

**MARMARA UNIVERSITY**

**FACULTY OF ENGINEERING DEPARTMENT OF**

**COMPUTER SCIENCE ENGINEERING**

**CSE 2046 – ANALYSIS OF ALGORITHMS**

**COMPARING SORTING ALGORITHMS**

**STUDENTS NUMBERS**

Serkan Koç 150118073

İbrahim Hakkı Candan 150118061

Atila İlhan Yatağan 150118033

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Asst.Prof. Ömer Korçak 11.05.2022

**Purpose of the Project**

The main goal of this project is to design an experiment to compare different algorithms for the selection problem (i.e., finding *k*’ th smallest element in an unsorted list of n numbers.) and to compare our findings with theoretical complexity values.

Algorithms used in the comparisons:

1. Insertion-sort
2. Merge-sort
3. Quick-sort
4. Partial selection-sort
5. Partial heap-sort
6. Quick select algorithm (based on array partitioning, first element as pivot)
7. Quick select algorithm (median-of-three pivot selection)

**Step 1: Designing the Experiment:**

**Deciding on reasonable inputs:**

This part of the report only explains the input selections for each algorithm. Extensive explanations for each algorithm is provided individually.

Different input sizes for algorithms are selected as 100,500,1000,10000. The purpose of selecting such input sizes is to make the comparisons (the empirical results of the experiments) easier.

**1) Insertion-sort inputs**

Insertion sort is a decrease and conquer algorithm and a simple sorting algorithm that is based on splitting an array into two parts as sorted and unsorted.

* The best-case input is an array that is already sorted. In this case insertion sort has a linear running time (i.e., O(*n*))
* The simplest worst-case input is an array sorted in reverse order. The set of all worst-case inputs consists of all arrays where each element is the smallest or second smallest of the elements before it. This gives insertion sort a quadratic running time (i.e., O(*n*2))
* The average case is also quadratic, which makes insertion sort impractical for sorting large arrays. Average case input is an array that is not sorted. (random elements)

1. **Merge-sort inputs**

Merge sort is a divide and conquer algorithm. It divides the input array into two halves, calls itself for the two halves, and then merges the two sorted halves. The time complexity of all cases is O(nlogn).

* Best case input is a sorted array in ascending order algorithm to reduce the comparisons between the elements.
* Worst case input is a permutation that parses the array into n parts and reorganizes according to the algorithm. We took inputs that have 2n elements.
* Average case, random inputs that generated with varied sizes.

1. **Quick-sort inputs**

Quick Sort algorithm depends on choosing a pivot among items and finding its correct place in the array. After that array is divided into two parts from the point that pivot exists at, and the process keeps go on recursively until correct places of all items are found. Thereby array becomes sorted.

* Best case input choosing first element pivot emerges when correct position of the pivot divides array into two equal parts. And this can be possible when array is unsorted and items randomly distributed.
* Worst case input of choosing the first element as pivot emerges when the array is already sorted ascending or descending order. Since every item is already located at their correct position, when partitioning process ended array is divided into very unbalanced parts.
* Average case, random inputs that generated with varied sizes.

1. **Partial selection-sort inputs**
2. **Partial heap-sort inputs**

Heap sort is a comparison-based sorting technique based on Binary Heap data structure. It is like selection sort where we first find the minimum element and place the minimum element at the beginning. We repeat the same process for the remaining elements.

* Best case input for heap sort is when all the elements are equal. In this case, no max heapify needs to be performed.
* Worst case input for heap sort might happen when all elements in the list are distinct or reversed listed (ascending order for min heap, descending order for max heap. Therefore, we would need to call max heapify every time we remove an element.
* Average case, random inputs that generated with varied sizes.

1. Quick select algorithm (based on array partitioning, first element as pivot)
2. Quick select algorithm (median-of-three pivot selection)

**Inputs burada bitecek !!**

**Insertion Sort**

Insertion sort is a simple [sorting algorithm](https://en.wikipedia.org/wiki/Sorting_algorithm) that builds the final [sorted array](https://en.wikipedia.org/wiki/Sorted_array) (or list) one item at a time. It is much less efficient on large lists than more advanced algorithms such as [quicksort](https://en.wikipedia.org/wiki/Quicksort), [heapsort](https://en.wikipedia.org/wiki/Heapsort), or [merge sort](https://en.wikipedia.org/wiki/Merge_sort).

**Insertion Sort Algorithm**

1. Set a marker for sorted section after the first element
2. Repeat the following until unsorted section is empty

* Select the first unsorted element
* Swap other elements to the right to create the correct position and shift the unsorted element
* Advance the marker to the next element

**Insertion Sort Visualization**

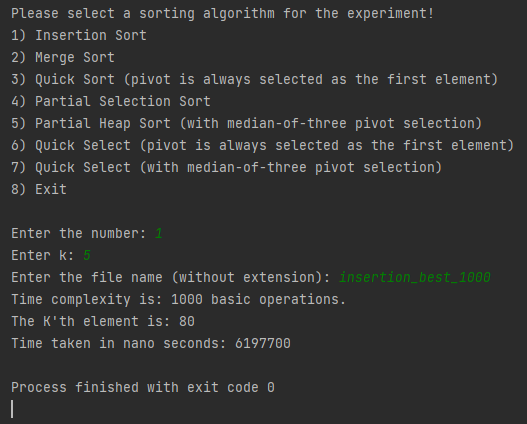
** Insertion Sort Time Complexity Analysis**

* **Best Case Complexity:** The insertion sort algorithm has a best-case time complexity of **O(n)** for the already sorted array because here, only the outer loop is running n times, and the inner loop is kept still.
* **Average Case Complexity:** The average-case time complexity for the insertion sort algorithm is **O(n2)**, which is incurred when the existing elements are in jumbled order, i.e., neither in the ascending order nor in the descending order.
* **Worst Case Complexity:** The worst-case time complexity is also **O(n2)**, which occurs when we sort the ascending order of an array into the descending order.  
  In this algorithm, every individual element is compared with the rest of the elements, due to which n-1 comparisons are made for every nthelement.

**Insertion Sort Experiment Results**

**Best case examples:**

**metin içeren bir resim

Açıklama otomatik olarak oluşturuldu **

**Worst case examples:**

**metin içeren bir resim

Açıklama otomatik olarak oluşturuldu metin içeren bir resim

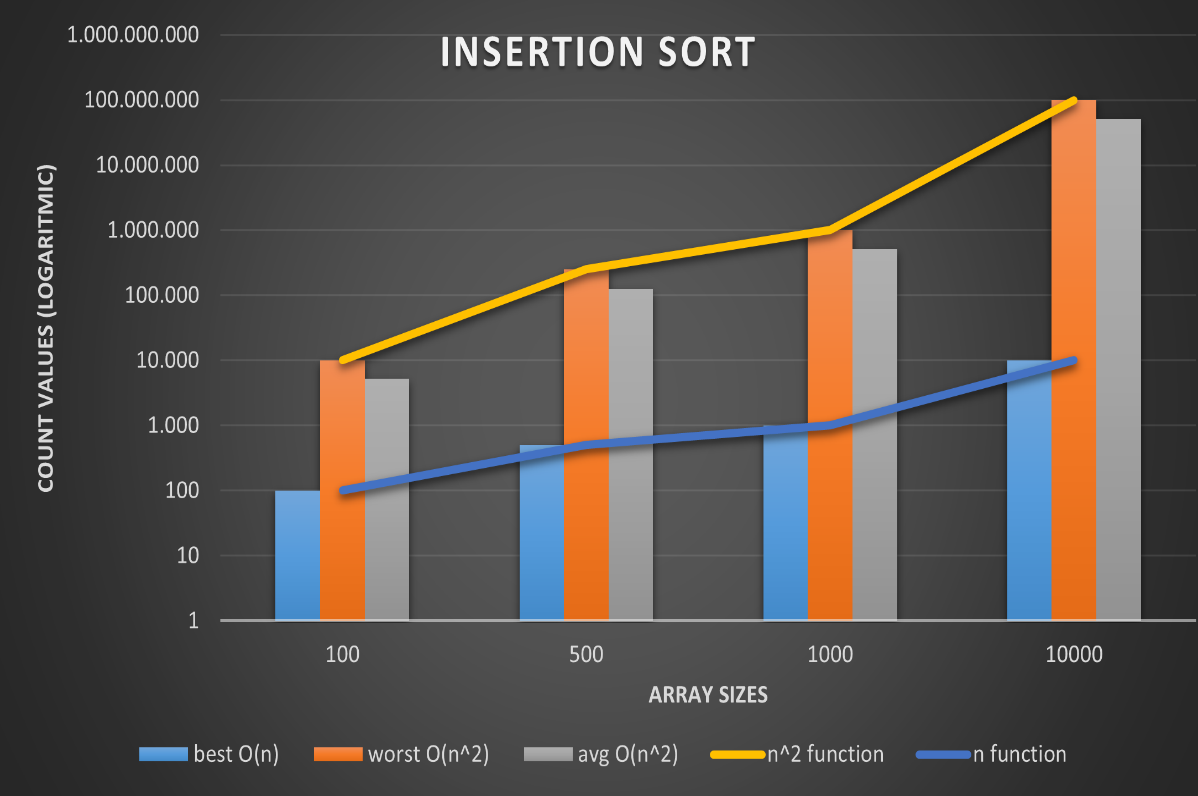
Açıklama otomatik olarak oluşturuldu**

**Average case examples:**

**metin içeren bir resim

Açıklama otomatik olarak oluşturuldu metin içeren bir resim

Açıklama otomatik olarak oluşturuldu**



**(This chart represents the results logarithmically)**

**Theoretical Expectations and Experiment Results Comparison**

**Approved Facts:**

Insertion sort theoretical time complexity expectation for best case is big O of *n* when the list is already sorted, and our experiment met with this fact.

In insertion experiment we saw that experimental results met with theoretical expectations. We confirmed that by looking at the chart above, for variant input sizes, the experimental results do not exceed the real *n^2* (shown in yellow)function for worst and average cases.

**For each individual input size scenario, the experimental results for basic operation counts turned out as expected in the theoretical analysis.**

* Big o of **n** for best case
* Big o of **n^2** for average and worst cases
* Average case (random list) is always smaller than the worst case (reverse ordered list) in basic operations count.

**Experimental Disjunctions:**

**No experimental disjunction has seen in the experiments for insertion sort.**

**Partial Heapsort**

**Partial sorting** is a [relaxed](https://en.wikipedia.org/wiki/Relaxation_(approximation)) variant of the [sorting](https://en.wikipedia.org/wiki/Sorting_algorithm) problem. Total sorting is the problem of returning a list of items such that its elements all appear in order, while partial sorting is returning a list of the *k* smallest (or *k* largest) elements in order. The other elements (above the *k* smallest ones) may also be sorted, as in an in-place partial sort, or may be discarded, which is common in streaming partial sorts.

**Heapsort** is a [comparison-based](https://en.wikipedia.org/wiki/Comparison_sort) [sorting algorithm](https://en.wikipedia.org/wiki/Sorting_algorithm). Heapsort can be thought of as an improved [selection sort](https://en.wikipedia.org/wiki/Selection_sort): like selection sort, heapsort divides its input into a sorted and an unsorted region, and it iteratively shrinks the unsorted region by extracting the largest element from it and inserting it into the sorted region. Unlike selection sort, heapsort does not waste time with a linear-time scan of the unsorted region; rather, heap sort maintains the unsorted region in a [heap](https://en.wikipedia.org/wiki/Heap_(data_structure)) data structure to more quickly find the largest element in each step.

**Binary Heap:**

A **complete binary tree** is a binary tree in which all the levels are filled except the lowest one, which is filled from the left.

Complete binary tree is just like a full binary tree, but with two major differences.

1) All the leaf elements must lean towards the left. 2)The last leaf element might not have a right sibling i.e. a complete binary tree doesn't have to be a full binary tree.

A [**Binary**](https://www.geeksforgeeks.org/binary-heap/) **Heap** is a Complete Binary Tree where items are stored in a special order such that value in a parent node is greater (or smaller) than the values in its two child’s nodes. The former is called as max heap and the latter is called min-heap. The heap can be represented by a binary tree or array.

Since a Binary Heap is a Complete Binary Tree, it can be easily represented as an array and the array-based representation is space-efficient. If the parent node is stored at index I, the left child can be calculated by 2 \* I + 1 and right child by 2 \* I + 2 (assuming the indexing starts at 0).

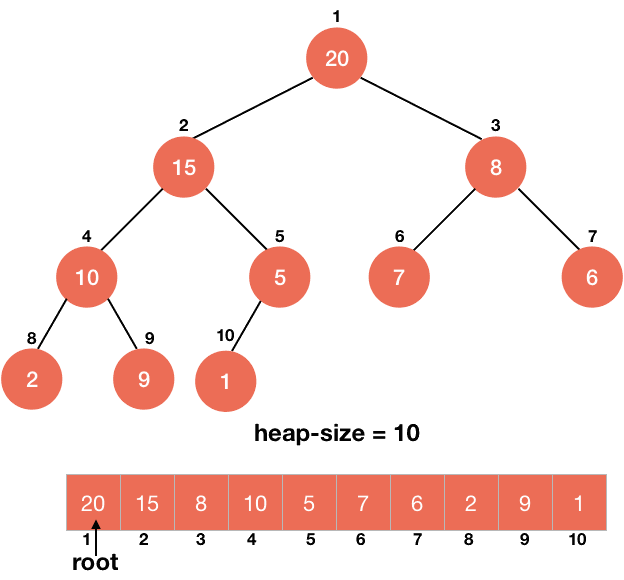
Heaps with **arrays with indexing** such as

* + Parent of a node i is ⌊i/2⌋
  + Left child of the node i is 2∗i
  + Right child of the node i is (2∗i) + 1
  + Max-heap property → The value of a node is greater than or equal to the value of its children i.e., A[Parent[i]] ≥ A[i] for all nodes i > 1.
  + Min-heap property → The value of a node is either smaller or equal to the value
  + of its children i.e., A[Parent[i]] ≤ A[i] for all nodes i >1.

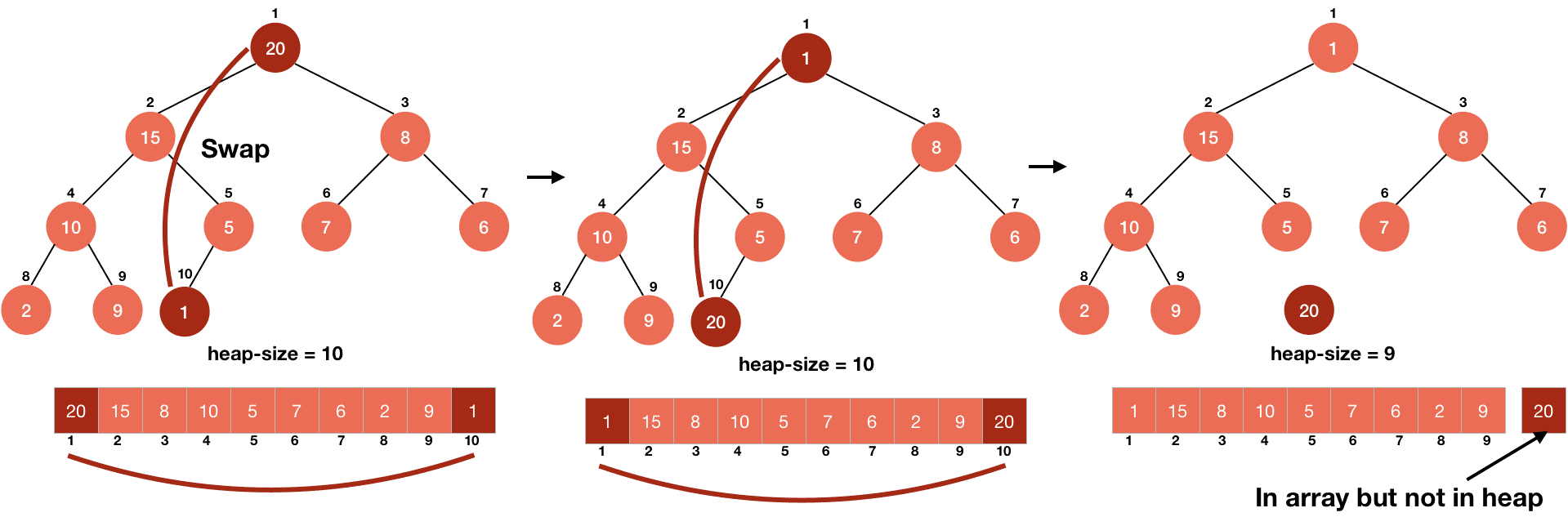
**Heap Sort Algorithm (for sorting in increasing order):**   
**1.** Build a max heap from the input data using heapify.  
**2.** At this point, the largest item is stored at the root of the heap. Replace it with the last item of the heap followed by reducing the size of heap by one. Finally, heapify the root of the tree.   
**3.** Repeat step 2 while size of the heap is greater than one.

**HEAPIFY** is a function used to maintain the heap property of any heap. It is applied to a node when the children of the node are following the property of a heap but the node itself may be violating it. It runs in O(logn) time.

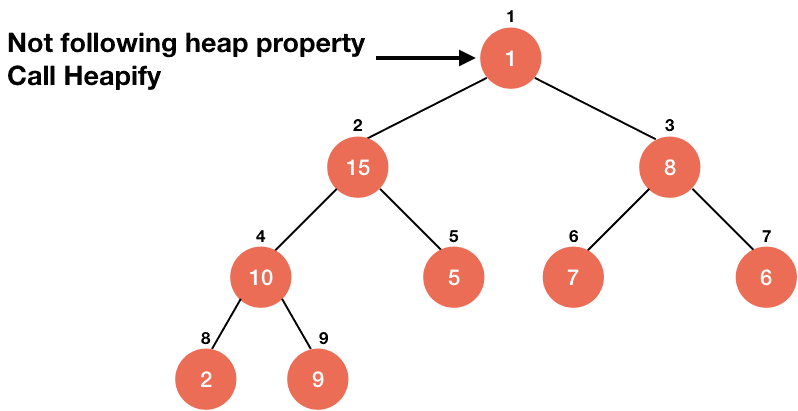
**Heapsort algorithm visualization**



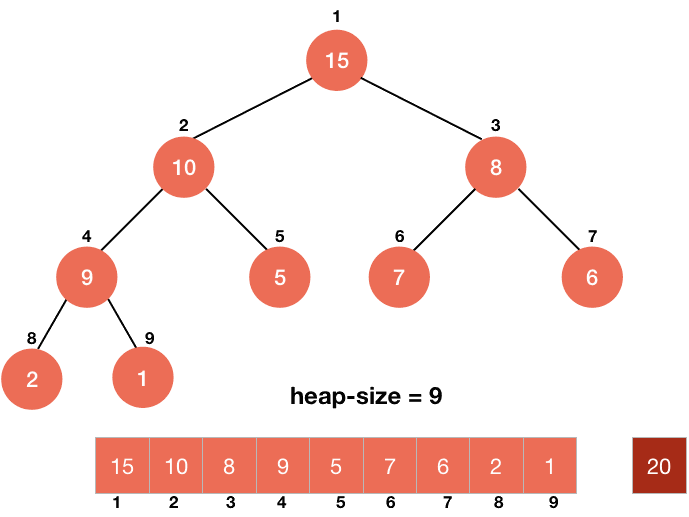
Now, we this maximum element must be at the last element of our sorted array. So, we swap it with the last element and then discard this element from the heap by reducing the size of the heap.



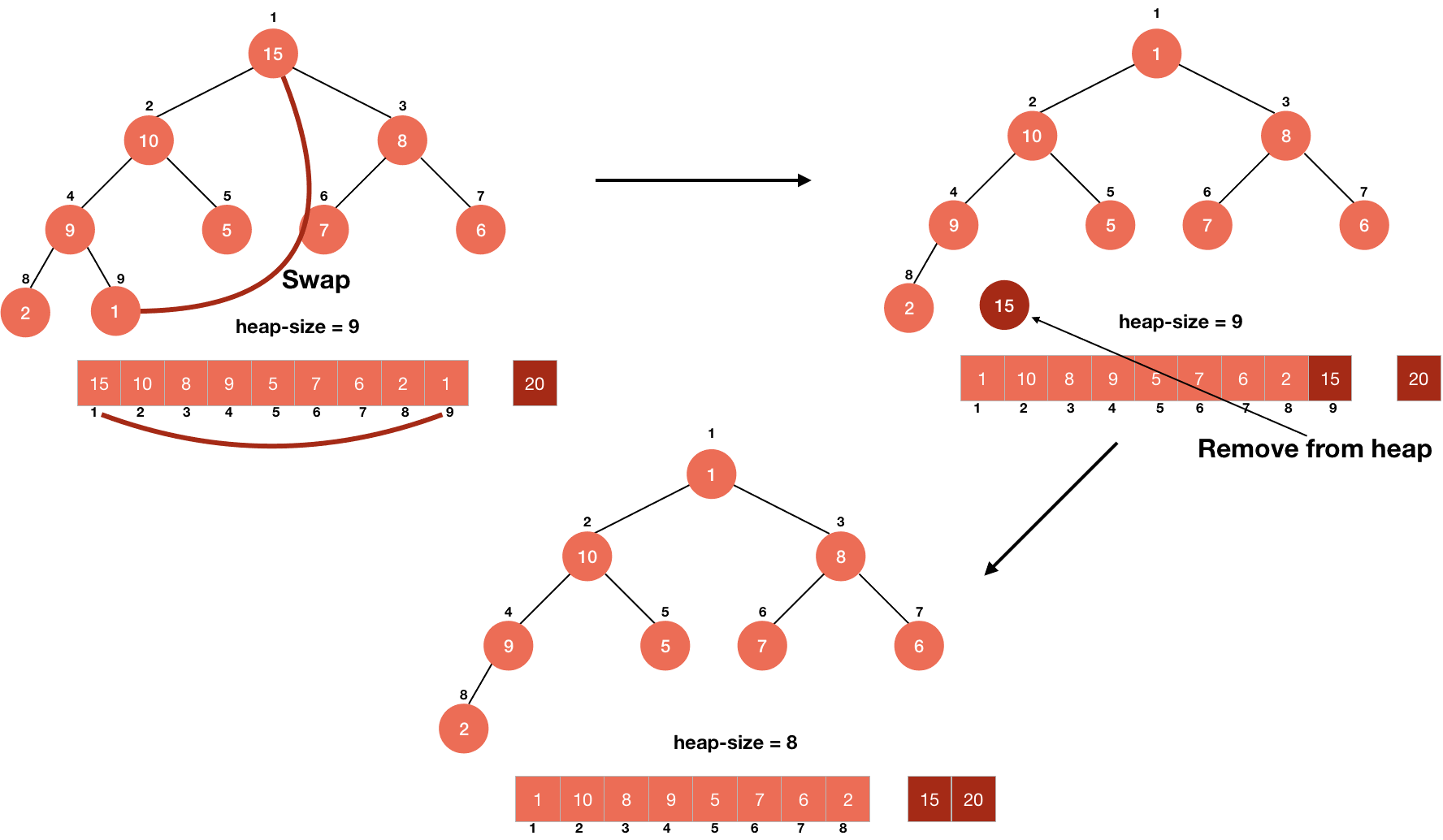
So, we have correctly put the largest element at the correct position, but in doing so, we have disturbed our heap or more precisely, the root of the heap because we haven't touched any child of the root yet. Thus, they are still following the max-heap property.

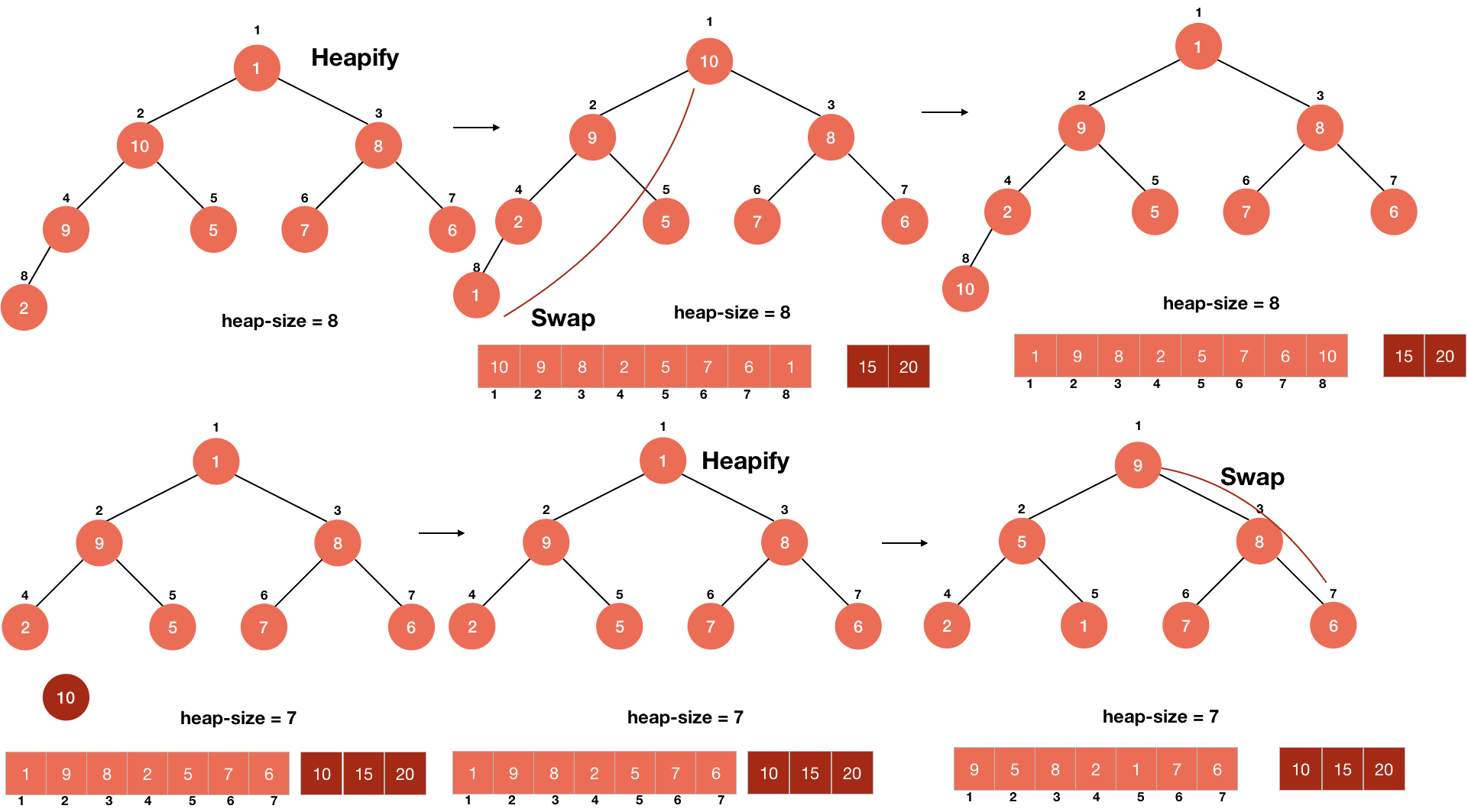


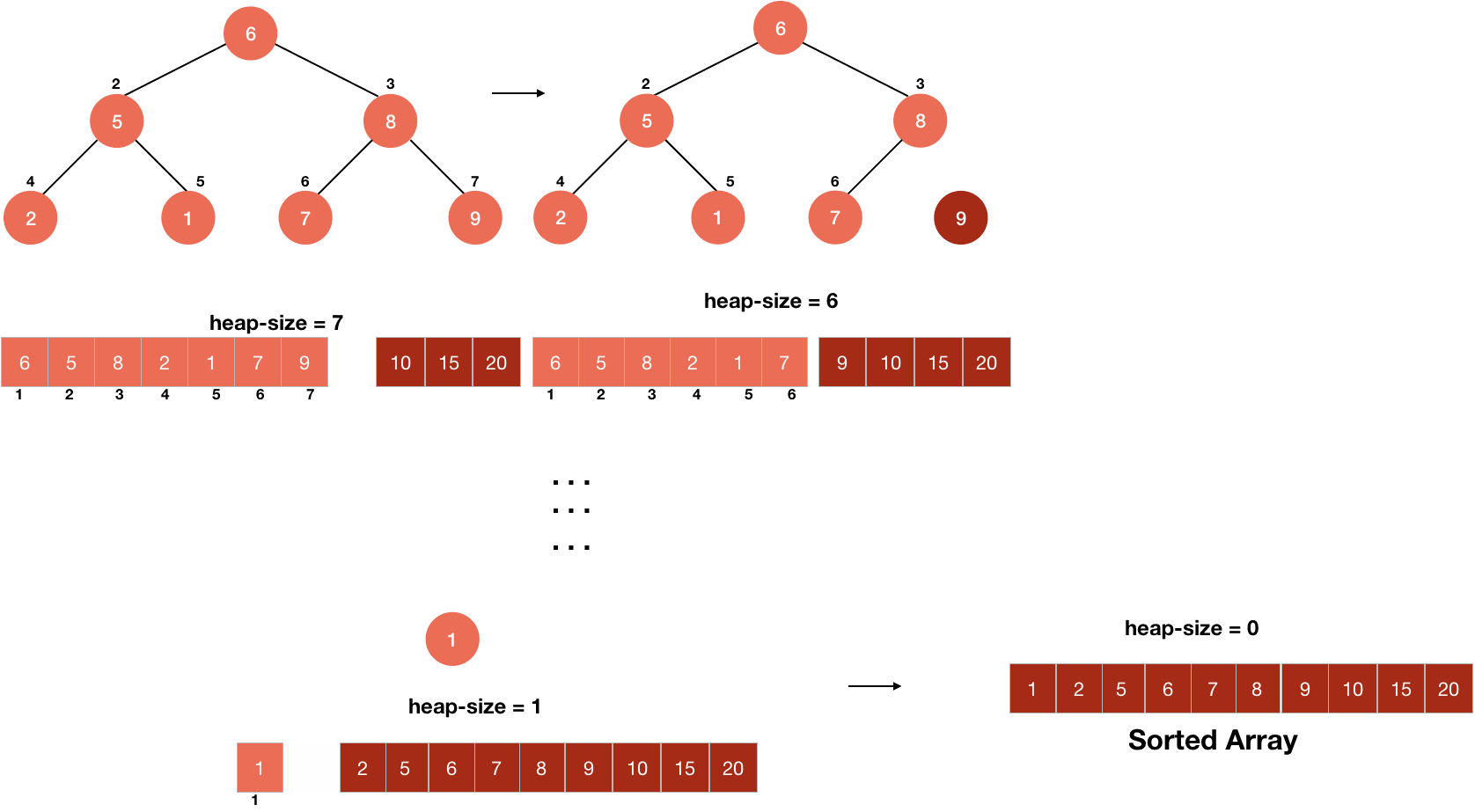
We can easily deal with this problem by calling HEAPIFY on the root of the tree and that will make our tree a max heap again, but this time the largest element won't be the part of the heap.



Now, we will just repeat this process until every element of the heap is correctly placed in sorted order.







**Difference Between Heap Sort and Partial Heap Sort**

Difference Between Heap Sort and Partial Heap Sort is the number of root deleting and heap rebuilding operations. In heap sort main goal is to build a heap and delete all the items one by one (only root items) and store them into the end of the array. This process continues until the last heap element has reached and deleted from the heap. On the other hand, in partial heap sort we only delete the necessary items after building the initial heap to reach the desired index or the subarray (which is sorted). This process reduces the time and computing power that is used for calculations. Reducing the number of operations makes a bigger impact when the desired index is smaller since we do not delete the root element and rebuild the heap repeatedly.

**Partial Heap Sort Experiment Results**

**metin içeren bir resim

Açıklama otomatik olarak oluşturuldu metin içeren bir resim

Açıklama otomatik olarak oluşturuldu**

**metin içeren bir resim

Açıklama otomatik olarak oluşturuldu metin içeren bir resim

Açıklama otomatik olarak oluşturuldu**

**metin içeren bir resim

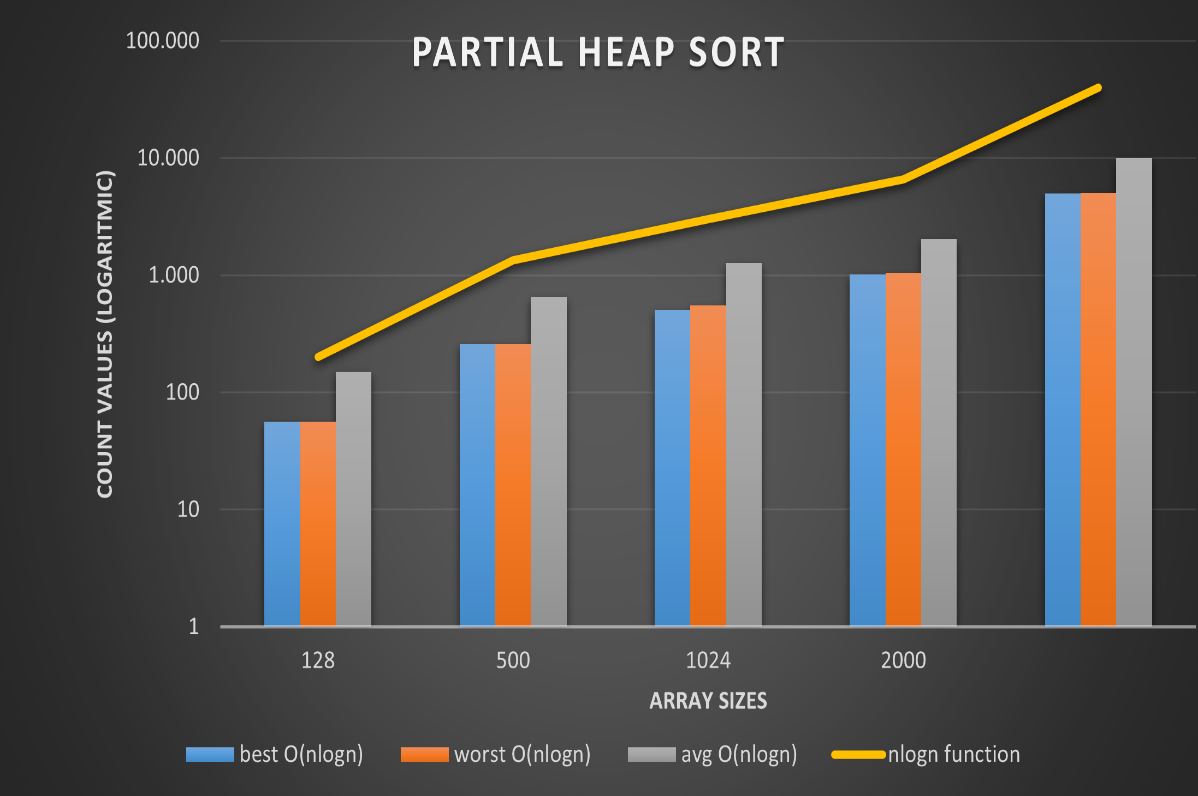
Açıklama otomatik olarak oluşturuldu metin içeren bir resim

Açıklama otomatik olarak oluşturuldu**

**metin içeren bir resim

Açıklama otomatik olarak oluşturuldu metin içeren bir resim

Açıklama otomatik olarak oluşturuldu**



**(This chart represents the results logarithmically)**

**Theoretical Expectations and Experiment Results Comparison**

**Approved Facts:**

Heap sort theoretical time complexity expectation was big O of *nlogn* for all best worst and average cases.

In heap sort experiment we saw that experimental results met with theoretical expectations. We confirmed that by looking at the chart above, for variant input sizes, the experimental results do not exceed the real *nlogn* function (shown in yellow).

**Experimental Disjunctions:**

**In heap sort experiment we expected that for each individual input size scenario the experimental results for basic operation counts would be same (or much closer to each other) but we could not approve it. As seen in the figure above average cases (which are random lists) always exceed the best and worst-case scenarios in basic operation counts.**