

Logic and Functional Programming

Controlling Backtracking in Prolog

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The ! (cut) predicate

The "fail" predicate

Types of cuts

Green When used to prevent backtracking on branches known not to lead to a solution.

$f(X,0) :- X < 3.$ $f(X,0) :- X < 3, !.$

$f(X,1) :- 3 = < X, X < 6.$ $f(X,1) :- 3 = < X, X < 6, !.$

$f(X,2) :- 6 = < X.$ $f(X,2) :- 6 = < X.$

Red When used to change the logic of the program. Try to avoid.

$f(X,0) :- X < 3.$ $f(X,0) :- X < 3, !.$

$f(X,1) :- X < 6.$ $f(X,1) :- X < 6, !.$

$f(X,2) :-.$ $f(X,2) :-.$

Case instructions

Cuts are used to prevent checking other values once a previous goal is satisfied.

r(1):- !, a, b, c.

r(2):- !, d.

r(3):- !, e.

r(_):-write("default case").

r(X):- X=1, !, a, b, c.

r(X):- X=2, !, d.

r(X):- X=3, !, e.

r(_):-write("default case").

Where will the output be?

p(1).

p(2).

q(3).

q(4).

r1(X, Y) :- !, p(X), q(Y).

r2(X, Y) :- p(X), !, q(Y).

r3(X, Y) :- p(X), q(Y), !.

Whare will the output be?

p(1).

p(2).

q(3).

q(4).

r1(X, Y) :- !, p(X), q(Y).

r2(X, Y) :- p(X), !, q(Y).

r3(X, Y) :- p(X), q(Y), !.

?- r1.

X=1 Y=3

X=1 Y=4

X=2 Y=3

X=2 Y=4

Whare will the output be?

p(1).

p(2).

q(3).

q(4).

r1(X, Y) :- !, p(X), q(Y).

r2(X, Y) :- p(X), !, q(Y).

r3(X, Y) :- p(X), q(Y), !.

?- r1.

X=1 Y=3

X=1 Y=4

X=2 Y=3

X=2 Y=4

?- r2.

X=1 Y=3

X=1 Y=4

Whare will the output be?

p(1).

p(2).

q(3).

q(4).

r1(X, Y) :- !, p(X), q(Y).

r2(X, Y) :- p(X), !, q(Y).

r3(X, Y) :- p(X), q(Y), !.

?- r1.

X=1 Y=3

X=1 Y=4

X=2 Y=3

X=2 Y=4

?- r2.

X=1 Y=3

X=1 Y=4

?- r3.

X=1 Y=3

Whare will the output be?

```
p([], 0).  
p([H|T], S) :-  
    H > 0,  
    !,  
    p(T, S1),  
    S is S1 + H.  
p([-|T], S) :- p(T, S).
```

Where will the output be?

```
p([], 0).
```

```
p([H|T], S) :-
```

```
    H > 0,
```

```
    !,
```

```
    p(T, S1),
```

```
    S is S1 + H.
```

```
p([-|T], S) :- p(T, S).
```

```
?- p([1, 2, 3, 4], S).
```

```
S=10.
```

```
?- p([1, -1, 2, -2], S).
```

```
S=3.
```

Where will the output be?

```
p([], 0).
```

```
p([H|T], S) :-
```

```
!,
```

```
H > 0,
```

```
p(T, S1),
```

```
S is S1 + H.
```

```
p([-|T], S) :- p(T, S).
```

Whare will the output be?

```
p([], 0).
```

```
p([H|T], S) :-
```

```
!,
```

```
H > 0,
```

```
p(T, S1),
```

```
S is S1 + H.
```

```
p([-|T], S) :- p(T, S).
```

```
? p([1, 2, 3, 4], S).
```

```
S=10.
```

```
? p([1, -1, 2, -2], S).
```

```
false
```

The "fail" predicate

p(a,b).

p(c,d).

p(e,f).

all :-

```
p(X,Y),  
write(X),  
write(Y), nl,  
fail.
```

all1 :-

```
p(X,Y),  
write(X),  
write(Y), nl.
```

- ▶ Forces backtracking.
- ▶ Same effect as an impossible predicate, e.g., $2=3$
- ▶ No statement in a rule after fail will be evaluated
- ▶ Similar to a while loop:

while:-

```
< condition >,  
< statements >,  
fail.
```

The "fail" predicate

```
p(a,b).           ?- all.
```

```
p(c,d).           ab
```

```
p(e,f).           cd
```

```
all :-             ef
```

```
              false.
```

```
    p(X,Y),
```

```
    write(X),
```

```
    write(Y), nl,
```

```
    fail.
```

```
all1 :-
```

```
    p(X,Y),
```

```
    write(X),
```

```
    write(Y), nl.
```

The "fail" predicate

p(a,b).	?- all.
p(c,d).	ab
p(e,f).	cd
all :-	ef
p(X,Y),	false.
write(X),	?-all1.
write(Y), nl,	ab
fail.	true;
all1 :-	cd
p(X,Y),	true;
write(X),	ef
write(Y), nl.	true.

The "fail" predicate

p(a,b).

p(c,d).

p(e,f).

all :-

 p(X,Y),

 write(X),

 write(Y), nl,

 fail.

all1 :-

 p(X,Y),

 write(X),

 write(Y), nl.

?- all.

ab

cd

ef

false.

?-all1.

ab

true;

cd

true;

ef

true.

?-p(X,Y).

X = a,

Y = b;

X = c,

Y = d;

X = e,

Y = f.