

## Lecture 24. Diagonalization

Def Let  $A$  be an  $n \times n$  matrix.

(1) A diagonalization of  $A$  is an expression

$$A = PDP^{-1}$$

with an invertible matrix  $P$  and a diagonal matrix  $D$ .

(2) An eigenbasis for  $A$  is a basis of  $\mathbb{R}^n$  whose elements are all eigenvectors of  $A$ .

Thm An  $n \times n$  matrix  $A$  has a diagonalization

$\Leftrightarrow \mathbb{R}^n$  has an eigenbasis for  $A$ .

pf Take the linear transformation  $T$  with standard matrix  $A$   
 $\mathbb{R}^n$  has an eigenbasis  $\mathcal{B} = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  for  $A$   
(with  $A\vec{v}_i = \lambda_i \vec{v}_i$  for some  $\lambda_i \in \mathbb{R}$ )

$\Leftrightarrow \mathbb{R}^n$  has a basis  $\mathcal{B}$  such that the  $\mathcal{B}$ -matrix of  $T$  is

$$A_{\mathcal{B}} = \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix} \text{ diagonal}$$

$\Leftrightarrow A = PDP^{-1}$  with  $D = A_{\mathcal{B}}$  being diagonal

Note For a diagonalization  $A = PDP^{-1}$ , the columns of  $P$  form an eigenbasis for  $A$  with the corresponding eigenvalues given by the diagonal entries of  $D$ .

Prop Let  $A$  be an  $n \times n$  matrix.

(1) Eigenvectors of  $A$  that correspond to distinct eigenvalues are linearly independent.

(2)  $\mathbb{R}^n$  has an eigenbasis for  $A$

$\Leftrightarrow$  The geometric multiplicities of all eigenvalues add up to  $n$

Note If  $\mathbb{R}^n$  has an eigenbasis for  $A$ , it is formed by merging bases of all eigenspaces.

Prop If an  $n \times n$  matrix  $A$  has  $n$  distinct eigenvalues, it has a diagonalization.

pf  $A$  has  $n$  distinct eigenvalues  $\alpha_1, \alpha_2, \dots, \alpha_n$

$$\Rightarrow P_A(\lambda) = (\lambda - \alpha_1)(\lambda - \alpha_2) \cdots (\lambda - \alpha_n)$$

$\Rightarrow$  All eigenvalues of  $A$  have algebraic multiplicity 1

$\Rightarrow$  All eigenvalues of  $A$  have geometric multiplicity 1

$\Rightarrow$  The geometric multiplicities of all eigenvalues add up to  $n$

$$(1+1+\cdots+1=1 \cdot n=n)$$

$\Rightarrow \mathbb{R}^n$  has an eigenbasis for  $A$

$\Rightarrow A$  has a diagonalization

Note It is possible that  $A$  has a diagonalization without having  $n$  distinct eigenvalues.

Ex If possible, diagonalize each matrix by writing it as  $PDP^{-1}$  with an invertible matrix  $P$  and a diagonal matrix  $D$ .

$$(1) \quad A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\underline{\text{Sol}} \quad P_A(\lambda) = \lambda^2 - (2+2)\lambda + (2 \cdot 2 - 1 \cdot 1) = \lambda^2 - 4\lambda + 3 = (\lambda - 1)(\lambda - 3)$$

$\Rightarrow A$  has eigenvalues  $\lambda = 1, 3$

$\Rightarrow A$  is diagonalizable (2x2 matrix with 2 distinct eigenvalues)

$$A - I = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \Rightarrow \text{RREF}(A - I) = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

$$(A - I)\vec{x} = \vec{0} \Rightarrow x_1 + x_2 = 0 \Rightarrow x_1 = -x_2 \Rightarrow \vec{x} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\Rightarrow \text{Nul}(A - I) \text{ has a basis given by } \vec{v} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$A - 3I = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \Rightarrow \text{RREF}(A - 3I) = \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$$

$$(A - 3I)\vec{x} = \vec{0} \Rightarrow x_1 - x_2 = 0 \Rightarrow x_1 = x_2 \Rightarrow \vec{x} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow \text{Nul}(A - 3I) \text{ has a basis given by } \vec{w} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Hence  $A$  has a diagonalization  $A = PDP^{-1}$  with

$$P = \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad D = \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}$$

$\vec{v} \quad \vec{w}$

eigenvalues  
for  $\vec{v}, \vec{w}$   
(in order!)

$$(2) \quad B = \begin{bmatrix} 3 & 0 & 2 \\ 0 & 3 & 4 \\ 0 & 0 & 1 \end{bmatrix}$$

Sol B is triangular  $\Rightarrow$  B has eigenvalues  $\lambda = 1, 3$  (diagonal entries)

$$\lambda = 1 : B - I = \begin{bmatrix} 2 & 0 & 2 \\ 0 & 2 & 4 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{RREF}(B - I) = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{array}{l} \text{col 3 with} \\ \text{no leading 1's} \end{array}$$

$$\Rightarrow \dim(\text{Nul}(B - I)) = 1$$

$$\lambda = 3 : B - 3I = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 0 & 4 \\ 0 & 0 & -2 \end{bmatrix} \Rightarrow \text{RREF}(B - 3I) = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{array}{l} \text{col 1, col 2 with} \\ \text{no leading 1's} \end{array}$$

$$\Rightarrow \dim(\text{Nul}(B - 3I)) = 2$$

B is diagonalizable. (sum of geometric multiplicities:  $1 + 2 = 3$ )

$$(B - I)\vec{x} = \vec{0} \Rightarrow \begin{cases} x_1 + x_3 = 0 \\ x_2 + 2x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = -x_3 \\ x_2 = -2x_3 \end{cases} \stackrel{x_3=t}{\Rightarrow} \vec{x} = t \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}$$

$$\Rightarrow \text{Nul}(B - I) \text{ has a basis given by } \vec{u} = \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}$$

$$(B - 3I)\vec{x} = \vec{0} \Rightarrow x_3 = 0 \stackrel{\begin{array}{l} x_1=s \\ x_2=t \end{array}}{\Rightarrow} \vec{x} = s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow \text{Nul}(B - 3I) \text{ has a basis given by } \vec{v} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \vec{w} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Hence B has a diagonalization  $B = PDP^{-1}$  with

$P = \begin{bmatrix} -1 & 1 & 0 \\ -2 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$ and $D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$	<span style="color: orange;">eigenvalues for <math>\vec{u}, \vec{v}, \vec{w}</math> (in order!)</span>
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$\vec{u} \quad \vec{v} \quad \vec{w}$

$$(3) \quad C = \begin{bmatrix} 2 & 1 & 4 \\ 0 & 2 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

Sol  $C$  is triangular  $\Rightarrow C$  has eigenvalues  $\lambda = 1, 2$  (diagonal entries)

$$\lambda = 1 : C - I = \begin{bmatrix} 1 & 1 & 4 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{RREF}(C - I) = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix} \begin{array}{l} \text{col 3 with} \\ \text{no leading 1's} \end{array}$$

$$\Rightarrow \dim(\text{Nul}(C - I)) = 1$$

$$\lambda = 2 : C - 2I = \begin{bmatrix} 0 & 1 & 4 \\ 0 & 0 & 3 \\ 0 & 0 & -1 \end{bmatrix} \Rightarrow \text{RREF}(C - 2I) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{array}{l} \text{col 1 with} \\ \text{no leading 1's} \end{array}$$

$$\Rightarrow \dim(\text{Nul}(C - 2I)) = 1$$

$C$  is not diagonalizable (sum of geometric multiplicities:  $1+1=2$ )