

# Bayesian Hierarchical Models and INLA

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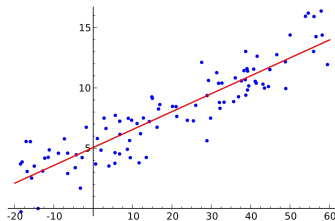
# Agenda

- 1 Linear Models and Inference
- 2 INLA
- 3 Case Study: Road Safety in the City of Toronto
- 4 Conclusion

# Linear Models and Inference

## Linear Regression

- Starting point for most modeling problems
- Two flavors: ML and **model-based**
- The latter offers solid inference framework based on probability and statistical theory
- Former is algorithmic (more flexible in certain cases) and perhaps more popular in industry



# Linear Models and Inference

## Maximum Likelihood Estimation

$$\begin{aligned}y &= X'\beta + \epsilon \\ \epsilon &\sim N(0, \Sigma)\end{aligned}\tag{1}$$

- We wish to solve for the set of parameters that maximize the likelihood of the data
  - i.e., the parameters that best explain the underlying phenomenon

$$\begin{aligned}l(D; \theta) &= \log \left( \prod_{i=1}^n P(y^i | x^i, \theta) \right) \\ \hat{\theta} &= \operatorname{argmax}_{\theta \in \mathcal{R}^p} l(D; \theta)\end{aligned}\tag{2}$$

- Then we build CIs for our parameters, our predictions, etc.

# Linear Models and Inference

## Bayesian Estimation

- MLE above gives us distributions and CIs for the parameters  $\beta$ s
- Why not imbue them with a prior probability distribution right out of the bat? (Wakefield, 2013)
  - $\beta \sim P$ ?
- This is done for regularization, numerical stability, more rigorous inference, better science, expensive data acquisition

$$\begin{aligned} P(\theta|D) &= \frac{P(D|\theta)P(\theta)}{\int P(D|\theta)P(\theta)d\theta} \\ &\propto P(D|\theta)P(\theta) \end{aligned} \tag{3}$$

- MCMC! (Rosenthal, 2009)

# Linear Models and Inference

## Priors!

- What are good priors?
  - Tractability? Conjugates!
  - Scientific relevance
  - Regularization
- Ideally, priors should come without ever looking at data
  - Uninformative (flat) priors
  - Weakly informative priors
  - Informative priors (Usually based on expert opinion or solid scientific knowledge)
- **PC Framework!** (Simpson et al, 2017)
  - KL discrepancy to measure the increased complexity introduced by  $\psi > 0$
  - $P(\mu > u) = \alpha$  for base  $N(0, 1)$  and upgrade  $N(\mu, 1)$ ,  $\mu > 0$

# INLA

## Origin and Set-up

- **Integrated Nested Laplacian Approximation** (Rue et al, 2009) (Faraway et al, 2018)
  - I: Numerical Integration
  - N: Modeling and harnessing latent variables
  - L: Approximating Normal R.V.'s (Normal's easy)
  - A: Duh
- More stable than MCMC
- Only give marginal posteriors
- Great for full and mixed/practical Bayesian!

## INLA

## How-to

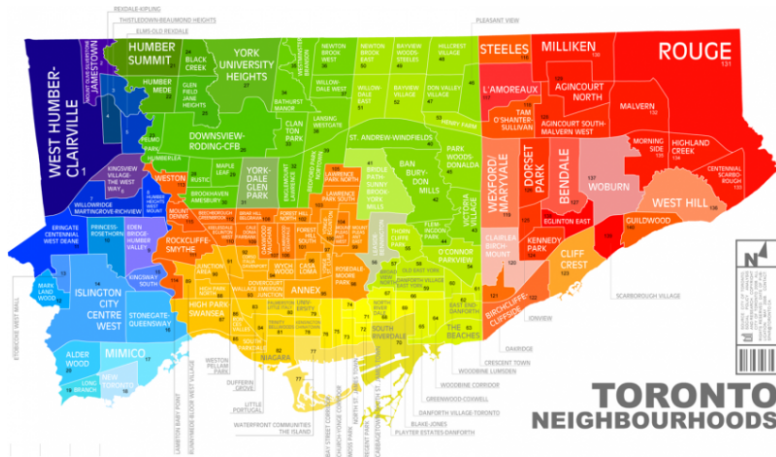
```
1  install.packages("INLA", repos=c(getOption("repos"),\
2  INLA="https://inla.r-inla-download.org/R/stable"),\
3  dep=TRUE);library(inla)
4
5  # Let's simulate some data
6  N = 100 #500, 5000, 25000, 100000
7  x = rnorm(N, mean=6,sd=2);y = rnorm(N, mean=x,sd=1)
8  data = list(x=x,y=y,N=N)
9
10 # Inla Regression - Beware of INLA default priors
11 inla(y~x, family = c("gaussian"), \
12 data = data, control.predictor=list(link=1))
```



# Introduction

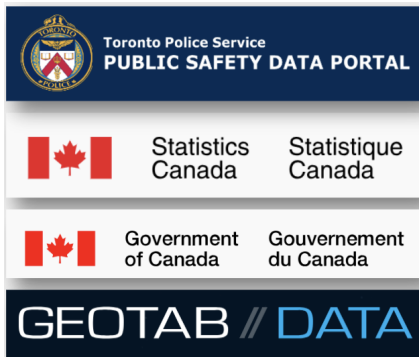
- Road safety is close to all of us
  - At any point in a given day we commute as bikers, pedestrians, drivers, etc.
- In the last five years, in the City of Toronto, 190 pedestrians and 16 cyclists were killed in collisions with vehicles
- We examined road safety in the City of Toronto from 2007 to 2017, exploring the areas with highest risk of a traffic incident, controlling for different fixed factors, neighborhoods, and time

# Introduction



# Toronto Safety

## Dataset



Automobile accident-level data each row representing a person involved from 2007 - 2017

2016 and 2011 Census population by neighborhood

Daily weather measurements for Toronto taken in University of Toronto

Rolling annual average of harsh braking incidents and number of accidents

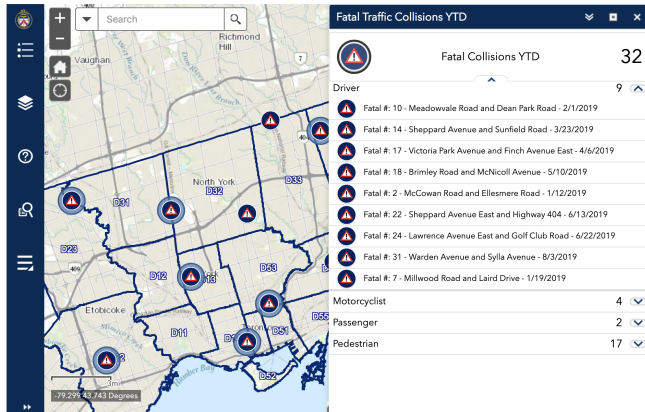
# Toronto Safety

## IDE: Existing Visualization

<https://www.cp24.com/news/fatal-traffic-collisions>

mail school tech

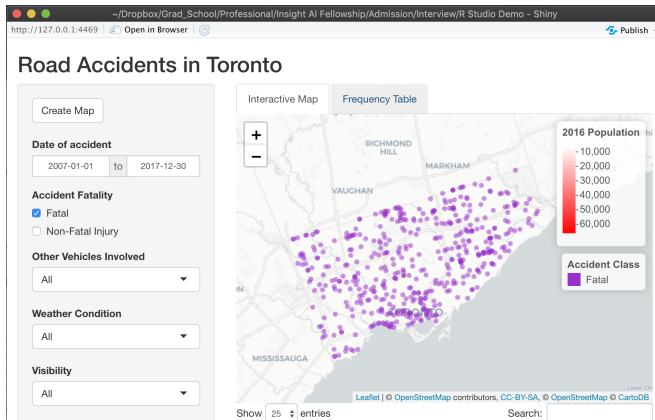
### FATAL TRAFFIC COLLISIONS



# Toronto Safety

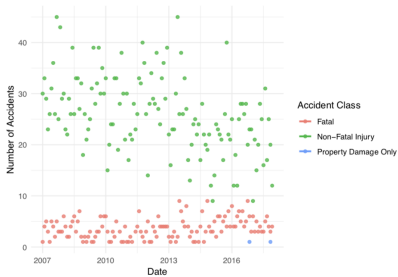
## IDE: Our App

- Created a webapp with Shiny for visualizing accidents by different filters (time, parties involved, weather, etc)

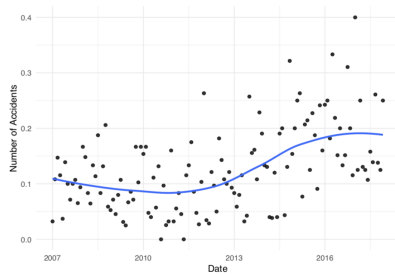


# Toronto Safety

## IDE



(a) Accidents by Class



(b) Total Number of Accidents

# Modeling

## Some math

$$Y_{ijt} \sim \text{bernoulli}(\pi_{ijt})$$

$$\text{logit}(\pi_{ijt}) = X_{ijt}\beta + U_j + V_t + f(W_t)$$

$$U_j \sim N(0, \sigma_U^2) \quad (\text{Residual Neighborhood Component})$$

$$V_t \sim N(0, \sigma_V^2) \quad (\text{Residual Time Component})$$

$$W_{t+1} - W_t \sim N(0, \sigma_W^2) \quad (\text{RW1 - Time Trend Component})$$

# Results

## Fixed Effects

**Objective:** Estimate the odds of fatality, subject to being in a vehicular accident, accounting for differences across neighborhoods and time

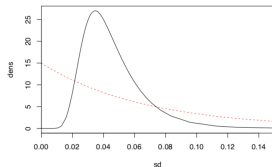
**Results:**

- Odds of fatality increasing till mid-2016, then slowly falling (Vision Zero?)
- Expressway: +73% odds of fatality
- Traffic Sign (stop, pedestrian crossing): -13% odds of fatality
- Traffic Light: -46% odds of fatality
- Pedestrian not involved: -38% odds of fatality
- +1 mm of precipitation: -2% odds of fatality

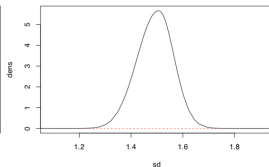


# Results

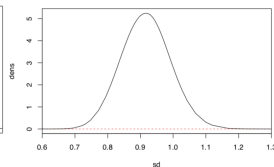
## Priors-Posteriors on Hierarchical Parameters



(a) SD of time trend



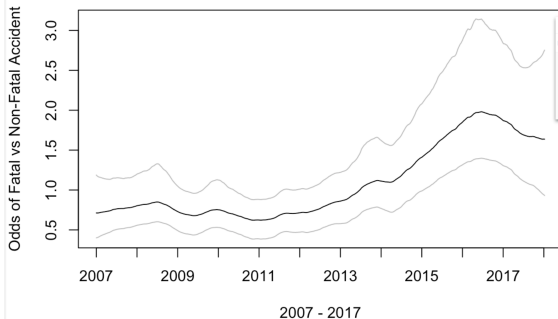
(b) SD of residual time variation



(c) SD of neighborhood random effect

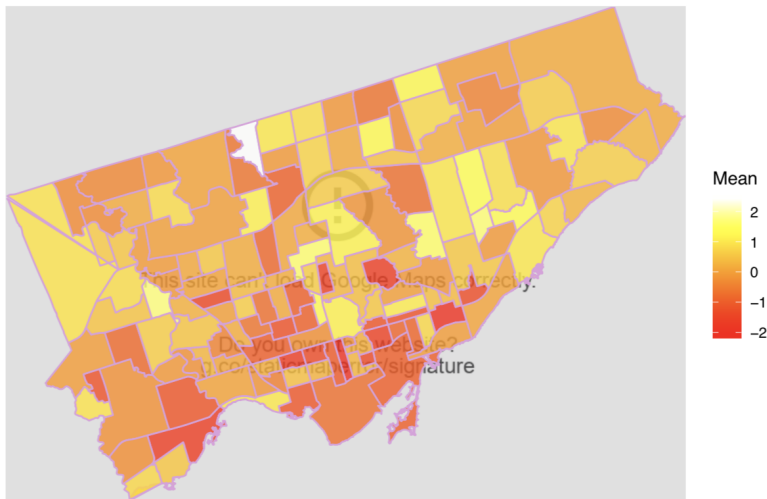
# Results

## Time Trend Effect



# Results

## Neighborhood Random Effects



# Results

## Discussion

- Great time modelling! :)
- Not great in explaining neighborhood variations
  - No inputs to model describing road density, road infrastructure, neighborhood density, traffic intensities through the day
- We can strengthen inference with a spatio-temporal model (HARD!)
  - We tried this as a (Log-Cox Gaussian) point process but current spatial data not available (very expensive)
  - Satellite data?
- Need better data for both

# Conclusion

## Some thoughts

- Bayesian inference and computation have enjoyed a splendid renaissance in recent years with better computing HW and SW
  - more involved than reg MLE or many ML implementations
- LOTS of active research into Bayesian DL and RL
  - Causal Inference
  - Bayesian optimization of hyperparams (AlphaGo)
  - Multi-task learning
  - Exploration in RL
  - Efficient, computationally stable MCMC (HMC)
- Most people are exposed to MLE only in their undergraduate studies and in industry...
- For full Bayesian methodology, and greater flexibility, use **stan** (Carpenter et al., 2017)

# Conclusion

## References

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- Simpson, Daniel, Haavard Rue, Andrea Riebler, Thiago G. Martins, and Sigrunn H. Sorbye (Feb. 2017). “Penalising Model Component Complexity: A Principled, Practical Approach to Constructing Priors”. In: Statistical Science 32.1, pp. 1–28. doi: 10.1214/16-STS576.
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