Convex Optimization for Parallel Energy Minimization

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Overview

Submodularity and Examples

Notations and Definitions

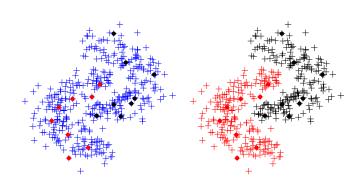
SFM and the corresponding smooth problems

Active set methods for submodular minimization

Active set methods for parallel submodular minimization

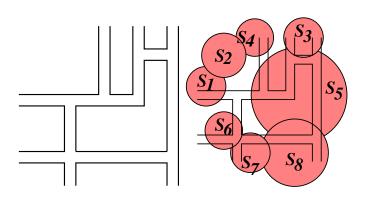
Results

Semi - supervised clustering



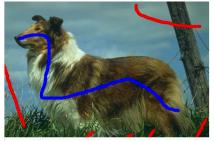
Submodular function minimization

Sensor placement



- ► Krause and Guestrin, 2005.
- ► Submodular function maximization

Energy Minimization in Computer Vision





Graph cuts and image segmentation

Total Variation Denoising





► Chambolle, 2005.

Definition: $F: 2^V \to \mathbb{R}$ is **submodular** if and only if

$$\forall A, B \subseteq V, F(A) + F(B) \ge F(A \cup B) + F(A \cap B)$$

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- Always assume $F(\emptyset) = 0$.

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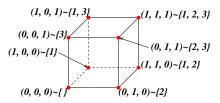
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Diminishing returns property

Subsets as pseudo boolean functions

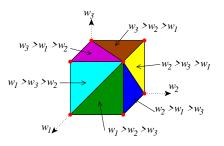
▶ Subsets may be identified with elements of $\{0,1\}^p$.



Lovász extension

lacktriangle Given any set-function F and w such that $w_{j_1}\geqslant \cdots \geqslant w_{j_p}$,

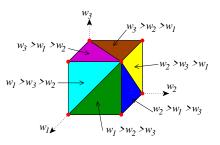
$$f(w) = \sum_{k=1}^{p-1} (w_{j_k} - w_{j_{k+1}}) F(\{j_1, \dots, j_k\}) + w_{j_p} F(\{j_1, \dots, j_p\})$$



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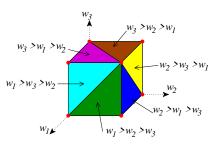


- f is piecewise-linear and positively homogeneous
- if $w = 1_A$, f(w) = F(A)
- **Extension from** $\{0,1\}^p$ to \mathbb{R}^p

Lovász extension

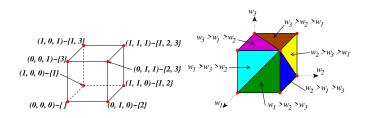
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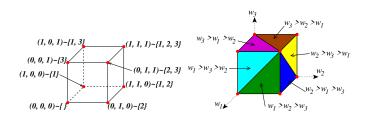
- f is piecewise-linear and positively homogeneous
- if $w = 1_A$, f(w) = F(A)
- ightharpoonup Extension from $\{0,1\}^p$ to \mathbb{R}^p
- ► **Theorem**: *F* is submodular if and only if *f* is convex

Cut functions and Lovász extension



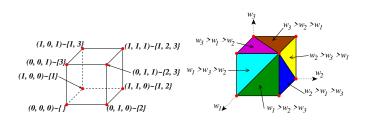
▶ Cut function. $F: 2^V \to \mathbb{R}$ such that $F(A) = \sum_{i \in V} \sum_{j \in \mathcal{N}(i)} a_{ij} |1_{i \in A} - 1_{j \in A}|$.

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- ▶ If *F* is a <u>cut function</u> then *f* is the corresponding <u>total</u> <u>variation</u> problem.

From submodular minimization to smooth problems

Related optimization problems

(D) Discrete
$$\min_{A \subset V} F(A) - u(A)^{1} = \min_{w \in \{0,1\}^{p}} f(w) - u^{\top} w$$
(C) Continuous
$$\min_{A \subset V} f(w) = u^{\top} w$$

(C) Continuous
$$\min_{w \in [0,1]^p} f(w) - u^\top w$$

(S) Smooth
$$\min_{w \in \mathbb{R}^p} f(w) - u^\top w + \frac{1}{2} \|w\|_2^2$$

 $^{^{1}}u(A) = u^{\top}1_{A}$

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► Solving (S) is equivalent to

$$\min_{A\subset V} F(A) - u(A) + \lambda |A|, \forall \lambda \in \mathbb{R}$$

- $\Rightarrow \arg\min_{A \subset V} F(A) u(A) + \lambda |A| = \{k, w_k \geqslant \lambda\}$
- Consequence of F being submodular.
- $\lambda = 0$ solves **(D)**.

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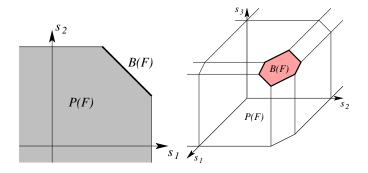
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- ▶ If **(D)** is graph cut \Rightarrow **(S)** is parametric maxflow.

 $^{^{1}}u(A) = u^{\top}1_{A}$

Submodular Functions and base polyhedra

- Submodular polyhedron: $P(F) = \left\{ s \in \mathbb{R}^p, \ \forall A \subset V, \ s(A) \leqslant F(A) \right\}$
- ▶ Base polyhedron: $B(F) = P(F) \cap \{s(V) = F(V)\}$
- ▶ Many facets (up to 2^p), many extreme points (up to p!)



Lovász extension and base polyhedra

- Fundamental property: If F is submodular, maximizing linear functions may be done by a "greedy algorithm"
 - Let $w \in \mathbb{R}^p_+$ such that $w_{i_1} \geqslant \cdots \geqslant w_{i_n}$
 - ▶ Let $s_{j_k} = F(\{j_1, ..., j_k\}) F(\{j_1, ..., j_{k-1}\})$ for $k \in \{1, ..., p\}$ ▶ Then $f(w) = \max_{s \in P(F)} w^{\top} s = \max_{s \in B(F)} w^{\top} s$

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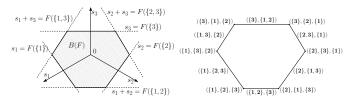
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- Primal Dual
 - **Primal**: $\min_{w \in \mathbb{R}^p} f(w) u^\top w + \frac{1}{2} ||w||_2^2$
 - ▶ **Dual** : $\max_{s \in B(F)} -\frac{1}{2} \|u s\|_2^2$
 - At optimal, $w^* = u s^*$

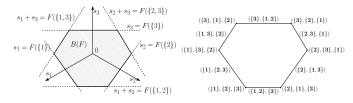
Faces of the Base Polyhedon and Ordered Partitions

$$B(F) = \{ s \in \mathbb{R}^p, \ \forall A \subset V, \ s(A) \leqslant F(A), s(V) = F(V) \}$$



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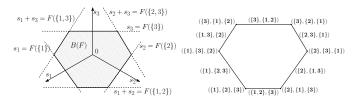
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- ▶ Given an Ordered Partition $\mathcal{A} = (A_1, \dots, A_m)$
- ▶ Let $B_i = A_1 \cup ... \cup A_i, \forall i = 1,..., m$. $B_m = V$

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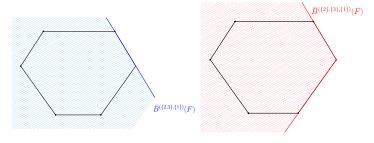
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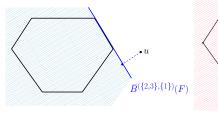
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- lacktriangle Outer approximation of B(F) by the ordered partition $\mathcal A$

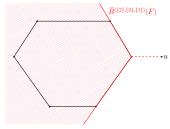
$$\widehat{B}^{\mathcal{A}}(F) = \{s \in \mathbb{R}^n, s(V) = F(V), \forall i = \{1, \dots, m-1\}, s(B_i) \leq F(B_i)\}$$

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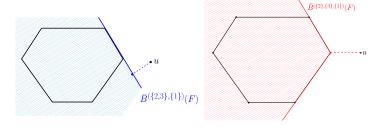


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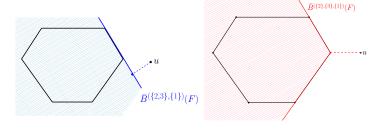


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- $\max_{s \in \widehat{B}^{\mathcal{A}}(F)} -\frac{1}{2} \|u s\|_2^2$
- $ightharpoonup \min_{w \in \mathbb{R}^p} f(w) u^\top w + \frac{1}{2} \|w\|_2^2$, s.t. w is compatible with \mathcal{A}

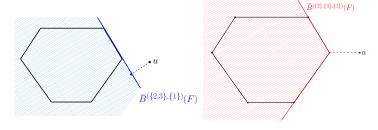
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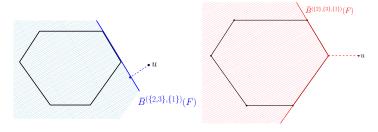
 - $w = \sum_{i=1}^{m} v_i 1_{A_i}$ $f(w) = \sum_{i=1}^{m} v_i [F(B_i) F(B_{i-1})]$

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- \blacktriangleright min_{$w \in \mathbb{R}^p$} $f(w) u^\top w + \frac{1}{2} ||w||_2^2$, s.t. w is compatible with \mathcal{A}
 - $\mathbf{w} = \sum_{i=1}^{m} v_i 1_{A_i}$
 - $f(w) = \sum_{i=1}^{m} v_i [F(B_i) F(B_{i-1})]$
- ▶ $\min_{v \in \mathbb{R}^m} \sum_{i=1}^m v_i [F(B_i) F(B_i 1) u(A_i)] + \frac{1}{2} \sum_{i=1}^m |A_i| v_i^2$ such that $v_1 \ge \ldots \ge v_m$

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- $ightharpoonup \max_{s \in \widehat{B}^{\mathcal{A}}(F)} -\frac{1}{2} \|u s\|_{2}^{2}$
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- ▶ $\min_{v \in \mathbb{R}^m} \sum_{i=1}^m v_i [F(B_i) F(B_i 1) u(A_i)] + \frac{1}{2} \sum_{i=1}^m |A_i| v_i^2$ such that $v_1 > \ldots > v_m$
- lsotonic regression solved using wpav, s = u w
- ▶ Refines A by merging partitions and ensuring $v_1 > ... > v_{m'}$

Optimality test and Splitting partitions

▶
$$s \in B(F)$$
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Optimality test and Splitting partitions

- ▶ $s \in B(F)$, i.e., $\forall A \subset V, s(A) \leq F(A)$
- SFM oracle which solves

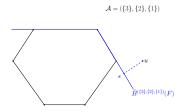
$$C = \min_{A \subset V} F(A) - s(A)$$

Optimality test and Splitting partitions

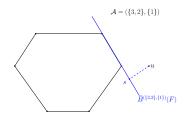
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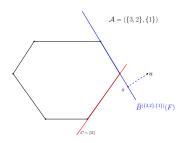
▶ If F(C) - s(C) < 0 then split all the ordered partitions of A that intersect with C



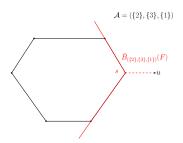
- Input : Submodular function F with SFM oracle, $u \in \mathbb{R}^p$, ordered partition \mathcal{A}
- Algorithm : iterate until convergence
 - (a) Project u onto outer-approximation $\widehat{B}^{\mathcal{A}}(F)$ (using isotonic regression)



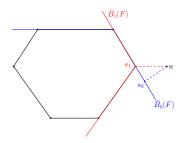
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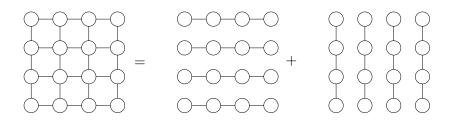


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 - (d) If not optimal then split the ordered partitions of A that intersect with C and goto (a).



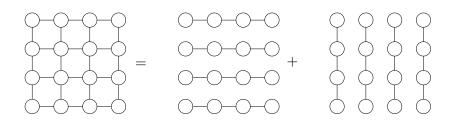
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Decomposable functions



► **Goal:** Use simpler SFM oracles to solve (S) and as a consequence solve (D)

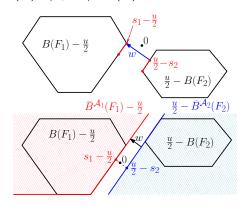
Decomposable functions



- ➤ **Goal:** Use simpler SFM oracles to solve (S) and as a consequence solve (D)
- **(D)** : $\min_{A \subset V} F_1(A) + F_2(A) u(A)$
- **(S)** : $\min_{w \in \mathbb{R}^p} f_1(w) + f_2(w) u^\top w + \frac{1}{2} ||w||_2^2$
- ▶ **Dual**: $\min_{s_1 \in B(F_1) u/2, -s_2 \in u/2 B(F_2)} ||s_1 (-s_2)||_2$

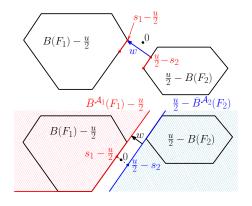
Closest points between two polytopes

Dual: $\min_{s_1 \in B(F_1) - u/2, s_2 \in u/2 - B(F_2)} \|s_1 - s_2\|_2$



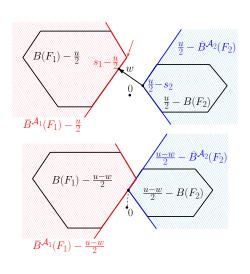
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- Reflection methods for user-friendly submodular optimization. S.Jegelka, F. Bach and S. Sra, NIPS-2013.
- Uses expensive TV oracles.

Translated intersecting polytopes



- ▶ **Input**: Submodular function F_1 and F_2 with SFM oracles, $u \in \mathbb{R}^n$, ordered partitions A_1, A_2
- ▶ **Algorithm**: iterate until convergence (i.e., $\varepsilon_1 + \varepsilon_2$ small enough)

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 - (a) Find $\mathcal{A} = \operatorname{coalesce}(\mathcal{A}_1, \mathcal{A}_2)$ and run isotonic regression to minimize $f(w) u^\top w + \frac{1}{2} \|w\|_2^2$ such that w is compatible with \mathcal{A} .

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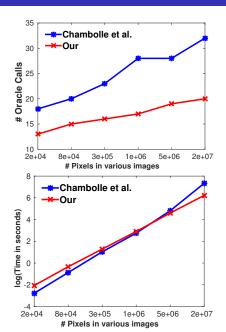
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 - (d) Check optimality by solving $\min_{C_{j,i_j} \subseteq A_{j,i_j}} F_j(B_{j,i_j-1} \cup C_{j,i_j}) F_j(B_{j,i+j-1}) s_j(C_{j,i_j})$ for $i_j \in \{1, \ldots, m_j\}$, Monitor ε_1 and ε_2 such that $F_j(C_j) s_j(C_j) \geqslant -\varepsilon_j$, j = 1, 2.

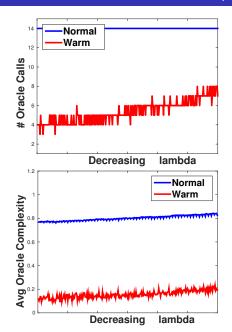
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 - (e) If both s_1 and s_2 not optimal, for all C_{j,i_j} which are different from \emptyset and A_{i,i_j} , split partitions.
- **Output**: $w \in \mathbb{R}^n$ and $s_1 \in B(F_1)$, $s_2 \in B(F_2)$.

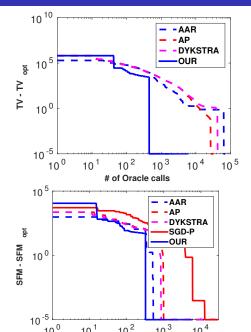
Results for 2D TV without decomposition



Results for 2D TV without decomposition (Warm Start)



Results for 2D TV with decomposition into 1D



Thank You. Questions?