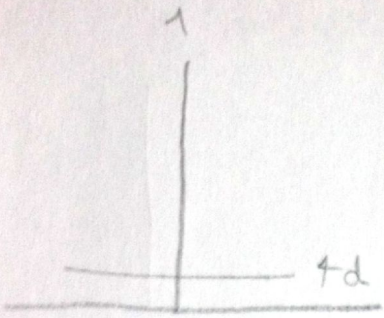
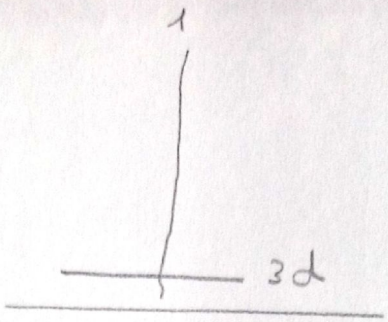
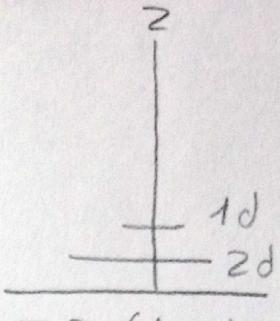
hanoi (4,0,1,2) X → (4,1,1,2)



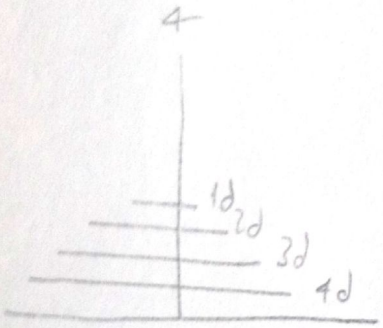
T1 (Origen)



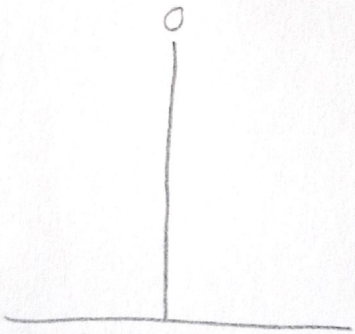
T2 (destí)



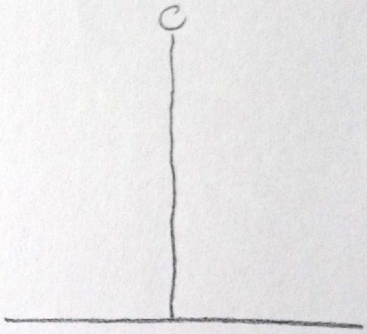
T 3 (Aux)



T1 (Origen)



T2 (Destí)



T3 (Aux)

Primer moviment T1 (1d) a T2

Segon moviment T1 (2d) a T3

Tercer moviment T2 (1d) a T3

Quart moviment T1 (3d) a T2