

Definition 1 (Device).

$$Device := (w_0, G_d(N_d, V_d, w_{\mathcal{F}}))$$

where

$$\begin{cases} w_0 = \tau_{decoherence} / \tau_{2\text{-qubit gate time}} \\ w_{\mathcal{F}}(v) = -\log(\bar{\mathcal{F}}_{2\text{-qubit gate on edge } v}) \end{cases}$$

Definition 2 (Partial Allocation).

$$Partial Allocation \phi : N \rightarrow N_d$$

Definition 3 (Actions and Costs). *Simple actions are*

- *Allocate:* $\phi \mapsto \phi \cup \{(n, n_d)\}$, *cost:* 0
- *Swap:* $\phi \mapsto \phi \circ \sigma_{ab}$, *cost:* $w_{\mathcal{F}}(v) + (n - 2)w_0$?
- *Apply:* $\phi \mapsto \phi$, *cost:* $w_{\mathcal{F}}(v) + (n - 2)w_0$?
- *Bridge??*

Plus compound actions with reduced cost

- *Compose:* *If a swap and an apply are on the same edge, then the cost halves.*
- *Parallelize:* *If k simple actions have no node in common, total cost will be reduced by $(k - 1)nw_0$.*

Definition 4. *Applicability of (n_1, n_2) is checking that $(\phi(n_1), \phi(n_2)) \in V_d$*

Definition 5.

$$d(n_1, n_2) := d_w(\phi(n_1), \phi(n_2))$$

Definition 6.

$$d(\phi_1, \phi_2) := \text{minimum cost of reaching 2 from 1 by swaps and allocations}$$

The target is to apply all $T \subseteq N \times N$. We may add some dependencies later.

The algorithm is an A*, with only branching to $t \in T$ applicable...

Best initial allocation is NP-Hard.