

Práctica 3. Redes neuronales Ejercicio a realizar

Alfons Juan, Jorge Civera

Departament de Sistemes Informàtics i Computació

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1. Construcción de una red neuronal

► Variante del tutorial oficial: cuaderno jupyter mlp

https://github.com/apr-upv/apr2223/blob/master/mlp.ipynb

▶ Librerías:

```
import os
import torch
from torch import nn
from torch.utils.data import DataLoader
from torchvision import datasets, transforms
```

► Carga del conjunto de datos: *FashionMNIST*



1.1. Preparación de los datos para entrenamiento

DataLoader: procesa los datos definiendo batches de 64 muestras, barajando tras cada pasada completa por todos los datos

```
torch.manual_seed(23)
train_dataloader = DataLoader(training_data, batch_size=64,
    shuffle=True)
test_dataloader = DataLoader(test_data, batch_size=64,
    shuffle=True)
```

- ▷ El tamaño de batch batch_size es un parámetro que afecta al proceso de optimización
 - → batch_size ↑: gradientes más estables
 - *→ batch_size* ↓: gradientes más inestables



1.2. Definición de la clase

- ▷ Red: subclase de nn. Module
- nn. ModuleList: lista de f. lineal seguida de f. de activación

```
class NeuralNetwork(nn.Module):
 def __init__(self, input_size, layers: list, num_classes):
    super(NeuralNetwork, self). init ()
    self.flatten = nn.Flatten()
    self.layers = nn.ModuleList()
    self.input_size = input_size
    for output size, activation function in layers:
      self.layers.append(nn.Linear(input_size, output_size))
      input_size = output_size
      self.layers.append(activation_function)
    self.layers.append(nn.Linear(input_size, num_classes))
 def forward(self, x):
   x = self.flatten(x)
    for layer in self.layers:
      x = layer(x)
    return x
```



▷ Instanciación:

```
torch.manual_seed(23)
C = 10
N,H,W = training_data.data.shape; D = H*W
M1, M2 = 512, 512
model = NeuralNetwork(D, [(M1, nn.ReLU()), (M2, nn.ReLU())], C)
```

▶ Parámetros de entrada de la clase NeuralNetwork:

- → D: dimensionalidad de los datos de entrada
- → [(M1, nn.Relu()), (M2, nn.Relu())]: Lista de capas
- → Una capa es una tupla (nº neuronas f. lineal, f. de activación)
- → C: número de clases



1.3. Bucles de entrenamiento y test

```
def train_loop(dataloader, model, loss_fn, optimizer):
 size = len(dataloader.dataset)
  for batch, (X, y) in enumerate(dataloader):
   pred = model(X); loss = loss_fn(pred, y)
   optimizer.zero_grad(); loss.backward(); optimizer.step() # backprop
   if batch % 100 == 0:
     loss, current = loss.item(), batch * len(X)
     print(f"trloss: {loss:>7f} [{current:>5d}/{size:>5d}]")
def test loop(dataloader, model, loss fn):
 size = len(dataloader.dataset); nbatches = len(dataloader)
 teloss, correct = 0, 0
 with torch.no_grad():
   for X, y in dataloader:
     pred = model(X); teloss += loss_fn(pred, y).item()
     correct += (pred.argmax(1) == y).type(torch.float).sum().item()
 teloss /= nbatches; correct /= size
 print(f"teacc: {(100*correct):>0.1f}%, teloss: {teloss:>8f} \n")
```

1.4. Programa principal

▷ El optimizador *Adam* obtiene mejores resultados que *SGD*

Epoch 1	Epoch 5	Epoch 9
trioss: 0.47983 [25600/60000] trioss: 0.42242 [32000/60000] trioss: 0.25505 [38400/60000] trioss: 0.33612 [44800/60000] trioss: 0.47841 [51200/60000] trioss: 0.32768 [57600/60000] teacc: 84.5%, teloss: 0.41862	trioss: 0.17982 [19200/60000] trioss: 0.20465 [25600/60000] trioss: 0.19099 [32000/60000] trioss: 0.23198 [38400/60000] trioss: 0.26447 [44800/60000] trioss: 0.18140 [51200/60000] trioss: 0.28073 [57600/60000] teacc: 87.8%, teloss: 0.34975	Epoch 9 trloss: 0.24297 [0/60000] trloss: 0.20781 [6400/60000] trloss: 0.22742 [12800/60000] trloss: 0.43565 [19200/60000] trloss: 0.41562 [25600/60000] trloss: 0.28409 [32000/60000] trloss: 0.14712 [38400/60000] trloss: 0.30157 [44800/60000] trloss: 0.20163 [51200/60000] trloss: 0.24971 [57600/60000] teacc: 88.8%, teloss: 0.31972
Epoch 2	Epoch 6	Epoch 10
trloss: 0.11267 [32000/60000] trloss: 0.27980 [38400/60000] trloss: 0.29777 [44800/60000] trloss: 0.31008 [51200/60000]	Epoch 6 trloss: 0.21330 [0/60000] trloss: 0.25425 [6400/60000] trloss: 0.23986 [12800/60000] trloss: 0.18474 [19200/60000] trloss: 0.29163 [25600/60000] trloss: 0.21085 [32000/60000] trloss: 0.24115 [38400/60000] trloss: 0.28910 [44800/60000] trloss: 0.19631 [51200/60000] trloss: 0.26648 [57600/60000] teacc: 88.1%, teloss: 0.33128	trloss: 0.15803 [0/60000] trloss: 0.14329 [6400/60000] trloss: 0.15694 [12800/60000] trloss: 0.22337 [19200/60000] trloss: 0.26118 [25600/60000] trloss: 0.29932 [32000/60000] trloss: 0.36831 [38400/60000] trloss: 0.22759 [44800/60000] trloss: 0.22564 [51200/60000] trloss: 0.29680 [57600/60000] teacc: 88.7%, teloss: 0.33955
Epoch 3	Epoch 7	Done!
trloss: 0.39776 [0/60000] trloss: 0.26003 [6400/60000] trloss: 0.39063 [12800/60000] trloss: 0.45137 [19200/60000] trloss: 0.37927 [25600/60000] trloss: 0.42785 [32000/60000] trloss: 0.35296 [38400/60000] trloss: 0.25597 [44800/60000] trloss: 0.37669 [51200/60000] trloss: 0.47831 [57600/60000] teacc: 87.7%, teloss: 0.33948	trloss: 0.23661 [0/60000] trloss: 0.40972 [6400/60000] trloss: 0.23502 [12800/60000] trloss: 0.23649 [19200/60000] trloss: 0.42267 [25600/60000] trloss: 0.13239 [32000/60000] trloss: 0.29857 [38400/60000] trloss: 0.15905 [44800/60000] trloss: 0.20443 [51200/60000] trloss: 0.31361 [57600/60000] teacc: 88.6%, teloss: 0.33019	
Epoch 4	Epoch 8	
trloss: 0.30808 [0/60000] trloss: 0.18359 [6400/60000] trloss: 0.26920 [12800/60000] trloss: 0.13372 [19200/60000] trloss: 0.40757 [25600/60000] trloss: 0.27605 [32000/60000] trloss: 0.25818 [38400/60000] trloss: 0.15146 [44800/60000] trloss: 0.25695 [51200/60000] trloss: 0.21173 [57600/60000] teacc: 86.3%, teloss: 0.36847	trloss: 0.41880 [0/60000] trloss: 0.21917 [6400/60000]	

2. Ejercicio

- Objetivo: entrena un clasificador basado en redes neuronales que minimice el error de clasificación de FashionMNIST en test
- Principales parámetros ajustables: número de neuronas, número de épocas y factor de aprendizaje
 - → Otros parámetros: nº de capas y tamaño de batch
- Entrega una memoria que describa los experimentos realizados para ajustar los parámetros del clasificador y el mejor resultado obtenido.

