is the maximum number of nodes with in-degree  $\geq 3$  on a directed path from an input node to the output node.

#### Example



A depth-3, weft-1 Boolean circuit with inputs a, b, c, d, e.

#### Weighted Circuit Satisfiability

Given an assignment of Boolean values to the input gates, the circuit determines Boolean values at each node in the obvious way.

If the value of the output node is 1 for an input assignment, we say that this assignment satisfies the circuit.

The weight of an assignment is its number of 1s.

WEIGHTED CIRCUIT SATISFIABILITY (WCS)

Input: A Boolean circuit C, an integer k

Parameter: k

Question: Is there an assignment with weight k that satisfies C?

**Exercise**: Show that Weighted Circuit Satisfiability  $\in$  XP.

### WCS for special circuits

**Definition 4.** The class of circuits  $C_{t,d}$  contains the circuits with weft  $\leq t$  and depth  $\leq d$ .

For any class of circuits C, we can define the following problem.

WCS[C]

Input: A Boolean circuit  $C \in \mathcal{C}$ , an integer k

Parameter: k

Question: Is there an assignment with weight k that satisfies C?

#### W classes

**Definition 5** (W-hierarchy). Let  $t \in \{1, 2, ...\}$ . A parameterized problem  $\Pi$  is in the parameterized complexity class W[t] if there exists a parameterized reduction from  $\Pi$  to WCS[ $\mathcal{C}_{t,d}$ ] for some constant  $d \geq 1$ .

## Independent Set and Dominating Set

Theorem 6. Independent Set  $\in$  W[1].

Theorem 7. Dominating Set  $\in W[2]$ .

**Recall**: A dominating set of a graph G = (V, E) is a set of vertices  $S \subseteq V$  such that  $N_G[S] = V$ .

Dominating Set

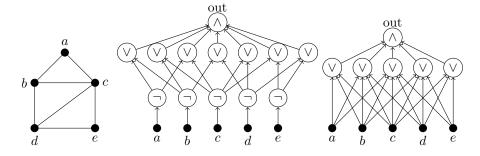
Input: A graph G = (V, E) and an integer k

Parameter: k

Question: Does G have a dominating set of size at most k?

#### "Proof" by picture

Parameterized reductions from Independent Set to WCS[ $\mathcal{C}_{1,3}$ ] and from Dominating Set to WCS[ $\mathcal{C}_{2,2}$ ].



Setting an input node to 1 corresponds to adding the corresponding vertex to the independent set / dominating set.

#### W-hardness

**Definition 8.** Let  $t \in \{1, 2, ...\}$ . A parameterized decision problem  $\Pi$  is W[t]-hard if for every parameterized decision problem  $\Pi'$  in W[t], there is a parameterized reduction from  $\Pi'$  to  $\Pi$ .  $\Pi$  is W[t]-complete if  $\Pi \in W[t]$  and  $\Pi$  is W[t]-hard.

Theorem 9 ((Downey and Fellows, 1995b)). Independent Set is W[1]-complete.

Theorem 10 ((Downey and Fellows, 1995a)). Dominating Set is W[2]-complete.

## **Proving W-hardness**

To show that a parameterized decision problem  $\Pi$  is W[t]-hard:

- Select a W[t]-hard problem  $\Pi'$
- Show that  $\Pi' \leq_{\text{FPT}} \Pi$  by designing a parameterized reduction from  $\Pi'$  to  $\Pi$ 
  - Design an algorithm, that, for any instance I' of  $\Pi'$  with parameter k', produces an equivalent instance I of  $\Pi$  with parameter k
  - Show that k is upper bounded by a function of k'
  - Show that there exists a function f such that the running time of the algorithm is  $f(k') \cdot |I'|^{O(1)}$

## 2 Case study

### Clique

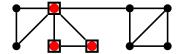
A clique in a graph G = (V, E) is a subset of its vertices  $S \subseteq V$  such that every two vertices from S are adjacent in G.

CLIQUE

Input: Graph G = (V, E), integer k

Parameter: k

Question: Does G have a clique of size k?



• We will show that CLIQUE is W[1]-hard by a parameterized reduction from INDEPENDENT SET.

Lemma 11. Independent Set < FPT CLIQUE.

*Proof.* Given any instance (G = (V, E), k) for INDEPENDENT SET, we need to describe an FPT algorithm that constructs an equivalent instance (G', k') for CLIQUE such that  $k' \leq g(k)$  for some computable function g.

Construction. Set  $k' \leftarrow k$  and  $\overrightarrow{G'} \leftarrow \overline{\overrightarrow{G}} = (V, \{uv : u, v \in V, u \neq v, uv \notin E\})$ .

**Equivalence.** We need to show that (G, k) is a YES-instance for INDEPENDENT SET if and only if (G', k') is a YES-instance for CLIQUE.

(⇒): Let S be an independent set of size k in G. For every two vertices  $u, v \in S$ , we have that  $uv \notin E$ . Therefore,  $uv \in E(\overline{G})$  for every two vertices in S. We conclude that S is a clique of size k in  $\overline{G}$ .

 $(\Leftarrow)$ : Let S be a clique of size k in  $\overline{G}$ . By a similar argument, S is an independent set of size k in G.

Parameter.  $k' \leq k$ .

Running time. The construction can clearly be done in FPT time, and even in polynomial time.

Corollary 12. CLIQUE is W[1]-hard

# 3 Further Reading

- Chapter 13, Fixed-parameter Intractability in (Cygan et al., 2015)
- Chapter 13, Parameterized Complexity Theory in (Niedermeier, 2006)
- Elements of Chapters 20–23 in (Downey and Fellows, 2013)

## References

- Marek Cygan, Fedor V. Fomin, Łukasz Kowalik, Daniel Lokshtanov, Dániel Marx, Marcin Pilipczuk, Michał Pilipczuk, and Saket Saurabh (2015). *Parameterized Algorithms*. Springer. DOI: 10.1007/978-3-319-21275-3. Rodney G. Downey and Michael R. Fellows (1995a). "Fixed-Parameter Tractability and Completeness I: Basic
- Results". In: SIAM Journal on Computing 24.4, pp. 873–921.
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