ML process of training a piece of software, called model, to make useful predictions or to generate content from

Types:

 Unsupervised learning(clusterization common) • Reinforcement learning(penalties and rewards->generated policy)

• Supervised learning(two most common use cases - regression and classification)

• Generative AI(generate something from input)

Online and batch learning.

1. Numerical

 \boldsymbol{Y} - the variable that we predict.

2. Categorical Ordinal

• Nominal

1.1. Data mining

1.2. Supervised Solves regression and classification tasks. $X \longrightarrow F \longrightarrow y$

Regression model predicts continuous values. Classification model predicts categorical values.

Tasks:

1. Clustering 2. Anomaly detection

3. Dimensionality reduction 4. Association rule learning

Problems:

- 1. Underfitting/overfitting 2. Too few data/non representative data
- 1.3. Unsupervised

- 1.4. Reinforement learning

1. Problems for which solution requires a lot of hand-tuning

2. Four types of problems where it shines

3. Fluctuating environments - online models can adapt 4. Getting insights about large amount of data.

2.1. Other differentiations Batch vs live. Instance-Based vs Model-Based learning.

Algorithms:

- Algorithms: · Linear regression

3. Main challenges

1. Insufficient quantity of training data.

2. Feature extraction(e.g. compression)

2. Non representative training data. Representative dataset - accurely reflect structure and the diversity of the real-world scenario.

1. Feature selection

3. Creating new features

gorithms. The translation is a hard problem, but amount of data produces very precise prediction.

3.3. On text processing. (the unreasonable effectiveness of data)

to it and how to run inference.

3.5. Selection bias

Goal is to test model ability to predict new data by.(struggling with overfitting and selection bias) Validation performed with different portions of data to test and train model.

4. Optimisation and loss function 4.1. Gradient descent **Gradient**(∇f) defines direction and rate of fastest increase of scalar-valued differentiable function f.

4.2. Optimization Optimisation target minimize loss function. Simple example of the loss function is a MSE.

Where h is a learning step.

Simplify each *i* argument:

Final differential formula:

inside f v.

How much *i*'s would be in a N dataset?

 $MSE = \frac{1}{N} \sum_{(x,y) \in D} (y - prediction(x))^{2}$ Iteration step for model paraneter:

 $\Theta^{i+1} = \Theta^i - h \frac{\partial f}{\partial \Theta^i}$

 $\frac{\partial f}{\partial \Theta_i} = \frac{1}{2N} \sum_{i=1}^n \left(\left(\sum_{j=1}^m (\Theta_j x_j) - y_i \right)^2 \right)$

note: N is the iteration dataset(or batch) size, x_j is a point in vector, Θj is the parameter value that is const if not

imums.

Stop criteria for the gradient descent can be a threshold for the gradient value.

Mean squared error(MSE) measures the average of squeared errors.

TODO [Comparison of batch sizes link] **epoch** one pass of all the training examples batch size the number of training examples in one pass. The higher the batch size, the more memory space

iterations number of batches in epoch. each iteration adjusts model's parameters.

 $\frac{1}{2N} \sum_{i=1}^{3} \left(\left(\sum_{i=1}^{2} (\Theta_{j} x_{j}) - y_{i} \right)^{2} \right)$

Process is simple, count *gradient* for each *parameter* and change parameters by gradient descent.
$$\Theta_i \longrightarrow \text{gradient} \longrightarrow \Theta_i^T$$
4.3. Linear regression

 $\frac{\partial f}{\partial \Theta_i} = x_i \frac{1}{N} \sum_{i=1}^n \left(\sum_{j=1}^m \Theta_j x_j - y_i \right)$

Figure 1: Synthetic features for regression with linear Θ params How to choose function to create additional features? Intuitively as a hyperparams. There are automatic methods to make models - feature selection approach.

4.3.1. Normal Linear Regression Model

5. Data

overfitting.

 $y \in \{1, 2, 3, .., k\}$

bias

variance

4.3. Linear regression When we have not linear plot, to solve this linear regression problem we can add additional polynomial(x^2) or functional($\sin(x), \sqrt{x}$) features.

Regularization formula L2(makes features balance):
$$L = \frac{1}{2N} \sum_{j=1}^{n} \left(y(x_i) - y_i \right)^2 + \Lambda \sum_{i=1}^{m} (\Theta_i^2) \longrightarrow \min_{\Theta}$$
 Regularization formula L1(makes feature selection):
$$L = \frac{1}{2N} \sum_{j=1}^{n} \left(y(x_i) - y_i \right)^2 + \Lambda \sum_{i=1}^{m} (|\Theta|) \longrightarrow \min_{\Theta}$$
 6. Classification
$$y \in \{1, 2, 3, ..., k\}$$
 Task make a function, that separates known classes.

 $\begin{cases} -\log(p_i), y_i = 1 \\ -\log(1-p_i), y_i = 0 \end{cases}$ p_i - model output probability for i example. (class 1) $BCE = -y_i \log(p_i) - (1 - y_i) \log(1 - p_i)$

To define success of model **metrics** are used. $A = \left(\frac{N_{\text{correct}}}{N}\right)100\%$

Precision TP/(TP+FP). How model is confident for class a.

Recall TF/(TF+FN). Which coverage for class a.

7. Regressions comparison

0

Logistic regression is a S-shaped curve:

BCE(Binary cross entropy) loss function

6.1.1. Formula

6.1.2. Loss function

6.2. Metrics

Criteria

Output type

Target

Usecase Distribution type

Regression plot dependency

· Predicting the height of an adult based on the mother's and father's height

3. Root mean squared error

https://en.wikipedia.org/wiki/Logistic_regression

• K-neighbors regression(need to define neighborhood function) **Model-Based learning** makes model to generalize data and predict new value by formula. Uses utility function to tweak the formula.

3.1. Bad data To detect use model performance metrics - precision/recall and cross validation.

features with larger dataset. For classification check classes distribution. 3. Poor quality data(NULLS especially). Need to define how to treat outliners and NULLS. 3.2. Feature engineering

The ontology and other structuring is not possible at this scale because the profit is not obvious and not profitable. So at large scale it's more efficient to use unsupervised algorithms on unlabeled data. 3.4. Cross validation

Selecting individuals in such a way that proper randomization(representation) is not achieved.

Example for gradient in cartesian coordinate system f: $\nabla f = \frac{\partial f}{\partial x}i + \frac{\partial f}{\partial y}i + \frac{\partial f}{\partial z}k$ **Gradient descent** iterative optimization algorithm of the first order to find the local minimum of the function.

differentiated,
$$y_i$$
 is a constant for each i.
Let's simplify function for two parameters and 3 data slices:

With formula of compound derivative
$$(u(v))'=u'(v)*v'$$

$$\left(\left(\Theta_0x_0+C_i\right)^2\right)'=2(\Theta_0x_0+C_i)(x_0)$$
 TODO

 $\left(\sum_{i=1}^{2} (\Theta_{j} x_{j}) - y_{i}\right)^{2} = (\Theta_{0} x_{0} + \Theta_{1} x_{1} - y_{i})^{2}$

 $\Theta_1 x_1$ and y_i is a constants if we differentiate by Θ_0 , so we have: $\left(\left(\Theta_0 x_0 + C_i\right)^2\right)'$, also: $\left(\Theta_0 x_0 + C_i\right)$ is an

 $y = \frac{\theta_0}{100} + \frac{\theta_1 \chi_1 + \theta_2 \chi_2}{100} + \frac{\theta_3 \chi_1^2 + \theta_4 \chi_1^2 + \theta_5 \chi_1 \chi_2}{100}$

TODO https://www.statlect.com/fundamentals-of-statistics/normal-linear-regression-model

not have semantic intersections(same people, same cars, same buildings etc.).

Dataset should be divided minimum for train(60), validation(20) and final test(20). This divided datasets must

Cross validation - method, which on small dataset find conceptual ML model that possibly solves task. TODO

Accordingly to image, linear regression is not suitable for this type of task(especially right) Firstly, we will solve binary classification task $\{0, 1\}$. Model will have 1 output - probability of x is from class 1. 6.1. Logistic regression Logistic regression type of regression that predicts a probability of an outcome given one or more independent variables. With a threshold returned probability can be mapped to a discrete value.

Figure 2: Classification visualization

Figure 3: Logistic regression

 $y = \frac{1}{1 + e^{-\sum_{i=1}^{m} \Theta_i X_i + \Theta_0}}$

$$\begin{cases} \operatorname{TP}\ y_i, p_i = \{1,1\}\ \operatorname{BSE} = 0 \\ \operatorname{TN}\ y_i, p_i = \{0,0\}\ \operatorname{BSE} = 0 \\ \operatorname{FN}\ y_i, p_i = \{1,0\}\ \operatorname{BSE} \to \inf \\ \operatorname{FP}\ y_i, p_i = \{0,1\}\ \operatorname{BSE} \to \inf \end{cases}$$
 Loss for gradient:
$$L = -\frac{1}{N} \sum_{i=1}^n (y_i \log(p_i) + (1-y_i) \log(1-p_i)) \longrightarrow \min$$

$$\frac{\partial f}{\partial \Theta_i} = -\frac{1}{N} \sum_{i=1}^n (y_i \log(p_i) + (1-y_i) \log(1-p_i))'$$

Give a most precise number

Linear regression

Straight line

Continuous

Logistic

S-shaped curve

Probability (0,1) of the value

Give a probability of belonging to category

from the finite category

9. Selecting a performance measure for regression

 $RMSE = \sqrt{\frac{\sum_{i=1}^{n} (e_i)^2}{n}}$ https://www.statlect.com/

https://towardsdatascience.com/logistic-regression-detailed-overview-46c4da4303bc

• Predicting pumpkin sales volume based on the price, time of year, and store location Logistic examples: • Predicting if a person will get a disease based on status, salary, genetics • Prediction if a person will quit a job based on meetings, pull requests, office time. • Predicting the marriage of a person based by car, salary, outlook, office time, education, country. 8. Removing correlated features Before train model it may be worth to perform "dimensionality reduction" to save space, without loosing too much information 1. Mean absolute error $MAE = \frac{\sum_{i=1}^{n} |e_i|}{n}$ Disregard difference between under, over estimation. 2. Mean squared error $MSE = \frac{\sum_{i=1}^{n} (e_i)^2}{n}$

https://towardsdatascience.com/

10. Lib

Feature(x) the variable in the data vector. Types: **Hyperparam** meta parameter for model. Model do not learn it. Data mining applying ML techniques to dig into large amounts of data can help discover factors, that are not immediately apparent.

 $X \longrightarrow F \longrightarrow X'$ The learning system, called agent can observe the environment, select and perform actions, and get rewards or penalties. It must learn then by itself what is the best strategy, called a policy to get the most reward over the time.

2. Complex problems, for which there is no good solution exists