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1. INTRODUCTION and PURPOSE:

Magnetic resonance imaging (MRI) of the brain has been widely used during the last years in clinical practice. This image modality presents a high contrast for soft tissues, including white matter lesions (WML). Expert tracing of these lesions may be a time-consuming task and prone to variability due to the large number of MRI slices and the different conditions between experts. In order to reduce these limitations, here we present a novel supervised automated 3D voxelwise lesion detection and segmentation classifier that is based on a cascade of two identical Convolutional Neural Network (CNN) architectures with posterior refinement.

2. METHOD:

2.1 CNN architecture:

Isotropic 3D patches centered around the voxel of interest are selected to increase the number of training samples.

3D patches reduce the number of false positives in areas where normal tissue appears similar to the lesion intensity profile.

CNN architecture (**Figure 1**):

- preprocessed FLAIR, T1, T2 and PD modalities
- $15 \times 15 \times 15 \times 4$ input
- $32 \times 7 \times 7 \times 7$ convolutional layer
- average pooling with size 2 and stride 2
- $64 \times 3 \times 3 \times 3$ convolutional layer
- average pooling with size 2 and stride 2
- dropout layer with ($t = 0.5$)
- 256 units fully connected layer
- 2 units soft-max layer

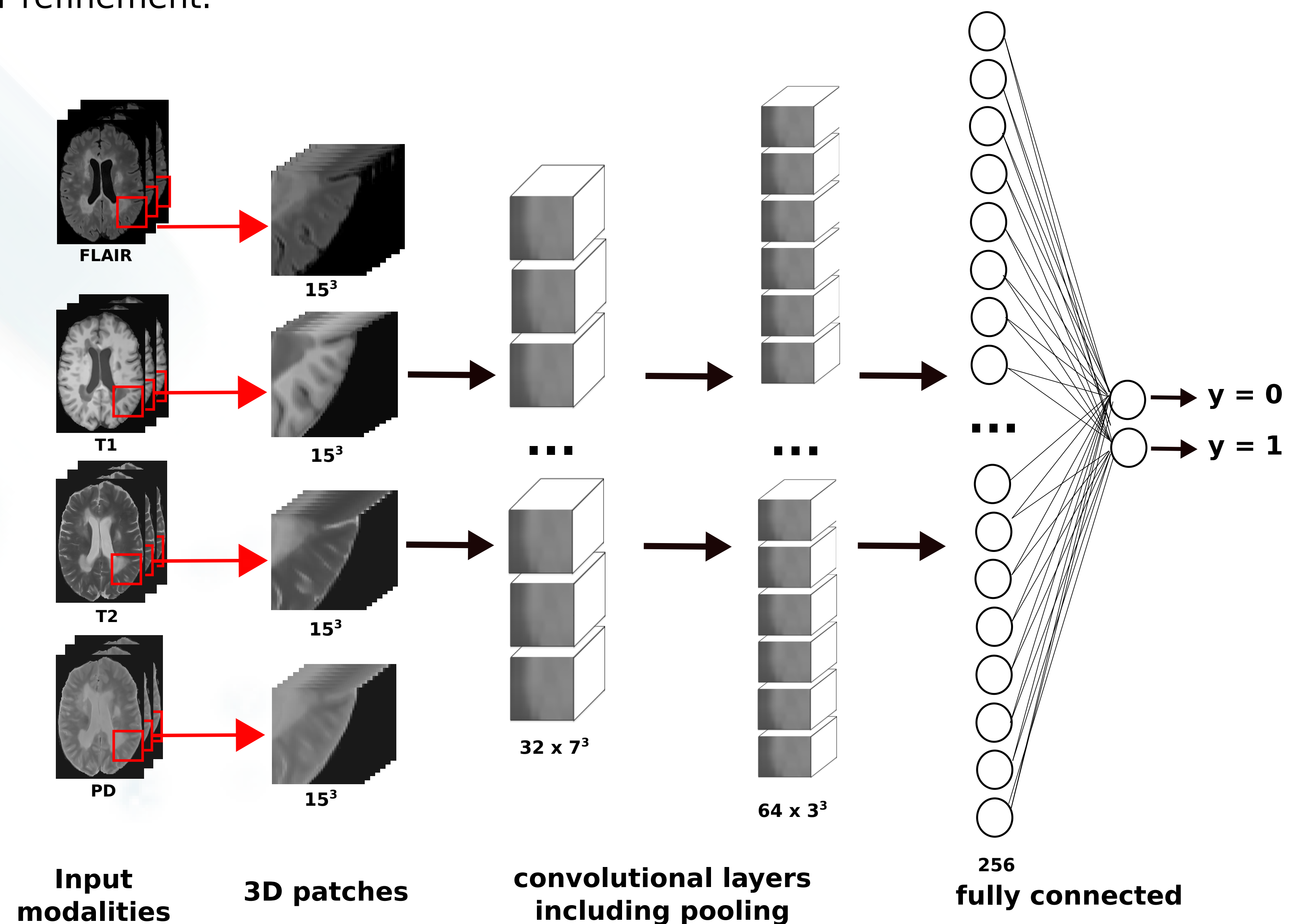


Figure 1: Architecture of the convolutional network taking candidate patches of size $15 \times 15 \times 15$ as inputs.

2.2 Training:

A cascade of two identical classifiers is implemented in order to reduce the effect of false positives (**Figure 2**):

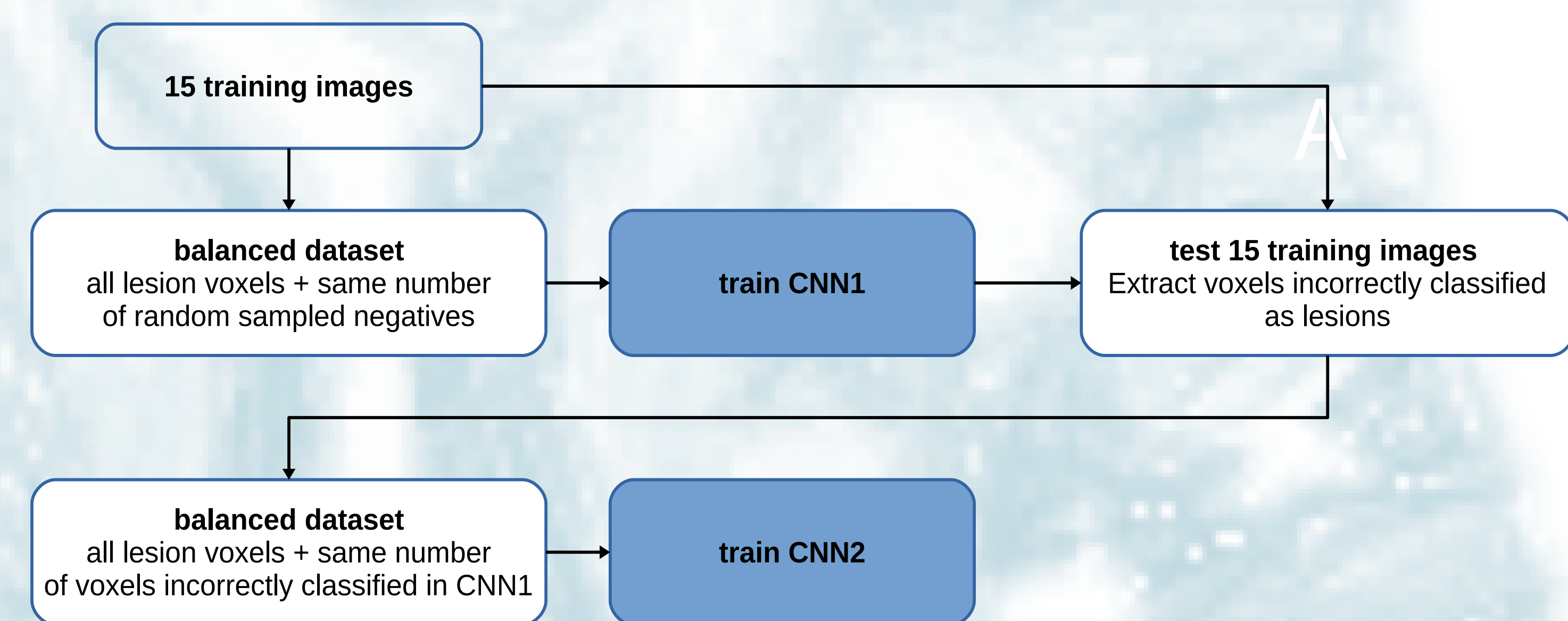


Figure 2: The proposed architecture is trained in two steps: First, we use all the voxels defined as lesion in the consensus and a random sampling of the same size of all the candidates that are not lesion. After training the CNN1, we test all the training images with the CNN1, obtaining a probabilistic map for each image voxel. These maps are used to select the most challenging false positives. Then, we randomly select a sample of these false positive voxels of the same size as the lesion voxels and we train a second classifier CNN2 using this dataset.

2.3 Testing:

For each new testing image, all its voxels are evaluated using both nets CNN1 and CNN2. The probabilistic maps obtained in each case are multiplied and obtained lesion regions are filtered (**Figure 3**):

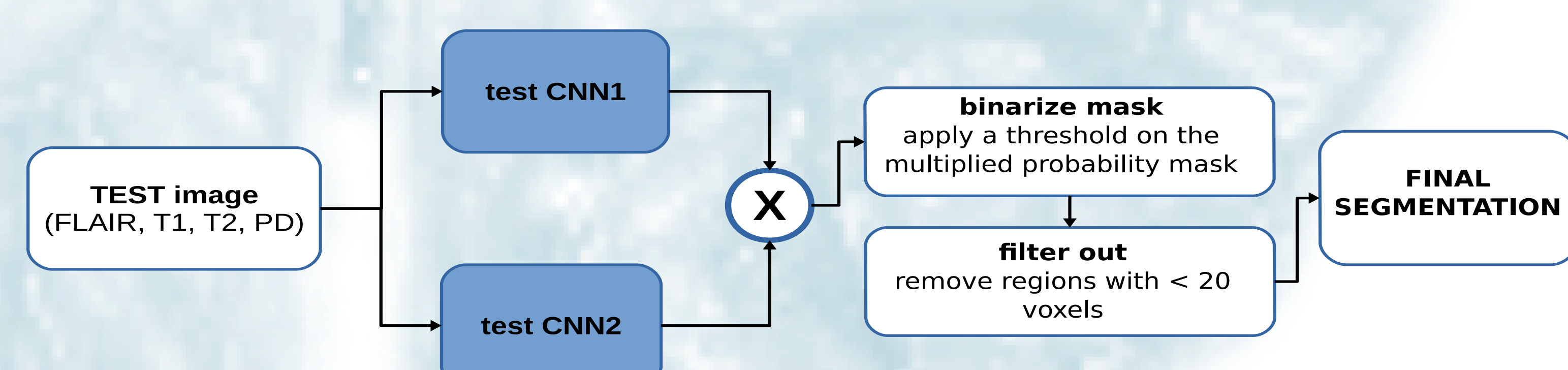


Figure 3: Since both networks use the same positive voxels, when testing all lesions are considered in both nets. However, since we used different negative voxels, the probabilistic maps present different false positive detections that do not overlap after output multiplication, reducing the number of false positives. Finally, the probabilistic map is binarized and small regions are removed.

3. EVALUATION:

A qualitative evaluation of the proposed pipeline is shown in (**Figure 4**):

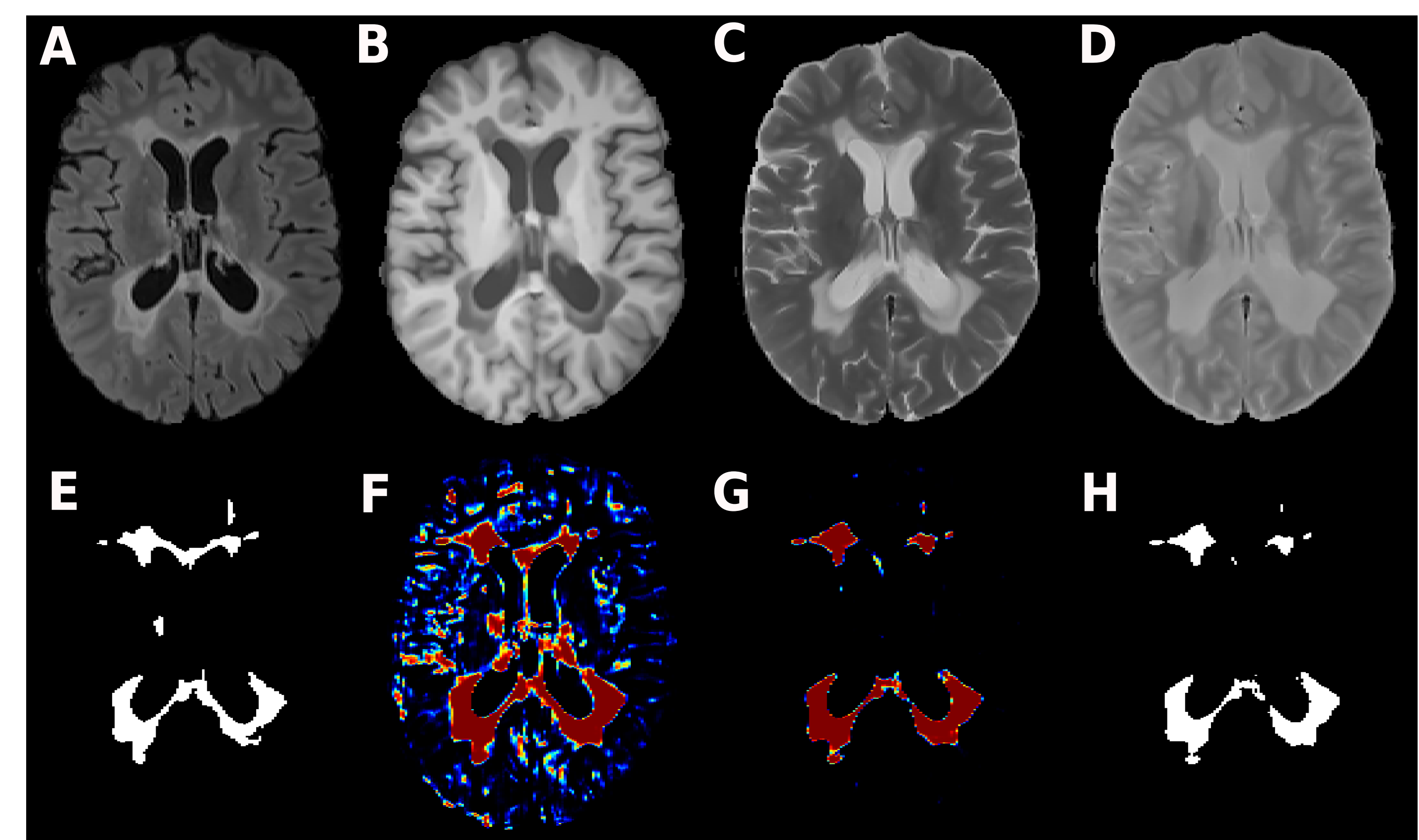


Figure 4: Qualitative evaluation of the training case 01016SACH after training it using leave-one-out. Pre processed input images A) FLAIR , B) T1, C) T2 and D) PD. E) Consensus ground-truth annotation. F) Output map after testing the input image with the F) CNN1 net and G) CNN2 net. H) Final resulting output segmentation mask after multiplying the CNN1 and CNN2 outputs, binarizing and removing regions with small area.

4. CONCLUSION:

The presented pipeline is our first attempt to segment MS lesion using a simple deep learning approach. Although quantitative evaluations are still not available, evaluations on training data suggest that these techniques are very promising. In this aspect, we are currently studying more sophisticated pipelines with the aim of increasing the accuracy of automated MS lesion segmentation.

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