<untitled> #21

```
MODELS
Model-01
               Flashlight
Model-02
               Radio
Model-03
              Toy Car
Model-04
               Ball Point Pen
If model-01 is disassemble in line -- 1; otherwise -- 0 = 1
If model-02 is disassemble in line -- 1; otherwise -- \theta = \theta
If model-03 is disassemble in line -- 1; otherwise -- 0 = 0
If model-04 is disassemble in line -- 1; otherwise -- 0 = 1
Warning: your license will expire in 3 days
-----
Using license file C:\gurobi903\win64\bin\gurobi.lic
Academic license - for non-commercial use only
Gurobi Optimizer version 9.0.3 build v9.0.3rc0 (win64)
Optimize a model with 4131 rows, 567 columns and 20520 nonzeros
Model fingerprint: 0xedc3a598
Variable types: 30 continuous, 537 integer (537 binary)
Coefficient statistics:
 Matrix range
                  [1e+00, 1e+05]
 Objective range [5e-06, 1e+00]
 Bounds range
                [1e+00, 1e+00]
 RHS range
                 [1e+00, 3e+05]
Presolve removed 3775 rows and 396 columns
Presolve time: 0.05s
Presolved: 356 rows, 171 columns, 2356 nonzeros
Variable types: 23 continuous, 148 integer (148 binary)
Found heuristic solution: objective 3.0122300
Found heuristic solution: objective 3.0122260
Root relaxation: objective 1.440298e+00, 217 iterations, 0.00 seconds
```

	Nodes	5	Current	: Node	2	Object:	ive Bounds	I	Worl	<
Ex	pl Une	expl	Obj Dept	h Int	tInf	Incumbent	BestBd	Gap	It/Node	Time
	0	0	1.44030	0	30	3.01223	1.44030	52.2%	_	0s
	0	0	2.00523	0	27	3.01223	2.00523	33.4%	_	0s
Н	0	0				3.0102300	2.00523	33.4%	-	0s
	0	0	2.00523	0	25	3.01023	2.00523	33.4%	-	0s
	0	0	2.00639	0	30	3.01023	2.00639	33.3%	-	0s
Н	0	0				3.0092300	2.00639	33.3%	-	0s
	0	0	2.00641	0	34	3.00923	2.00641	33.3%	-	0s
	0	0	2.00675	0	27	3.00923	2.00675	33.3%	-	0s
	0	0	2.00675	0	27	3.00923	2.00675	33.3%	-	0s
	0	2	2.00675	0	27	3.00923	2.00675	33.3%	-	0s

Cutting planes: Learned: 3

Page 1, last modified [no file date] [no file time]

<untitled> #21

Gomory: 2 Cover: 15 Clique: 15 MIR: 9

Flow cover: 6 GUB cover: 1 Zero half: 3

RLT: 1

Relax-and-lift: 2

Explored 24 nodes (752 simplex iterations) in 0.23 seconds Thread count was 4 (of 4 available processors)

Solution count 4: 3.00923 3.01023 3.01223 3.01223

Optimal solution found (tolerance 1.00e-04) Best objective 3.009230000000e+00, best bound 3.009230000000e+00, gap 0.0000% <gurobi.Model MIP instance MILP Model: 4131 constrs, 567 vars, No parameter changes>

Solution Results

Time = 0.652289867401123 second

Total number of stations opened from both sides : : Total number of stations opened from only one side 1.0 Total number of stations opened 5.0

####	MODEL-	m1	####	
,	• 、		/· \	

#### MODEL- IIII	ππππ			
(m, i)	(j,s)	Processing Time	Starting Time	Ending Time
('m1', 1) :	[(1, 1)]	30	10.0	40.0
('m1', 3) :	[(2, 2)]	12	0.0	12.0
('m1', 6) :	[(2, 1)]	21	19.0	40.0
('m1', 7) :	[(2, 1)]	6	12.0	18.0
('m1', 9) :	[(2, 2)]	25	15.0	40.0
('m1', 10) :	[(3, 2)]	10	0.0	10.0
#### MODEL- m4	####			
(m, i)	(j,s)	Processing Time	Starting Time	Ending Time
('m4', 1) :	[(1, 1)]	5	0.0	5.0
('m4', 4) :	[(1, 2)]	7	22.0	29.0
('m4', 6) :	[(1, 2)]	11	29.0	40.0
('m4', 9) :	[(1, 2)]	16	5.0	21.0
('m4', 11) :	[(2, 1)]	33	0.0	33.0
('m4', 13) :	[(1, 1)]	6	34.0	40.0
('m4', 17) :	[(3, 2)]	16	0.0	16.0
('m4', 18) :	[(2, 2)]	32	0.0	32.0

Page 2, last modified [no file date] [no file time]