Homework - 3

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Question 1

The following are the point group operations which leaves the cluster unchanged:

$$\text{Identity (E)}: \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \text{Inverse (I)}: \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, \text{Mirror-x } (M_x): \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \text{Mirror-y } (M_y): \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}.$$

The force constant matrix can be expressed as a sum over tensor basis:

$$\begin{bmatrix} \phi_{xx} & \phi_{xy} \\ \phi_{yx} & \phi_{yy} \end{bmatrix} = \phi_{xx} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \phi_{xy} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + \phi_{yx} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + \phi_{yy} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$
(1)

To find the symmetry invariant basis, apply Reynold's operator

$$\tilde{\Lambda}_i = \frac{1}{|S|} \sum_{S} S^{T} \Lambda_i S \tag{2}$$

where S can be any of the symmetry operator which leaves the cluster unchanged (E, I, M_x, M_y).

Applying Reynold's operator on $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ gives:

$$\frac{1}{4} \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \right)$$

$$= \frac{1}{4} \begin{bmatrix} 4 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

Applying Reynold's operator on $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ gives:

$$\frac{1}{4} \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \right) \\
= \frac{1}{4} \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Applying Reynold's operator on $\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$ gives:

$$\frac{1}{4} \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \right) \\
= \frac{1}{4} \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Applying Reynold's operator on $\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ gives:

$$\frac{1}{4} \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \right)$$

$$= \frac{1}{4} \begin{bmatrix} 0 & 0 \\ 0 & 4 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

The force constant matrix (Φ) expressed in the symmetry invariant tensor basis is,

$$\Phi = \alpha_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \alpha_1 & 0 \\ 0 & \alpha_2 \end{bmatrix}$$
 (3)

Question 2

Dynamical matrix (D) is given by,

$$D = \frac{1}{m} \sum_{\vec{\mathbf{r}}_l} \Phi(0, \vec{\mathbf{r}}_l) e^{-i\vec{\mathbf{k}} \cdot \vec{\mathbf{r}}_l}$$

$$\tag{4}$$

where \vec{r}_l is position vector of the neighboring atoms, \vec{k} is the crystal momentum and Φ is the force constant matrix. To obtain D, we need Φ of all the nearest neighbors. It can be obtained using the relation: $\Phi(0, \vec{r}_l) = S^T \Phi(0, \vec{r}_1) S$, where S is the symmetry operation which transforms the cluster $(0, \vec{r}_1)$ to $(0, \vec{r}_l)$. The following are the force constant matrices for all the 6 pair clusters.

$$\begin{split} \Phi(0,r_1) &= \begin{bmatrix} \alpha_1 & 0 \\ 0 & \alpha_2 \end{bmatrix} \\ \Phi(0,r_2) &= \begin{bmatrix} \frac{1}{4}\alpha_1 + \frac{3}{4}\alpha_2 & \frac{\sqrt{3}}{4}(\alpha_1 - \alpha_2) \\ \frac{\sqrt{3}}{4}(\alpha_1 - \alpha_2) & \frac{3}{4}\alpha_1 + \frac{1}{4}\alpha_2 \end{bmatrix} \\ \Phi(0,r_3) &= \begin{bmatrix} \frac{1}{4}\alpha_1 + \frac{3}{4}\alpha_2 & \frac{\sqrt{3}}{4}(\alpha_2 - \alpha_1) \\ \frac{\sqrt{3}}{4}(\alpha_2 - \alpha_1) & \frac{3}{4}\alpha_1 + \frac{1}{4}\alpha_2 \end{bmatrix} \\ \Phi(0,r_4) &= \begin{bmatrix} \alpha_1 & 0 \\ 0 & \alpha_2 \end{bmatrix} \\ \Phi(0,r_5) &= \begin{bmatrix} \frac{1}{4}\alpha_1 + \frac{3}{4}\alpha_2 & \frac{\sqrt{3}}{4}(\alpha_1 - \alpha_2) \\ \frac{\sqrt{3}}{4}(\alpha_1 - \alpha_2) & \frac{3}{4}\alpha_1 + \frac{1}{4}\alpha_2 \end{bmatrix} \\ \Phi(0,r_6) &= \begin{bmatrix} \frac{1}{4}\alpha_1 + \frac{3}{4}\alpha_2 & \frac{\sqrt{3}}{4}(\alpha_2 - \alpha_1) \\ \frac{\sqrt{3}}{4}(\alpha_2 - \alpha_1) & \frac{3}{4}\alpha_1 + \frac{1}{4}\alpha_2 \end{bmatrix} \end{split}$$

Plugging in the force constant matrices in Equation. 4, gives:

$$D = \frac{1}{m} \begin{bmatrix} 2\alpha_1 \cos(ak_x) + (\alpha_1 + 3\alpha_2)\cos(\frac{a}{2}k_x)\cos(\frac{a\sqrt{3}}{2}k_y) & -\sqrt{3}(\alpha_1 - \alpha_2)\sin(\frac{a}{2}k_x)\sin(\frac{a\sqrt{3}}{2}k_y) \\ -\sqrt{3}(\alpha_1 - \alpha_2)\sin(\frac{a}{2}k_x)\sin(\frac{a\sqrt{3}}{2}k_y) & 2\alpha_2\cos(ak_x) + (3\alpha_1 + \alpha_2)\cos(\frac{a}{2}k_x)\cos(\frac{a\sqrt{3}}{2}k_y) \end{bmatrix}$$
(5)

Question 3

Considering (a,0), $(\frac{a}{2}, \frac{a\sqrt{3}}{2})$ to be the real space lattice vectors of the triangular lattice, the reciprocal lattice vectors are given by: $\frac{2\pi}{a}(0, \frac{2}{\sqrt{3}})$ and $\frac{2\pi}{a}(1, \frac{-1}{\sqrt{3}})$.

Figure.1 shows the first Brillouin zone (shaded portion) and some of the high symmetry points (black dots) of the triangular lattice.

Question 4

The analytical expression for the eigen values of the Dynamical matrix obtained in Question 2 is given by,

$$e = \frac{1}{m} \left((\alpha_1 + \alpha_2) \left(\cos(ak_x) + 2\cos(\frac{a}{2}k_x) \cos(\frac{a\sqrt{3}}{2}k_y) \right)$$

$$\pm (\alpha_1 - \alpha_2) \sqrt{\left(\cos(ak_x) - \cos(\frac{a}{2}k_x) \cos(\frac{a\sqrt{3}}{2}k_y) \right)^2 + 3\sin^2(\frac{a}{2}k_x) \sin^2(\frac{a\sqrt{3}}{2}k_y)} \right)$$

$$(6)$$

Figure 2 shows the dispersion curves along some high symmetry directions (Γ , K, M) for m = 1, α_1 = 0.1, and α_2 = 0.2.

Question 5

The displacement field corresponding to an eigen vector (e_{α}) at a k point (\vec{k}) is given by:

$$\vec{\mathbf{u}}(\vec{\mathbf{k}}) = \mathbf{c}\vec{e}_{\alpha}(\vec{\mathbf{k}}) \tag{7}$$

Figure. 3 shows the displacement field corresponding to the two eigen vectors at M point. The black and blue arrows represent displacement fields corresponding to 2 different eigen vectors.

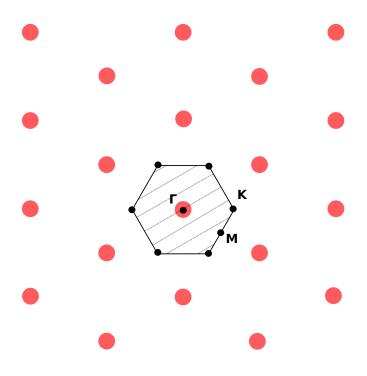


Figure 1: Reciprocal lattice

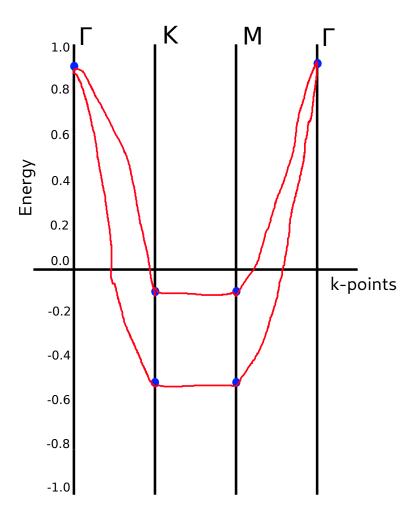


Figure 2: Dispersion curves

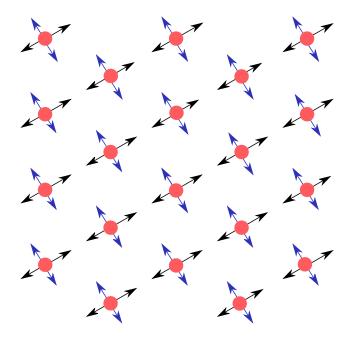


Figure 3: Displacement field