

Lecture 33. The Gram-Schmidt process

Thm (The Gram-Schmidt process)

If V is a subspace of \mathbb{R}^n together with a basis $B = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m\}$,

it has an orthogonal basis given as follows:

- $\vec{u}_1 = \vec{v}_1$,

- $\vec{u}_2 = \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1$,

- $\vec{u}_3 = \vec{v}_3 - \frac{\vec{v}_3 \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 - \frac{\vec{v}_3 \cdot \vec{u}_2}{\vec{u}_2 \cdot \vec{u}_2} \vec{u}_2$,

⋮

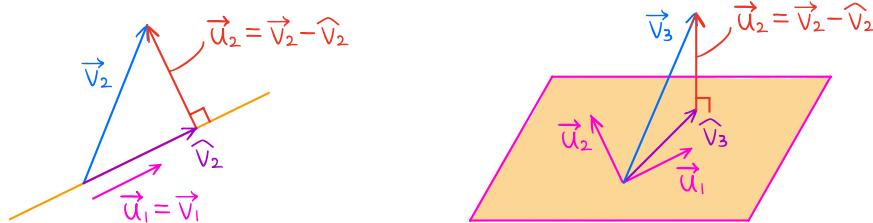
- $\vec{u}_m = \vec{v}_m - \frac{\vec{v}_m \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 - \frac{\vec{v}_m \cdot \vec{u}_2}{\vec{u}_2 \cdot \vec{u}_2} \vec{u}_2 - \dots - \frac{\vec{v}_m \cdot \vec{u}_{m-1}}{\vec{u}_{m-1} \cdot \vec{u}_{m-1}} \vec{u}_{m-1}$

Note (1) We can replace each \vec{u}_i by its multiple to simplify computation.

(2) The orthogonal basis above is recursively constructed by

$$\vec{u}_i = \vec{v}_i - \hat{v}_i$$

where \hat{v}_i is the orthogonal projection of \vec{v}_i onto the subspace spanned by $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_{i-1}$.



$\Rightarrow \vec{u}_i$ is orthogonal to $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_{i-1}$.

Ex Find an orthogonal basis of each vector space.

(1) The column space of

$$A = \begin{bmatrix} 2 & 1 & 3 & 3 \\ 1 & 3 & 4 & -1 \\ 1 & 1 & 2 & 1 \end{bmatrix} \text{ with } \text{RREF}(A) = \begin{bmatrix} 1 & 0 & 1 & -2 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Sol RREF(A) has leading 1's in column 1 and column 2.

\Rightarrow A basis of $\text{Col}(A)$ is given by

$$\vec{v}_1 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \text{ and } \vec{v}_2 = \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix} \text{ (column 1 and column 2 in } A)$$

We apply the Gram-Schmidt process.

$$\vec{u}_1 = \vec{v}_1 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix},$$

$$\vec{u}_2 = \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 = \vec{v}_2 - \frac{6}{6} \vec{u}_1 = \vec{v}_2 - \vec{u}_1 = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}.$$

\Rightarrow $\text{Col}(A)$ has an orthogonal basis given by

$$\boxed{\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}}$$

(2) The null space of

$$B = \begin{bmatrix} 2 & 1 & -1 & 3 \\ 1 & 0 & -1 & 0 \\ -1 & 1 & 2 & 3 \end{bmatrix} \text{ with } \text{RREF}(B) = \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Sol We solve the equation $B\vec{x} = \vec{0}$ using RREF(B).

$$\begin{cases} x_1 - x_3 = 0 \\ x_2 + x_3 + 3x_4 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = x_3 \\ x_2 = -x_3 - 3x_4 \end{cases} \Rightarrow \vec{x} = s \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

\Rightarrow A basis of $\text{Nul}(B)$ is given by

$$\vec{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix} \text{ and } \vec{v}_2 = \begin{bmatrix} 0 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

The Gram-Schmidt process yields

$$\vec{u}_1 = \vec{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix},$$

$$\vec{u}_2 = \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 = \vec{v}_2 - \frac{3}{3} \vec{u}_1 = \vec{v}_2 - \vec{u}_1 = \begin{bmatrix} -1 \\ -2 \\ -1 \\ 1 \end{bmatrix}.$$

$\Rightarrow \text{Nul}(B)$ has an orthogonal basis given by

$$\boxed{\begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -2 \\ -1 \\ 1 \end{bmatrix}}$$

(3) The row space of

$$C = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & -1 & 1 & 2 \\ 2 & 0 & 1 & 1 \end{bmatrix} \text{ with } \text{RREF}(C) = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 3 \end{bmatrix}.$$

Sol A basis of $\text{Row}(C)$ is given by the nonzero rows in $\text{RREF}(C)$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 3 \end{bmatrix}.$$

The Gram-Schmidt process yields

$$\vec{u}_1 = \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix},$$

$$\vec{u}_2 = \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 = \vec{v}_2 + \frac{1}{2} \vec{u}_1 = \frac{1}{2} \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix} \rightsquigarrow \vec{u}'_2 = 2\vec{u}_2 = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix},$$

$$\vec{u}_3 = \vec{v}_3 - \frac{\vec{v}_3 \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 - \frac{\vec{v}_3 \cdot \vec{u}_2}{\vec{u}_2 \cdot \vec{u}_2} \vec{u}'_2 = \vec{v}_3 + \frac{3}{2} \vec{u}_1 - \frac{1}{2} \vec{u}'_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}.$$

$\Rightarrow \text{Row}(C)$ has an orthogonal basis given by

$$\boxed{\begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}}$$