

# Logic and Functional Programming

## Controlling Backtracking in Prolog

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The ! (cut) predicate

The "fail" predicate

## Types of cuts

**Green** When used to prevent backtracking on branches known not to lead to a solution.

$f(X,0):- X < 3.$	$f(X,0):- X < 3, !.$
$f(X,1):- 3 \leq X, X < 6.$	$f(X,1):- 3 \leq X, X < 6, !.$
$f(X,2):- 6 \leq X.$	$f(X,2):- 6 \leq X.$

**Red** When used to change the logic of the program. Try to avoid.

$f(X,0):- X < 3.$	$f(X,0):- X < 3, !.$
$f(X,1):- X < 6.$	$f(X,1):- X < 6, !.$
$f(X,2):-.$	$f(X,2):-.$

## Case instructions

Cuts are used to prevent checking other values once a previous goal is satisfied.

`r(1):- !, a, b, c.`

`r(2):- !, d.`

`r(3):- !, e.`

`r(_):-write("default case").`

`r(X):- X=1, !, a, b, c.`

`r(X):- X=2, !, d.`

`r(X):- X=3, !, e.`

`r(_):-write("default case").`

Where will the output be?

p(1).

p(2).

q(3).

q(4).

r1(X, Y) :- !, p(X), q(Y).

r2(X, Y) :- p(X), !, q(Y).

r3(X, Y) :- p(X), q(Y), !.

Where will the output be?

p(1).

p(2).

q(3).

q(4).

r1(X, Y) :- !, p(X), q(Y).

r2(X, Y) :- p(X), !, q(Y).

r3(X, Y) :- p(X), q(Y), !.

?- r1.

X=1 Y=3

X=1 Y=4

X=2 Y=3

X=2 Y=4

Where will the output be?

p(1).

p(2).

q(3).

q(4).

r1(X, Y) :- !, p(X), q(Y).

r2(X, Y) :- p(X), !, q(Y).

r3(X, Y) :- p(X), q(Y), !.

?- r1.

X=1 Y=3

X=1 Y=4

X=2 Y=3

X=2 Y=4

?- r2.

X=1 Y=3

X=1 Y=4

Where will the output be?

p(1).

p(2).

q(3).

q(4).

r1(X, Y) :- !, p(X), q(Y).

r2(X, Y) :- p(X), !, q(Y).

r3(X, Y) :- p(X), q(Y), !.

?- r1.

X=1 Y=3

X=1 Y=4

X=2 Y=3

X=2 Y=4

?- r2.

X=1 Y=3

X=1 Y=4

?- r3.

X=1 Y=3



Where will the output be?

$p([], 0).$

$p([H|T], S) :-$

$H > 0,$

$!,$

$p(T, S1),$

$S \text{ is } S1 + H.$

$p([-|T], S) :- p(T, S).$

Where will the output be?

$p([], 0).$

$p([H|T], S) :-$

$H > 0,$

$!,$

$p(T, S1),$

$S \text{ is } S1 + H.$

$p([-|T], S) :- p(T, S).$

$?- p([1, 2, 3, 4], S).$

$S=10.$

$?- p([1, -1, 2, -2], S).$

$S=3.$

Where will the output be?

$p([], 0).$

$p([H|T], S) :-$

!,

$H > 0,$

$p(T, S1),$

$S \text{ is } S1 + H.$

$p([-|T], S) :- p(T, S).$

Where will the output be?

$p([], 0).$

$p([H|T], S) :-$

!,

$H > 0,$

$p(T, S1),$

$S \text{ is } S1 + H.$

$p([-|T], S) :- p(T, S).$

?  $p([1, 2, 3, 4], S).$

$S=10.$

?  $p([1, -1, 2, -2], S).$

false

## The "fail" predicate

```
p(a,b).
```

```
p(c,d).
```

```
p(e,f).
```

```
all :-
```

```
    p(X,Y),  
    write(X),  
    write(Y), nl,  
    fail.
```

```
all1 :-
```

```
    p(X,Y),  
    write(X),  
    write(Y), nl.
```

- ▶ Forces backtracking.
- ▶ Same effect as an impossible predicate, e.g.,  $2=3$
- ▶ No statement in a rule after fail will be evaluated
- ▶ Similar to a while loop:

```
while:-
```

```
    < condition >,  
    < statements >,  
    fail.
```

## The "fail" predicate

```
p(a,b).
```

```
p(c,d).
```

```
p(e,f).
```

```
all :-
```

```
    p(X,Y),  
    write(X),  
    write(Y), nl,  
    fail.
```

```
all1 :-
```

```
    p(X,Y),  
    write(X),  
    write(Y), nl.
```

```
?- all.
```

```
ab
```

```
cd
```

```
ef
```

```
false.
```

## The "fail" predicate

p(a,b).	?- all.
p(c,d).	ab
p(e,f).	cd
all :-	ef
p(X,Y),	false.
write(X),	?-all1.
write(Y), nl,	ab
fail.	true;
	cd
all1 :-	true;
p(X,Y),	ef
write(X),	true.
write(Y), nl.	

## The "fail" predicate

```
p(a,b).  
p(c,d).  
p(e,f).  
all :-  
    p(X,Y),  
    write(X),  
    write(Y), nl,  
    fail.  
all1 :-  
    p(X,Y),  
    write(X),  
    write(Y), nl.
```

```
?- all.  
ab  
cd  
ef  
false.  
?-all1.  
ab  
true;  
cd  
true;  
ef  
true.
```

```
?-p(X,Y).  
X = a,  
Y = b;  
X = c,  
Y = d;  
X = e,  
Y = f.
```