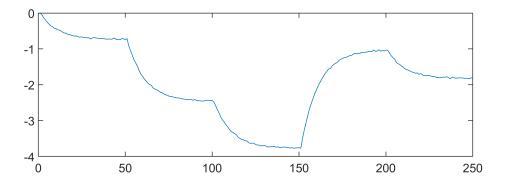
```
clear variables
load('lab8_1.mat')
```

Warning: Updating objects saved with previous MATLAB version... Resave your MAT files to improve loading speed.

```
yid = id.y;
uid = id.u;
yval = val.y;
uval = val.u;
Ts = val.Ts;

figure,
subplot(211)
plot(yval)
hold on
```



```
% Stepsize
alpha = 0.5;
% Threshold
gama = 1e-4;
% Iteration range
lmax = 250;
% Initial parameter vector
theta = [1;1];
f = theta(1);
```

```
b = theta(2);
N = length(transpose(yid));
l = 1;
```

## Computing recursion formulas and applying them to find Epsilon(k)

```
Epsilon_derivated = zeros(2,N);
Epsilon = zeros(1,N);
for k = 2 : 1 : N
    Epsilon_derivated(1,k) = yid(k-1) - f*Epsilon_derivated(1,(k-1)) - Epsilon(k-1);
    Epsilon_derivated(2,k) = -uid(k-1) - f*Epsilon_derivated(2,(k-1));
end

Epsilon_derivated_recursive = zeros(2,N);
```

## Repeat the steps below

until I reaches Imax or the norm between 2 consecutives theta terms is greater than gamma

```
while ((1 < lmax) \mid | (norm(theta(:,1) - theta(:,(1-1))) > gama))
             for k = 2 : 1 : N
                           Epsilon(k) = yid(k) + theta(1,1)*yid(k-1) - theta(2,1)*uid(k-1) - f*Epsilon(k-1);
                          Epsilon\_derivated\_recursive(1,k) = yid(k-1) - theta(1,l)*Epsilon\_derivated\_recursive(1,k) = yid(k-1) - theta(1,k) = yid(k
                           Epsilon_derivated_recursive(2,k) = -uid(k-1) - theta(1,l)*Epsilon_derivated_recursive(2,k)
             end
             % Compute gradient of the objective function
             gradient_sum = 0;
             for k = 1 : 1 : N
                           gradient sum = gradient sum + Epsilon(:,k)*Epsilon derivated recursive(:,k);
             end
             dV dtheta = 2*gradient sum / N;
            % Compute approximate Hessian of the objective function
             hessian sum = 0;
             for k = 1 : 1 : N
                           hessian_sum = hessian_sum + Epsilon_derivated_recursive(:,k)*transpose(Epsilon_derivated_recursive(:,k)
             end
            H = 2*hessian_sum / N;
             % Apply Gauss-Newton update formula
            theta(:,(1+1)) = theta(:,1) - alpha*inv(H)*dV_dtheta;
            % Increment the counter
             1 = 1+1;
end
```

## Plot the results

```
subplot(212)
mOE = idpoly(1,[0 theta(2,end)],1,1,[1 theta(1,end)],0,Ts);
compare(val,mOE)
hold off
```

