

Gradient based optimization

• Gradient descent:

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \xi \sum_{n=1}^{N} \nabla_{\mathbf{w}^{(t)}} L(y^{(n)}, y^{*(n)}(\mathbf{w}^{(t)}))$$

where ξ is the learning rate.

- Frequency of updates:
 - Batch gradient descent: Updates after evaluating the loss gradient w.r.t. all training examples.
 - Stochastic gradient descent: Updates after evaluating the loss gradient w.r.t. every training example.
 - Mini-batch gradient descent: Updates after evaluating the loss gradient w.r.t.
 a subset of the training dataset.
- Type of updates:
 - Fixed learning rate
 - With momentum
 - Adaptive learning rate
 - Adaptive learning rate + Momentum

Ravines

• Stochastic gradient descent has difficulty navigating ravines.



Momentum based gradient descent

- Builds up speed in directions with gentle and consistent gradient.
- Damps oscillations in direction of high curvature.
- The effect of the gradient is to increment the previous velocity. The velocity also decay by a factor β which is slightly less than one.
- Running average makes the gradient less dependent on its current value, and rely more on the general behaviour of the gradient in the past updates.
- More interested in the expected value of the gradient rather on the particular gradient value at a particular iteration.

$$\mathbf{v}^{(t)} = \beta \mathbf{v}^{(t-1)} + (1 - \beta) \nabla_{\mathbf{w}^{(t)}} L$$
$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \xi \mathbf{v}^{(t)}$$

Momentum based gradient descent: updates

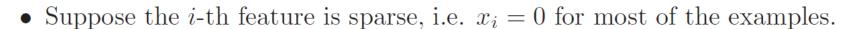
$$\mathbf{v}^{(0)} = 0$$

- Update 1: $\mathbf{v}^{(1)} = \beta \mathbf{v}^{(0)} + (1 \beta) \nabla_{\mathbf{w}^{(1)}} L$ = $(1 - \beta) \nabla_{\mathbf{w}^{(1)}} L$
- Update 2: $\mathbf{v}^{(2)} = \beta \mathbf{v}^{(1)} + (1 \beta) \nabla_{\mathbf{w}^{(2)}} L$ = $\beta (1 - \beta) \nabla_{\mathbf{w}^{(1)}} L + (1 - \beta) \nabla_{\mathbf{w}^{(2)}} L$
- Update 3: $\mathbf{v}^{(3)} = \beta \mathbf{v}^{(2)} + (1 \beta) \nabla_{\mathbf{w}^{(3)}} L$ $= \beta \left(\beta (1 - \beta) \nabla_{\mathbf{w}^{(1)}} L + (1 - \beta) \nabla_{\mathbf{w}^{(2)}} L \right) + (1 - \beta) \nabla_{\mathbf{w}^{(3)}} L$ $= (1 - \beta) \left[\beta^2 \nabla_{\mathbf{w}^{(1)}} L + \beta^1 \nabla_{\mathbf{w}^{(2)}} L + \nabla_{\mathbf{w}^{(3)}} L \right]$
- Update t: $\mathbf{v}^{(t)} = (1 \beta) \left[\beta^{(t-1)} \nabla_{\mathbf{w}^{(1)}} L + \beta^{(t-2)} \nabla_{\mathbf{w}^{(2)}} L + \dots + \nabla_{\mathbf{w}^{(t)}} L \right]$

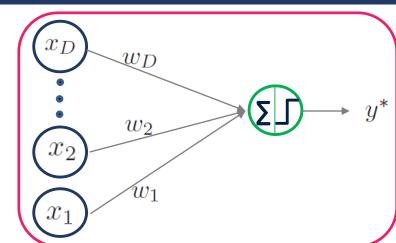
Shortcomings

- Binary classification problem
- Binary cross-entropy loss function
- Update: $w_i := w_i \xi \frac{\partial L}{\partial w_i}$





- In that case the weight w_i associated with x_i will have few updates as the gradient is 0 in most cases.
- Our results can be seriously impacted if x_i happens to be a very important feature.
- Want an algorithm that gives higher learning rate to sparse features.



Adagrad

- Adapts the learning rate of the parameters.
 - Higher learning rate for sparse features.
 - Lower learning rate for dense features.
- More updates of a parameter indicate more decay of its learning rate.

$$\mathbf{s}^{(t)} = \mathbf{s}^{(t-1)} + \left(\nabla_{\mathbf{w}^{(t)}} L\right)^{2}$$
$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \frac{\xi}{\sqrt{\mathbf{s}^{(t)} + \epsilon}} \odot \nabla_{\mathbf{w}^{(t)}} L$$

• Method appropriate for dealing with sparse datasets.

RMSProp

- Adagrad reduces the learning rates of parameters associated with dense features very fast. So the corresponding weight updates will be small.
- Adagrad: Sum of squares of the past gradients.
- RMSProp: Exponentially decaying (moving) average of the squares of past gradients.

$$\mathbf{s}^{(t)} = \beta \mathbf{s}^{(t-1)} + (1 - \beta) (\nabla_{\mathbf{w}^{(t)}} L)^{2}$$
$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \frac{\xi}{\sqrt{\mathbf{s}^{(t)} + \epsilon}} \odot \nabla_{\mathbf{w}^{(t)}} L$$

• RMSProp addresses the learning rate decay problem of Adagrad.

ADAM

- Adaptive Moment Estimation (ADAM).
- Adaptive learning rate + Momentum
 - Keeps an exponentially decaying average of past gradients (like momentum).
 - Also keeps an exponentially decaying average of past squared gradients (like RMSProp).

$$\mathbf{v}^{(t)} = \beta_1 \mathbf{v}^{(t-1)} + (1 - \beta_1) \nabla_{\mathbf{w}^{(t)}} L$$
$$\mathbf{s}^{(t)} = \beta_2 \mathbf{s}^{(t-1)} + (1 - \beta_2) (\nabla_{\mathbf{w}^{(t)}} L)^2$$

- $\mathbf{v}^{(t)}$ is the vector of first moment (mean) estimates of the mean of the gradients.
- $\mathbf{s}^{(t)}$ is the vector of second moment (uncentered variance) estimates of the gradients.
- Bias corrections: $\overline{\mathbf{v}}^{(t)} = \frac{\mathbf{v}^{(t)}}{1 \beta_1^t}$ $\overline{\mathbf{s}}^{(t)} = \frac{\mathbf{s}^{(t)}}{1 \beta_2^t}$
- Update of weights: $\mathbf{w}^{(t+1)} := \mathbf{w}^{(t)} \frac{\xi}{\sqrt{\overline{\mathbf{s}}^{(t)} + \epsilon}} \odot \overline{\mathbf{v}}^{(t)}$

ADAM: Bias correction

- We have seen that $\mathbf{v}^{(t)} = (1 \beta_1) \sum_{j=1}^{t} \beta^{t-j} \nabla_{\mathbf{w}^{(j)}} L$
- Taking Expectation on both sides yields

$$\mathbb{E}[\mathbf{v}^{(t)}] = \mathbb{E}\Big[(1 - \beta_1) \sum_{j=1}^{t} \beta^{t-j} \nabla_{\mathbf{w}^{(j)}} L\Big]$$

$$= (1 - \beta_1) \mathbb{E}\Big[\sum_{j=1}^{t} \beta^{t-j} \nabla_{\mathbf{w}^{(j)}} L\Big]$$

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$$= (1 - \beta_1) \sum_{j=1}^{t} \beta^{t-j} \mathbb{E}\Big[\nabla_{\mathbf{w}^{(j)}} L\Big]$$

• Assumption: All gradients come from the same distribution, i.e.

$$\nabla_{\mathbf{w}^{(1)}} L = \nabla_{\mathbf{w}^{(2)}} L = \dots = \nabla_{\mathbf{w}^{(j)}} L = \nabla_{\mathbf{w}} L$$

ADAM: Bias correction

• So then we have

$$\mathbb{E}[\mathbf{v}^{(t)}] = (1 - \beta_1) \sum_{j=1}^{t} \beta^{t-j} \mathbb{E}[\nabla_{\mathbf{w}} L]$$

$$= (1 - \beta_1) \mathbb{E}[\nabla_{\mathbf{w}} L] \sum_{j=1}^{t} \beta_1^{t-j}$$

$$= (1 - \beta_1) \mathbb{E}[\nabla_{\mathbf{w}} L] (\beta_1^{t-1} + \beta_1^{t-2} + \dots + \beta_1^0)$$

$$= (1 - \beta_1) \mathbb{E}[\nabla_{\mathbf{w}} L] (\frac{1 - \beta_1^t}{1 - \beta_1})$$

$$= \mathbb{E}[\nabla_{\mathbf{w}} L] (1 - \beta_1^t)$$

Therefore

$$\mathbb{E}\left[\frac{\mathbf{v}^{(t)}}{1-\beta_1^t}\right] = \mathbb{E}\left[\nabla_{\mathbf{w}}L\right]$$
$$\mathbb{E}\left[\overline{\mathbf{v}}^{(t)}\right] = \mathbb{E}\left[\nabla_{\mathbf{w}}L\right]$$

Comparison

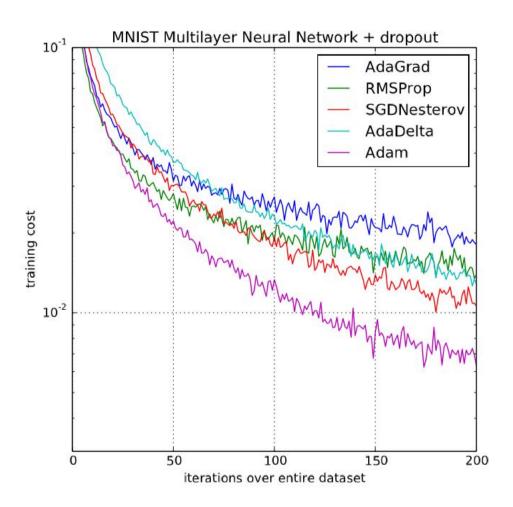


Figure source: Kingma and Lei Ba, ADAM: A method for stochastic optimization, 2015.