# Cooperative Learning of Disjoint Syntax and Semantics

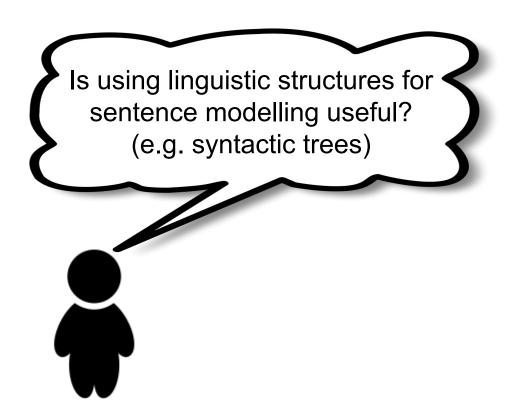
Serhii Havrylov

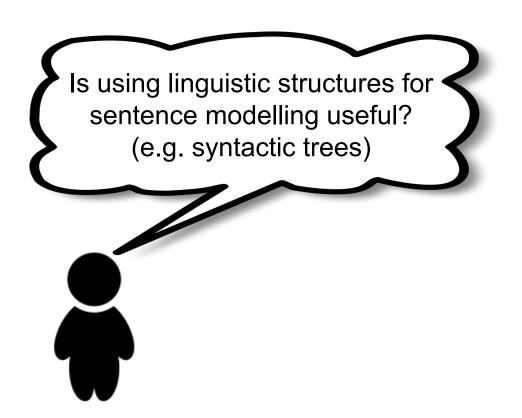




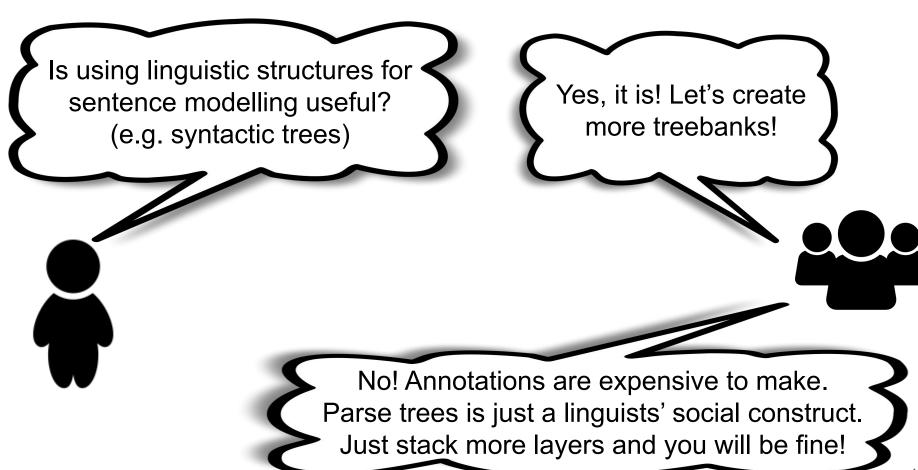
Germán Kruszewski Armand Joulin

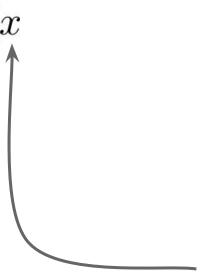




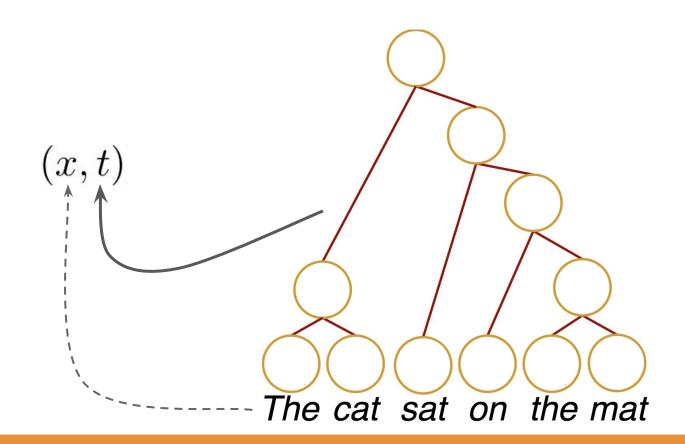


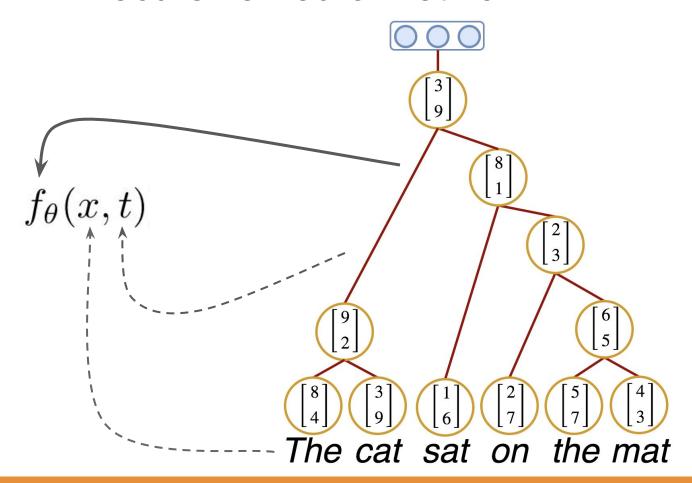


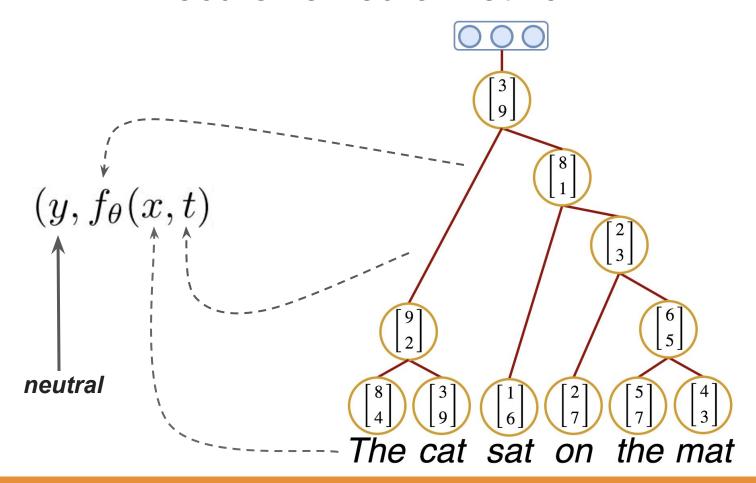


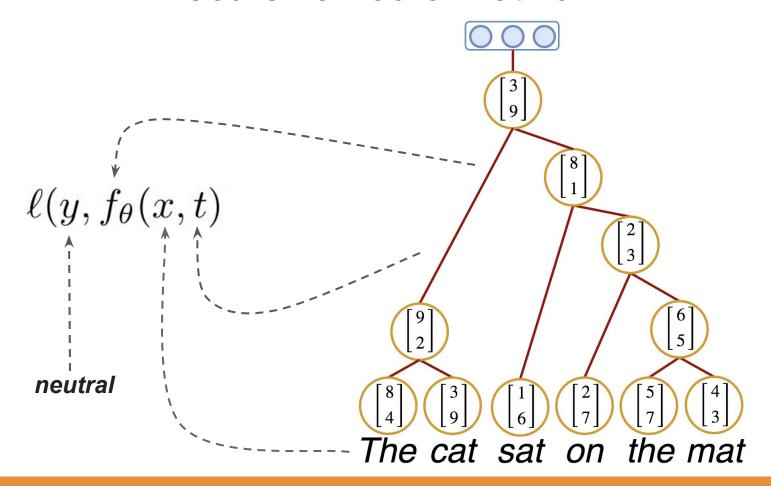


The cat sat on the mat



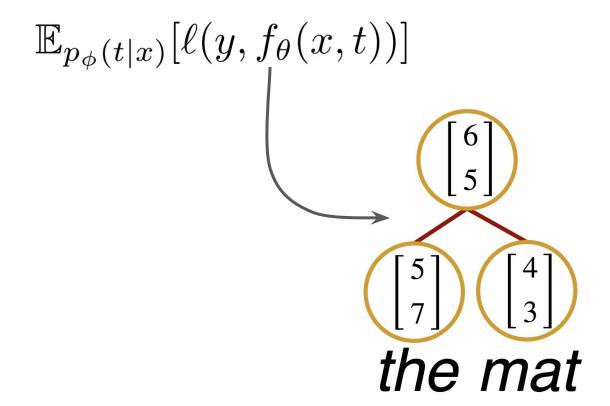


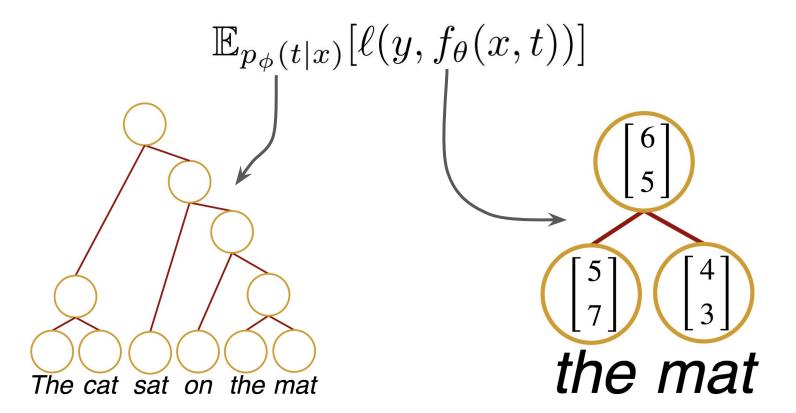


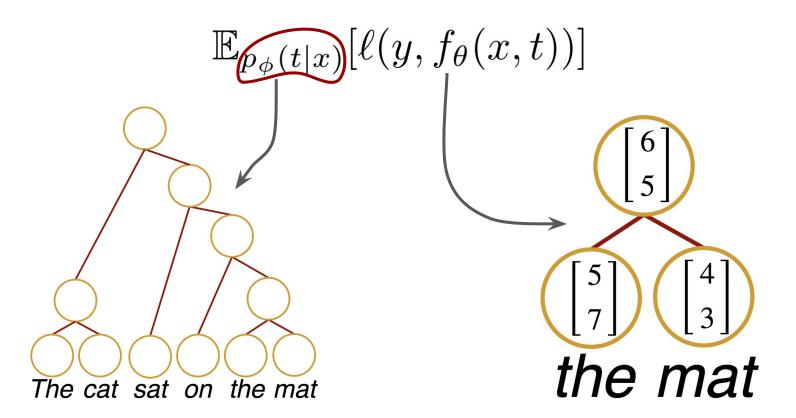


$$\ell(y, f_{\theta}(x, t))$$

$$\mathbb{E}_{p_{\phi}(t|x)}[\ell(y, f_{\theta}(x, t))]$$







• RL-SPINN: Yogatama et al., 2016

Soft-CYK: Maillard et al., 2017

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 Trees do not resemble any semantic or syntactic formalisms (Williams et al. 2018).

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- Trees do not resemble any semantic or syntactic formalisms (Williams et al. 2018).
- Parsing strategies are not consistent across random restarts (Williams et al. 2018).
- These models fail to learn the simple context-free grammar (Nangia et al. 2018).

### ListOps (Nangia, & Bowman (2018))

[MIN 1 [MAX [MIN 9 [MAX 10] 2 9 [MED 8 4 3]] [MIN 7 5] 6 9 3]]

[MAX 14 0 9 ]

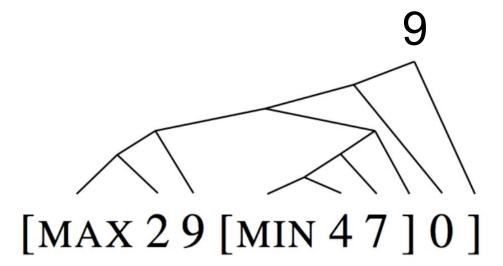
[MAX 71[MAX 6817][MIN 26]3]

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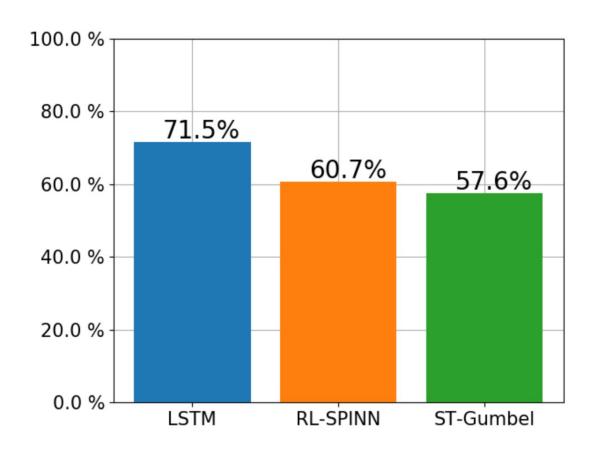
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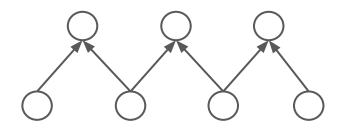
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# ListOps (Nangia, & Bowman (2018))

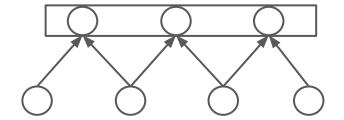






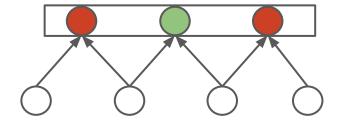
$$\mathbf{r}_i^{k+1} = \texttt{Tree-LSTM}(\mathbf{r}_i^k, \mathbf{r}_{i+1}^k)$$

$$s_k(i) = \langle \mathbf{q}, \mathbf{r}_i^{k+1} \rangle$$

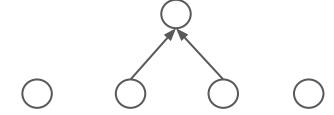


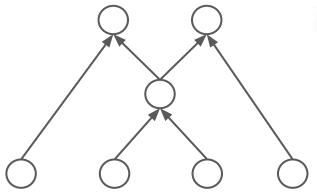
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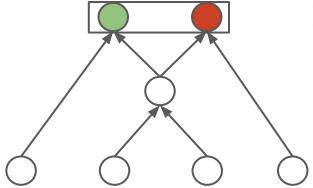




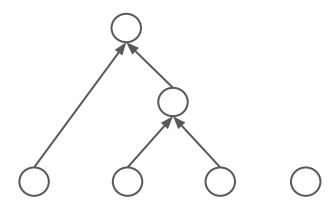
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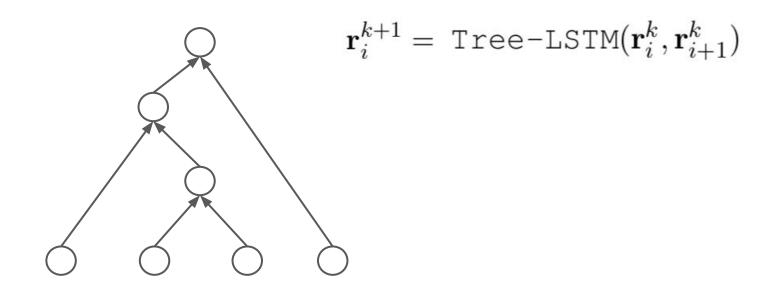
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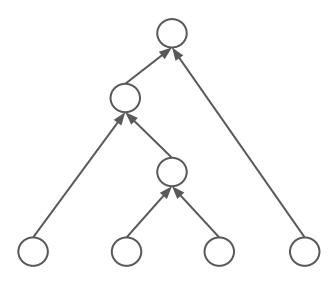
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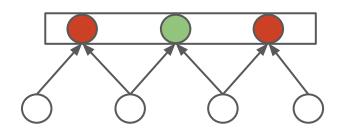


# Separation of syntax and semantics

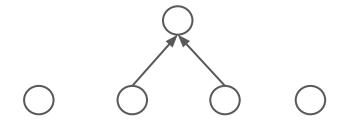
# Parser $\phi$

#### Compositional Function heta

$$s_k(i) = \langle \mathbf{q}, \mathtt{Tree-LSTM}(\mathbf{r}_i^k, \mathbf{r}_{i+1}^k) 
angle$$



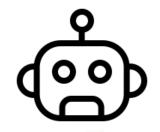
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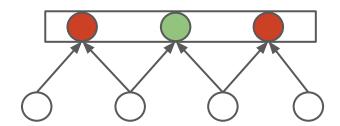
# Parsing as a RL problem

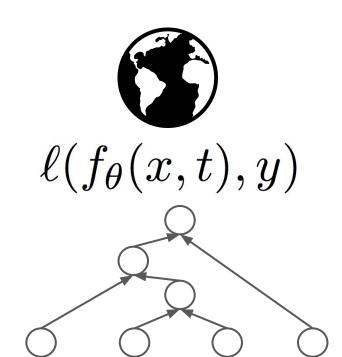
Parser  $\phi$ 

Compositional Function heta



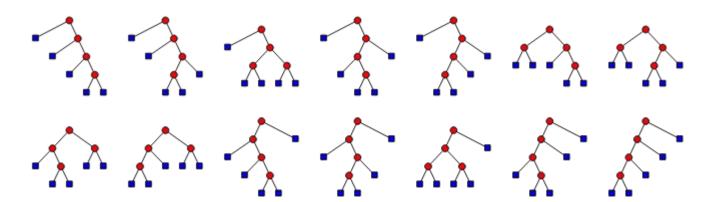
$$p_{\phi}(t|x) = \prod_{k=0}^{K} \pi_{\phi}(a_k^i|\mathbf{r}^k)$$





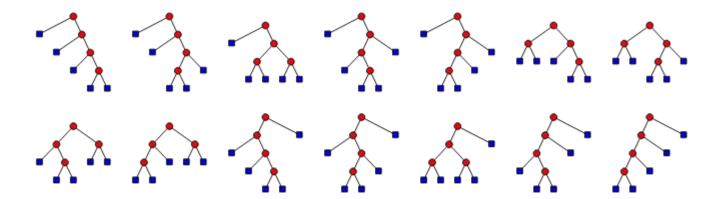
Size of the search space is

$$C_n \sim rac{4^n}{n^{3/2}\sqrt{\pi}}$$



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For a sentence with 20 words, there are 1\_767\_263\_190 possible trees.

Syntax and semantic has to be learnt simultaneously model has to infer from examples that [MIN 0 1] = 0

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 nonstationary environment (i.e the same sequence of actions can receive different rewards)

Typically, the *compositional function*  $\theta$  is learned faster than the *parser*  $\phi$ .





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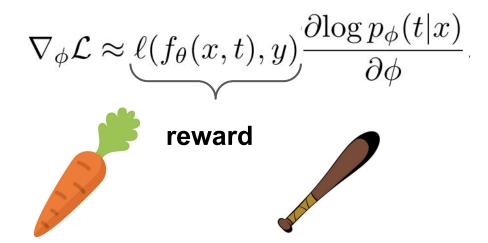
This fast coadaptation limits the exploration of the search space to parsing strategies similar to those found at the beginning of the training.

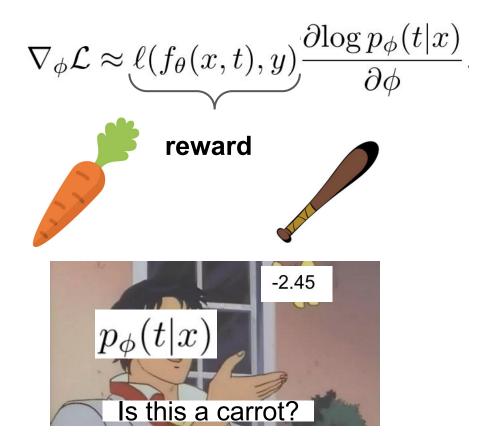
High variance in the estimate of a parser's gradient ∇<sub>φ</sub>
has to be addressed.

 <sup>1</sup>/<sub>2</sub> <sup>1</sup>

Learning paces of a parser θ and a compositional function φ have to be levelled off.

$$\nabla_{\phi} \mathcal{L} \approx \ell(f_{\theta}(x, t), y) \frac{\partial \log p_{\phi}(t|x)}{\partial \phi}$$





$$\nabla_{\phi} \mathcal{L} \approx \ell(f_{\theta}(x, t), y) \frac{\partial \log p_{\phi}(t|x)}{\partial \phi}$$

the moving average of recent rewards

$$\nabla_{\phi} \mathcal{L} \approx \underbrace{(\ell(f_{\theta}(x,t),y) - c)} \frac{\partial \log p_{\phi}(t|x)}{\partial \phi}$$

new reward

- [MIN 1 [MAX [MIN 9 [MIN 1 0 ] 2 [MED 8 4 3 ] ] [MAX 7 5 ] 6 9 ] ]
- [MAX 1 0 ]

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$$\nabla_{\phi} \mathcal{L} \approx (\ell(f_{\theta}(x, t), y) - c(x)) \frac{\partial \log p_{\phi}(t|x)}{\partial \phi}$$

- [MIN 1 [MAX [MIN 9 [MIN 1 0 ] 2 [MED 8 4 3 ] ] [MAX 7 5 ] 6 9 ] ]
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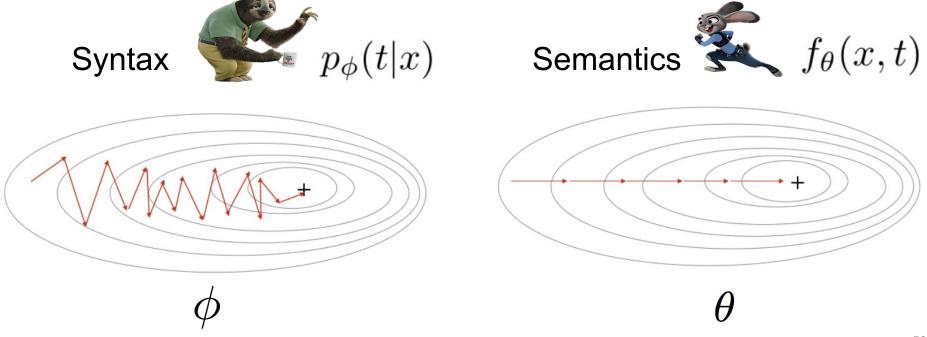
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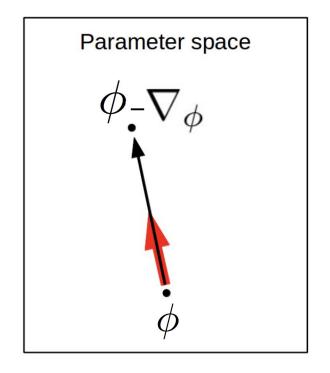
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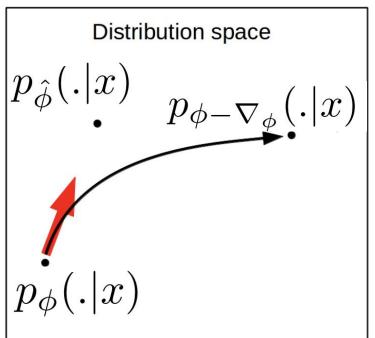
self-critical training (SCT) baseline Rennie et al. (2017)

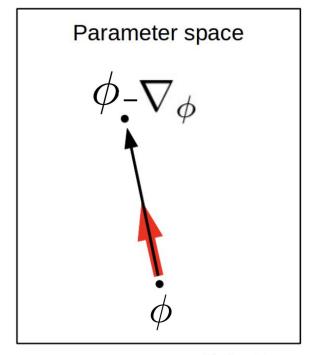
$$c(x) = \ell(f_{\theta}(x, \hat{t}), y)$$

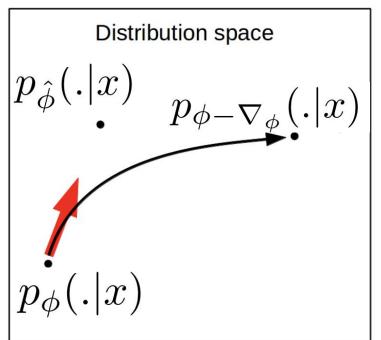
$$\hat{t} = \arg\max p_{\phi}(t|x)$$



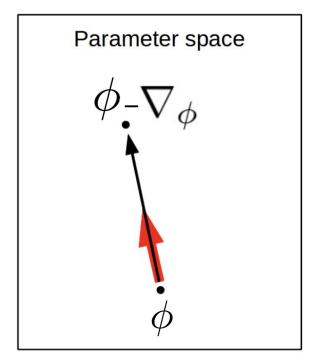


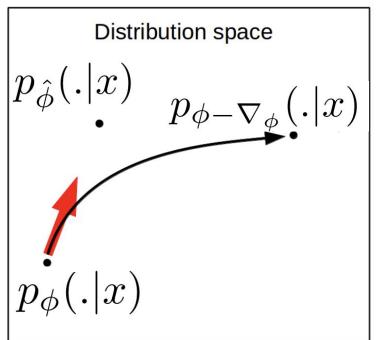






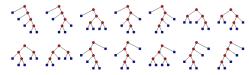
$$\frac{p_{\phi}(t|x)}{p_{\phi,11}(t|x)} \in [1 - \epsilon; 1 + \epsilon]$$





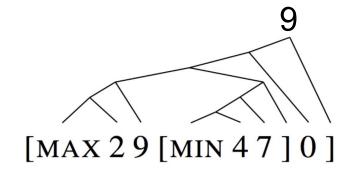
Proximal Policy Optimization (PPO) of Schulman et al. (2017)

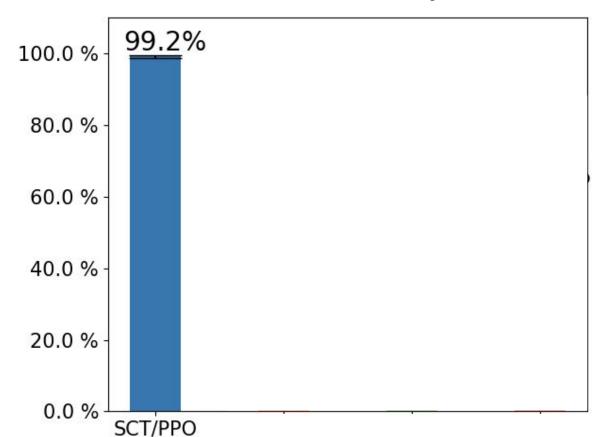
• High variance in the estimate of a parser's gradient  $\nabla_{\varphi}$  is addressed by using **self-critical training** (SCT) baseline of Rennie et al. (2017).

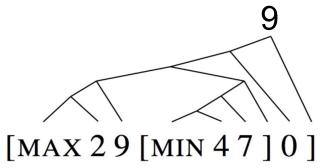


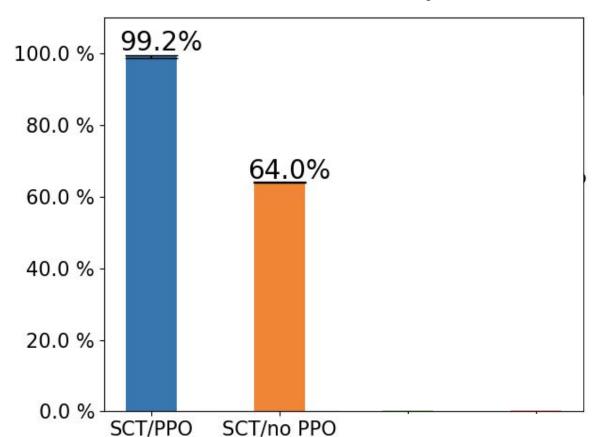
 Learning paces of a parser φ and a compositional function θ is levelled off by controlling parser's updates using Proximal Policy Optimization (PPO) of Schulman et al. (2017).

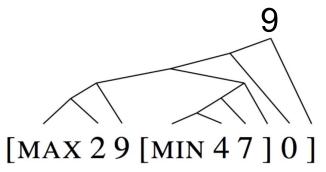


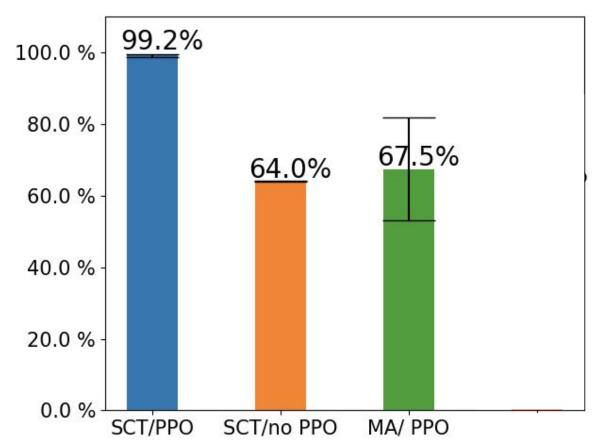


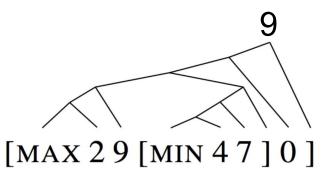


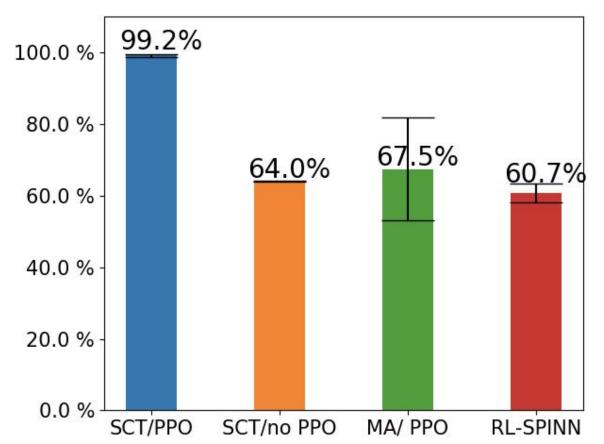


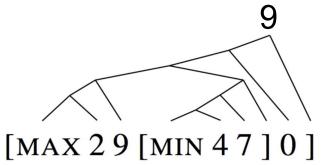




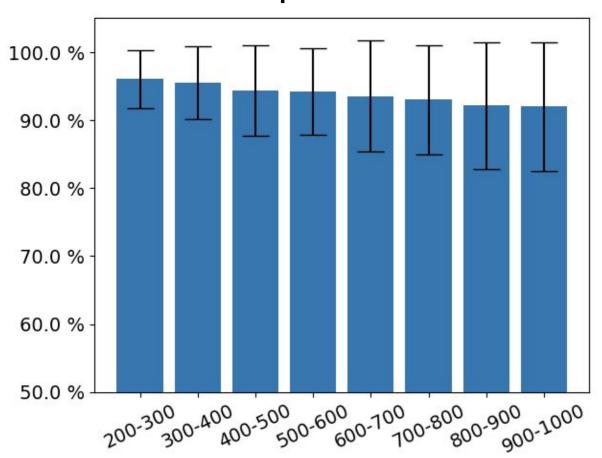


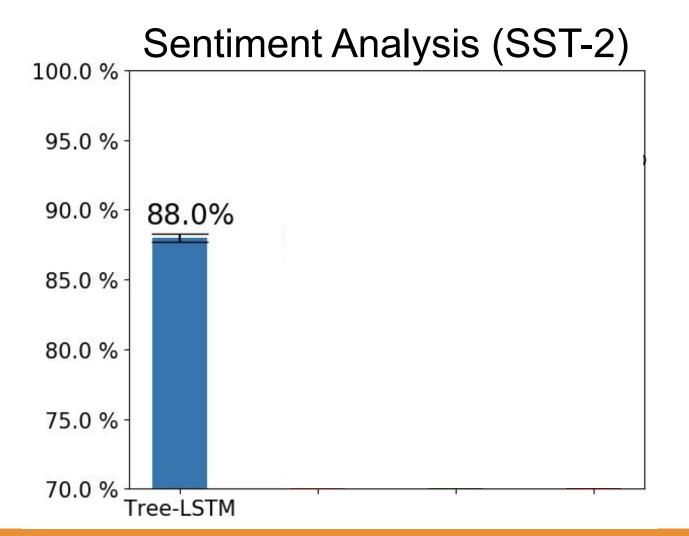


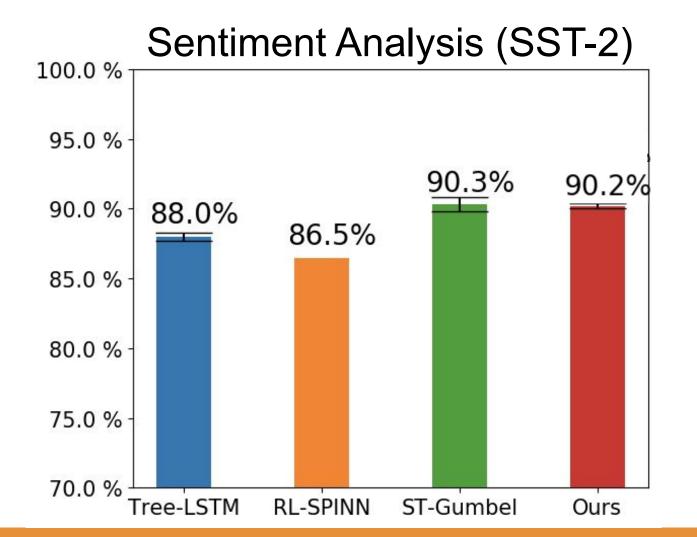




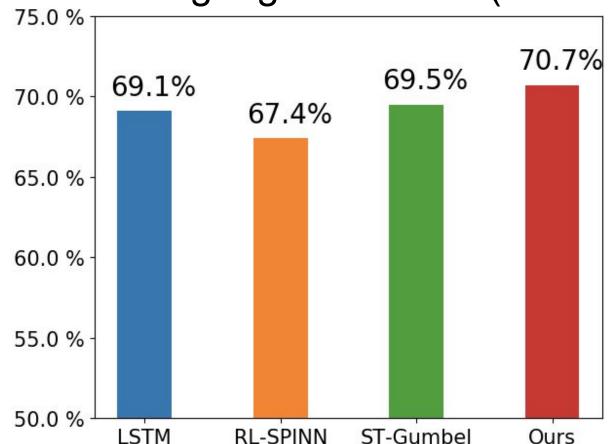
## Extrapolation







# Natural language inference (MultiNLI)



## Time and Space complexities

Method	Time complexity	Space complexity	ListOps
RL-SPINN: Yogatama et al., 2016	O(nd²)	O(nd²)	X
Soft-CYK: Maillard et al., 2017	O(n <sup>3</sup> d+n <sup>2</sup> d <sup>2</sup> )	O(n³d)	X
Gumbel Tree-LSTM: Choi et al., 2018	O(n <sup>2</sup> d+nd <sup>2</sup> )	O(n <sup>2</sup> d)	X
Ours	O(Knd²)	O(nd²)	<b>✓</b>

n – sentence length

d – tree-LSTM dimensionality

K – number of updates in PPO

### Conclusions

- The separation between syntax and semantics allows coordination between optimisation schemes for each module.
- Self-critical training mitigates credit assignment problem by distinguishing "hard" and "easy" to solve datapoints.
- The model **can recover** a simple context-free grammar of mathematical expressions.
- The model performs competitively on several real natural language tasks.



github.com/facebookresearch/latent-treelstm