

Задача багатьох тіл на прикладі сонячної системи

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Знайшов в мережі доволі цікаву програму написану на **Python** яка моделює Сонячну систему. В програмі врахована взаємодія не лише планет із Сонцем, а також взаємодія планет між собою. В систему можна додавати планети, та інші небесні тіла.

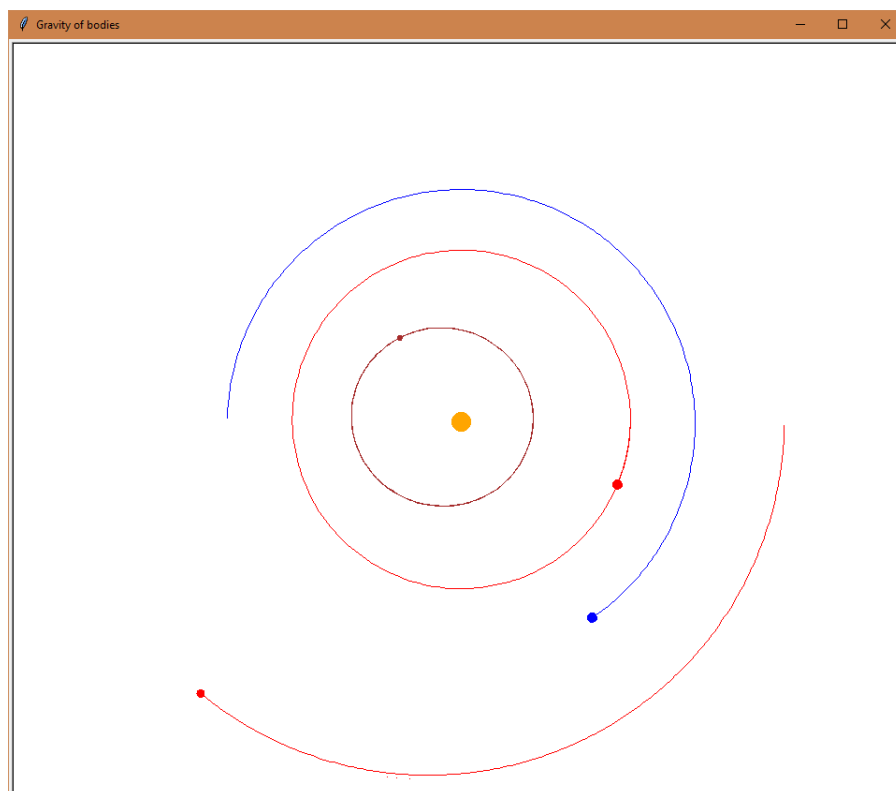


Рис. 1: Сонячна система з Сонцем, Меркурієм, Венерою, Землею та Марсом

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1  #!/usr/bin/env python3
2  #https://fiftyexamples.readthedocs.io/en/latest/gravity.html
3  import math
4  from turtle import *
5
6  # The gravitational constant G
7  G = 6.67428e-11
8  c = 299792458
9
10 # Assumed scale: 100 pixels = 1AU.
11 AU = (149.6e6 * 1000)      # 149.6 million km, in meters.
12 SCALE = 250 / AU
13 wn = Screen()
14 wn.title("Gravity of bodies")      # Set the window title
15
16
17 class Body(Turtle):
18     """Subclass of Turtle representing a gravitationally-acting body.
19
20     Extra attributes:
21     mass : mass in kg
22     vx, vy: x, y velocities in m/s
23     px, py: x, y positions in m
24     """
25
26     name = 'Body'
27     mass = None
28     vx = vy = 0.0
29     px = py = 0.0
30
31     def attraction(self, other):
32         """(Body): (fx, fy)
33
34         Returns the force exerted upon this body by the other body.
35         """
36
37         # Report an error if the other object is the same as this one.
38         if self is other:
39             raise ValueError("Attraction of object %r to itself requested"
40                               % self.name)
41
42         # Compute the distance of the other body.
43         sx, sy = self.px, self.py
44         ox, oy = other.px, other.py
45         dx = (ox-sx)
46         dy = (oy-sy)
47         d = math.sqrt(dx**2 + dy**2)
48
49         # Report an error if the distance is zero; otherwise we'll
50         # get a ZeroDivisionError exception further down.

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50     if d == 0:
51         raise ValueError("Collision between objects %r and %r"
52                             % (self.name, other.name))
53
54     # Compute the force of attraction
55     f = G * self.mass * other.mass / (d**2) / (math.sqrt(1 -
56         ↪ 2*G*other.mass/(d*c**2)))
57
58     # Compute the direction of the force.
59     theta = math.atan2(dy, dx)
60     fx = math.cos(theta) * f
61     fy = math.sin(theta) * f
62     return fx, fy
63
64 def update_info(step, bodies):
65     """(int, [Body])
66
67     Displays information about the status of the simulation.
68     """
69     print('Step #{}'.format(step))
70     for body in bodies:
71         s = '{:<8} Pos.={:>6.2f} {:>6.2f} Vel.={:>10.3f} {:>10.3f}'.format(
72             body.name, body.px/AU, body.py/AU, body.vx, body.vy)
73     print(s)
74     print()
75
76 def loop(bodies):
77     """([Body])
78
79     Never returns; loops through the simulation, updating the
80     positions of all the provided bodies.
81     """
82     timestep = 24*3600 # One day
83
84     for body in bodies:
85         body.penup()
86
87     step = 1
88     while True:
89         update_info(step, bodies)
90         step += 1
91
92         force = {}
93         for body in bodies:
94             # Add up all of the forces exerted on 'body'.
95             total_fx = total_fy = 0.0
96             for other in bodies:
97                 # Don't calculate the body's attraction to itself
98                 if body is other:

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99         continue
100         fx, fy = body.attraction(other)
101         total_fx += fx
102         total_fy += fy
103
104         # Record the total force exerted.
105         force[body] = (total_fx, total_fy)
106
107         # Update velocities based upon on the force.
108         for body in bodies:
109             fx, fy = force[body]
110             body.vx += fx / body.mass * timestep
111             body.vy += fy / body.mass * timestep
112
113             # Update positions
114             body.px += body.vx * timestep
115             body.py += body.vy * timestep
116             body.goto(body.px*SCALE, body.py*SCALE)
117             #body.dot(3)
118             body.pendown()
119
120
121 def main():
122     sun = Body()
123     sun.name = 'Sun'
124     sun.mass = 1.98892 * 10**30
125     sun.pencolor('red')
126     sun.color('orange')
127     sun.shape('circle')
128
129     earth = Body()
130     earth.name = 'Earth'
131     earth.mass = 5.9742 * 10**24
132     earth.px = -1*AU
133     earth.vy = 29.783 * 1000 # 29.783 km/sec
134     earth.pencolor('blue')
135     #earth.hideturtle()
136     earth.color('blue')
137     earth.shapesize(0.5,0.5,0.5)
138     earth.shape('circle')
139
140     # Venus parameters taken from
141     # http://nssdc.gsfc.nasa.gov/planetary/factsheet/venusfact.html
142     venus = Body()
143     venus.name = 'Venus'
144     venus.mass = 4.8685 * 10**24
145     venus.px = 0.723 * AU
146     venus.vy = -35.02 * 1000
147     venus.pencolor('red')
148     #venus.hideturtle()

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149 venus.color('red')
150 venus.shapesize(0.5,0.5,0.5)
151 venus.shape('circle')
152
153 mercury = Body()
154 mercury.name = 'Mercury'
155 mercury.mass = 3.30104 * 10**23
156 mercury.px = 0.307499 * AU
157 mercury.vy = -58.98 * 1000
158 mercury.pencolor('blue')
159 #mercury.hideturtle()
160 mercury.color('brown')
161 mercury.shapesize(0.25,0.25,0.25)
162 mercury.shape('circle')
163
164 mars = Body()
165 mars.name = 'Mars'
166 mars.mass = 6.4171 * 10**23
167 mars.px = 1.3814 * AU
168 mars.vy = -26.50 * 1000
169 mars.pencolor('blue')
170 #mars.hideturtle()
171 mars.color('red')
172 mars.shapesize(0.4,0.4,0.4)
173 mars.shape('circle')
174
175 comet = Body()
176 comet.name = 'comet'
177 comet.mass = 2.2 * 10**15
178 comet.px = 0.2 * AU
179 comet.vy = -90.56 * 1000
180 comet.pencolor('brown')
181 #comet.hideturtle()
182 comet.color('brown')
183 comet.shapesize(0.1,0.1,0.1)
184 comet.shape('circle')
185
186 loop([sun, earth, venus, mercury, mars, comet])
187 wn.mainloop()
188 if __name__ == '__main__':
189     main()

```