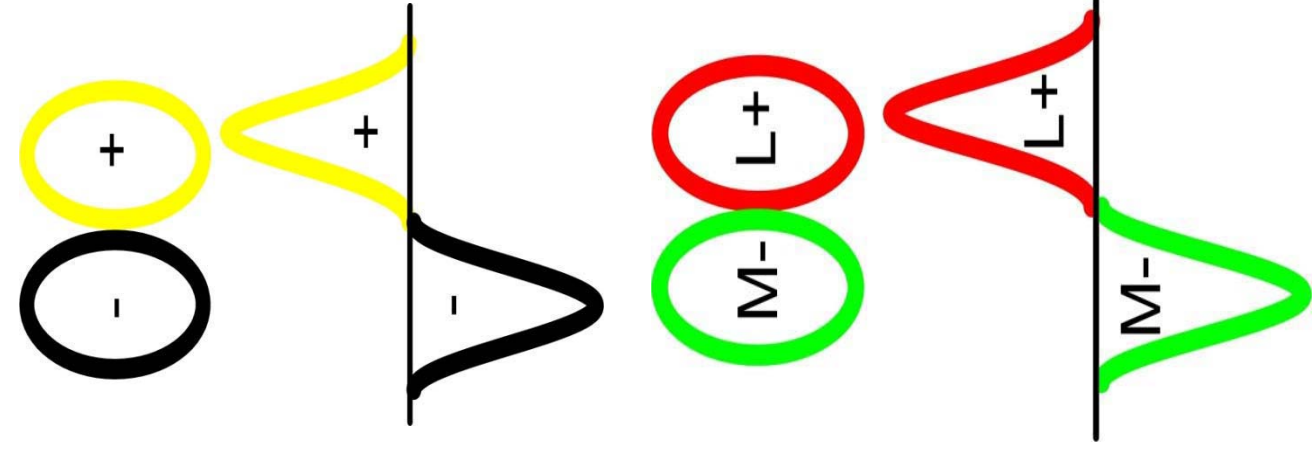
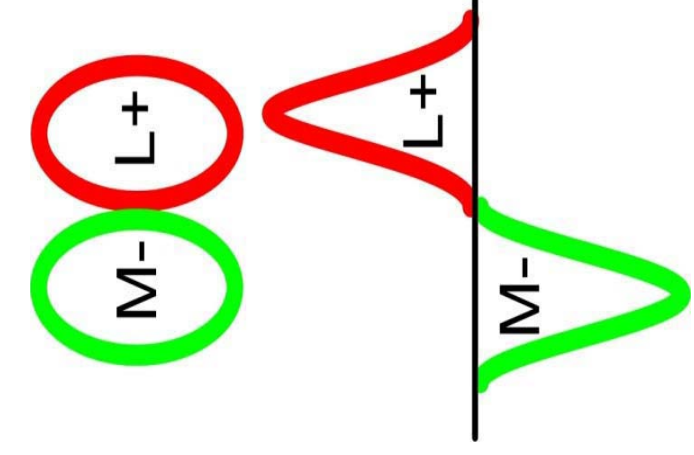


1. Motivation

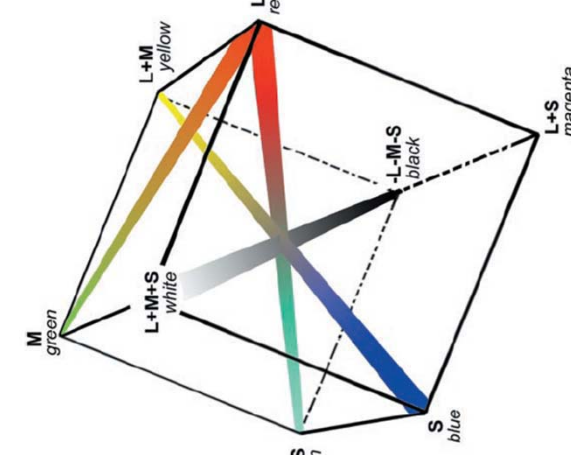
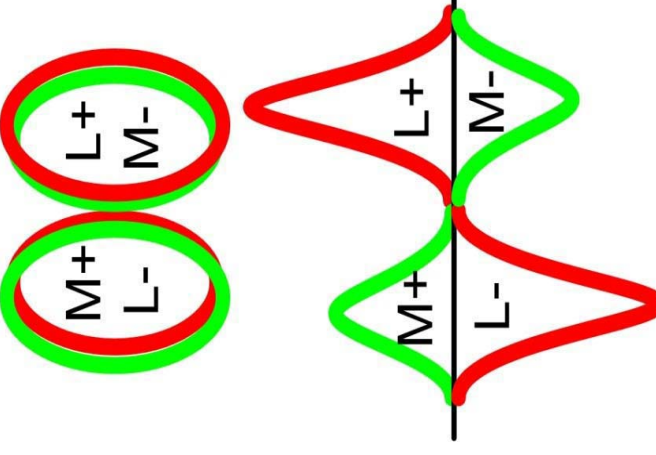
Luminance neurons with “ON” and “OFF” subunit organization are selective to orientations (and high spatial frequency) thus contribute to edge detection.



Single-Opponent (SO) neurons (color-prefering) with “ON” and “OFF” subunit organization with different cone inputs exhibit little or weak orientation selectivity but strong selectivity to color regions.



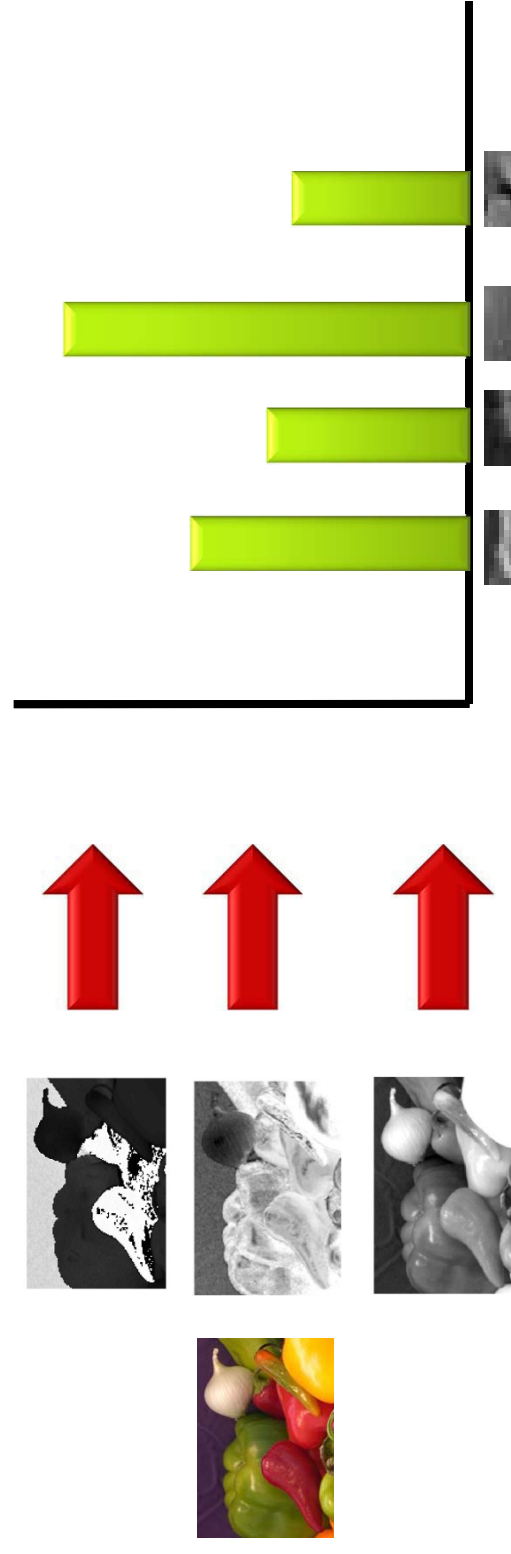
Double-Opponent (DO) neurons (color-luminance) with no defined “ON” and “OFF” subunit organization are selective for both color and orientations (and spatial frequency), and thought to influence the perception of form.



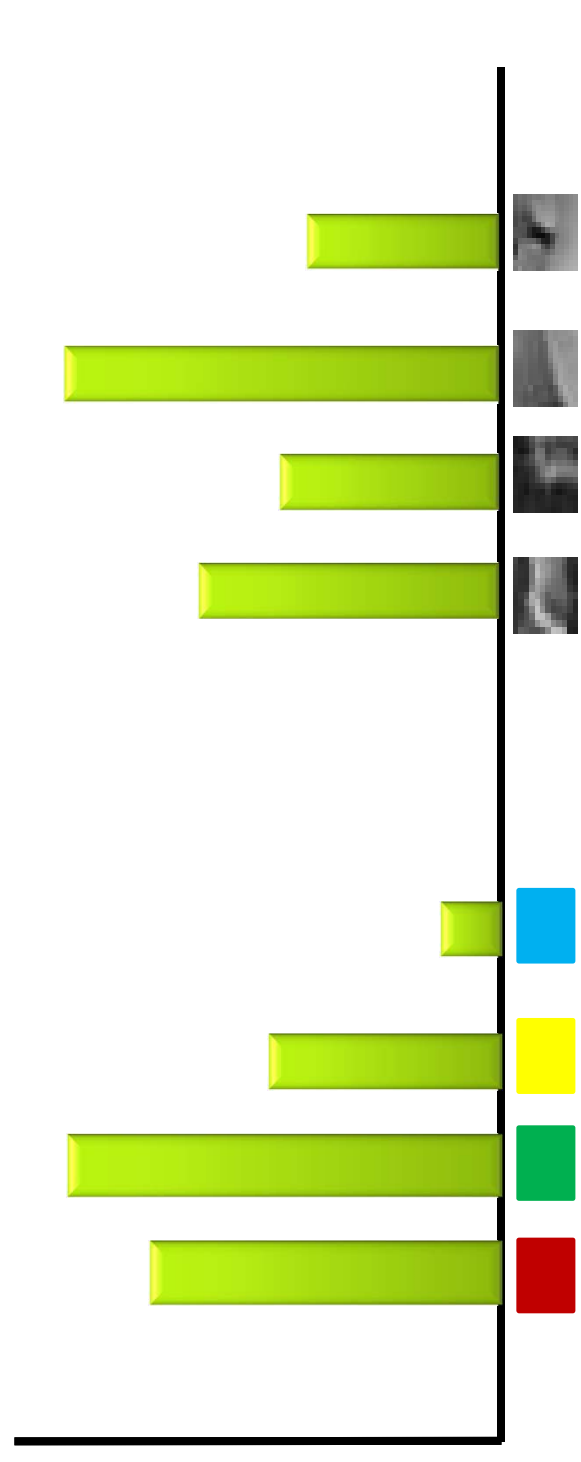
Consider chromatic axes as found in cortex.

2. Computer vision approaches

- Applying shape-based descriptors on individual color channels, e.g. HSV/SIFT.



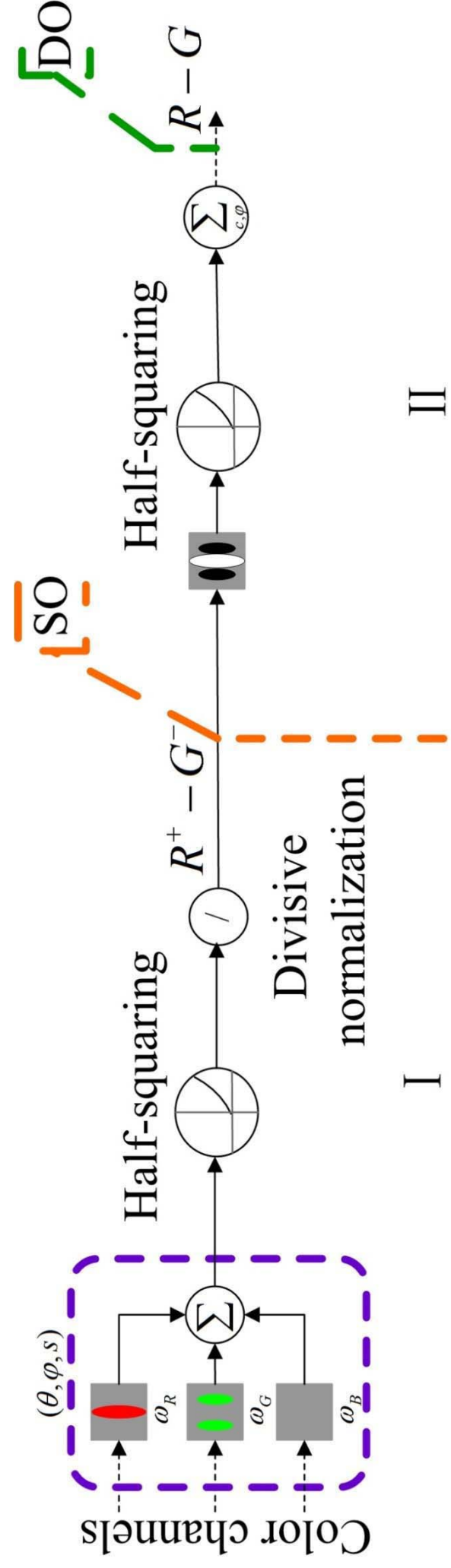
- Concatenation of shape-based descriptors with color histograms, e.g. HueSIFT.



3. Biological mechanisms

- Chromatic and spatial information should be represented **jointly** as done in the primate visual cortex.
- Neurons maintain **positive** firing rates, and neural circuits have been identified for **contrast gain controls**.

4. Approach overview



5. Approach details

Spatio-chromatic sensitivity function

$$f(x, y, \lambda) = w_R R(\lambda) f_R(x, y) + w_G G(\lambda) f_G(x, y) + w_B B(\lambda) f_B(x, y)$$

spatial sensitivity distribution excitatory/inhibitory center/surround component

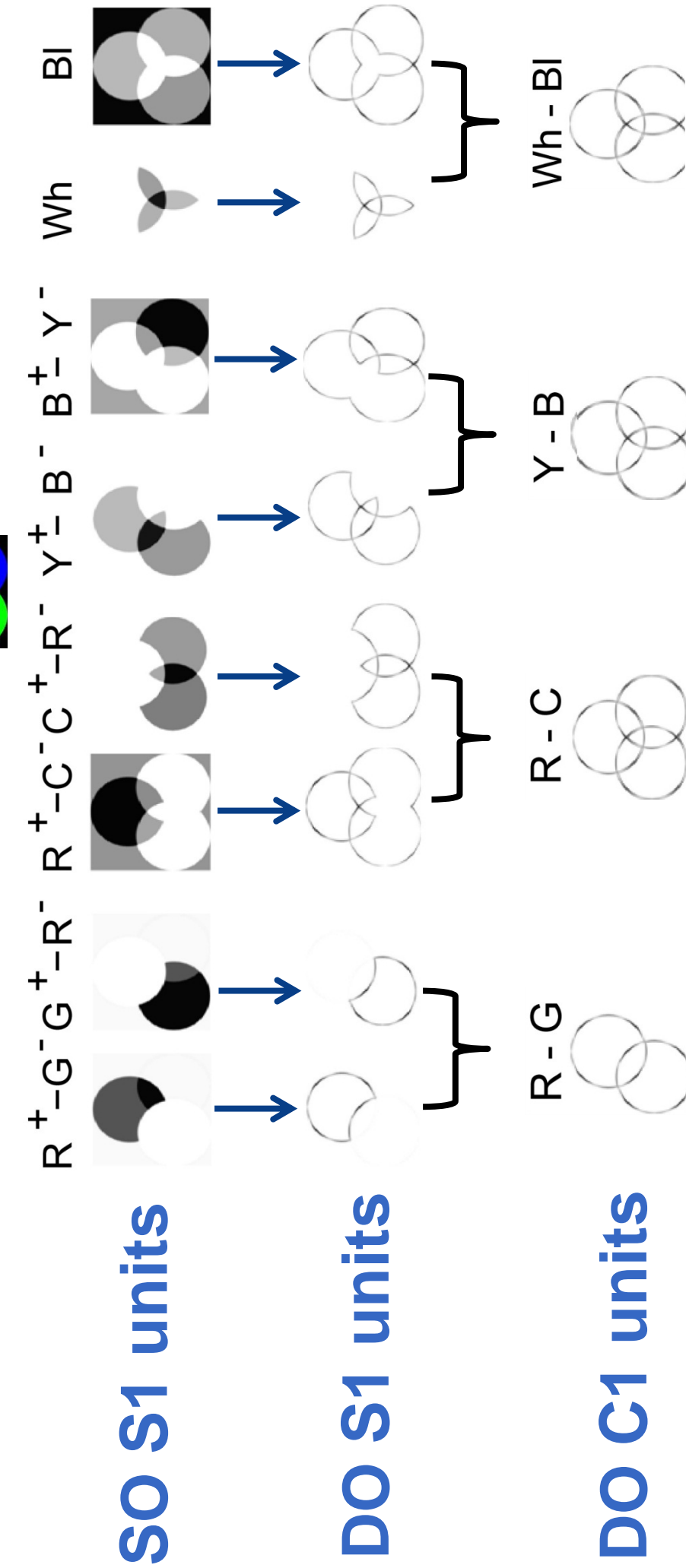
SO unit response: $s = I(x, y, \lambda) * f(x, y, \lambda)$

DO unit response: $d = s(x, y, c) * f(x, y)$

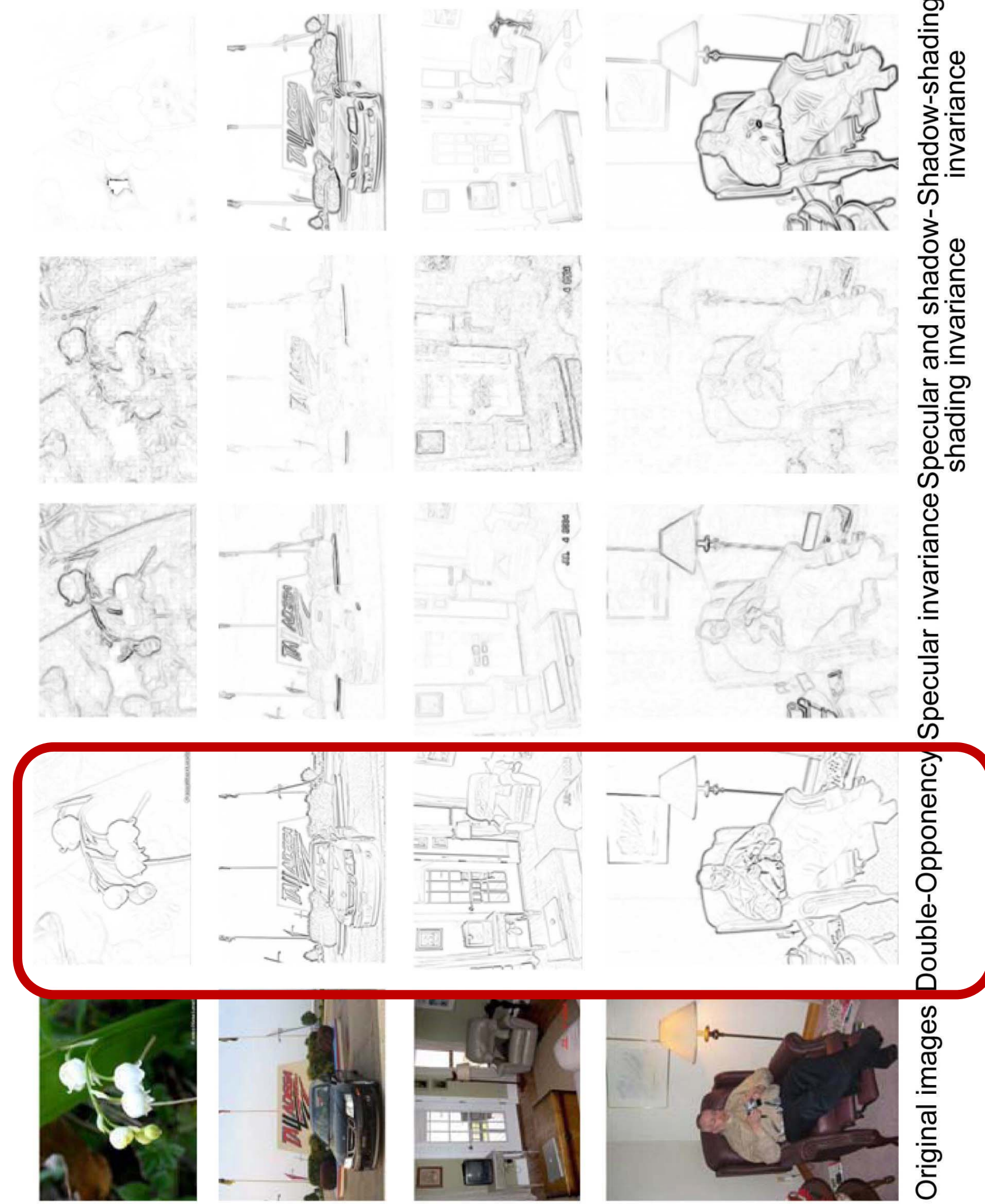
Non-linear operations: $v(x, y, \zeta) = \frac{\sqrt{k} \times u(x, y, \zeta)}{\sigma^2 + \sum u(x, y, \zeta)}$

half-squared SO: opponent colors DO: orientations divisive normalization pool

Response maps:

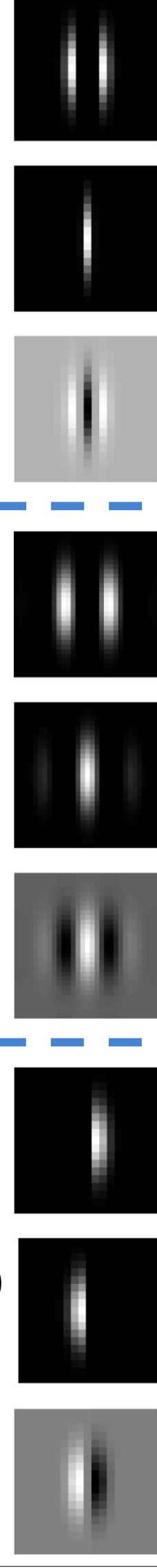


6. Color-gradient comparisons



7. System extensions

Different gradients / filters used in:



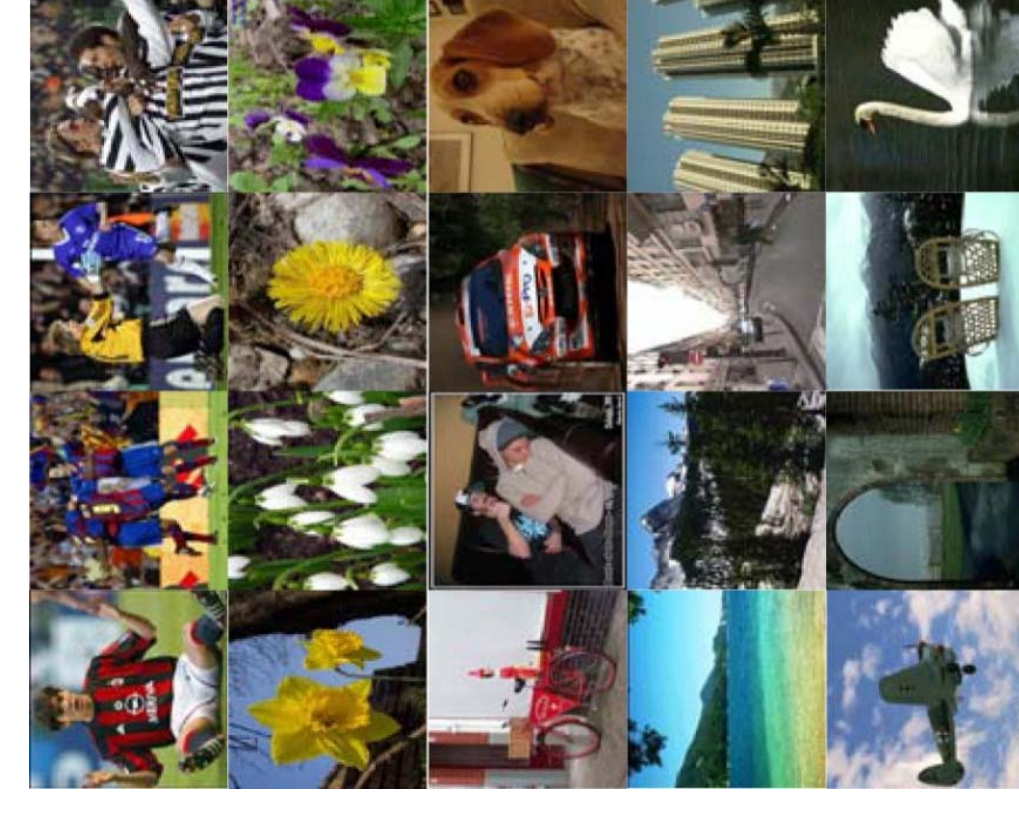
- SIFT-based bag-of-words approach

- HMAX model

- GIST algorithm for natural scene categorization

- BSDS500 for contour detection

Datasets



8. Results

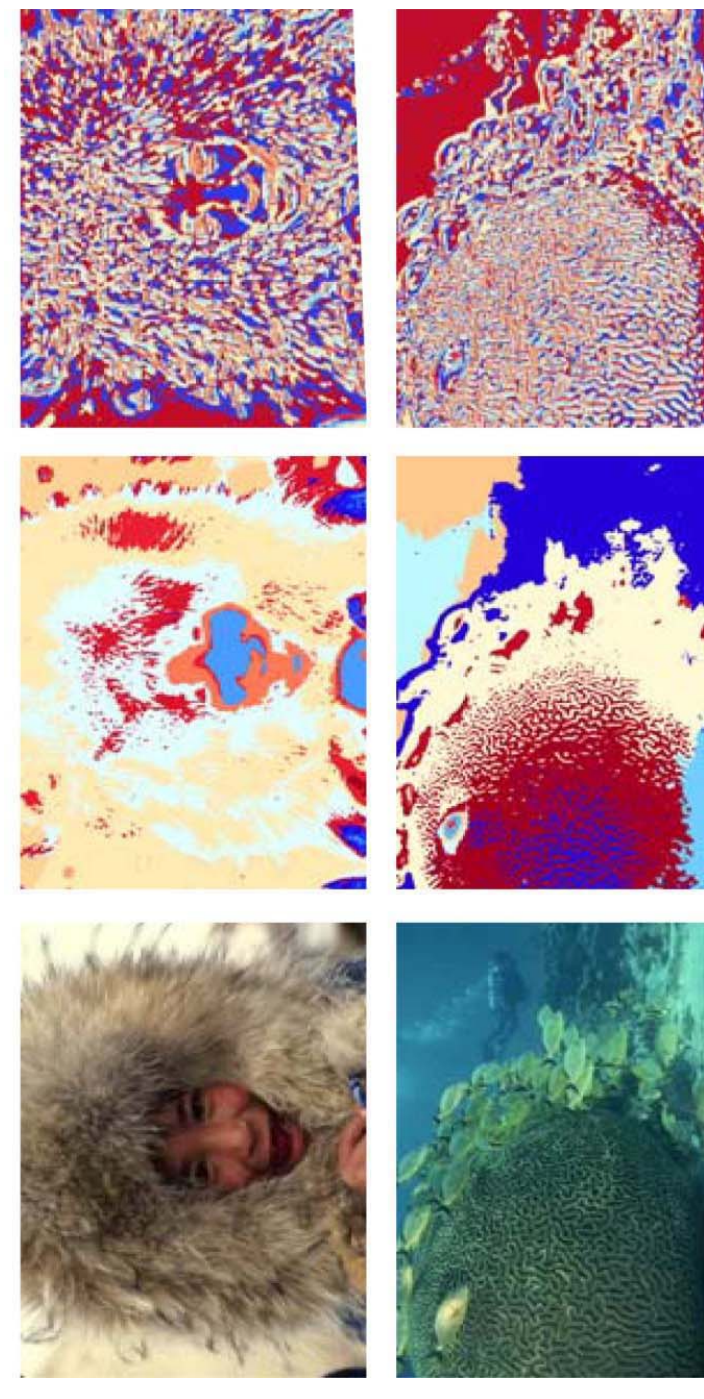
Shape predominant

Method	SIFT	HueSIFT	OpponentSIFT	CSIFT	SODOSIFT	SODOHMAX
AP	40(38.4)	41	43(42.5)	43(44.0)	46.5(33.3/39.8)	46.8(30.1/36.4)

Color predominant

Method	Color	Shape	Both	Color	Shape	Both
Hue/SIFT	69(67)	43(43)	73(73)	58(40)	65(65)	77(79)
Opp/SIFT	69(65)	43(43)	74(72)	57(39)	65(65)	74(79)
SOSIFT/DOSIFT	82	66	83	68	69	79
SOHMAX/DOHMAX	87	76	89	77	73	83

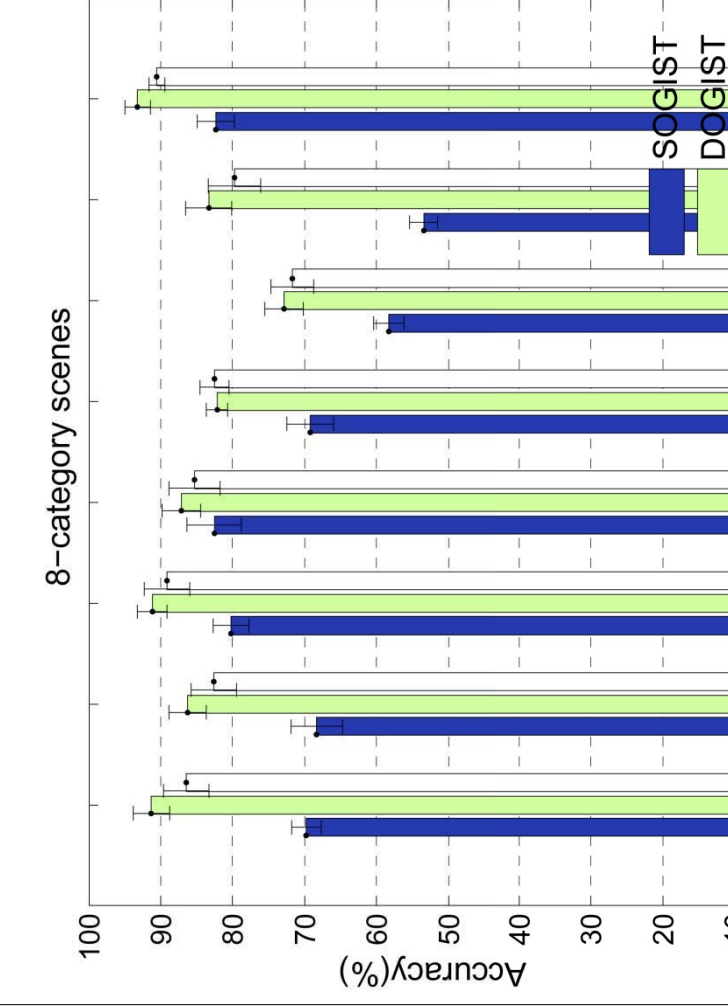
BSDS500



Color-texton map vs. grayscale texton map

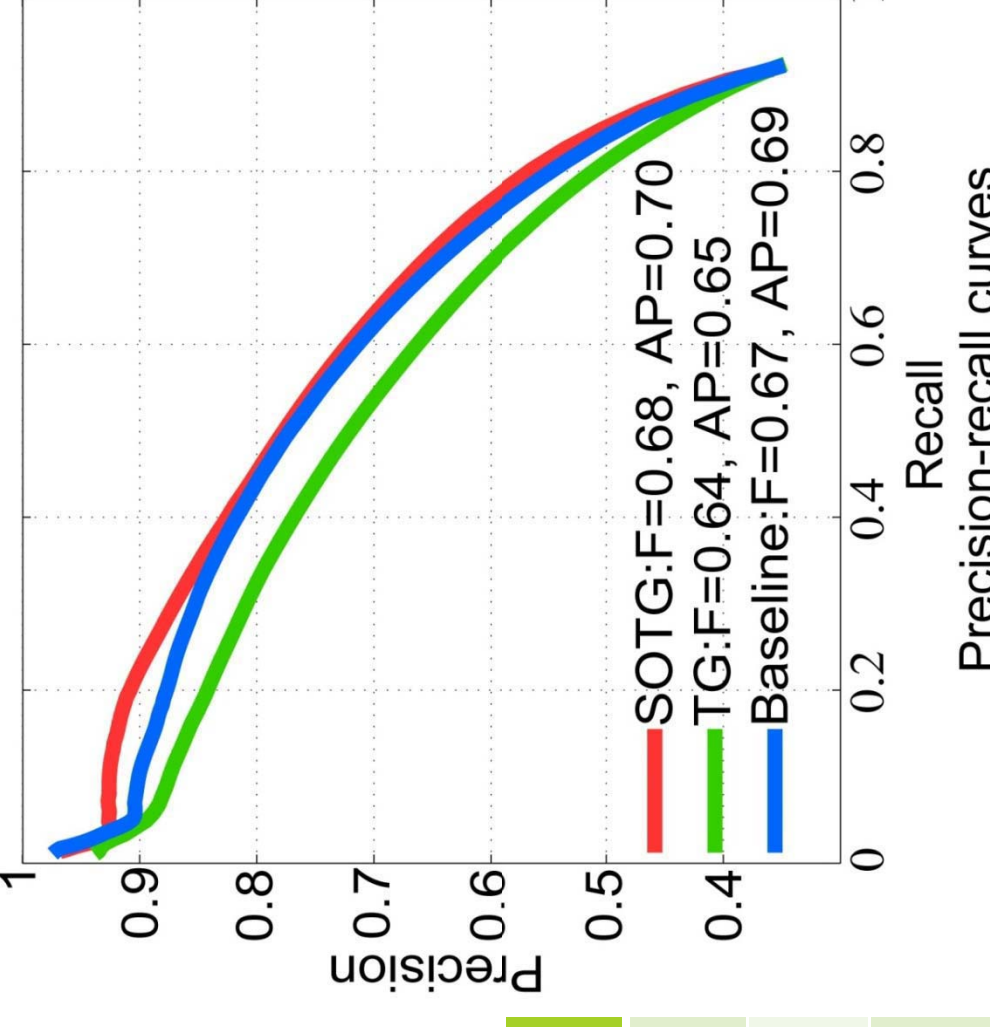
8-category scenes

Method	GIST	RGBGIST	SOGIST	DOGIST	SODOGIST
Accuracy	83.5	84.1	70.5	85.9	87.1



Soccer team

Method	Soccer team	PASCAL VOC 2007
Full model	82.0/66.0	33.3/39.8
Without half-squaring	62.0/60.0	30.3/36.7
Without normalization	70.0/53.0	32.9/40.7



9. Conclusions

- SO encodes color regions
- DO encodes color edges
- Proposed descriptors perform on par or better than other color and shape descriptors.

10. References

[1] Conway, B.R.: The Journal of Neuroscience, 2007 [2] van de Weijer, J., Schmid, C. ICIP, 2007. [3] van de Sande et al. TPAMI, 2010. [4] Oliva, A., Torralba, A. IJCV, 2001. [5] Arbelaez, P et al. TPAMI, 2010.

11. Acknowledgments

This work was supported by DARPA (N10AP20013) and ONR (N000141110743), the Center for Computation and Visualization of Brown University, and the Robert J. and Nancy D. Carney Fund for Scientific Innovation. J. Zhang was supported by China Scholarship Council (2010669020).