

1 Optimization Problem

let S be set of feasible Hamiltonians, $|\phi_0\rangle$ the ground state and $|\psi\rangle$ the target state.

formally, problem can be formulated by these equations

$$H^*, t^* = \arg \max_{H \in S, t \in \mathbb{R}} \mathcal{F}(e^{iHt} |\phi_0\rangle, |\psi\rangle) \quad (1)$$

where \mathcal{F} is fidelity.

1.1 Numerical Optimization

to be completed

1.2 Continuous Analytical Optimization

in a continuous framework, let $\vec{v} \in \mathbb{R}^m$ degrees of freedom for the whole evolution (Hamiltonian and time).

$$\begin{aligned} \tilde{H} &= Ht = f(\vec{v}) \\ \tilde{H} &= \sum_{i,j} H_{ij} |i\rangle\langle j| = \sum_{i,j} f_{ij}(\vec{v}) |i\rangle\langle j| \end{aligned}$$

then

$$\begin{aligned} \vec{\nabla} \mathcal{F}(e^{\tilde{H}(\vec{v})} |\phi_0\rangle, |\psi\rangle) \Big|_{\vec{v}=\vec{v}^*} &= \vec{0} \\ \forall k \quad \sum_{i,j} \frac{\partial \mathcal{F}(e^{iHt} |\phi_0\rangle, |\psi\rangle)}{\partial \tilde{H}_{ij}} \frac{\partial \tilde{H}_{ij}}{\partial v_k} \Big|_{\vec{v}=\vec{v}^*} &= 0 \end{aligned}$$

now we are going to compute $\frac{\partial \mathcal{F}}{\partial \tilde{H}_{ij}}$

Lemma 1.

$$\frac{\partial H^k}{\partial H_{mn}} = \sum_l H_{mi}^l H_{jn}^{k-l-1}$$

Lemma 2. if $H = U^\dagger D U$

$$\frac{\partial H^k}{\partial H_{mn}} = \sum_{i,j,\alpha,\beta} U_{m\alpha}^\dagger U_{i\beta}^\dagger U_{\alpha j} U_{\beta n} \frac{D_{\alpha\alpha}^k - D_{\beta\beta}^k}{D_{\alpha\alpha} - D_{\beta\beta}} |i\rangle\langle j|$$

without losing generalization, we can assume $|\phi_0\rangle = |1\rangle$

by using two aforementioned lemma, we can show

$$\frac{\partial \mathcal{F}}{\partial \tilde{H}_{ij}} = \sum_{p,q,\alpha,\beta,\gamma} \langle \psi | p \rangle \langle q | \psi \rangle U_{i\alpha}^\dagger U_{2\beta}^\dagger U_{\alpha 1} U_{\beta j} U_{1\gamma}^\dagger U_{\gamma p} \frac{(e^{iD_{\alpha\alpha}} - e^{iD_{\beta\beta}}) e^{-iD_{\gamma\gamma}} + (e^{-iD_{\alpha\alpha}} - e^{-iD_{\beta\beta}}) e^{iD_{\gamma\gamma}}}{D_{\alpha\alpha} - D_{\beta\beta}}$$