

Protocolos y Librerías espectrales en Espectroscopía de campo: de las buenas prácticas a una mayor utilidad de los datos

Synergies between field spectroscopy, sensors onboard drones, and Landsat-8/Sentinel-2 satellite imagery

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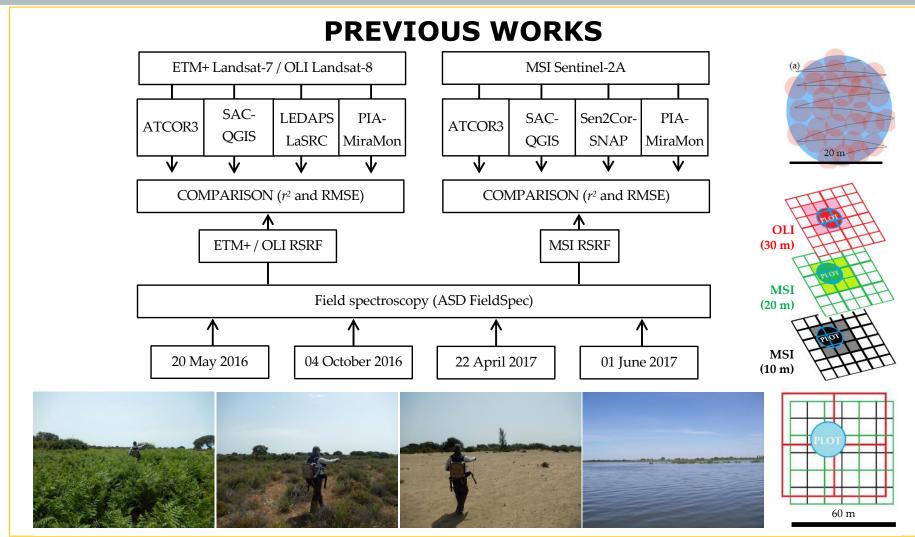








Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery























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PREVIOUS WORKS

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¿Is drone data feasible, fits field spectroscopy data?

¿does drone data fit satellite data?

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Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

1: Introduction and objectives | Hypothesis & objectives

HYPOTHESIS

Radiometric correction of satellite imagery can be improved introducing ground-truth measurements obtained from the synergy between conventional field spectroradiometry and sensors embedded in Unmanned Aerial Systems (UAS)

General Objective 1: Improvement of the radiometric treatment of imagery from OLI sensor onboard the L8 satellite and MSI sensor onboard the S2 satellites

General Objective 2:: Improvement of the treatment of UAS imagery, linking it with L8 and S2 imagery, and improvement of land cover mapping using UAS data









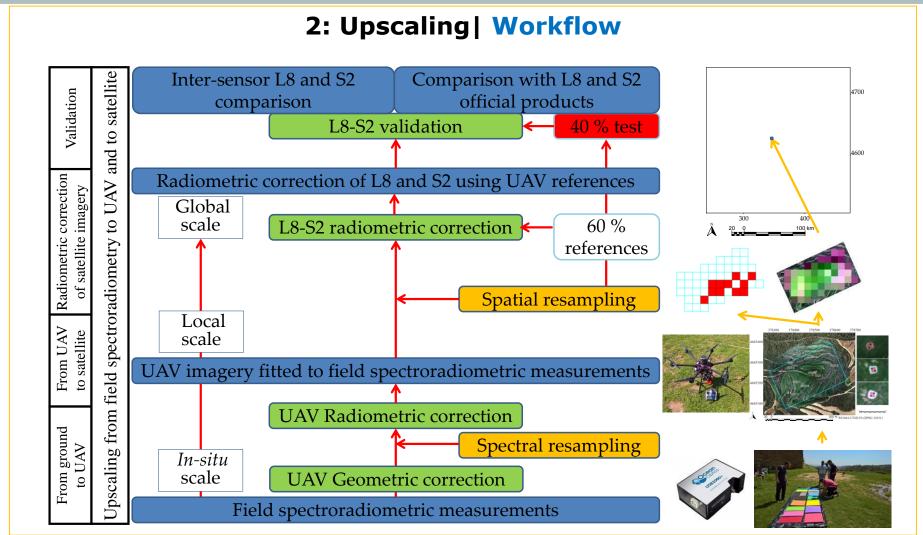








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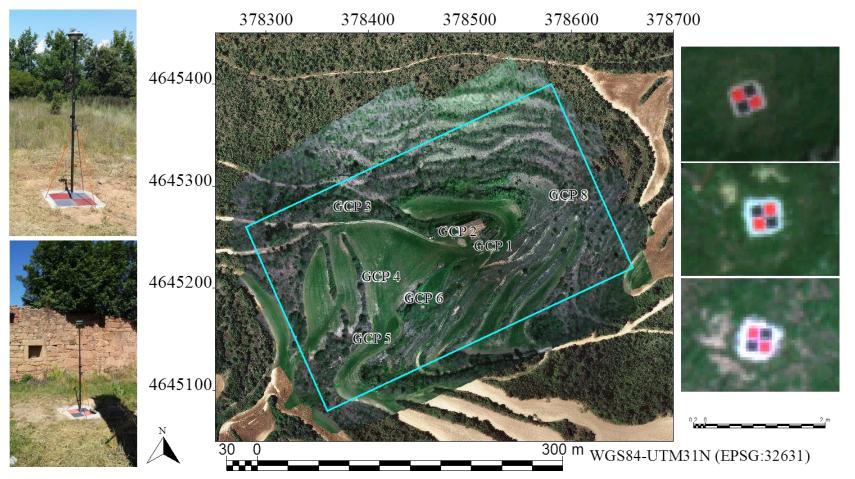






Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Linking field data, UAS and satellite imagery





















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Linking field data, UAS and satellite imagery

Complete publication reference:

Padró JC, Muñoz FJ, Planas J, Pons X (2019). Comparison of four UAV georeferencing methods for environmental monitoring purposes focusing on the combined use with airborne and satellite remote sensing platforms.

International Journal of Applied Earth Observation and Geoinformation, 79, 130-140. DOI: 10.1016/j.jag.2018.10.018.

https://www.sciencedirect.com/science/article/pii/S0303243418306421

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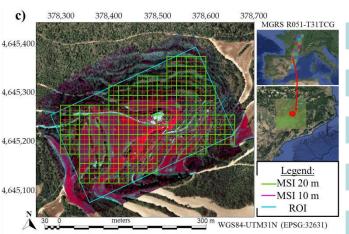




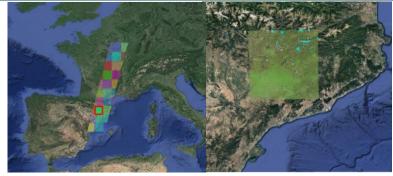
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2: Upscaling | Linking field data, UAS and satellite imagery





L8 (OLI): WRS-2 Scene 198-031 **S2 (MSI):** MGRS Scene R051-T31TCG









UAS Platform DJI S1000. Sensor MicaSense RedEdge Spatial resolution 6 cm @ 80 m. ρ_{λ} calibration panel





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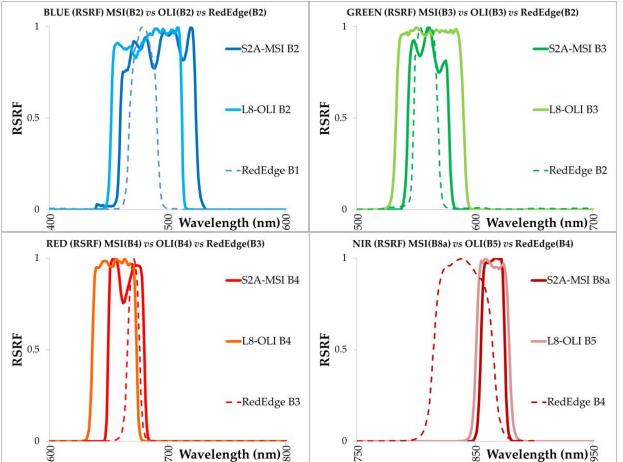






Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | UAS sensor (MicaSense RedEdge) and satellite sensors (OLI and MSI) matching bands

















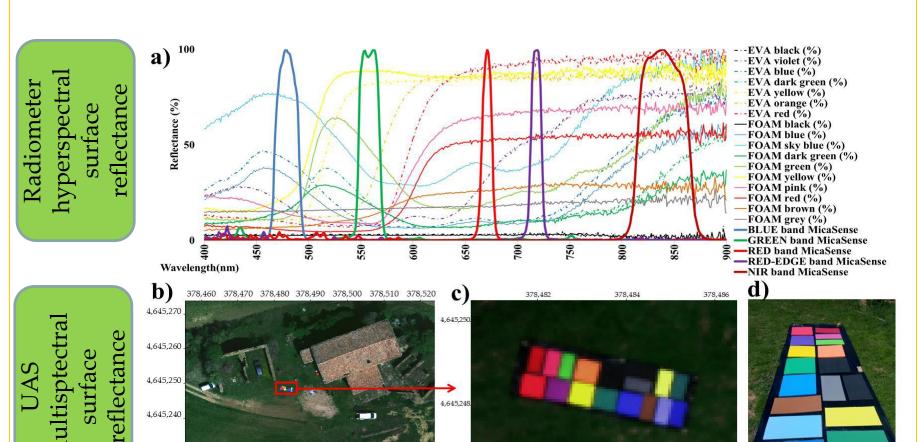






Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Linking field data and UAS imagery







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meters









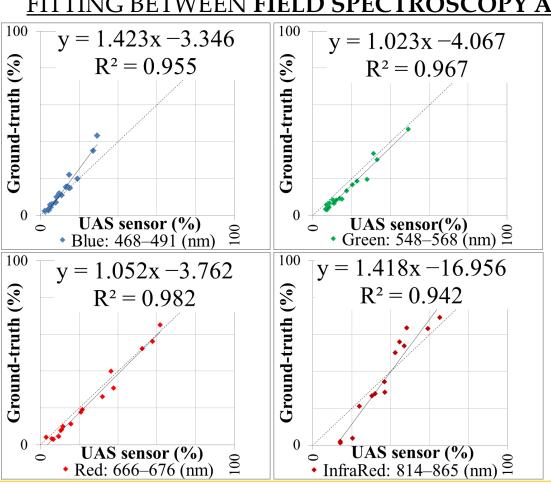


Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Linking field data and UAS imagery

FITTING BETWEEN FIELD SPECTROSCOPY AND DRONE DATA

Main results



UAS imagery corresponding to OLI sensor bands, sensed by L8 **overpass** correlated with field spectroscopy measurements over EVA panels





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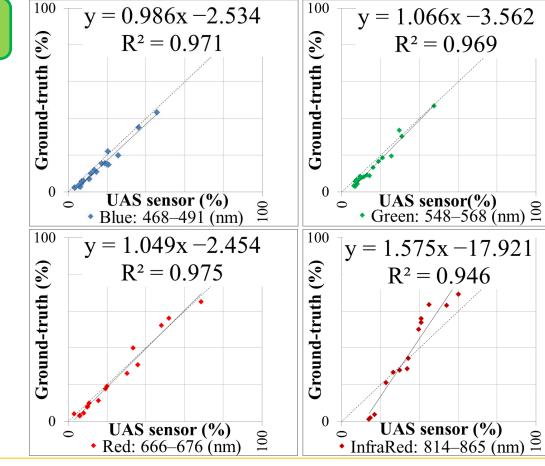


Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Linking field data and UAS imagery

FITTING BETWEEN FIELD SPECTROSCOPY AND DRONE DATA

Main results



UAS imagery corresponding to MSI sensor bands, sensed by S2 overpass correlated with field spectroscopy measurements over EVA panels





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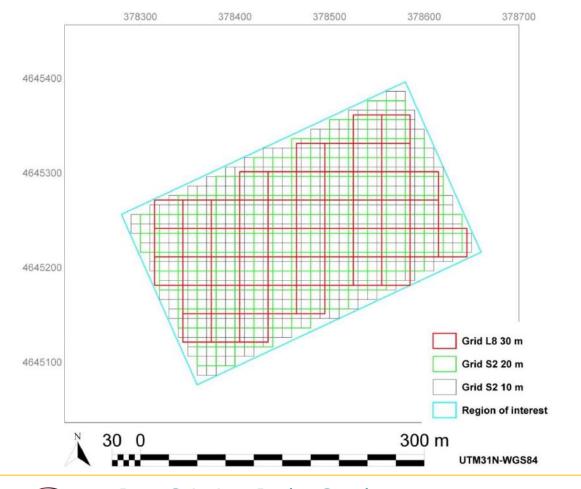






Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Linking UAS and satellite imagery

















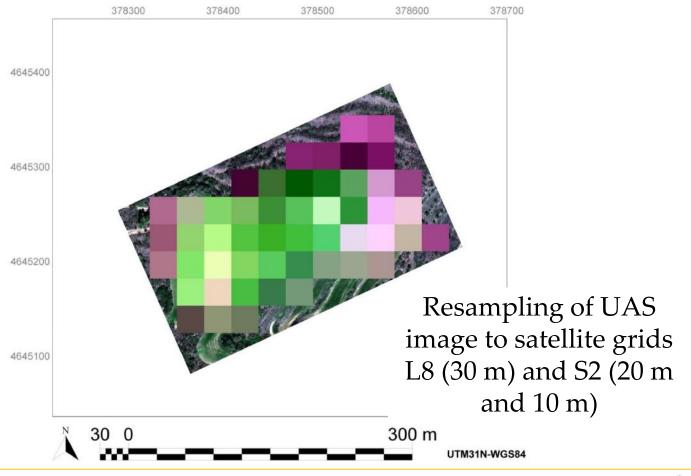






Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Linking UAS and satellite imagery























Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Linking UAS and satellite imagery

Main results

FITTING BETWEEN **DRONE DATA AND SATELLITE DATA**

RMSE (%) between all the UAS surface reflectance resampled pixels and:

a) L8 and S2 imagery without radiometric correction (TOA reflectance) b) Official products (LaSRC (L8) y Sen2Cor (S2)) surface reflectance

Band	BLUE		GREEN		RED		NIR	
RMSE UAS vs. Satellite	OLI #2 (n=51)	MSI #2 (n=517)	OLI #3 (n=51)	MSI #3 (n=517)	OLI #4 (n=51)	MSI #4 (n=517)	OLI #5 (n=51)	MSI #8a (n=143)
TOA	7.743	6.981	3.684	3.674	3.533	3.101	6.847	8.050
LaSRC or Sen2Cor	2.054	2.192	1.623	2.058	2.484	2.361	6.688	8.783





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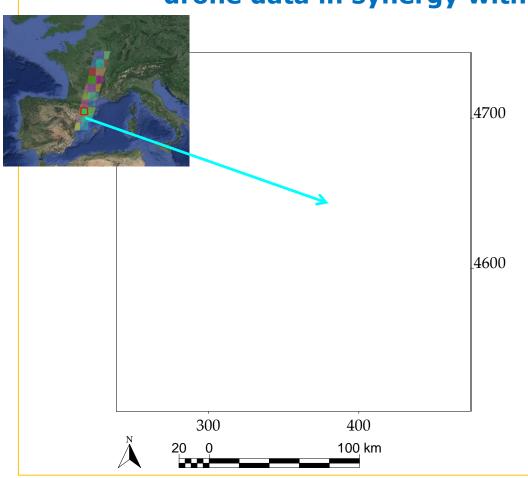






Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Radiometric correction of satellite imagery using drone data in synergy with field spectroscopy



Radiometric correction of 198031 (L8) and T31TCG (S2A) imagery fitting the CorRad-MiraMon algorithm model unknowns to the UAV references (60 %) (UAS-MiraMon): $\pi \cdot [L_1 - L_2]$

$$\boldsymbol{\rho}_{\lambda} = \frac{\boldsymbol{\pi} \cdot [\boldsymbol{L}_{\lambda} - \boldsymbol{L}\boldsymbol{a}_{\lambda}]}{\cos(\boldsymbol{\theta}) \cdot \boldsymbol{E}_{0\lambda} \cdot \boldsymbol{\tau}_{\lambda} \cdot \boldsymbol{\tau}_{\lambda}} \cdot d^{2}$$

Validation of the radiometric UAS-MiraMon correction and the official products (LaSRC y Sen2Cor) by means of the band-by-band RMSE in the test pixels (40 %)





















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Radiometric correction of satellite imagery using drone data in synergy with field spectroscopy

Main results

FITTING BETWEEN UAS-MIRAMON AND TEST AREAS

RMSE (%) between test areas and:

a) CorRad-MiraMon with UAS references (UAS-MiraMon) surface reflectanceb) Official products (LaSRC (L8) y Sen2Cor (S2)) surface reflectance

	BLUE		GREEN		RED		NIR	
RMSE Test areas vs. Satellite	OLI #2 (n=20)	MSI #2 (n=207)	OLI #3 (n=20)	MSI #3 (n=207)	OLI #4 (n=20)	MSI #4 (n=207)	OLI #5 (n=20)	MSI #8a (n=57)
UAS- MiraMon	0.712	0.745	1.000	1.230	1.871	2.018	7.530	6.760
LaSRC or Sen2Cor	2.197	2.149	1.653	1.806	2.680	2.192	5.841	7.690



















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

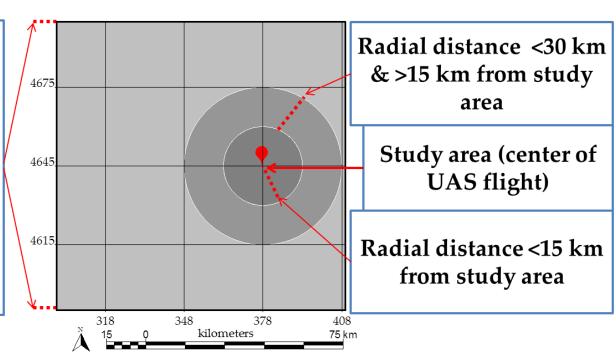
2: Upscaling | Radiometric correction of satellite imagery using drone data in synergy with field spectroscopy

Fitting between almost-simultaneous L8 and S2 imagery radiometrically corrected with UAS-MiraMon

(INTER-SENSOR COMPARISON)

Common extent L8 tile 198031 and S2 tile R051 TCG.

All S2 bands resampled to 30 m and L8 grid







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Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

2: Upscaling | Radiometric correction of satellite imagery using drone data in synergy with field spectroscopy

Fitting between almost-simultaneous L8 and S2 imagery radiometrically corrected with UAS-MiraMon
(INTER-SENSOR COMPARISON)

Main results

RMSE (%) between L8 and S2 imagery sensed within few minutes and radiometrically corrected with the UAS-MiraMon method

Radial distance from UAV flight area (Number of 30 m L8 and S2 compared pixels)	BLUE	GREEN	RED	NIR
0-15 km (n=681 950)	0.621	0.741	0.919	1.664
15-30 km (n=2 203 730)	0.739	0.815	0.984	1.666
TCG scene (n=12 148 700)	0.852	0.940	1.147	1.707





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Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

3: Discussion

Conventional field spectroscopy sampling

A) UAS imagery has greatly **improved** the **number and speed** of ground **references sampling** (51 OLI plots in ±5 minutes, repeating the flight 20 minutes later for MSI), and **including inaccessible land covers**.

UAS fitting to field spectroscopy data

B) UAS reflectance calibration using sensor manufacturer reference panel obtained high R2 (>0.942) with field measurements, but bias and gain remained (in-situ reflectance values were systematically lower than UAS sensor reflectance values).

















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3: Discussion

From UAV to satellite

- C) UAV MicaSense RedEdge calibrated data is, in general terms, coherent with L8 and S2 satellite imagery radiometrically corrected (up to 3% in reflectance in visible bands), in consonance with previous studies.
 - D) However, **NIR band mismatching** between MicaSense RedEdge and satellite sensors configuration **is too significant to be ignored and reflectance differences are not acceptable in this band**, which was not properly advised in previous studies.

















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

3: Discussion

Radiometric correction of L8-S2 using UAV data

E) CorRad-MiraMon radiometric correction algorithm using UAS references improves the local accuracy over official products, with accuracies up to 2% in reflectance in visible bands.

F) **UAS-MiraMon got a RMSEvis<1% inter-sensor coherence** not only in the study area but in all the common L8 and S2 scene.

















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

3: Discussion

Radiometric correction of L8-S2 using UAV data WEAK POINTS

- 1) This method should be only used by the simultaneous drone flight and satellite overpass.
 - 2) Currently not all satellite bands are available in low-weight UAV sensors, specially SWIR bands.
- 3) It is needed ground support to accurately radiometrically correct UAV imagery.

















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

4. Conclusions

This communication shows the increasing possibilities offered by Unmanned Aerial Systems (UAS) or drones, to collect *in-situ* data in order to improve calibration, validation, processing and/or interpretation of satellite data.

















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

4. Conclusions

This drone data, fitted to *in-situ* measurements of multiple reflectance references distributed in the spectral domain and covering a wide range of intensities, is reliable for its use as *in-situ* radiometric reference (or at least to complement conventional measurements).

















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

4. Conclusions

The sampling method using a drone is more systematic, fast, repeatable and extensive than that obtained with conventional field spectroscopy measurements. The data acquired with drone is carefully georeferenced and, given their raster nature (<10 cm), easily adapted to different satellite sensors grids such as Landsat-8 OLI (30 m) or Sentinel-2 MSI (20 m or 10 m).

















Synergies between field spectroscopy, sensors onboard Unmanned Aerial Systems (UAS), and Landsat-8/Sentinel-2 satellite imagery

4. Conclusions

The result of the radiometric correction of satellite imagery is improved locally. The proposed method provides a good fit for *in-situ* and intersensor data.

It is worth noting that field spectroscopy data is the backbone that supports the full upscaling workflow, and the radiometric feasibility of drone data.

















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Complete publication reference:

Padró JC, Muñoz FJ, Avila LA, Pesquer L, Pons X (2018). Radiometric Correction of Landsat-8 and Sentinel-2A Scenes Using Drone Imagery in Synergy with Field Spectroradiometry. Remote Sensing, 10 (11), 1687-1713. DOI: 10.3390/rs10111687.

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