

# BAKURETSU

29 de maig de 2019

## 1 Pre-Explosion

- P = momentum (initial i or final f)
- m = mass
- V = velocity
- C = particles

Explosion momentum:

$$P_i = P_f \quad (1)$$

$$\forall i \in C \quad m_i V_i = m_f V_f \quad (2)$$

$$\sum_i^n m_i V_i = P_f \quad (3)$$

Explosion angle:

- E = explosion center
- C = particle center
- V = velocity vector
- $\varphi$  = angle z-y
- $\theta$  = angle x-y

$$r = \sqrt{(E.y - C.y)^2 + (E.x - C.x)^2 + (E.z - C.z)^2}$$
$$V = (E.y - C.y), (E.x - C.x), (E.z - C.z)/r \quad (4)$$

$$\varphi = \arccos \frac{z}{r} \quad (5)$$

$$\theta = \arctan \frac{y}{x} \quad (6)$$

## 2 Post-Explosion

Parabolic fragment movement:

$$z = z_0 + v_0 t \sin \varphi \quad (7)$$

$$x = x_0 + v_0 t \cos \theta \quad (8)$$

$$y = -\frac{gt^2}{2} + y_0 + v_0 t \sin \theta \cos \varphi \quad (9)$$

## Collision Detection: AABB

### Listing 1: 2D AABB

```
return ( rect1.x < rect2.x + rect2.width && rect1.x + rect1.width > rect2.x &&
        rect1.y < rect2.y + rect2.height && rect1.height + rect1.y > rect2.y );
```

## Collision Resolution: 3<sup>o</sup> law of newton and restitution

- rv : difference of velocities
- n: normal
- e: resolution

$$impulse = \frac{-(1 + e) * dot(rv, n)}{massA + massB} n \quad (10)$$

$$velocityA = impuls / massA \quad (11)$$

$$velocityB = impuls / massB \quad (12)$$

### Listing 2: 2D Collision resolution

```
void Shape::resolveCollision(Shape& A, Shape& B)
{
    // Calculate relative velocity
    sf::Vector2f rv = B.velocity - A.velocity;
    sf::Vector2f n = B.pos - A.pos;
    n /= sqrt(n.x*n.x + n.y*n.y);
    // Calculate relative velocity in terms of the normal direction
    float velAlongNormal = rv.x * n.x + rv.y * n.y;

    // Do not resolve if velocities are separating
    if (velAlongNormal > 0) return;

    // Calculate restitution
    float e = (A.material.restitution < B.material.restitution) ?
        A.material.restitution : B.material.restitution;

    // Calculate impulse scalar
    float j = -(1 + e) * velAlongNormal;
    j /= A.massData.invMass + B.massData.invMass;

    // Apply impulse
    sf::Vector2f impulse = j * n;
    A.velocity -= A.massData.invMass * impulse;
    B.velocity += B.massData.invMass * impulse;
}
```