Stochastic gradient descent

GD minimizes:

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \underbrace{e\left(h(\mathbf{x}_n), y_n\right)}_{\ln\left(1 + e^{-y_n \mathbf{w}^\mathsf{T}} \mathbf{x}_n\right)} \leftarrow \text{in logistic regression}$$

by iterative steps along $-\nabla E_{\mathrm{in}}$:

$$\Delta \mathbf{w} = - \eta \nabla E_{\rm in}(\mathbf{w})$$

 $\nabla E_{\rm in}$ is based on all examples (\mathbf{x}_n,y_n)

"batch" GD

The stochastic aspect

Pick one $(\mathbf{x_n}, y_n)$ at a time. Apply GD to $\mathbf{e}(h(\mathbf{x_n}), y_n)$

$$\mathbb{E}_{\mathbf{n}}\left[-\nabla \mathbf{e}\left(h(\mathbf{x}_{\mathbf{n}}), y_{\mathbf{n}}\right)\right] = \frac{1}{N} \sum_{n=1}^{N} -\nabla \mathbf{e}\left(h(\mathbf{x}_{n}), y_{n}\right)$$

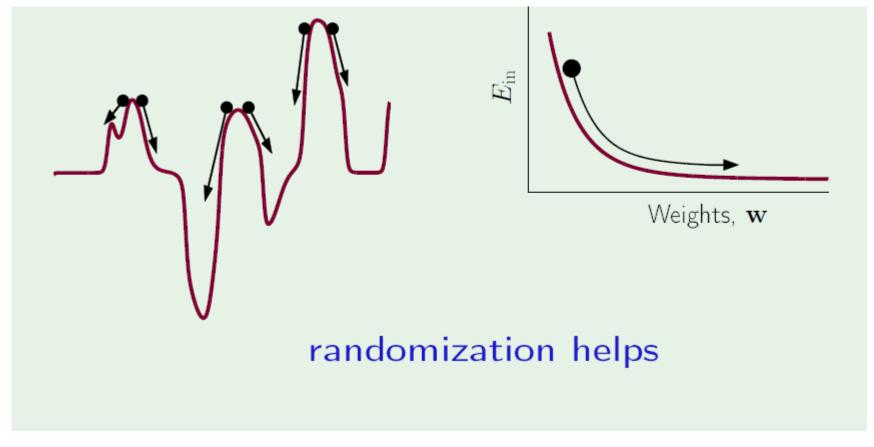
$$=-\nabla E_{\rm in}$$

randomized version of GD

stochastic gradient descent (SGD)

Benefits of SGD

- 1. cheaper computation
- 2. randomization
- 3. simple



Linear Regression

- Training datasets $\mathcal{D} = \{(x^{(1)}, t^{(1)}), ..., (x^{(i)}, t^{(i)}), ..., (x^{(N)}, t^{(N)})\}$ (target $t^{(i)}$: real value)
- Linear model $y(x) = w_0 + w_1 x_1 + w_2 x_2 + \dots + w_M x_M$
- Parameters

$$W_0, W_1, W_2, ..., W_M$$

Loss function

$$e(w) = \frac{1}{N} \sum_{i=1}^{N} [t^{(i)} - y(x^{(i)})]^2$$

• Goal: minimize e(w)

Closed-form solution
Directly calculate the pseudo-inverse

Logistic Regression

- Training datasets $\mathcal{D} = \{(x^{(1)}, t^{(1)}), \dots, (x^{(i)}, t^{(i)}), \dots, (x^{(N)}, t^{(N)})\}$ (target $t^{(i)}$: 0 or 1)
- Linear model $y(x) = \sigma(w_0 + w_1 x_1 + w_2 x_2 + \dots + w_M x_M)$
- Parameters

$$W_0, W_1, W_2, ..., W_M$$

Loss function

$$e(w) = \frac{1}{N} \sum_{i=1}^{N} \ln \left[1 + e^{-y_n w^T x_n} \right]$$

• Goal: minimize e(w)

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

Linear Regression

- Training datasets $\mathcal{D} = \{(x^{(1)}, t^{(1)}), ..., (x^{(i)}, t^{(i)}), ..., (x^{(N)}, t^{(N)})\}$ (target $t^{(i)}$: real value)
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- Linear model $y(x) = \sigma(w_0 + w_1 x_1 + w_2 x_2 + \dots + w_M x_M)$
- Parameters

$$W_0, W_1, W_2, ..., W_M$$

Loss function

$$e(w) = \frac{1}{N} \sum_{i=1}^{N} \ln \left[1 + e^{-y_n w^T x_n} \right]$$

• Goal: minimize e(w)

Steps:

- Initialize w (e.g., randomly)
- Repeatedly update w based on the gradient

$$w = w - \epsilon \nabla_{\!\!W} \ell(w)$$

where ϵ is the learning rate.

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

Key Concepts in Supervised Learning

- Loss function (measure error, or judge the fit)
- Optimization (how to find a good fit)
- Generalization (fit to unseen test data)
- Regularization (avoid overfitting)

(very very ... very important!!!)

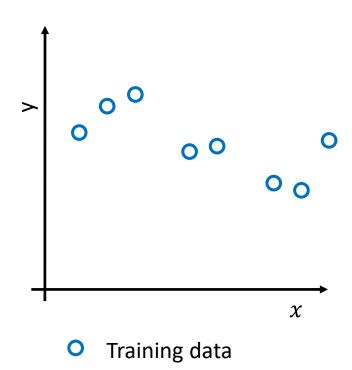
Linear Models for Regression

Let's discuss those key questions in the following cases

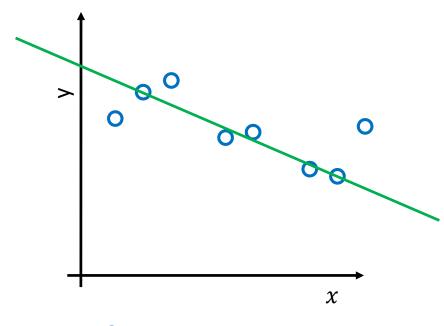
Generalization in Supervised Learning (one key concept)

Linear regression using polynomial fitting

- Generalization
 - Model's ability to predict new data



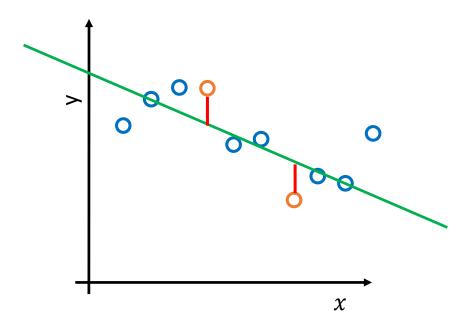
- Generalization
 - Model's ability to predict new data



Training data

- Generalization
 - Model's ability to predict new data

In fact, what we really care about is the error on new data (in Testing datasets)



- Training data
- Testing data

Courtesy of Dr. Andrew Ng

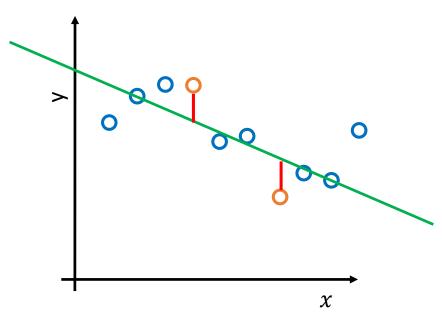
Generalization

- Generalization
 - Model's ability to predict new data

In fact, what we really care about is the error on new data (in Testing dataset)

Datasets in Machine Learning

- Training dataset
- Validation Dataset (important! we will discuss it soon.)
- Testing dataset



- Training data
- Testing data

Hyperplane

Linear regression models we learned:

• One variable

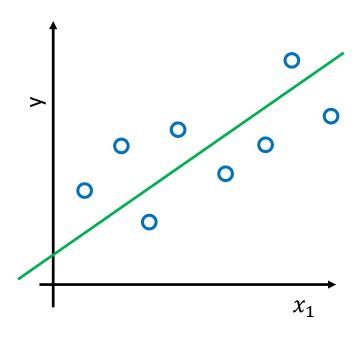
$$y(x) = w_0 + w_1 x_1$$

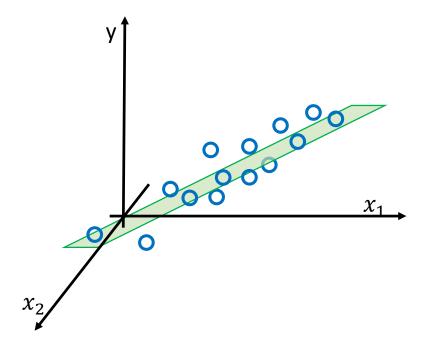
• Two variables

$$y(x) = w_0 + w_1 x_1 + w_2 x_2$$

More variables

$$y(x) = w_0 + w_1 x_1 + \dots + w_N x_N$$



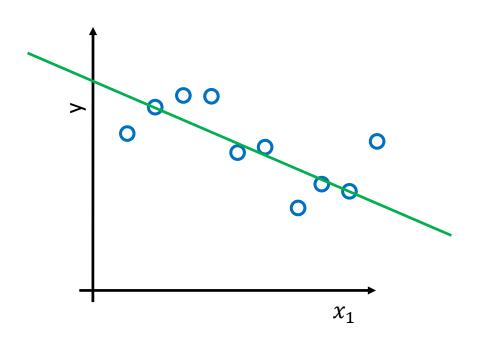




Courtesy of Dr. Sanja Fidler

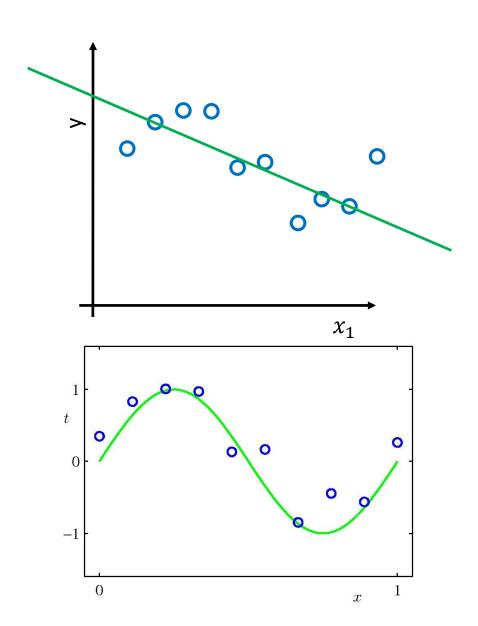
Generalization

• What if our linear model is not good? (for the data to right)



• What if our linear model is not good? (for the data to right)

 We can use a more complicated model (polynomial)



Linear Models for Regression

Let's discuss those key questions in the following cases

Generalization in Supervised Learning (one key concept)

Linear regression using polynomial fitting

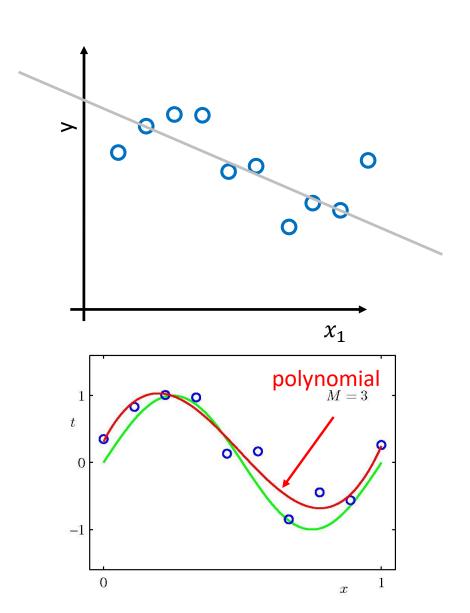
Courtesy of Dr. Sanja Fidler

Fitting a Polynomial

• Example: an *M*-th order polynomial function of one dimensional feature x:

$$y(x, w) = w_0 + \sum_{j=1}^{M} w_j x^j$$

where x^j is the j-th power of x.



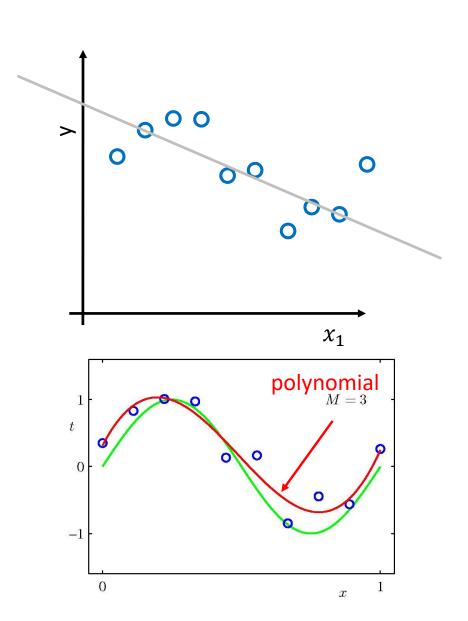
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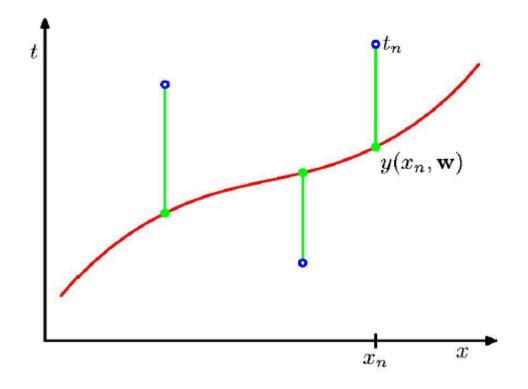
where x^j is the j-th power of x.

 Note: We can optimize for the weights w by using the same approach as we did for previous linear model.



Sum-of-Squares Error Function

The values of the coefficients will be determined by fitting the polynomial to the training data. This can be done by minimizing an error function that measures the misfit between the function y(x,w), for any given value of w, and the training set data points.

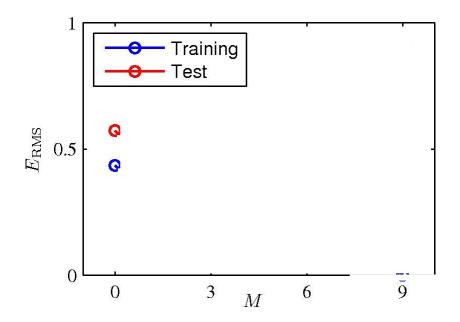


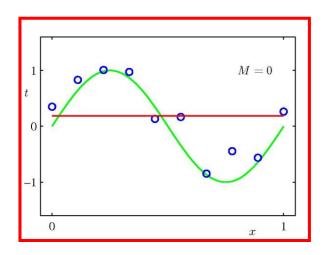
The sum of the squares error function:

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \{y(x_n, \mathbf{w}) - t_n\}^2$$

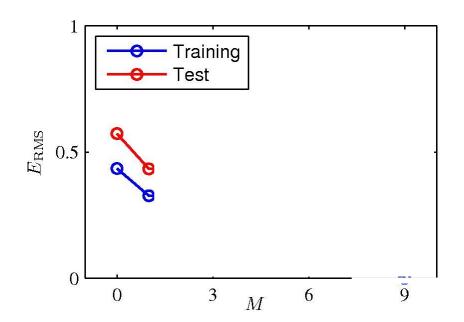
Root-Mean-Square (RMS) Error: $E_{\mathrm{RMS}} = \sqrt{2E(\mathbf{w}^\star)/N}$

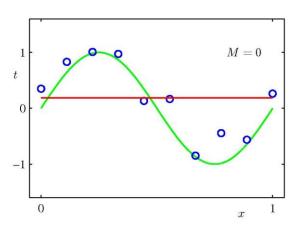
$$y(x, w) = w_0 + \sum_{j=1}^{M} w_j x^j$$

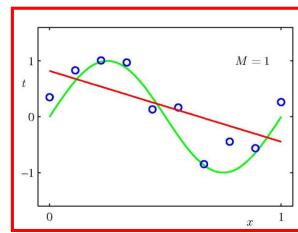




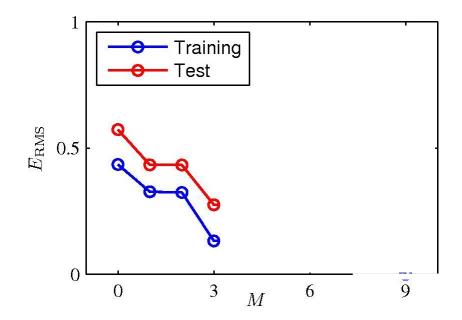
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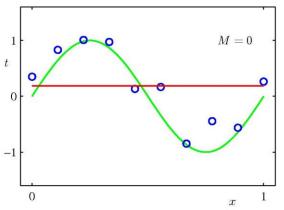


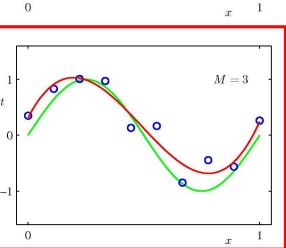


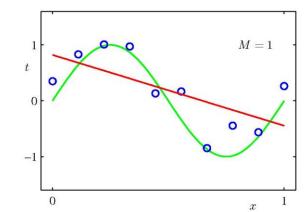


$$y(x, w) = w_0 + \sum_{j=1}^{M} w_j x^j$$

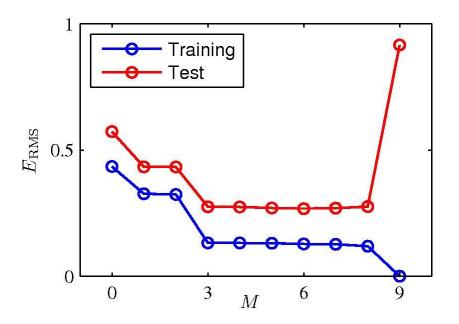


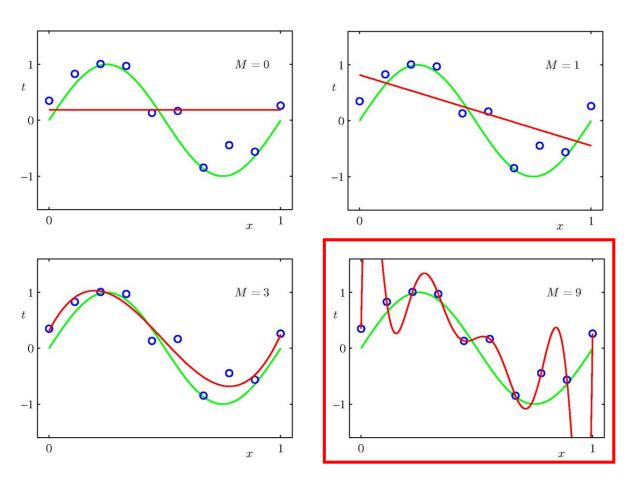






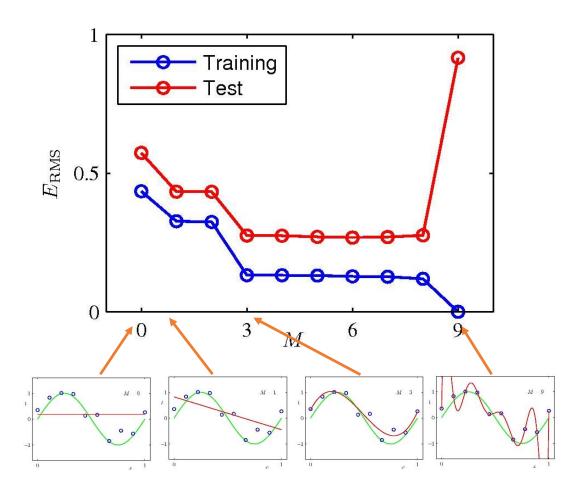
$$y(x, w) = w_0 + \sum_{j=1}^{M} w_j x^j$$





Observations

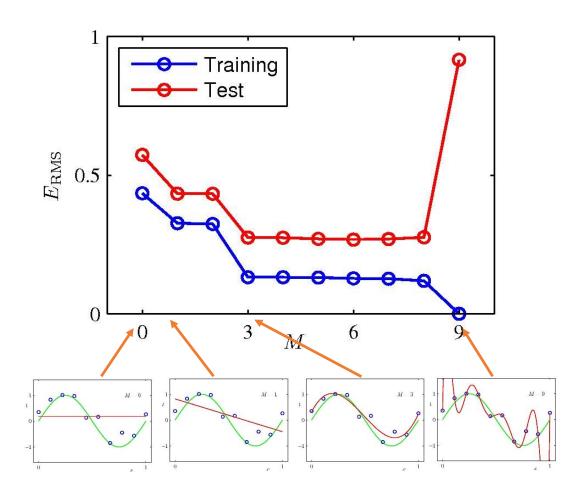
- A more complex model yields lower error on training data. (If we choose truly find the best function, the error on training data may go to zero)
- A more complex model may perform very badly on testing data (Our model with M = 9 overfits the data)



Courtesy of Dr. Hung-yi Lee

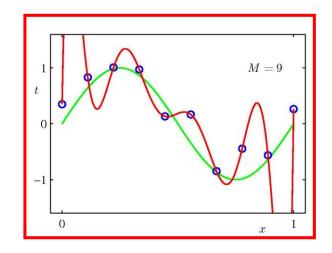
Question?

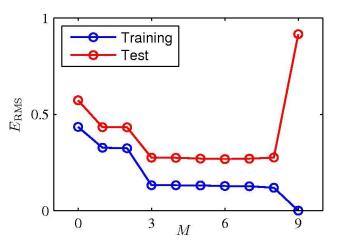
- Consider $y(x, w) = w_0 + \sum_{j=1}^{M} w_j x^j$
 - Why a more complex model can yield lower error on training data?
 - Why a more complex model can perform very badly on testing data (overfitting)?



Let's look at the estimated weights for various M

	M=0	M = 1	M = 6	M = 9
$\overline{w_0^\star}$	0.19	0.82	0.31	0.35
w_1^\star		-1.27	7.99	232.37
w_{2}^{\star}			-25.43	-5321.83
$w_3^{\overline{\star}}$			17.37	48568.31
w_4^\star				-231639.30
$w_5^{ ilde{\star}}$				640042.26
w_6^\star				-1061800.52
w_7^\star				1042400.18
w_8^{\star}				-557682.99
w_9^\star				125201.43



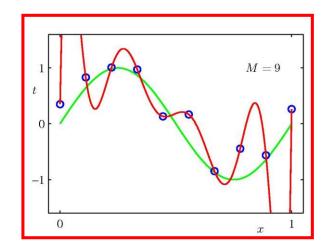


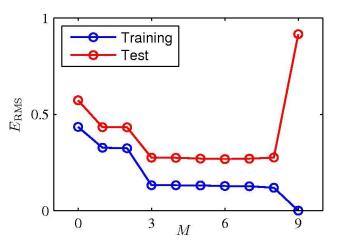
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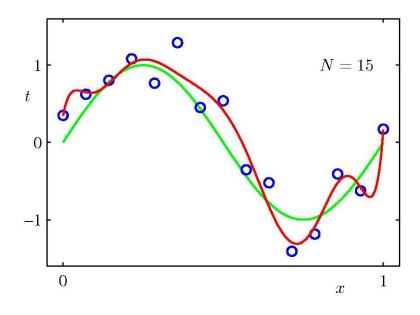
$$y(x, w) + large \ error \leftarrow w_0 + \sum_{j=1}^{M} w_j (x + small \ noise)^j$$

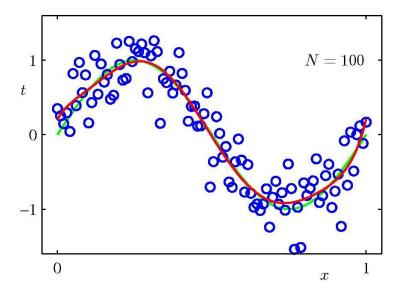
The weights are becoming huge to compensate for the noise. (a small noise on x will have much fluctuation on prediction y)





- Possible solutions
 - One workaround: Use more data





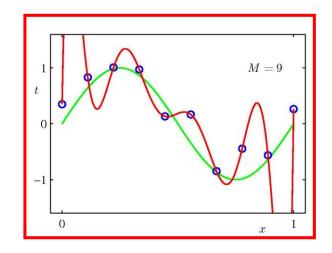
- Possible solutions
 - Second workaround: Use regularization (Very important!!!)

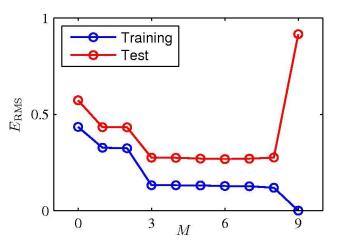
- Regularization
 - Redesign Loss function by introducing regularization term

$$\ell(w) = \frac{1}{2N} \left[\sum_{i=1}^{N} [t^{(i)} - y(x^{(i)})]^2 + \lambda \sum_{i=1}^{M} w_i^2 \right]$$

Let's look at the estimated weights for various M

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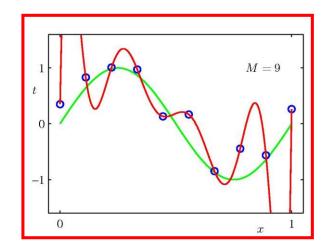


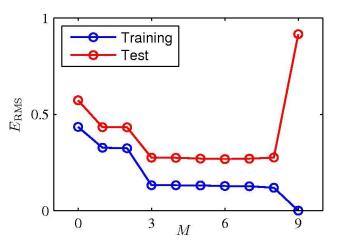
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$$y(x, w) + large \ error \leftarrow w_0 + \sum_{j=1}^{M} w_j (x + small \ noise)^j$$

The weights are becoming huge to compensate for the noise. (a small noise on x will have much fluctuation on prediction y)





 One way of dealing with this is to encourage the weights to be small. This is called regularization.

Standard approach

New loss function

$$\ell(w) = \frac{1}{2N} \left[\sum_{i=1}^{N} [t^{(i)} - y(x^{(i)})]^2 + \lambda \sum_{i=1}^{M} w_i^2 \right]$$

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- Standard approach
 - New loss function

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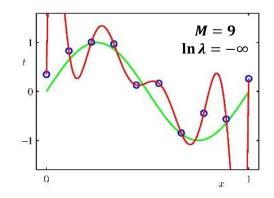
- When w_i 's are small, prediction y will be not sensitive to small change of x
- Smooth functions are preferred.

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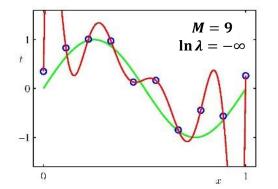


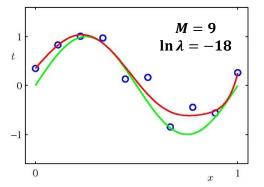
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- Standard approach
 - New loss function

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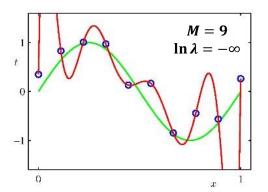


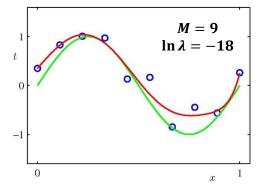
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- Standard approach
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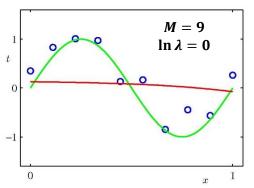
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- When w_i 's are small, prediction y will be not sensitive to small change of x
- Smooth functions are preferred.

	$\ln \lambda = -\infty$	$\ln \lambda = -18$	$\ln \lambda = 0$
w_0^{\star}	0.35	0.35	0.13
w_1^{\star}	232.37	4.74	-0.05
w_{2}^{\star}	-5321.83	-0.77	-0.06
$w_{3}^{\dot{\star}}$	48568.31	-31.97	-0.05
w_4^{\star}	-231639.30	-3.89	-0.03
w_{5}^{\star}	640042.26	55.28	-0.02
w_6^{\star}	-1061800.52	41.32	-0.01
w_7^{\star}	1042400.18	-45.95	-0.00
w_8^\star	-557682.99	-91.53	0.00
w_{9}^{\star}	125201.43	72.68	0.01
	•		





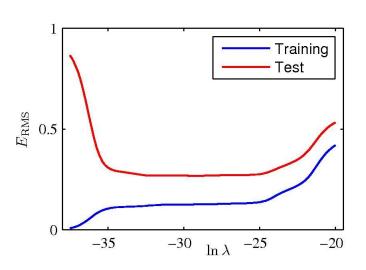


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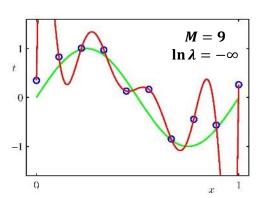
Standard approach

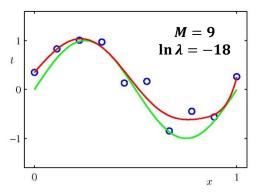
New loss function

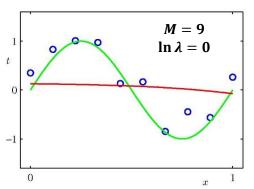
$$\ell(w) = \frac{1}{2N} \left[\sum_{i=1}^{N} [t^{(i)} - y(x^{(i)})]^2 + \lambda \sum_{i=1}^{M} w_i^2 \right]$$



However, choose value λ carefully (we prefer smooth function, but don't be too smooth)







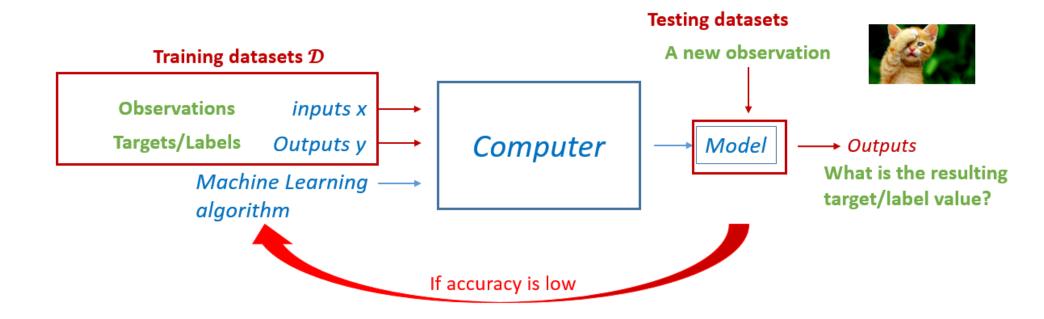
Key Concepts

Key concepts in Supervised Learning, not just for linear models

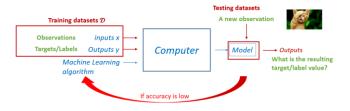
- To find a good model
 - Loss function (measure error, or judge the fit)
 - Optimization (how to find a good fit)
 - Generalization (fit to unseen test data)
 - Regularization (avoid overfitting)

Prediction error: validation

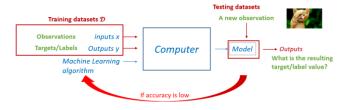
What we really care about is the prediction error on new data

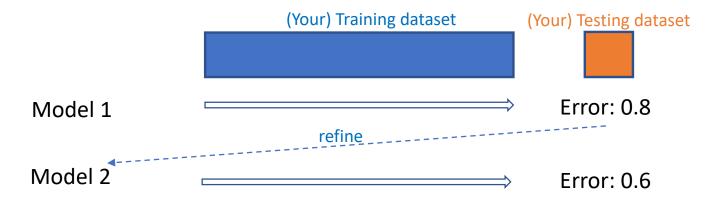


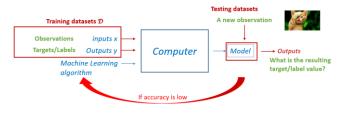


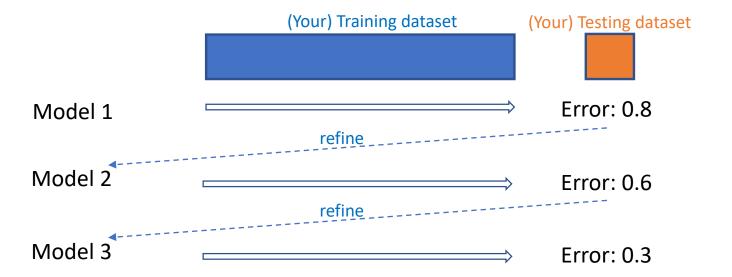


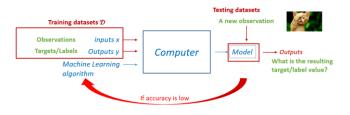


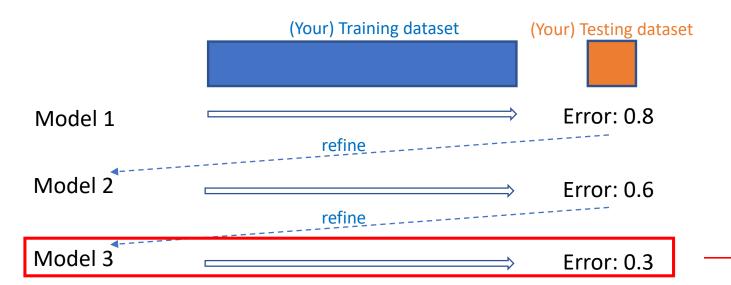




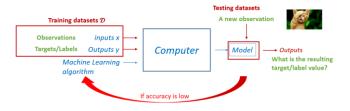




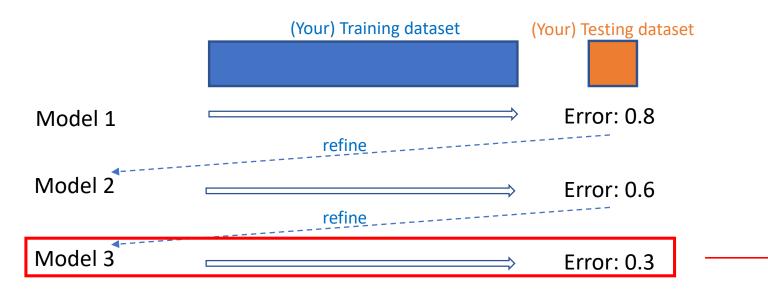






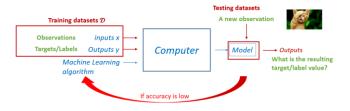


What you should NOT do in Machine learning

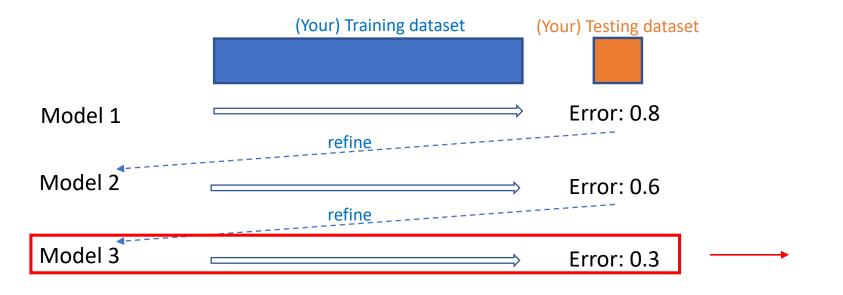


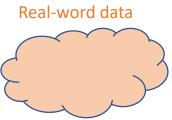


Error > 0.3



What you should NOT do in Machine learning

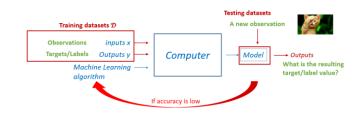




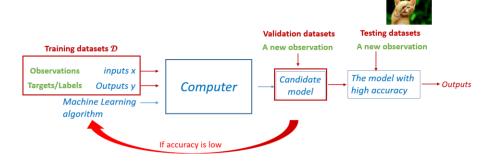
Error > 0.3

Testing data is usually used to judge the goodness of a fully-trained model. But here, it is used to refine (tune) the model.

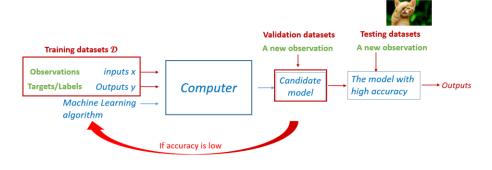
• The testing data here is not independent of training process and may not reflect the prediction on real world data.



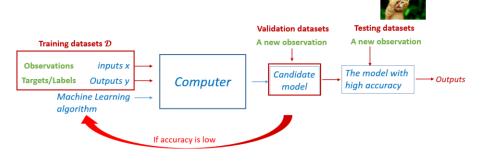


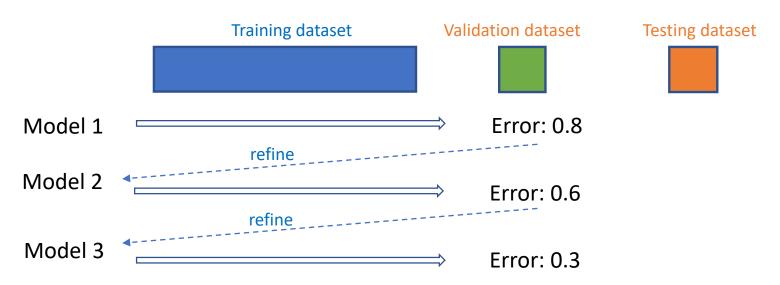


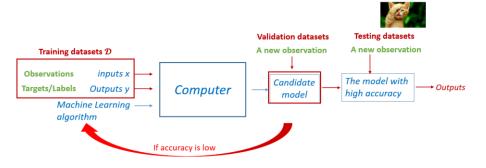


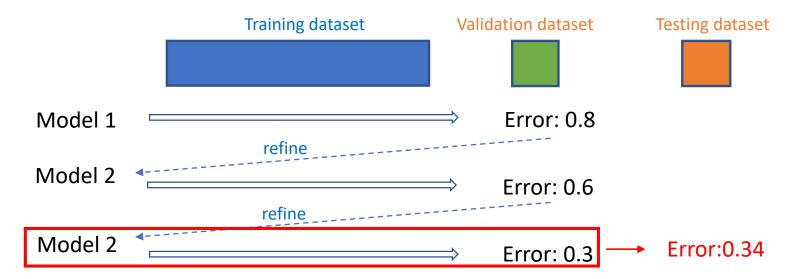


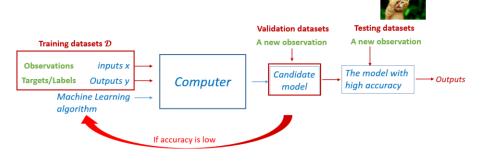


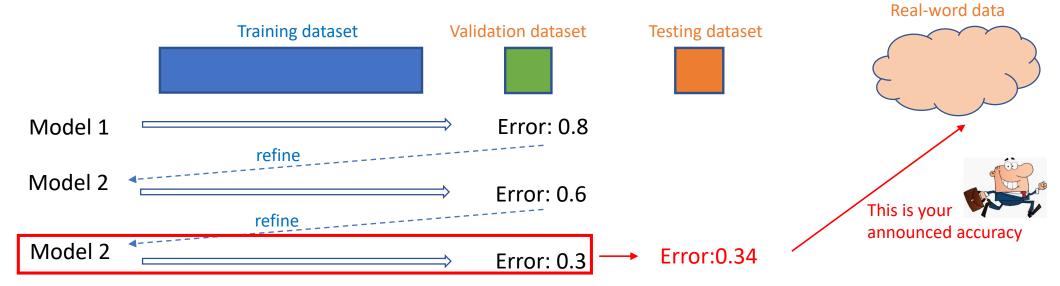


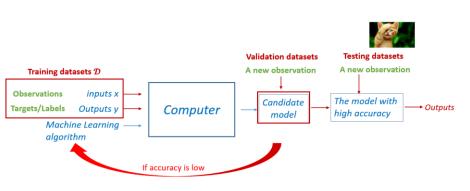




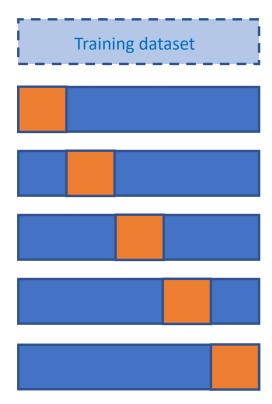




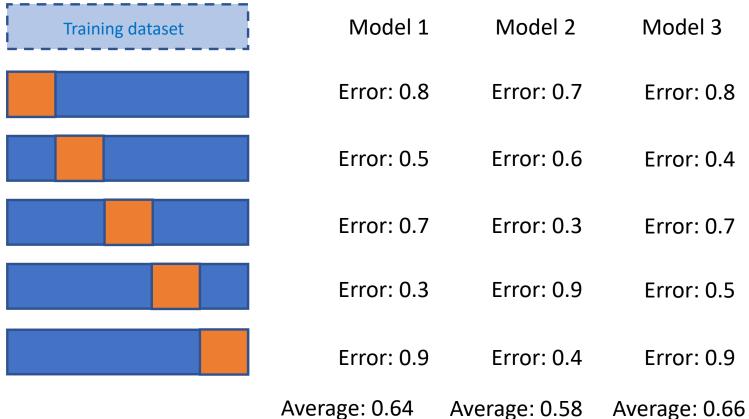


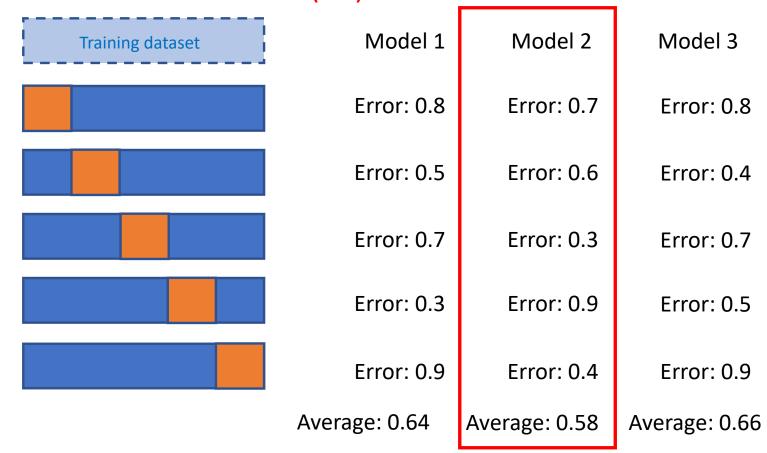






Training dataset	Model 1	Model 2	Model 3
	Error: 0.8	Error: 0.7	Error: 0.8
	Error: 0.5	Error: 0.6	Error: 0.4
	Error: 0.7	Error: 0.3	Error: 0.7
	Error: 0.3	Error: 0.9	Error: 0.5
	Error: 0.9	Error: 0.4	Error: 0.9



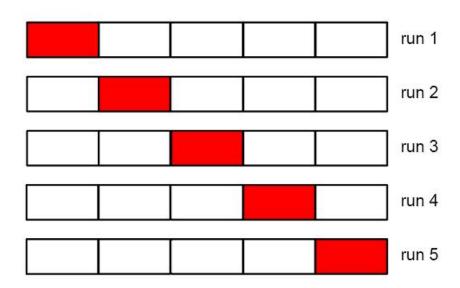


Cross Validation

- We split the training data into K folds; then, for each fold k ∈ {1, . . . ,K}, we train on all the folds but the k'th, and test on the k'th, in a roundrobin fashion.
- We then compute the error averaged over all the folds, and use this as a proxy for the test error.

(Note that each point gets predicted only once, although it will be used for training K-1 times.)

• It is common to use K = 5; this is called 5-fold CV.



Reading

- LFD: Chapter 4;
- Pattern Recognition and Machine Learning: 1.1 (optional)