#functions of non-linear activations def f\_sigmoid(X, deriv=False): if not deriv: return 1 / (1 + np.exp(-X))else: return f\_sigmoid(X)\*(1 - f\_sigmoid(X)) def f\_relu (X): **if** X > 0: return X else: return 0 def f\_softmax(X): Z = np.sum(np.exp(X), axis=1)Z = Z.reshape(Z.shape[0], 1)return np.exp(X) / Z In [3]: def exit\_with\_err(err\_str): print >> sys.stderr, err\_str sys.exit(1) In [4]: #Functionality of a single hidden layer class Layer: def \_\_init\_\_(self, size, batch\_size, is\_input=False, is\_output=False, activation=f\_sigmoid): self.is\_input = is\_input self.is\_output = is\_output # Z is the matrix that holds output values self.Z = np.zeros((batch\_size, size[0])) # The activation function is an externally defined function (with a # derivative) that is stored here self.activation = activation # W is the outgoing weight matrix for this layer self.W = None # S is the matrix that holds the inputs to this layer self.S = None # D is the matrix that holds the deltas for this layer self.D = None# Fp is the matrix that holds the derivatives of the activation function self.Fp = None if not is input: self.S = np.zeros((batch\_size, size[0])) self.D = np.zeros((batch\_size, size[0])) if not is\_output: self.W = np.random.normal(size=size, scale=1E-4) if not is input and not is output: self.Fp = np.zeros((size[0], batch\_size)) def forward\_propagate(self): if self.is\_input: return self.Z.dot(self.W) self.Z = self.activation(self.S) if self.is\_output: return self.Z else: # For hidden layers, we add the bias values here self.Z = np.append(self.Z, np.ones((self.Z.shape[0], 1)), axis=1) self.Fp = self.activation(self.S, deriv=True).T return self.Z.dot(self.W) In [16]: class MultiLayerPerceptron: def \_\_init\_\_(self, layer\_config, batch\_size=100): self.layers = [] self.num\_layers = len(layer\_config) self.minibatch\_size = batch\_size for i in range(self.num\_layers-1): **if** i == 0: print ("Initializing input layer with size {0}.".format(layer\_config[i])) # Here, we add an additional unit at the input for the bias # weight. self.layers.append(Layer([layer\_config[i]+1, layer\_config[i+1]], batch\_size, is\_input=True)) else: print ("Initializing hidden layer with size {0}.".format(layer\_config[i])) # Here we add an additional unit in the hidden layers for the # bias weight. self.layers.append(Layer([layer\_config[i]+1, layer\_config[i+1]], batch\_size, activation=f\_sigmoid)) print ("Initializing output layer with size {0}.".format(layer\_config[-1])) self.layers.append(Layer([layer\_config[-1], None], batch\_size, is\_output=True, activation=f\_softmax)) print ("Done!") def forward\_propagate(self, data): # We need to be sure to add bias values to the input self.layers[0].Z = np.append(data, np.ones((data.shape[0], 1)), axis=1) for i in range(self.num\_layers-1): self.layers[i+1].S = self.layers[i].forward\_propagate() return self.layers[-1].forward\_propagate() def backpropagate(self, yhat, labels): #exit\_with\_err("FIND ME IN THE CODE, What is computed in the next line of code?\n") self.layers[-1].D = (yhat - labels).T for i in range(self.num\_layers-2, 0, -1): # We do not calculate deltas for the bias values W\_nobias = self.layers[i].W[0:-1, :] #exit\_with\_err("FIND ME IN THE CODE, What does this 'for' Loop do?\n") self.layers[i].D = W\_nobias.dot(self.layers[i+1].D) \* self.layers[i].Fp def update\_weights(self, eta): for i in range(0, self.num\_layers-1): W\_grad = -eta\*(self.layers[i+1].D.dot(self.layers[i].Z)).T self.layers[i].W += W\_grad def evaluate(self, train\_data, train\_labels, test\_data, test\_labels, num\_epochs=70, eta=0.05, eval\_train=False, eval\_test=True): N\_train = len(train\_labels)\*len(train\_labels[0]) N\_test = len(test\_labels)\*len(test\_labels[0]) #print ("Training for {0} epochs...".format(num\_epochs)) for t in range(0, num\_epochs): out\_str = "[{0:4d}] ".format(t) for b\_data, b\_labels in zip(train\_data, train\_labels): output = self.forward\_propagate(b\_data) self.backpropagate(output, b\_labels) #exit\_with\_err("FIND ME IN THE CODE, How does weight update is implemented? What is eta?\n") self.update\_weights(eta=eta) if eval\_train: errs = 0for b\_data, b\_labels in zip(train\_data, train\_labels): output = self.forward\_propagate(b\_data) yhat = np.argmax(output, axis=1) errs += np.sum(1-b\_labels[np.arange(len(b\_labels)), yhat]) out\_str = ("{0} Training error: {1:.5f}".format(out\_str, float(errs)/N\_train)) if eval\_test: errs = 0for b\_data, b\_labels in zip(test\_data, test\_labels): output = self.forward\_propagate(b\_data) yhat = np.argmax(output, axis=1) errs += np.sum(1-b\_labels[np.arange(len(b\_labels)), yhat]) out\_str = ("{0} Test error: {1:.5f}").format(out\_str, float(errs)/N\_test) #print (out\_str) Task 1. Answers to the questions of the code: 1. The line self.layers[-1].D = (yhat - labels).T calculates the error in the last layer which will be backpropagated to calculate all the Deltas in the previous laters. 'yhat' is the prediction made by the network and the 'labels' are the correct instances. 2. self.layers[-1].D = (yhat - labels).T for i in range(self.num\_layers-2, 0, -1): # We do not calculate deltas for the bias values W\_nobias = self.layers[i].W[0:-1, :] self.layers[i].D = W\_nobias.dot(self.layers[i+1].D) \* self.layers[i].Fp The purpose of this loop is to calculate the deltas for each hidden layer, excluding the input layer. These deltas are then used to update the weights during the weight update step in the backpropagation algorithm. 3. How is the weight update implemented? What is eta? The weight update is implemented through a function "update\_weights" that calculates the gradient of each layer using a for loop iterating over each layer, multiplying its output by the delta error of the next layer and by "eta", which is the learning rate. In [6]: def label\_to\_bit\_vector(labels, nbits): bit\_vector = np.zeros((labels.shape[0], nbits)) for i in range(labels.shape[0]): bit\_vector[i, labels[i]] = 1.0 return bit\_vector In [7]: def create\_batches(data, labels, batch\_size, create\_bit\_vector=False): print ("Batch size {0}, the number of examples {1}.".format(batch\_size,N)) if N % batch\_size != 0: print ("Warning in create\_minibatches(): Batch size {0} does not " \ "evenly divide the number of examples {1}.".format(batch\_size,N))  $chunked_data = []$ chunked\_labels = [] idx = 0while idx + batch\_size <= N:</pre> chunked\_data.append(data[idx:idx+batch\_size, :]) if not create\_bit\_vector: chunked\_labels.append(labels[idx:idx+batch\_size]) bit\_vector = label\_to\_bit\_vector(labels[idx:idx+batch\_size], 10) chunked\_labels.append(bit\_vector) idx += batch\_size return chunked\_data, chunked\_labels In [8]: def prepare\_for\_backprop(batch\_size, Train\_images, Train\_labels, Valid\_images, Valid\_labels): print ("Creating data...") batched\_train\_data, batched\_train\_labels = create\_batches(Train\_images, Train\_labels, batch\_size, create\_bit\_vector=True) batched\_valid\_data, batched\_valid\_labels = create\_batches(Valid\_images, Valid\_labels, batch\_size, create\_bit\_vector=True) print ("Done!") return batched\_train\_data, batched\_train\_labels, batched\_valid\_data, batched\_valid\_labels from keras.datasets import mnist In [10]: (Xtr, Ltr), (X\_test, L\_test)=mnist.load\_data() Xtr = Xtr.reshape(60000, 784)  $X_{\text{test}} = X_{\text{test.reshape}}(10000, 784)$ Xtr = Xtr.astype('float32') X\_test = X\_test.astype('float32') Xtr /= 255 X\_test /= 255 print(Xtr.shape[0], 'train samples') print(X\_test.shape[0], 'test samples') 60000 train samples 10000 test samples In [11]: batch\_size=100; train\_data, train\_labels, valid\_data, valid\_labels=prepare\_for\_backprop(batch\_size, Xtr, Ltr, X\_test, L\_test) mlp = MultiLayerPerceptron(layer\_config=[784, 100, 100, 10], batch\_size=batch\_size) mlp.evaluate(train\_data, train\_labels, valid\_data, valid\_labels, eval\_train=True) print("Done:)\n") Creating data... Batch size 100, the number of examples 60000. Batch size 100, the number of examples 10000. Initializing input layer with size 784. Initializing hidden layer with size 100. Initializing hidden layer with size 100. Initializing output layer with size 10. Done! Training for 70 epochs... 0] Training error: 0.73552 Test error: 0.72000 Training error: 0.08963 Test error: 0.08910 Training error: 0.05932 Test error: 0.06110 Training error: 0.04727 Test error: 0.05160 4] Training error: 0.04153 Test error: 0.04770 5] Training error: 0.03540 Test error: 0.04290 6] Training error: 0.03230 Test error: 0.04060 Training error: 0.02750 Test error: 0.03740 [ Training error: 0.02318 Test error: 0.03580 Γ Training error: 0.02068 Test error: 0.03350 Training error: 0.01968 Test error: 0.03520 10] Training error: 0.01933 Test error: 0.03350 11] Training error: 0.01695 Test error: 0.03250 12] Training error: 0.01668 Test error: 0.03210 13] Training error: 0.02027 Test error: 0.03550 14] 15] Training error: 0.01318 Test error: 0.03380 Training error: 0.01235 Test error: 0.03150 Γ Training error: 0.01405 Test error: 0.03320 17] Γ Training error: 0.01513 Test error: 0.03210 [ 18] 19] Training error: 0.01195 Test error: 0.03170 Training error: 0.01092 Test error: 0.03130 Training error: 0.01153 Test error: 0.03180 [ 22] Training error: 0.00987 Test error: 0.03190 23] Training error: 0.00915 Test error: 0.03200 24] Training error: 0.00973 Test error: 0.03120 Training error: 0.00877 Test error: 0.02800 Training error: 0.00710 Test error: 0.02920 26] Training error: 0.00738 Test error: 0.03090 27] Training error: 0.00415 Test error: 0.02840 Training error: 0.00842 Test error: 0.03180 291 Training error: 0.00410 Test error: 0.02930 30] Training error: 0.00350 Test error: 0.02910 Training error: 0.00252 Test error: 0.02870 Γ Training error: 0.01137 Test error: 0.03320 Γ 33] Training error: 0.00740 Test error: 0.03040 34] [ Training error: 0.00572 Test error: 0.02980 [ Training error: 0.00512 Test error: 0.02920 Training error: 0.00483 Test error: 0.03020 [ Training error: 0.00608 Test error: 0.02940 Training error: 0.00370 Test error: 0.02980 Training error: 0.00345 Test error: 0.02950 Γ 41] Training error: 0.00265 Test error: 0.02730 Training error: 0.00157 Test error: 0.02630 42] Training error: 0.00158 Test error: 0.02680 43] Training error: 0.00585 Test error: 0.02970 44] Training error: 0.00408 Test error: 0.02690 45] Training error: 0.00338 Test error: 0.02800 46] 47] Training error: 0.00187 Test error: 0.02730 Training error: 0.00300 Test error: 0.02750 Γ 48] Training error: 0.00073 Test error: 0.02590 491 Γ Training error: 0.00082 Test error: 0.02640 50] [ [ Training error: 0.00023 Test error: 0.02490 Training error: 0.00008 Test error: 0.02520 Training error: 0.00003 Test error: 0.02510 [ Training error: 0.00003 Test error: 0.02510 Training error: 0.00003 Test error: 0.02460 Training error: 0.00003 Test error: 0.02480 57] Training error: 0.00002 Test error: 0.02520 Training error: 0.00002 Test error: 0.02530 Training error: 0.00002 Test error: 0.02530 59] Training error: 0.00002 Test error: 0.02510 [ 61] Training error: 0.00002 Test error: 0.02510 [ 62] Training error: 0.00002 Test error: 0.02490 [ 63] Training error: 0.00002 Test error: 0.02490 [ 64] Training error: 0.00002 Test error: 0.02490 [ 65] Training error: 0.00002 Test error: 0.02500 [ 66] Training error: 0.00002 Test error: 0.02510 67] Training error: 0.00002 Test error: 0.02530 [ 68] Training error: 0.00000 Test error: 0.02510 [ 69] Training error: 0.00002 Test error: 0.02520 Done:) Task 2: Run the code with the suggested configuration of the hyperparameters: number of epochs = 70 and learning rate = 0.05. What is the classification accuracy? In [14]: output = mlp.forward\_propagate(X\_test) y\_hat = np.argmax(output, axis = 1) accuracy = np.sum(y\_hat == L\_test)/len(L\_test) print(f"Accuracy: {accuracy:.4f}") Accuracy: 0.9748 The classification accuracy when training the MLP for 70 epochs witha a learning rate of 0.05 is 97.48% Task 3: Run the code with Learning rate = 0.005 and Learning rate = 0.5. Explain the observed differences in the functionality of the multi-layer perceptron. In [18]: mlp = MultiLayerPerceptron(layer\_config=[784, 100, 100, 10], batch\_size=batch\_size) learning\_rates = [0.005, 0.5] for i in range(2): mlp.evaluate(train\_data, train\_labels, valid\_data, valid\_labels, num\_epochs=70, eta=learning\_rates[i], eval\_train=F output = mlp.forward\_propagate(X\_test) y\_hat = np.argmax(output, axis = 1) accuracy = np.sum(y\_hat == L\_test)/len(L\_test) print(f"The Accuracy when training with a learning rate of {learning\_rates[i]} is: {accuracy:.4f}") Initializing input layer with size 784. Initializing hidden layer with size 100. Initializing hidden layer with size 100. Initializing output layer with size 10. The Accuracy when training with a learning rate of 0.005 is: 0.9749 C:\Users\sexysehe\AppData\Local\Temp\ipykernel\_22028\3670988153.py:4: RuntimeWarning: overflow encountered in exp return 1 / (1 + np.exp(-X))The Accuracy when training with a learning rate of 0.5 is: 0.0974 As we can see by the accuracies gotten for the different learning rates, increasing it to 0.5 has made the accuracy be much lower when testing the MLP. This could be because since the learning rate is so large it makes the optimization process jump around the minima. Task 4 Extend the code implementing the ReLU output function. Run the perceptron with the suggested by default configuration of hyperparameters: number of epochs = 70 and learning rate =0.05. What is the classification accuracy? We will first change the parts in the object oriented programming that are affected by this, you can see how below we change the activations from sigmoids to the relu that we have defined. In [44]: def f\_relu(X, deriv=False): if not deriv: return np.maximum(0, X) return np.where(X > 0, 1, 0) In [21]: #Functionality of a single hidden layer class Layer: def \_\_init\_\_(self, size, batch\_size, is\_input=False, is\_output=False, activation=f\_relu): self.is\_input = is\_input self.is\_output = is\_output # Z is the matrix that holds output values self.Z = np.zeros((batch\_size, size[0])) # The activation function is an externally defined function (with a # derivative) that is stored here self.activation = activation # W is the outgoing weight matrix for this layer self.W = None # S is the matrix that holds the inputs to this layer self.S = None # D is the matrix that holds the deltas for this layer self.D = None# Fp is the matrix that holds the derivatives of the activation function self.Fp = None if not is\_input: self.S = np.zeros((batch\_size, size[0])) self.D = np.zeros((batch\_size, size[0])) if not is output: self.W = np.random.normal(size=size, scale=1E-4) if not is\_input and not is\_output: self.Fp = np.zeros((size[0], batch\_size)) def forward\_propagate(self): if self.is\_input: return self.Z.dot(self.W) self.Z = self.activation(self.S) if self.is\_output: return self.Z else: # For hidden layers, we add the bias values here self.Z = np.append(self.Z, np.ones((self.Z.shape[0], 1)), axis=1) self.Fp = self.activation(self.S, deriv=True).T return self.Z.dot(self.W) In [34]: class MultiLayerPerceptron: def \_\_init\_\_(self, layer\_config, batch\_size=100): self.layers = [] self.num\_layers = len(layer\_config) self.minibatch\_size = batch\_size for i in range(self.num\_layers-1): **if** i **==** 0: print ("Initializing input layer with size {0}.".format(layer\_config[i])) # Here, we add an additional unit at the input for the bias self.layers.append(Layer([layer\_config[i]+1, layer\_config[i+1]], batch\_size, is\_input=True)) else: print ("Initializing hidden layer with size {0}.".format(layer\_config[i])) # Here we add an additional unit in the hidden layers for the # bias weight. self.layers.append(Layer([layer\_config[i]+1, layer\_config[i+1]], batch size, activation=f\_relu)) print ("Initializing output layer with size {0}.".format(layer\_config[-1])) self.layers.append(Layer([layer\_config[-1], None], batch size, is\_output=True, activation=f\_softmax)) print ("Done!") def forward\_propagate(self, data): # We need to be sure to add bias values to the input self.layers[0].Z = np.append(data, np.ones((data.shape[0], 1)), axis=1) for i in range(self.num\_layers-1): self.layers[i+1].S = self.layers[i].forward\_propagate() return self.layers[-1].forward\_propagate() def backpropagate(self, yhat, labels): #exit\_with\_err("FIND ME IN THE CODE, What is computed in the next line of code?\n") self.layers[-1].D = (yhat - labels).T for i in range(self.num\_layers-2, 0, -1): # We do not calculate deltas for the bias values W nobias = self.layers[i].W[0:-1, :] #exit\_with\_err("FIND ME IN THE CODE, What does this 'for' loop do?\n") self.layers[i].D = W\_nobias.dot(self.layers[i+1].D) \* self.layers[i].Fp def update\_weights(self, eta): for i in range(0, self.num\_layers-1): W\_grad = -eta\*(self.layers[i+1].D.dot(self.layers[i].Z)).T self.layers[i].W += W\_grad def evaluate(self, train data, train labels, test data, test labels, num\_epochs=70, eta=0.05, eval\_train=False, eval\_test=True): N\_train = len(train\_labels)\*len(train\_labels[0]) N\_test = len(test\_labels)\*len(test\_labels[0]) #print ("Training for {0} epochs...".format(num\_epochs)) for t in range(0, num\_epochs): out str = "[{0:4d}] ".format(t) for b\_data, b\_labels in zip(train\_data, train\_labels): output = self.forward\_propagate(b\_data) self.backpropagate(output, b labels) #exit\_with\_err("FIND ME IN THE CODE, How does weight update is implemented? What is eta?\n") self.update weights(eta=eta) if eval\_train: for b data, b labels in zip(train data, train labels): output = self.forward propagate(b data) yhat = np.argmax(output, axis=1) errs += np.sum(1-b\_labels[np.arange(len(b\_labels)), yhat]) out\_str = ("{0} Training error: {1:.5f}".format(out\_str, float(errs)/N\_train)) if eval\_test: errs = 0for b\_data, b\_labels in zip(test\_data, test\_labels): output = self.forward\_propagate(b\_data) yhat = np.argmax(output, axis=1) errs += np.sum(1-b\_labels[np.arange(len(b\_labels)), yhat]) out\_str = ("{0} Test error: {1:.5f}").format(out\_str, float(errs)/N\_test) print (out\_str) Below we will train the MLP using relu activation function, by not initializing the learning rate it stays at the default value of 0.05 which is the one required by this task, and the same goes with the number of epochs which by default is 70. In [45]: mlp\_relu = MultiLayerPerceptron(layer\_config=[784, 100, 100, 10], batch\_size=batch\_size) mlp\_relu.evaluate(train\_data, train\_labels, valid\_data, valid\_labels, eval train=True) print("Done:)\n")

Lab 5 D7041E: Artificial Neural Network and Backpropagation

Group 30: Sergio Serrano Hernández (serser-1) and Nicolas Scheidler (nicsch-3)

In [1]:

In [19]:

import numpy as np

print(f" <mark>Accuracy</mark> Accuracy: 0.0958	u.forward_propagate x(output, axis = 1) m(y_hat == L_test) : {accuracy:.4f}")  f the mlp using re % which is the fin	)	to the one using to this Lab	the sigmoid activ	ation function, g	iving us