



# DD2437 – Artificial Neural Networks and Deep Architectures (annda)

## Lecture 8: Hopfield networks

Pawel Herman

Computational Science and Technology (CST)  
KTH Royal Institute of Technology

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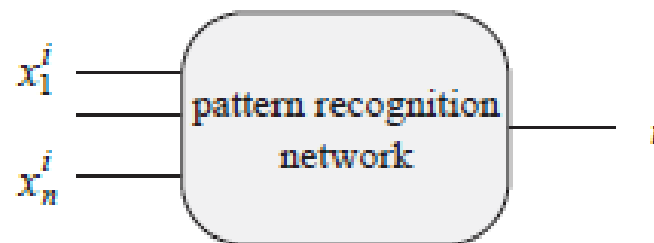
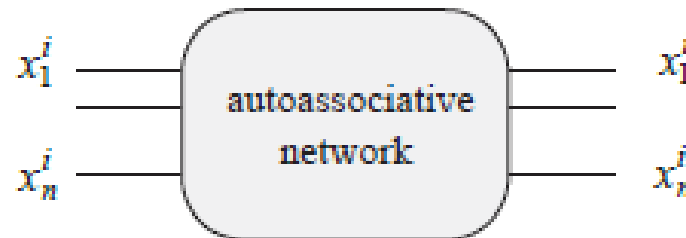
- Associative memory
- Hopfield networks
- Memory storage and TSP example
- Stochastic networks – Boltzmann machine

# Lecture overview

- Associative memory, learning
- Hopfield networks
- Storage capacity
- Optimisation with Hopfield networks

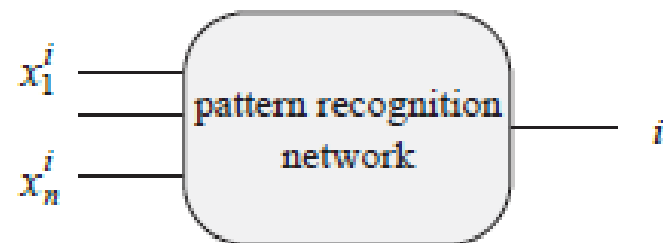
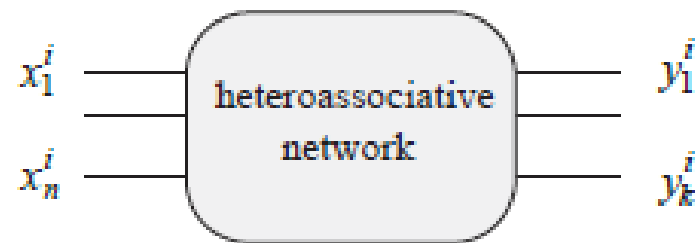
- **Associative memory**
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# Associative pattern recognition



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# Associative pattern recognition

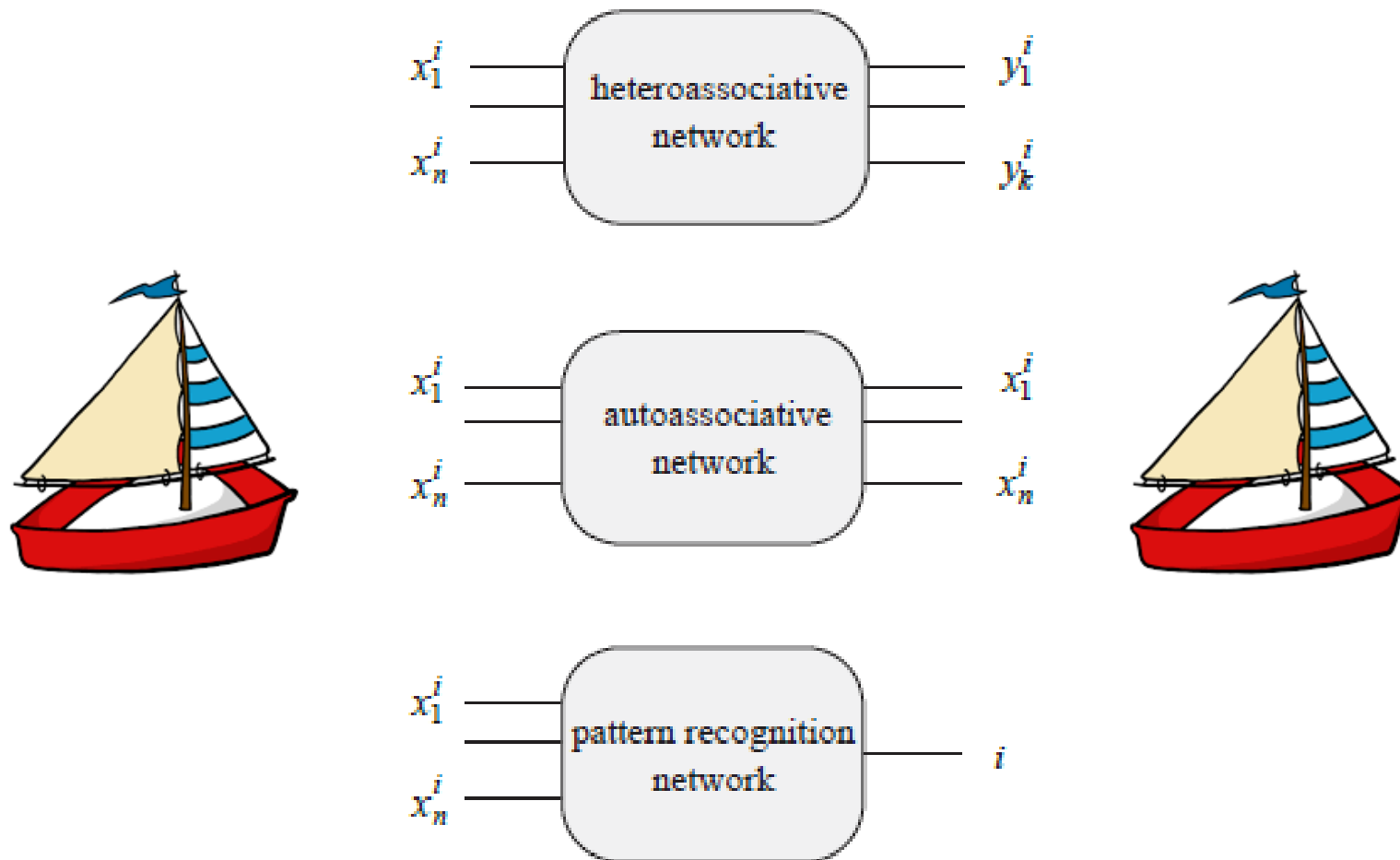


boat



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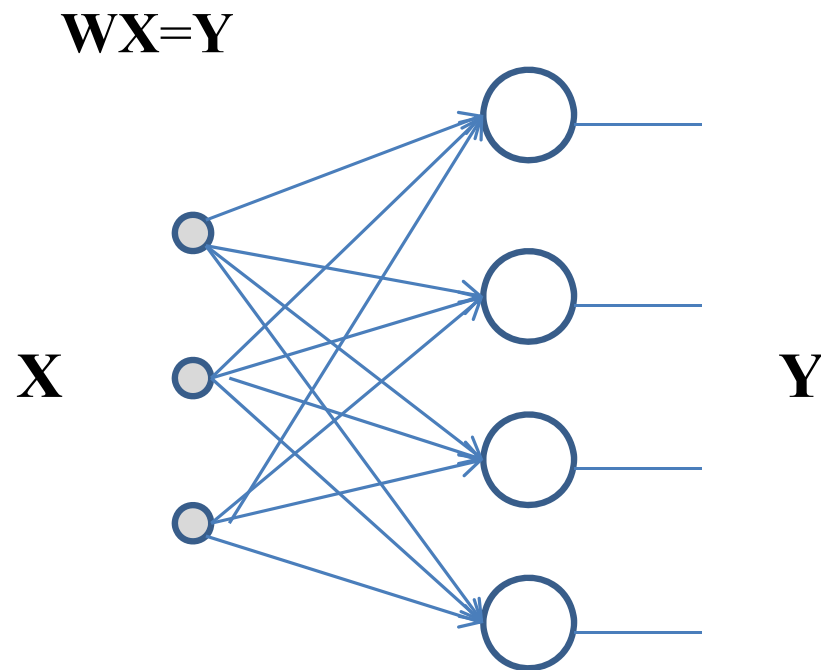
# Associative pattern recognition



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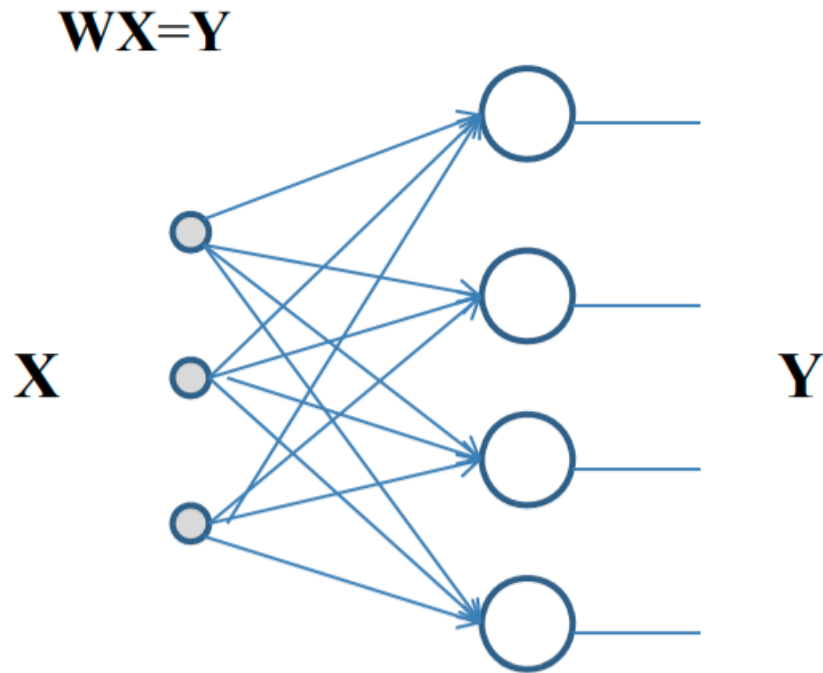
# Linear associative memory networks

- Single layer networks (see lecture 2, correlation memory)



without feedback  
(recall is a feedforward step)

# Slide 6



$$WX=Y$$

**X after W means  
patterns are column-wise**

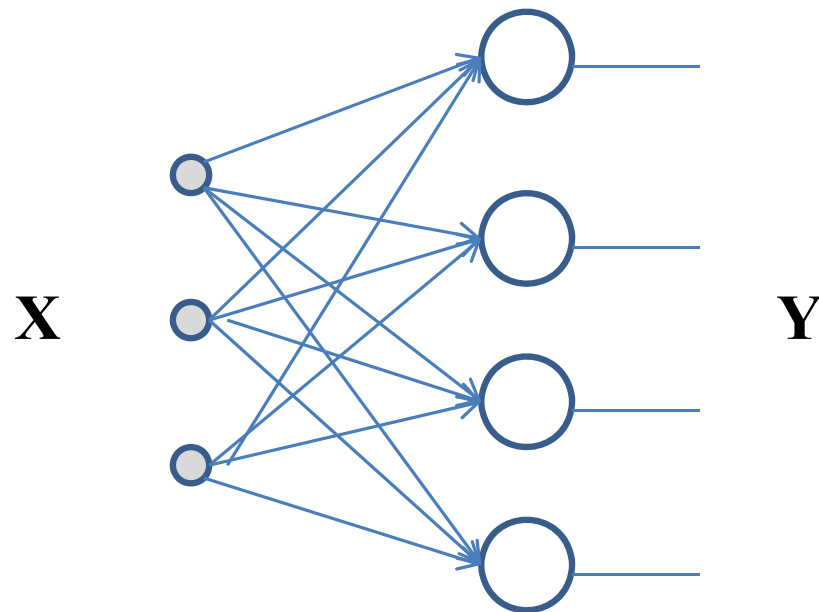
	<b>P11</b>	<b>P21</b>	<b>P31</b>
	<b>P12</b>	<b>P22</b>	<b>.</b>
<b>X =</b>	<b>P13</b>	<b>P23</b>	<b>.</b>
	<b>.</b>	<b>.</b>	<b>.</b>
	<b>.</b>	<b>.</b>	<b>.</b>

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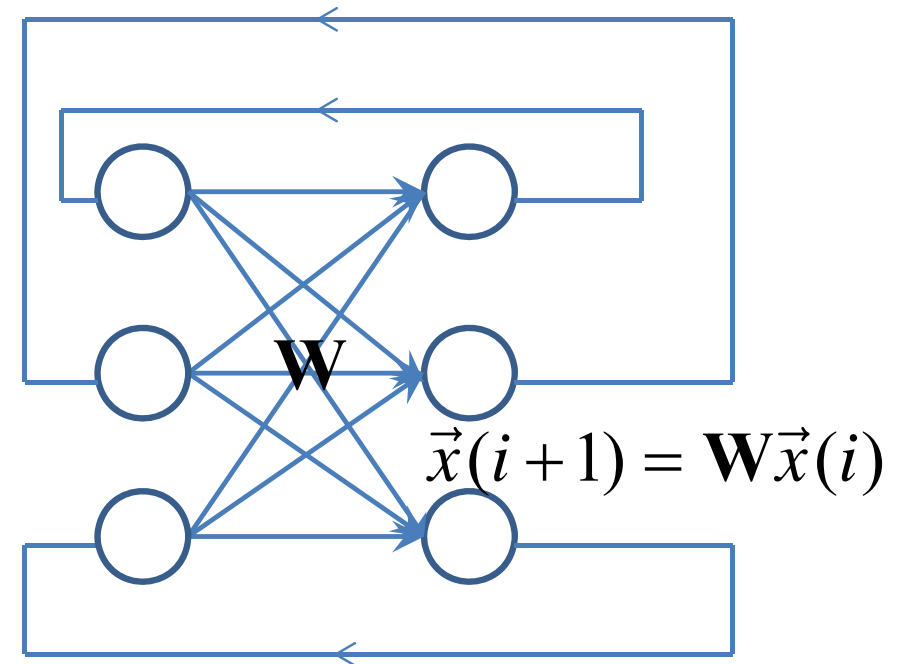
# Linear associative memory networks

- Simple single layer or recurrent networks

$$\mathbf{W}\mathbf{X}=\mathbf{Y}$$



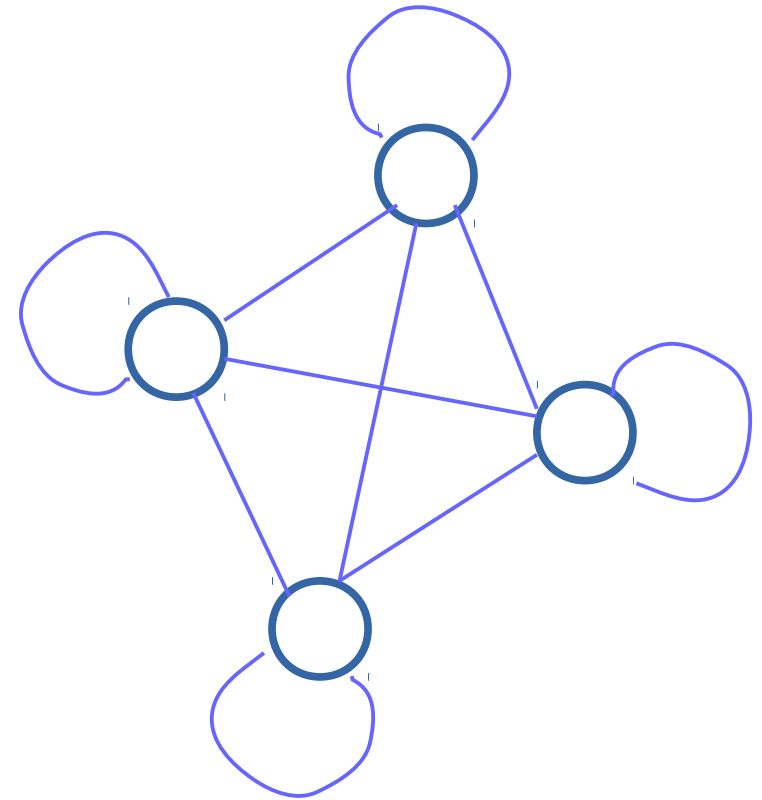
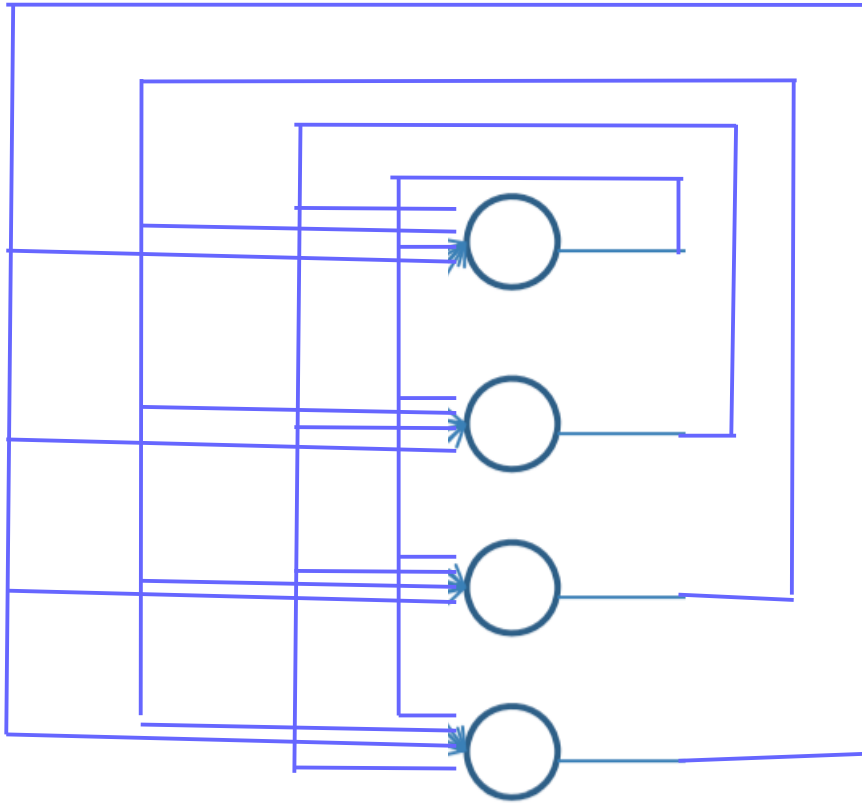
without feedback  
(recall is a feedforward step)



autoassociative recurrent network, with feedback  
(recall is an iterative process)



# Slide 7

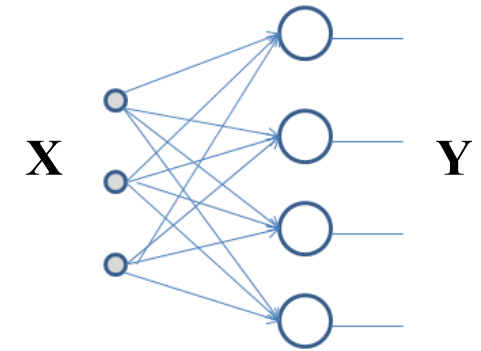


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# Associative learning in a single layer network

- Bipolar coding  $\{-1, 1\}$  with sign transform:

$$\text{sgn}(x) = \begin{cases} 1, & x \geq 0 \\ -1, & x < 0 \end{cases}$$

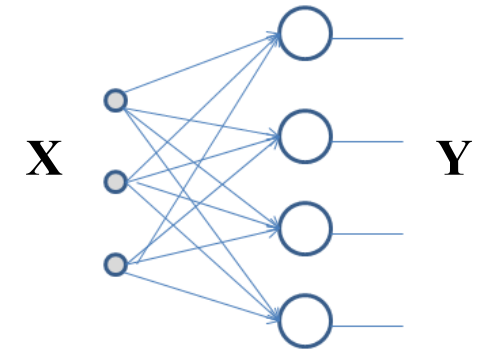


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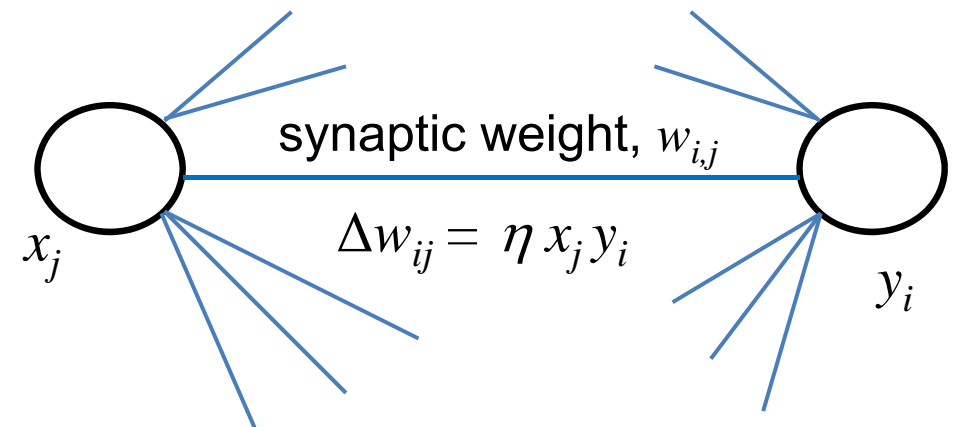
$$\text{sgn}(x) = \begin{cases} 1, & x \geq 0 \\ -1, & x < 0 \end{cases}$$



- Hebbian learning (correlation learning, outer product)

$$\mathbf{W} = \mathbf{W}^1 + \mathbf{W}^2 + \dots + \mathbf{W}^m$$

$$\mathbf{W}^k = [w_{ij}] = [x_j^k \ y_i^k] \quad (\text{outer product})$$



# Slide 9

$$\mathbf{W} = \mathbf{W}^1 + \mathbf{W}^2 + \dots + \mathbf{W}^m$$

$$\mathbf{W}^k = [w_{ij}] = [x_j^k \ y_i^k] \quad (\text{outer product})$$

All elements  
of  $\mathbf{W}^k$

columns

rows

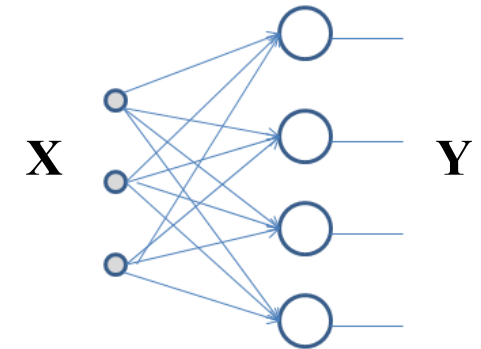
→ matrix

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# Associative learning in a single layer network

- Bipolar coding  $\{-1, 1\}$  with sign transform:

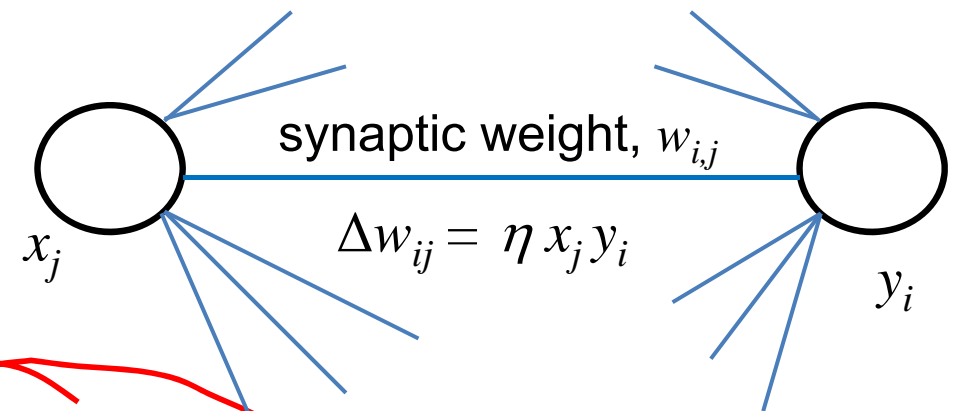
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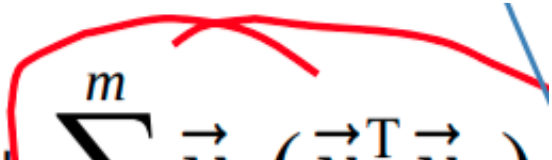


$$\vec{y}_p (\vec{x}_p^T \vec{x}_p) + \sum_{p \neq k}^m \vec{y}_k (\vec{x}_p^T \vec{x}_k)$$

**crosstalk**

# Slide 10

$$\mathbf{W}^k = [w_{ij}] = [x_j^k \ y_i^k] \quad (\text{outer product})$$

$$y_{\text{out}} = \mathbf{W} x_p = \sum_{k=1}^m (y_k x_k^T) x_p = \underbrace{\vec{y}_p (\vec{x}_p^T \vec{x}_p)}_{= \text{alpha}} + \sum_{k \neq p}^m \vec{y}_k (\underbrace{\vec{x}_p^T \vec{x}_k}_{= 0 \text{ if orthogonal}})$$


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# Hebbian learning for associative memory

- Autoassociative case

$$\mathbf{W} = \mathbf{X}\mathbf{X}^T$$

$$\text{sgn}(\mathbf{W}\vec{x}) = \vec{x}, \quad \text{sgn}(\mathbf{W}\mathbf{X}) = \mathbf{X}$$

Essentially,  $\vec{x}$  are the eigenvectors of nonlinear  $\text{sgn}$  operation so the idea is to find  $\mathbf{W}$  for which  $\text{sgn}(\mathbf{W}\mathbf{X})$  has these patterns as eigenvectors,

but we do not want  $\mathbf{W} = \mathbf{I}$  as a trivial solution of  $\text{sgn}(\mathbf{W}\mathbf{X}) = \mathbf{X}$

$$\text{for } \mathbf{W} = \mathbf{X}\mathbf{X}^T, \quad \text{sgn}(\mathbf{W}\mathbf{X}) = \text{sgn}(\underbrace{\mathbf{X}\mathbf{X}^T}_{\mathbf{I}}\mathbf{X}) = \text{sgn}(\mathbf{X}) = \mathbf{X}$$

For orthogonal  $\mathbf{X}$  (or nearly),  
 $\mathbf{X}^T\mathbf{X}$  is a scaled identity  $\mathbf{I}$  matrix

# Slide 11

Goal:  $\text{sgn}(\mathbf{W}\vec{x}) = \vec{x}$

Ansatz:  $\mathbf{W} = \mathbf{X}\mathbf{X}^T$

$$\text{sgn}(\mathbf{W}\mathbf{X}) = \text{sgn}(\underbrace{\mathbf{X}\mathbf{X}^T}_{\text{scaled identity}}\mathbf{X}) = \text{sgn}(\mathbf{X}) = \mathbf{X}$$

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$$\mathbf{W} = \mathbf{X}\mathbf{X}^T$$

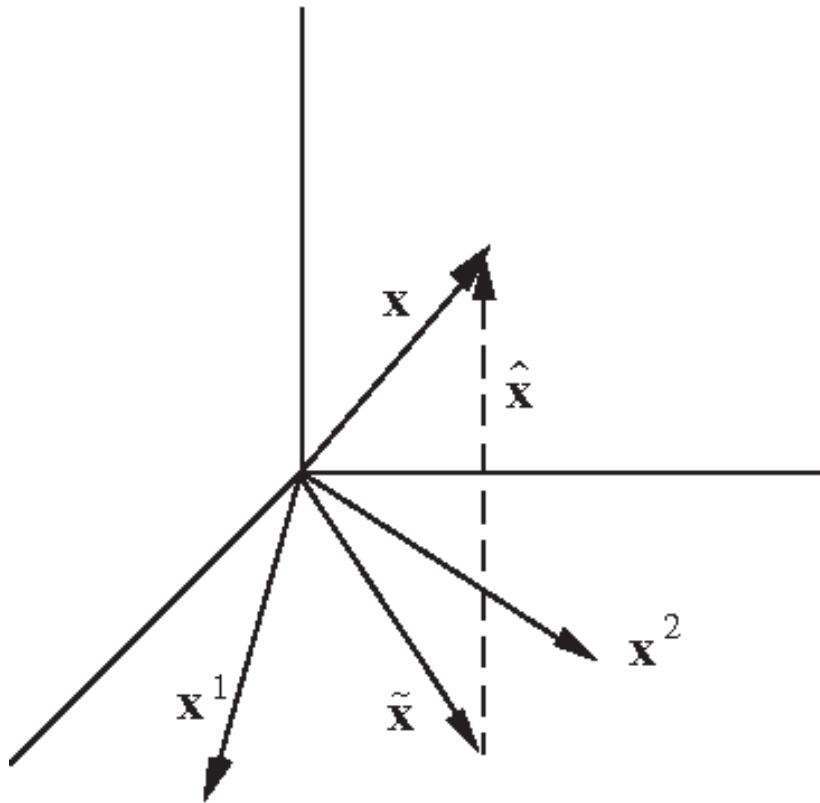
From a geometrical perspective:

$\mathbf{W}$  describes *non-orthogonal* projection on the subspace spanned by  $\vec{x}$ .

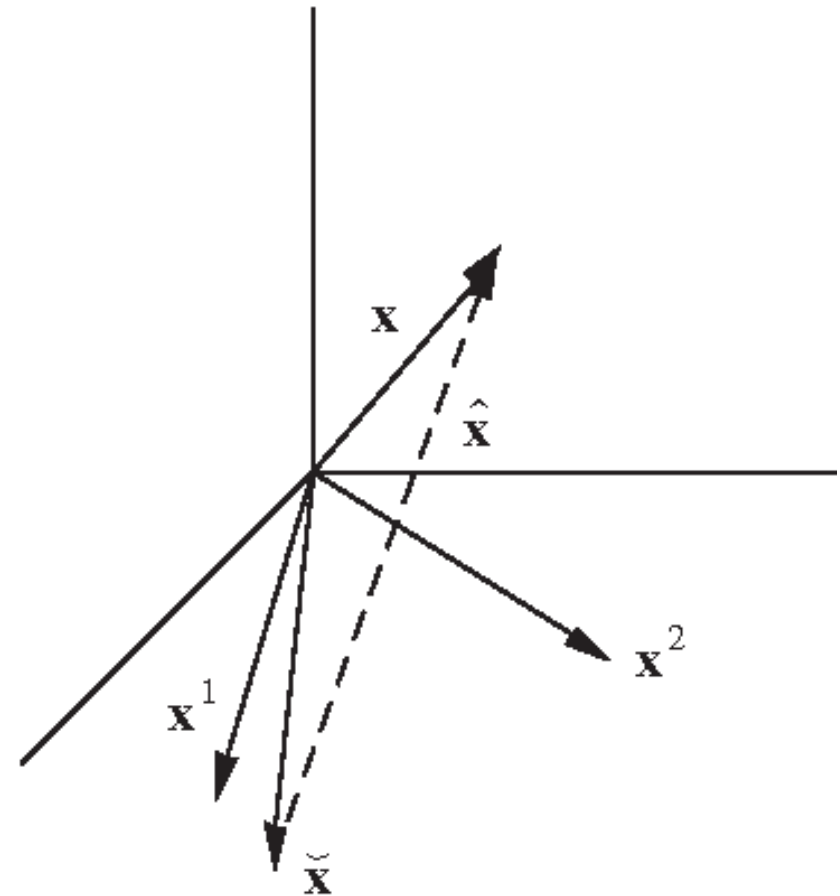
# Slide 12

## $W$ describes a projection

orthogonal projection



non-orthogonal projection



Pseudo inverse rule

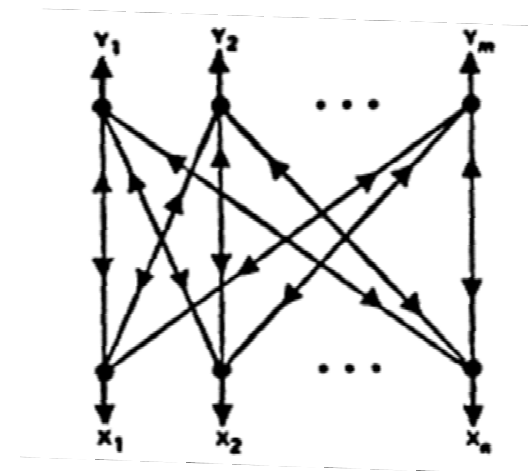
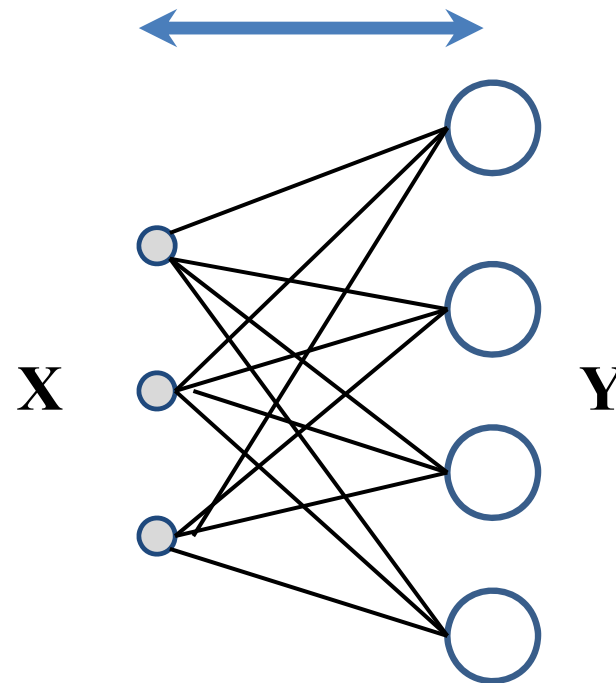
Hebb rule

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# Bidirectional associative memory (resonance)

Builds on the concept of memory networks with feedback (recursive)

- bipolar  $\{-1, 1\}$  coding
- sign activation function



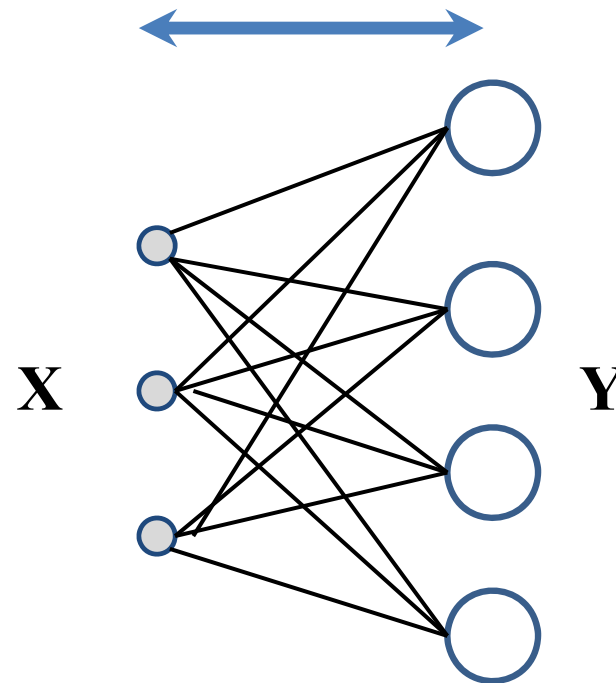
B. Kosko, 1988

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# Bidirectional associative memory (resonance)

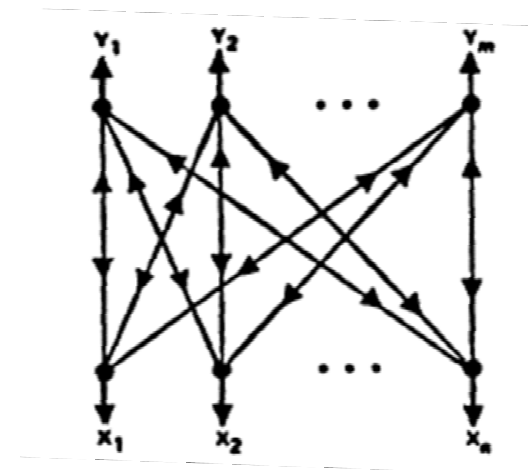
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Bidirectionality (feedback) imposes extra challenges

- synchronous vs asynchronous update
- different properties depending on updating mode



B. Kosko, 1988

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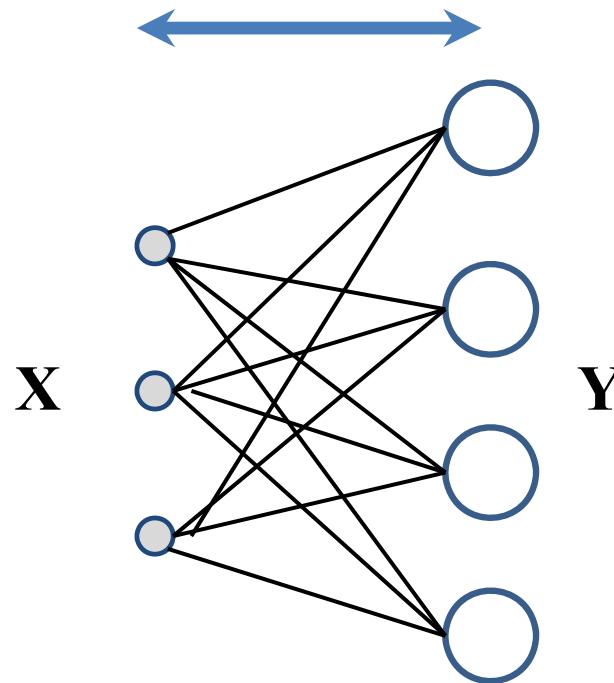
# Bidirectional associative memory (resonance)

Builds on the concept of memory networks with feedback (recursive)

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$$\vec{y}(t) = \text{sgn}(\mathbf{W}\vec{x}(t))$$

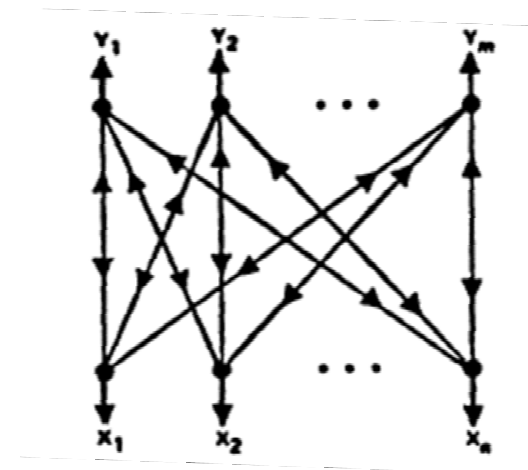
$$\vec{x}(t+1) = \text{sgn}(\mathbf{W}\vec{y}(t))$$



Does it converge?  
What are stable points?

Bidirectionality (feedback) imposes extra challenges

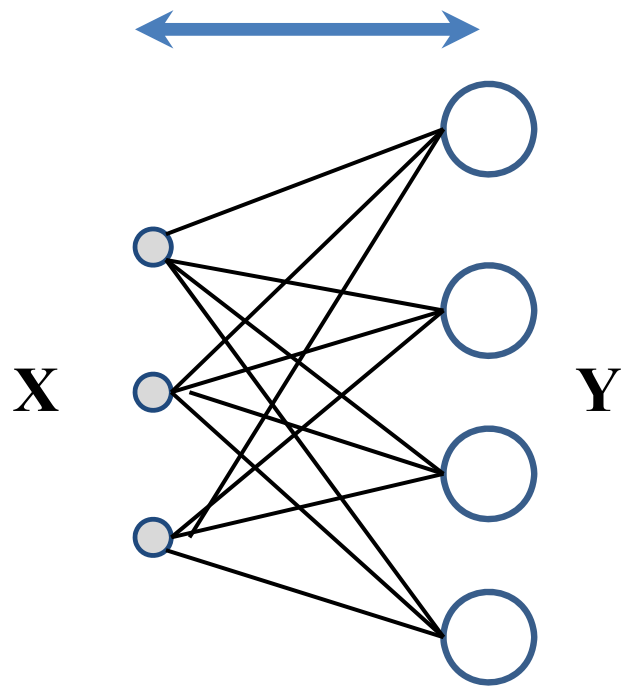
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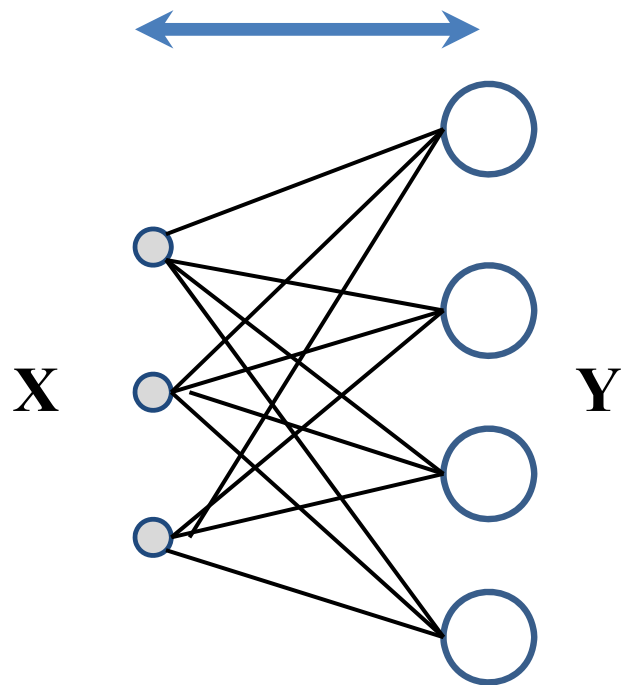
# Concept of energy in BAM



If  $(\vec{x}, \vec{y})$  is a stable point, then nearby points like  $(\vec{x}_0, \vec{y}_0)$  should converge.

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# Concept of energy in BAM



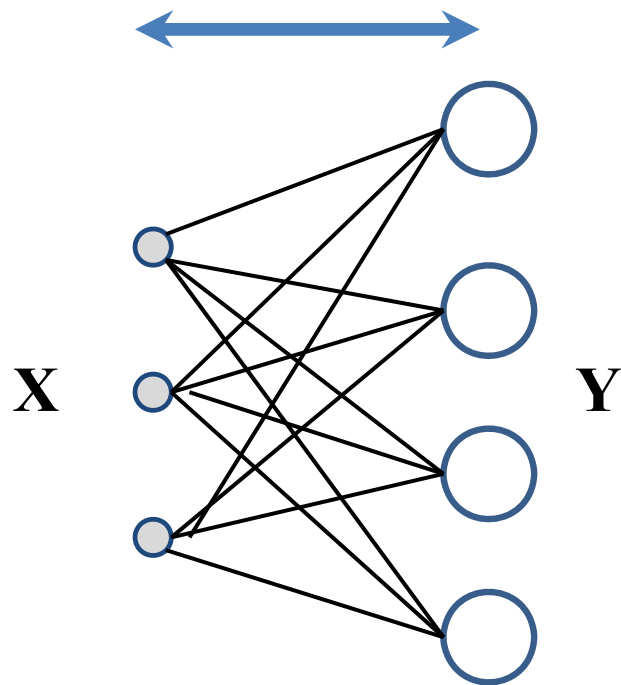
If  $(\vec{x}, \vec{y})$  is a stable point, then nearby points like  $(\vec{x}_0, \vec{y}_0)$  should converge.

$$\vec{y}_0 = \mathbf{W}\vec{x}_0, \text{ next } \vec{e} = \mathbf{W}^T \vec{y}_0$$

How far is  $\vec{e}$  from  $\vec{x}_0$ ?

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$$E = -\vec{x}_0^T \vec{e} = -\vec{x}_0^T \mathbf{W}^T \vec{y}_0 = -\vec{y}_0^T \mathbf{W} \vec{x}_0$$



# Slide 18

$$\vec{y}_0 = \mathbf{W}\vec{x}_0, \text{ next } \vec{e} = \mathbf{W}^T \vec{y}_0$$

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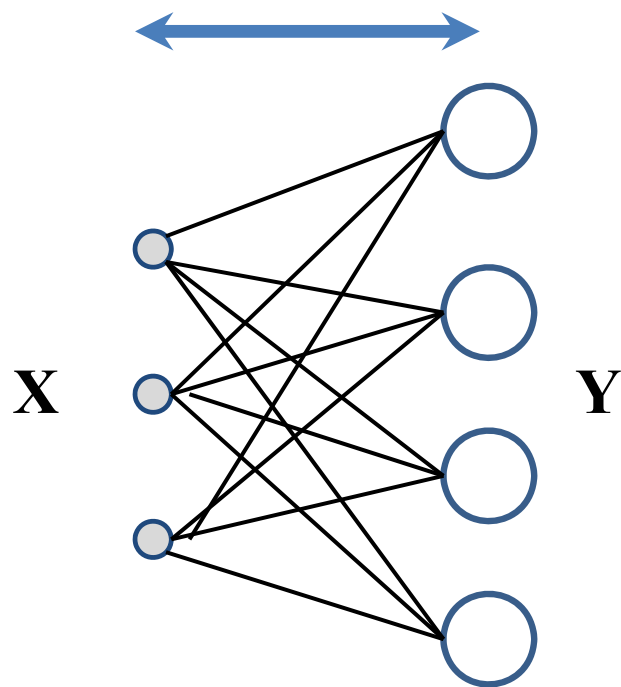
Scalar product,  
cosine distance

transpose

$$= -y_0^T y_0 = -\textit{alpha}$$

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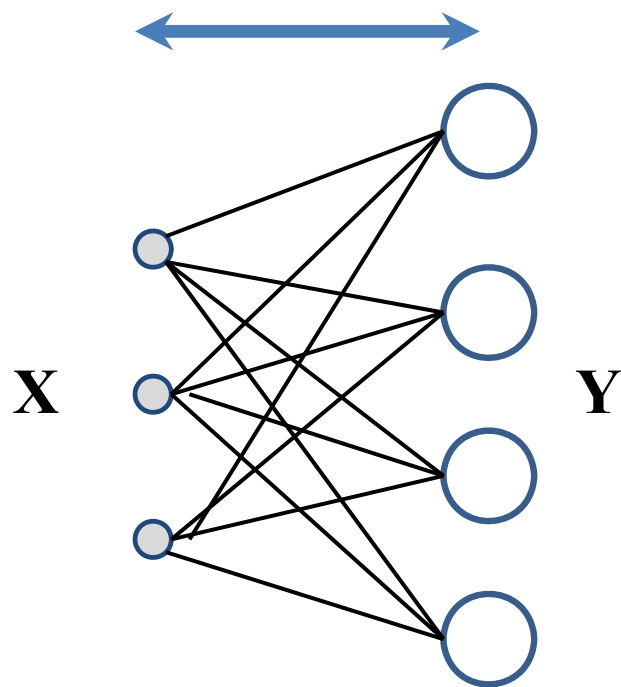
For the autoassociative BAM with  $\mathbf{W}$ , energy in the state  $\vec{x}$ :

$$E(\vec{x}, \vec{x}) = -\frac{1}{2} \vec{x}^T \mathbf{W} \vec{x}$$

$$E(\vec{x}) = -\frac{1}{2} \sum_{i,j=1}^n w_{i,j} x_i x_j$$

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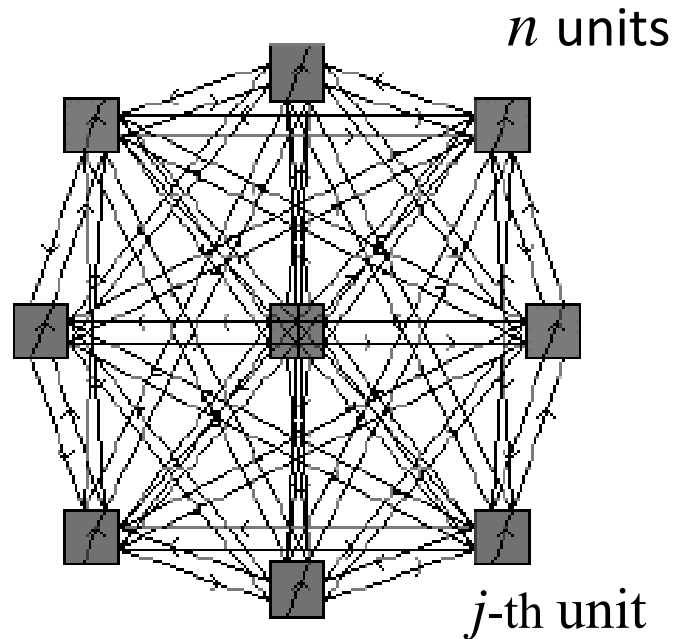
$$E(\vec{x}, \vec{x}) = -\frac{1}{2} \vec{x}^T \mathbf{W} \vec{x} + \vec{x}^T \vec{\theta}$$

**If bias is added**

$$E(\vec{x}) = -\frac{1}{2} \sum_{i,j=1}^n w_{i,j} x_i x_j + \sum_{i=1}^n \theta_i x_i$$

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# Hopfield network



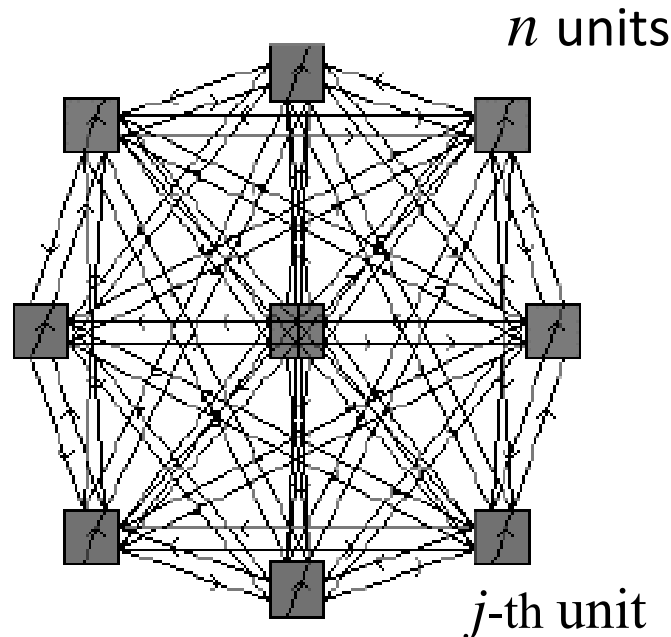
$$\forall_i w_{i,i} = 0 \quad \text{no self-connections}$$

$$\vec{x}' = \text{sgn}(\mathbf{W}\vec{x} + \vec{\theta})$$

$$E(\text{state} = \vec{x}) = -\frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n w_{i,j} x_i x_j + \sum_{i=1}^n \theta_i x_i$$

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# Hopfield network



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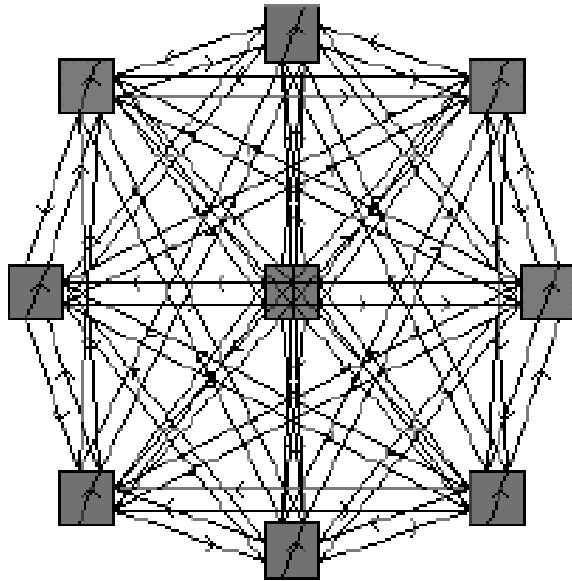
Iterative recall with asynchronous update

- 1) Apply input probe  $\xi_p = [\xi_{1,p}, \xi_{2,p}, \dots, \xi_{n,p}]$ , i.e.  $x_j(0) = \xi_{j,p}$
- 2) Iterate *asynchronous* update until convergence (until the state  $\mathbf{x}$  remains unchanged)

$$x_j(t+1) = \text{sgn}\left(\sum_{i=1}^n w_{j,i} x_i(t)\right) \quad j=1,\dots,n \text{ is randomly selected one at a time}$$

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# Hopfield network



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Update occurs only when the state changes, so.....

$$\Delta E_{x_j \rightarrow x_j^*} = -\frac{1}{2} \left( \sum_i^n w_{i,j} x_i x_j^* - \sum_i^n w_{i,j} x_i x_j \right) = -\frac{1}{2} (x_j^* - x_j) \sum_i^n w_{i,j} x_i \leq 0$$

## Slide 23

$$\Delta E_{x_j \rightarrow x_j^*} = -\frac{1}{2} \left( \sum_i^n w_{i,j} x_i x_j^* - \sum_i^n w_{i,j} x_i x_j \right) =$$

$W$  symmetric

Rearrange and  
find update rule

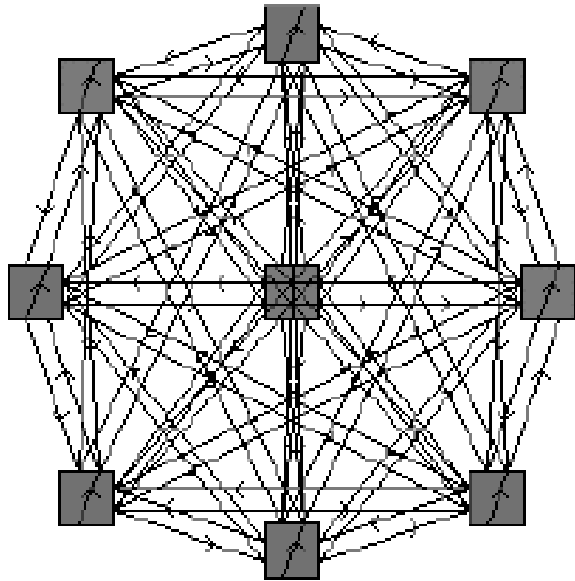
$$= -\frac{1}{2} (x_j^* - x_j) \sum_i^n w_{i,j} x_i \leq 0$$

If node turns on,  $x_j^*$  is  
larger and  $(.)$  is positive

Input to  $k$ :th node, if positive  
the node turns on

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# Hopfield network



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**W should be symmetric with diag=0 for convergence**

Update occurs only when the state changes, so.....

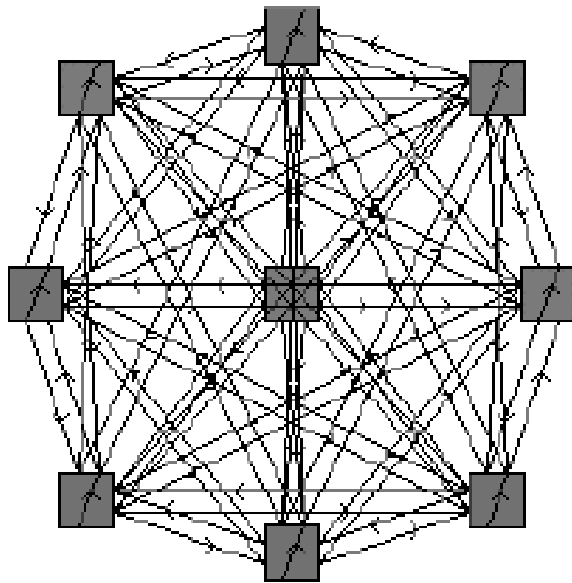
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**towards lower energy – convergence!**



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# Hopfield network



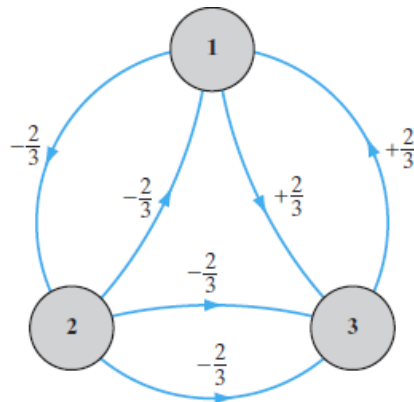
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$$E(\text{state} = \vec{x}) = -\frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n w_{i,j} x_i x_j + \sum_{i=1}^n \theta_i x_i$$

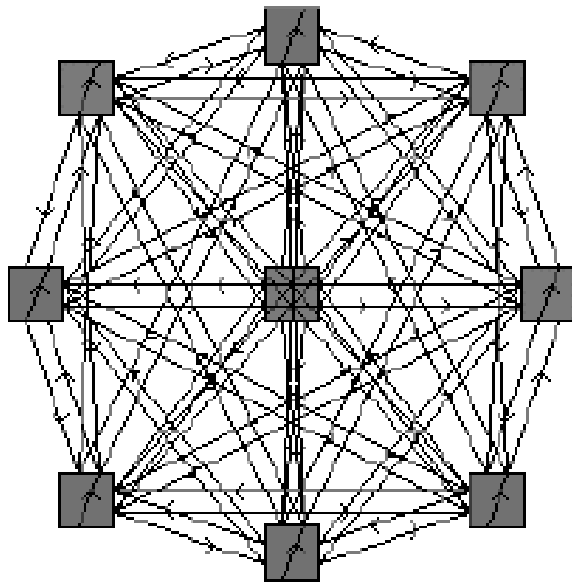
$\mathbf{W}$  should be symmetric with  $\text{diag}=0$  for convergence

How many states are candidates for fixed states?



- Associative memory
- **Hopfield networks**
- Memory storage and TSP example
- Stochastic networks – Boltzmann machine

# Hopfield network

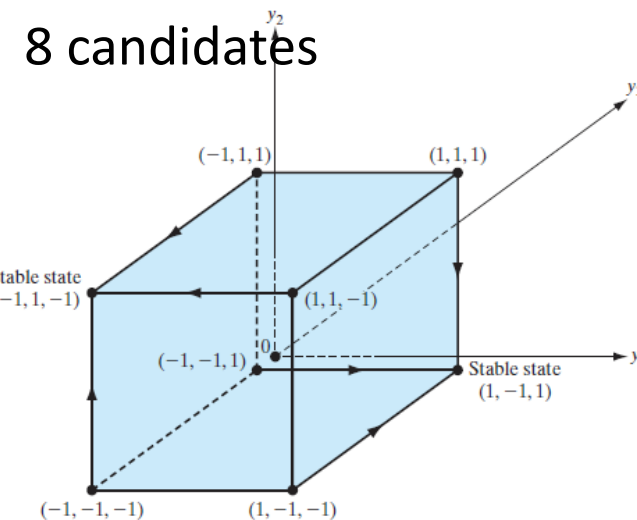
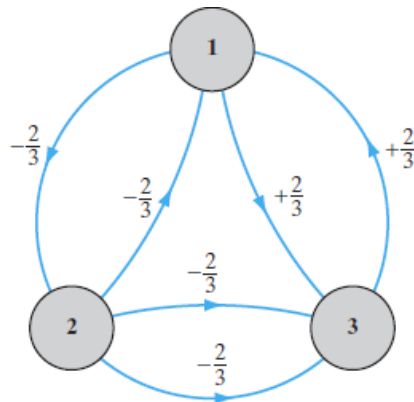


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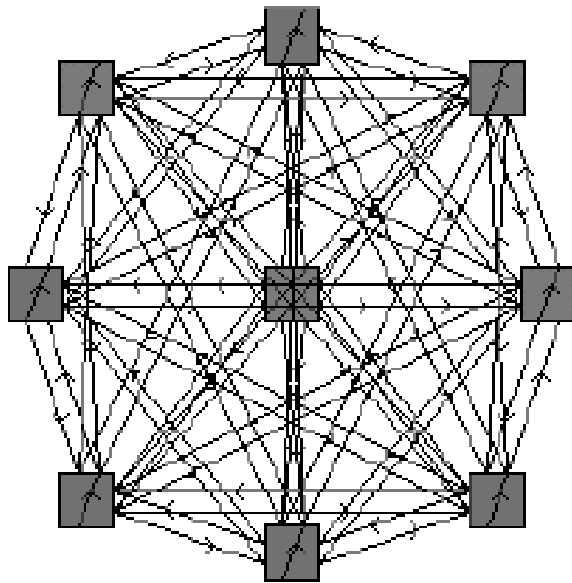
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# Hopfield network

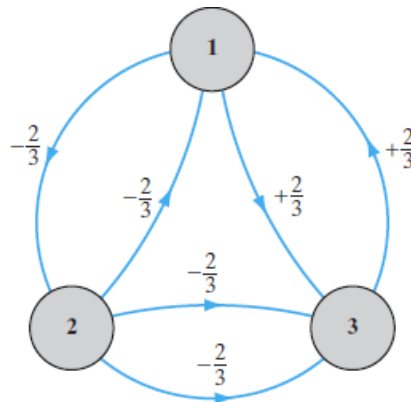


$$\forall_i w_{i,i} = 0 \quad \text{no self-connections}$$

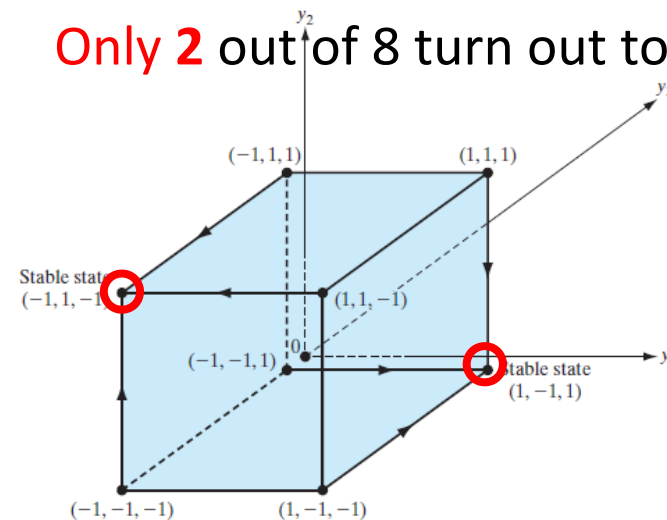
$$\vec{x}' = \text{sgn}(\mathbf{W}\vec{x} + \vec{\theta})$$

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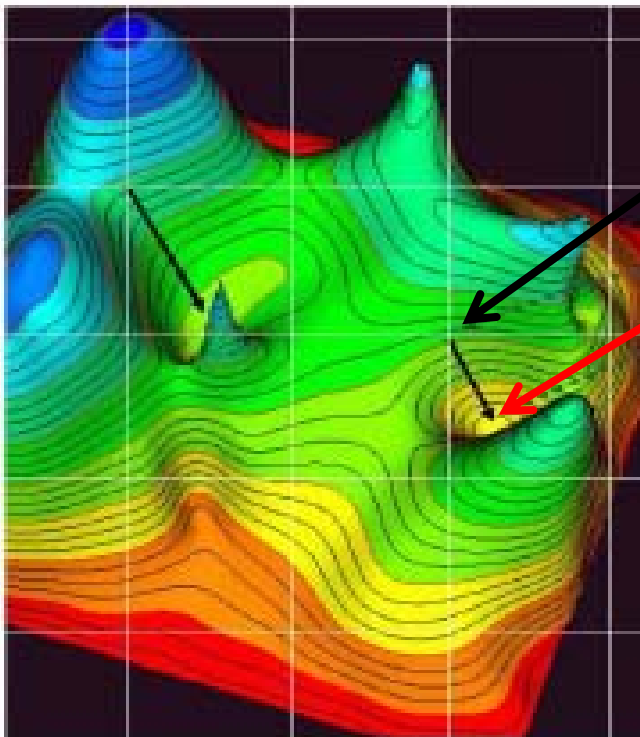


Only 2 out of 8 turn out to be stable!



- Associative memory
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# Attractor dynamics



**Memory cue**

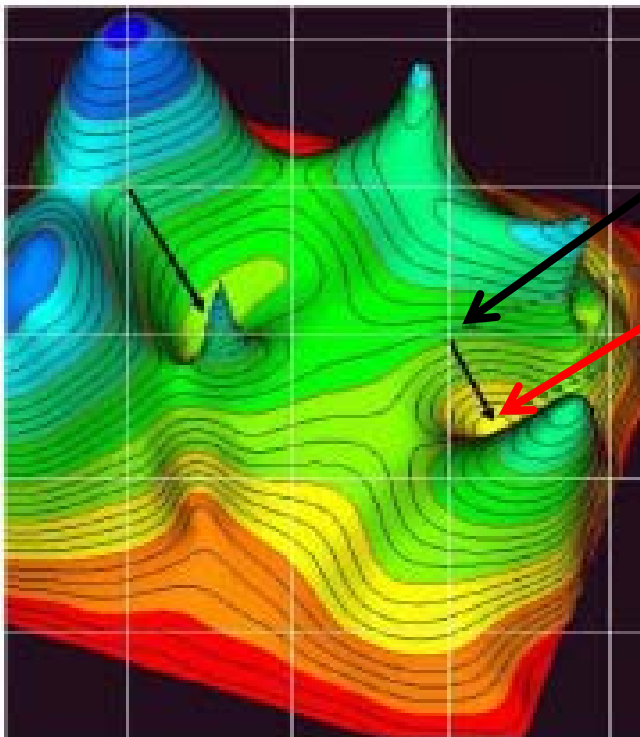
(within the basin of attractor)

**Memory state**

(local energy minimum,  
stable point, attractor)

- Associative memory
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# Attractor dynamics



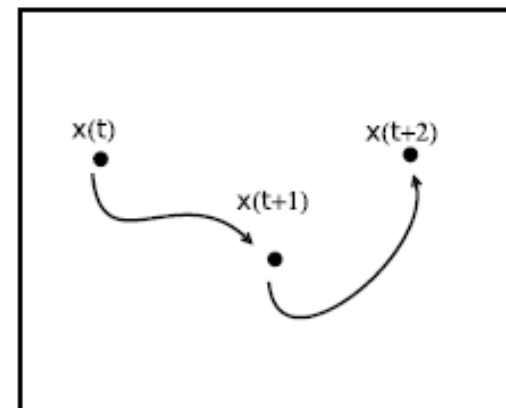
**Memory cue**

(within the basin of attractor)

**Memory state**

(local energy minimum, stable point, **fixed-point attractor**)

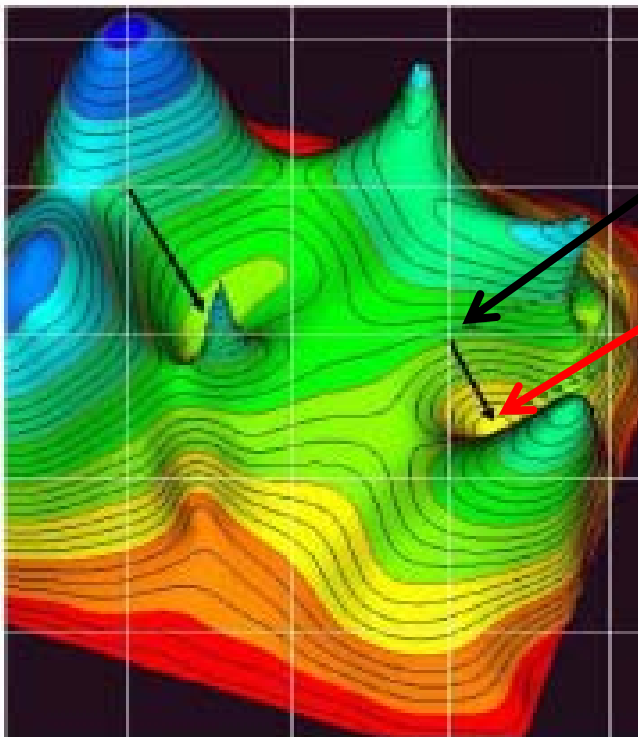
Dynamics travelling in the energy landscape and attracted to the energy minimum



In *discrete* Hopfield network, the energy landscape is discrete!

- Associative memory
- **Hopfield networks**
- Memory storage and TSP example
- Stochastic networks – Boltzmann machine

# Attractor dynamics



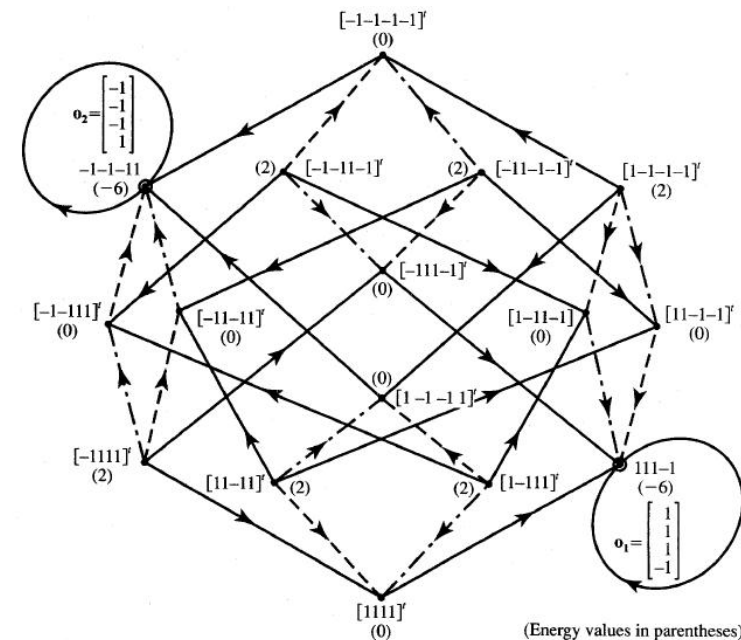
**Memory cue**

(within the basin of attractor)

**Memory state**

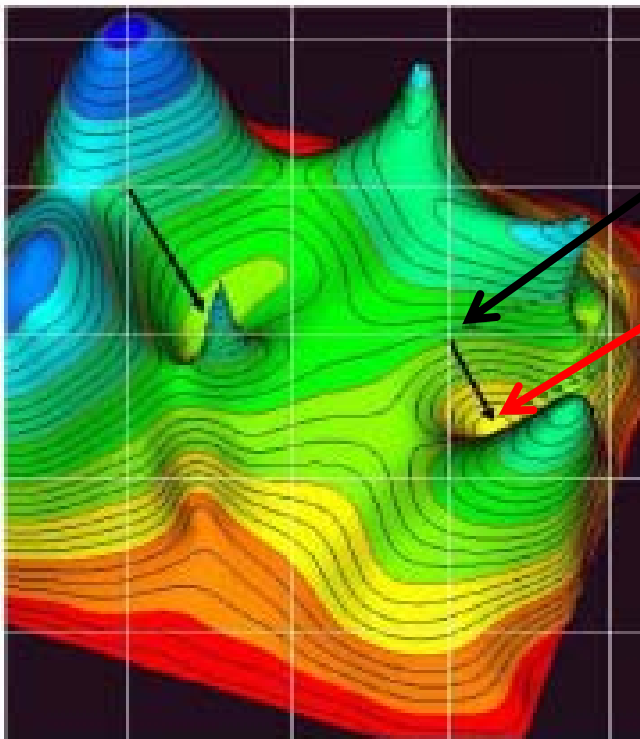
(local energy minimum, stable point, **fixed-point attractor**)

In *discrete* Hopfield network, the energy landscape is discrete!



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# Attractor dynamics



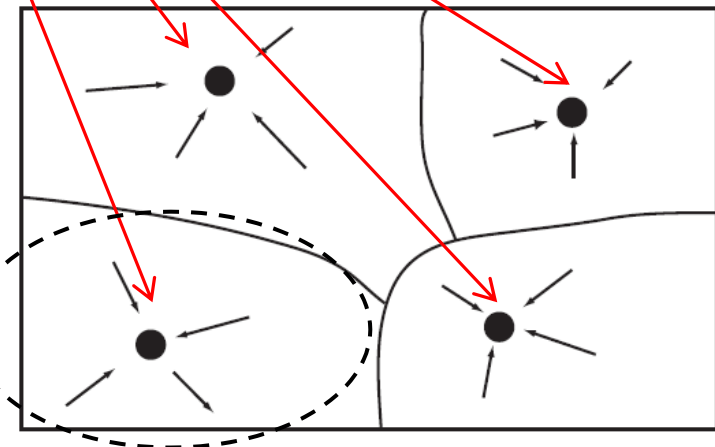
**Memory cue**

(within the basin of attractor)

**Memory state**

(local energy minimum,  
stable point, **fixed-point attractor**)

Around each fixed point (attractor), there is  
a ***basin of attraction***



- Associative memory
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- Stochastic networks – Boltzmann machine

# How do we learn memories for storage?

## Hopfield network as a content addressable memory

A set of memory patterns  $\{\xi_1, \xi_2, \dots, \xi_M\}$  to be learnt.

$$\xi_k = [\xi_{k,1}, \xi_{k,2}, \dots, \xi_{k,n}], \quad k=1, \dots, M$$

Outer product rule (Hebbian-like learning) is used to compute **W**:

$$w_{j,i} = \begin{cases} \frac{1}{n} \sum_{k=1}^M \xi_{k,j} \cdot \xi_{k,i}, & j \neq i \\ 0, & j = i \end{cases}$$



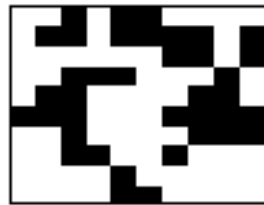
- Associative memory
- Hopfield networks
- **Memory storage and TSP example**
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# Pattern storage and recall example

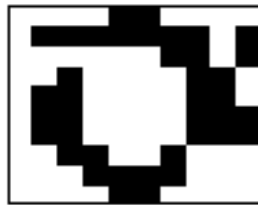
- ▶ The following patterns  $\xi^1$ ,  $\xi^2$ ,  $\xi^3$  were stored in the weight matrix  $W$ :



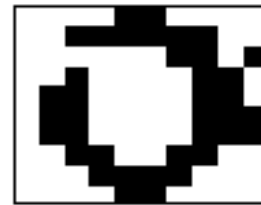
- ▶ Four snapshots of the state evolution  $x(t)$ :



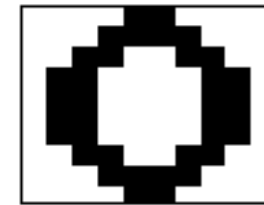
$t = 0$



$t = 50$

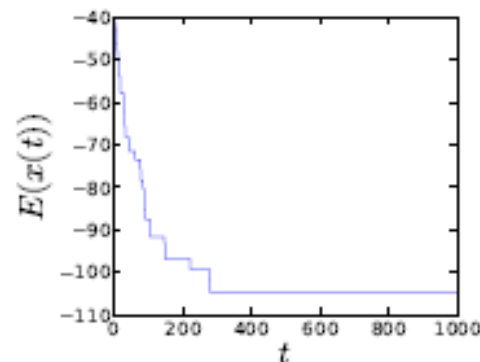


$t = 100$



$t = 300$

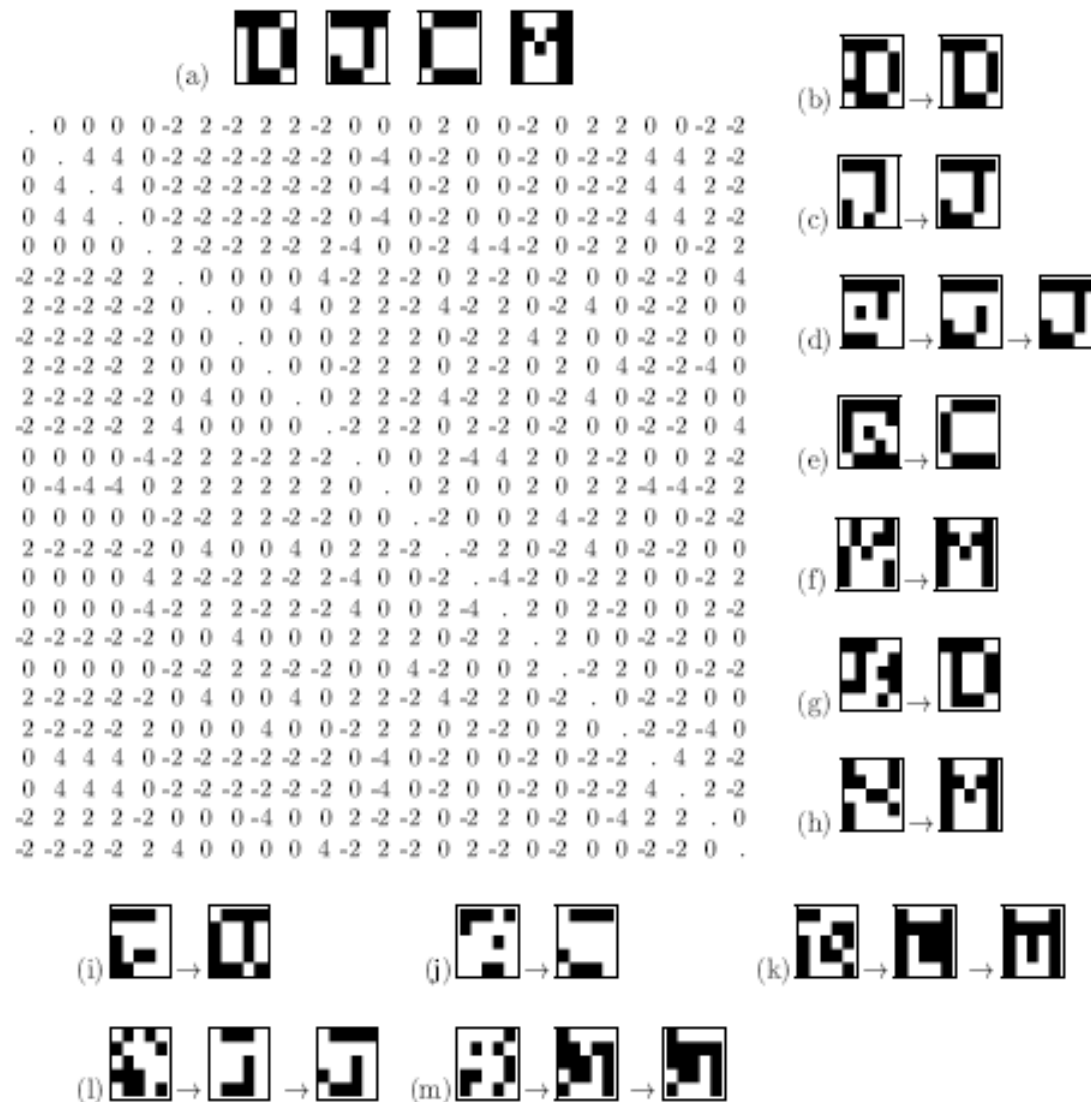
- ▶ Evolution of the energy  $E(x(t))$ :



adapted from L. Busing (TU Graz)

- Associative memory
- Hopfield networks
- **Memory storage and TSP example**
- Stochastic networks – Boltzmann machine

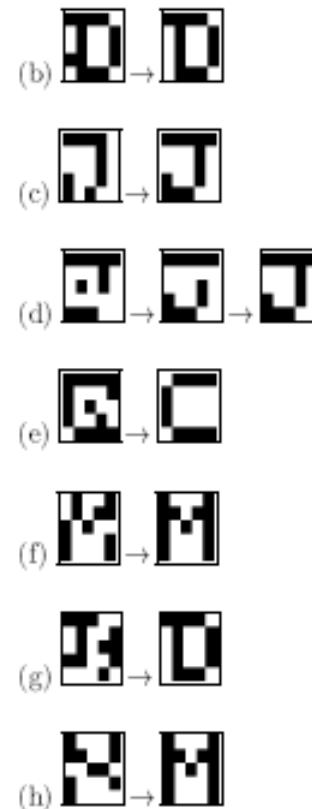
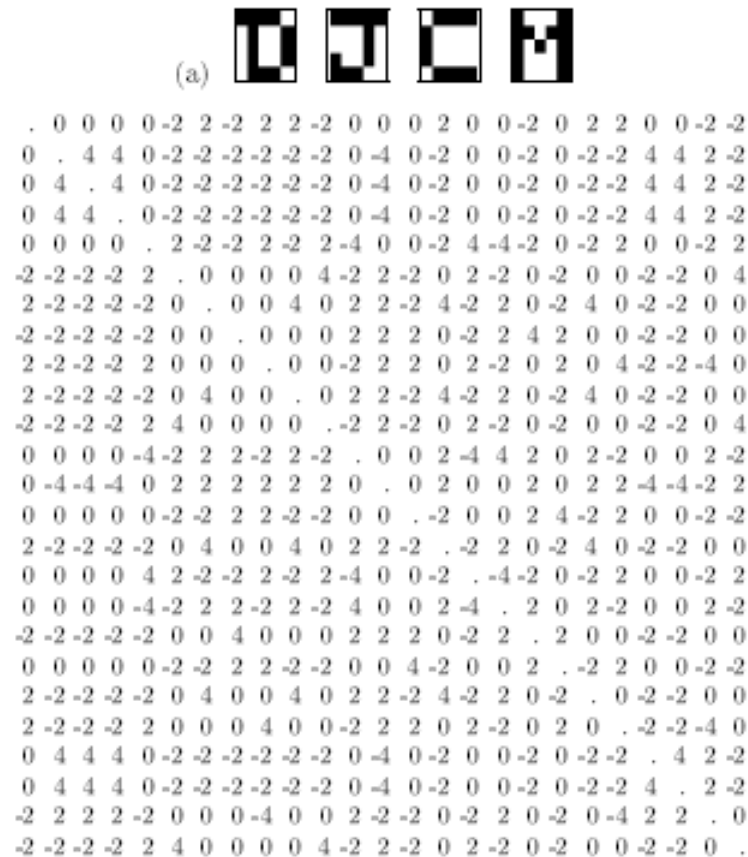
# Pattern storage and recall example



adapted from McKay

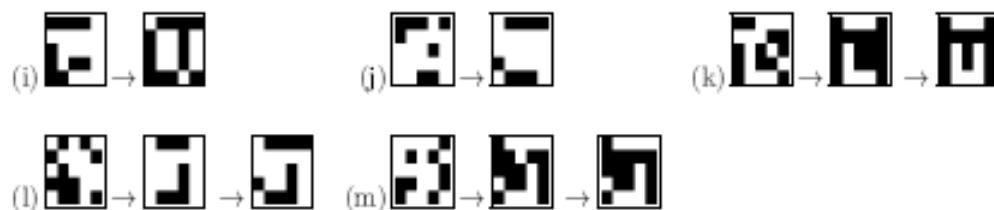
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- **Memory storage and TSP example**
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# Pattern storage and recall example



## Common problems

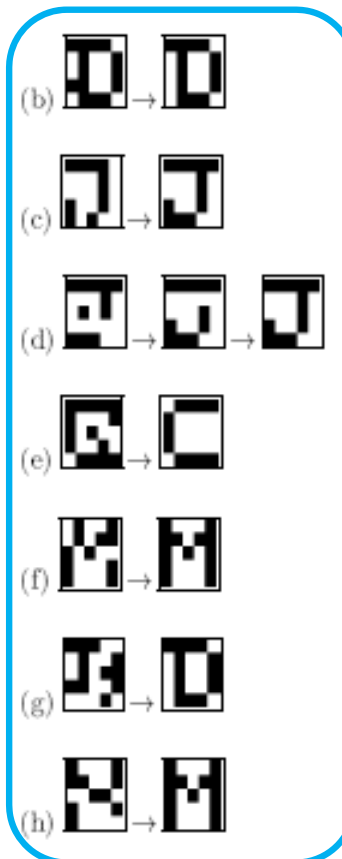
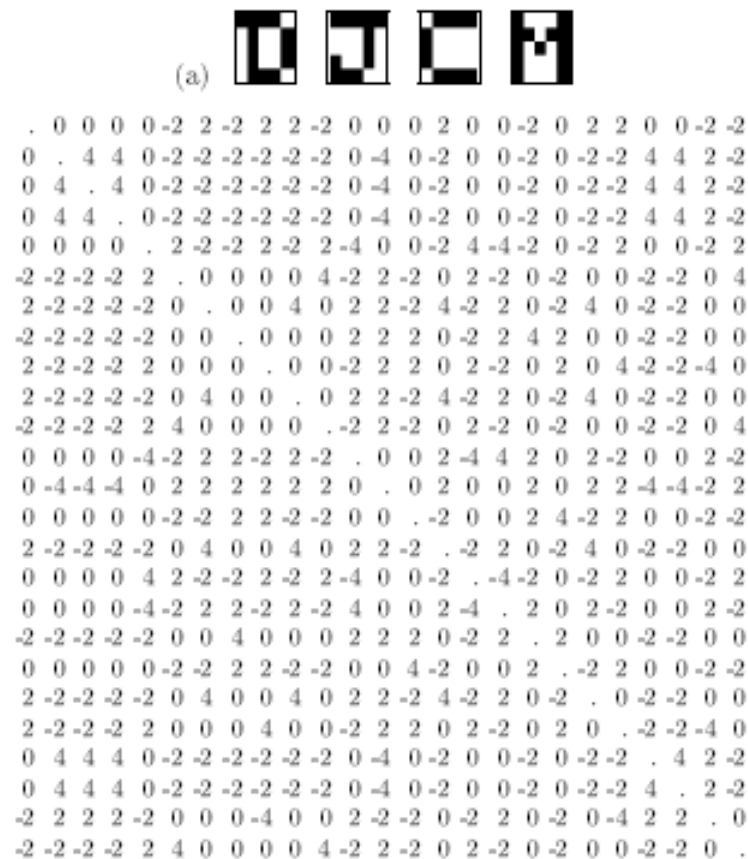
1. Corruption of individual bits.
2. Lack of encoded memory or a very small basin of attraction.
3. Appearance of spurious additional memories.



adapted from McKay

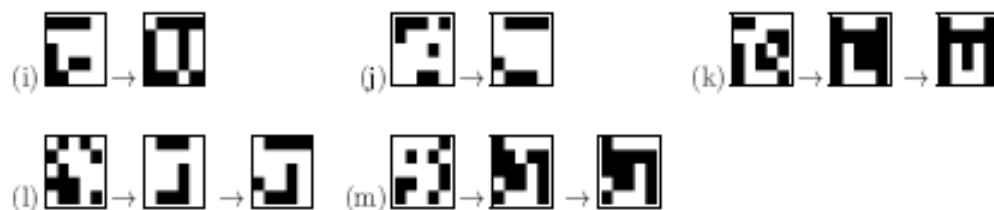
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# Pattern storage and recall example



## Common problems

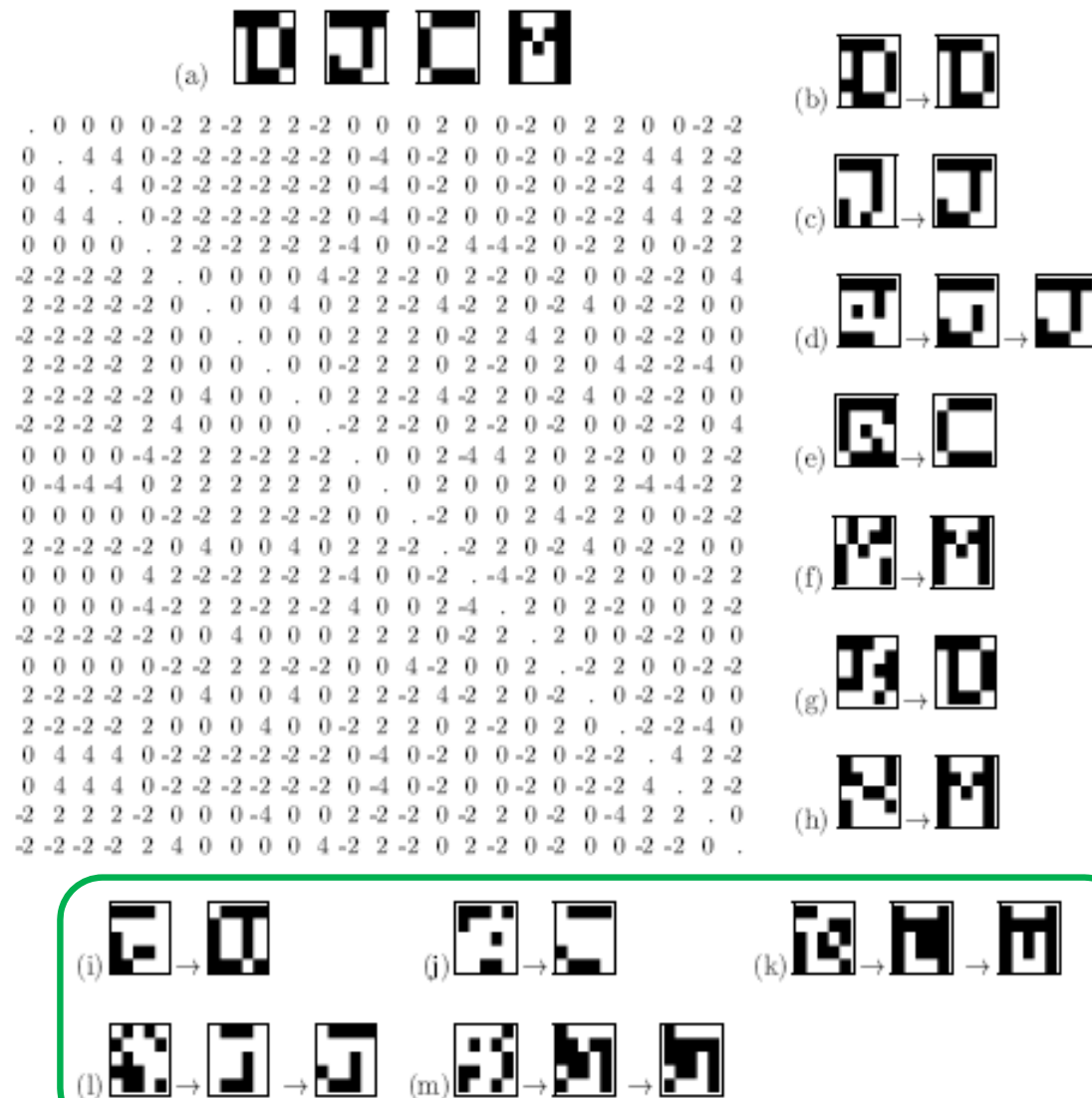
1. [Corruption of individual bits.](#)
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# Pattern storage and recall example



## Common problems

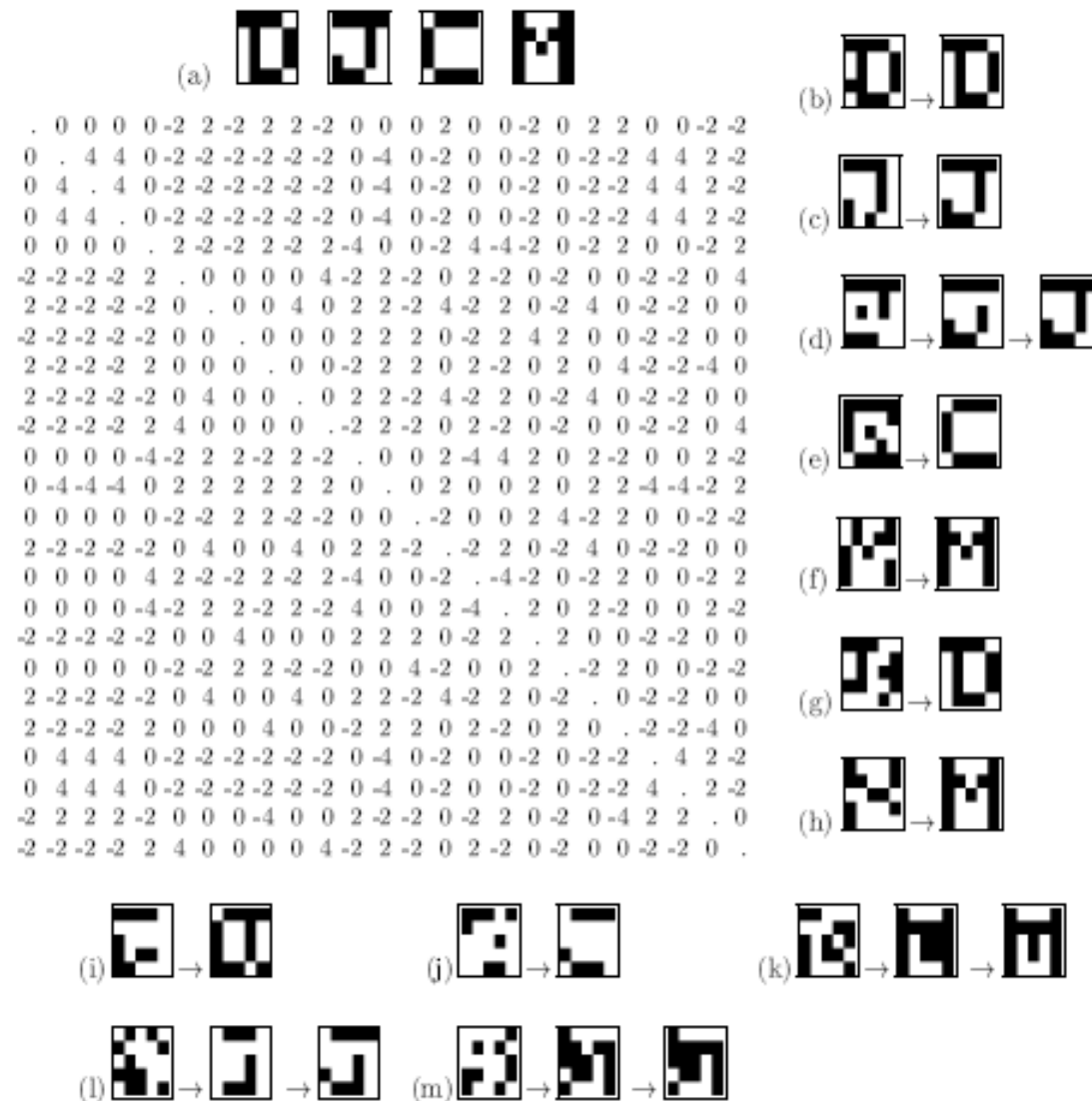
1. Corruption of individual bits.
2. Lack of encoded memory or a very small basin of attraction.
3. Appearance of spurious additional memories.

Spurious states often arise out of degenerate eigenvectors.

adapted from McKay

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# Pattern storage and recall example

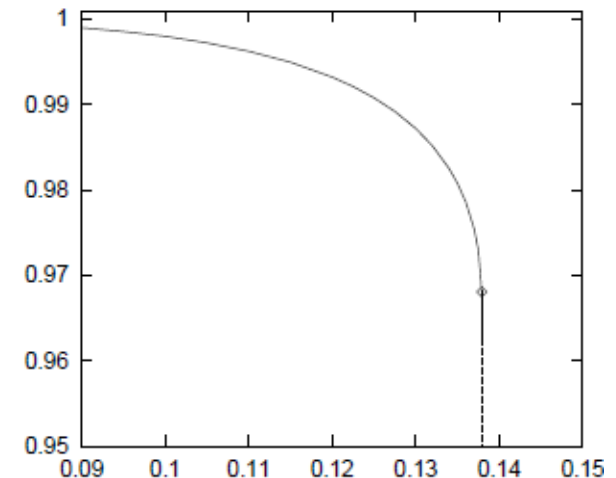
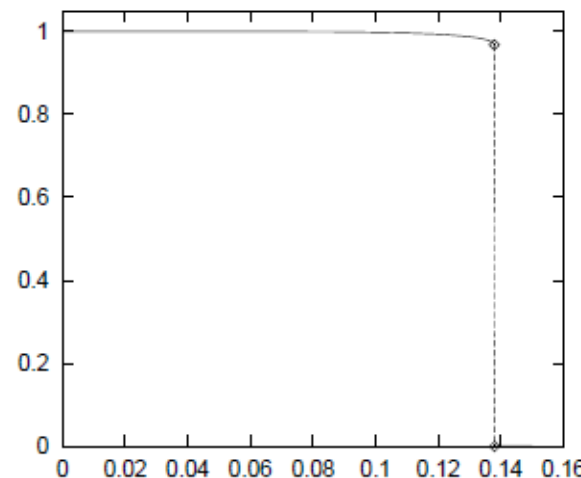


- Associative memory
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# Memory capacity

- Cross-talk between memory patterns is key to limited capacity
- Memory capacity is usually tested on independent random patterns
  - Hopfield network can store roughly  $M \leq 0.138 n$  of such random patterns (sharp discontinuity)
  - for large  $M/n$ , unstable bits may unfold into an avalanche effect
  - for sparse patterns in the order of  $n \cdot \log(n)$
- To guarantee stability of all patterns with high probability, we must ensure

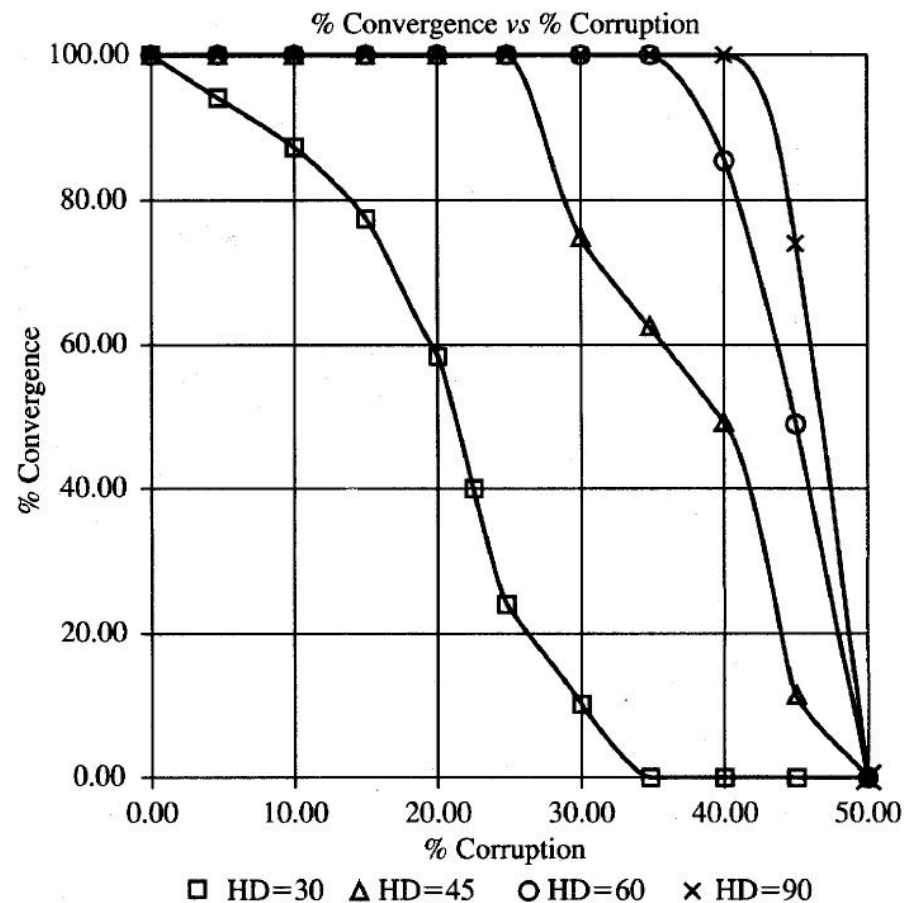
$$M \leq \frac{n}{4 \ln n}$$





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# Catastrophic forgetting effect



*Convergence rate* is defined based on the convergence criterion, often expressed as the upper bound on *Hamming distance*.

Network properties are not robust for synchronous updates.

Also, problems for continuous networks.

$$a_i = \sum_j w_{ij} x_j \quad x_i = \tanh(a_i).$$

Better behaviour for continuous continuous –time Hopfield network

$$a_i(t) = \sum_j w_{ij} x_j(t). \quad \frac{d}{dt} x_i(t) = -\frac{1}{\tau} (x_i(t) - f(a_i)),$$



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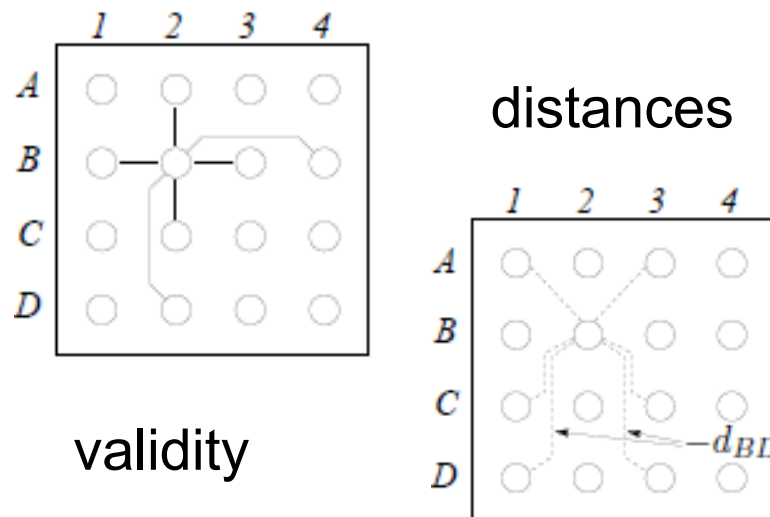
# Hopfield networks for optimisation problems

- Hopfield network's dynamics minimises an energy function
- Some optimisation problems could be mapped to the quadratic energy function (particularly constrain satisfaction problems(CSPs))

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# Hopfield networks for optimisation problems

- Hopfield network's dynamics minimises an energy function
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- Travelling salesman problem (TSP) as a classic CSP problem

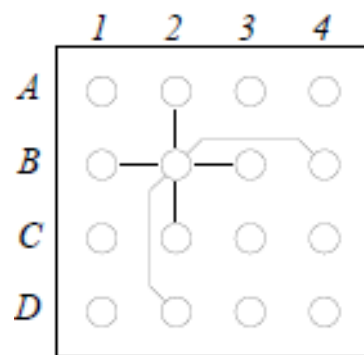


$$E = \underbrace{\frac{1}{2} \sum_{i,j,k} d_{ij} x_{ik} x_{j,k+1}}_{\text{sum of distances}} + \underbrace{\frac{\gamma}{2} \left( \sum_{j=1}^n \left( \sum_{i=1}^n x_{ij} - 1 \right)^2 + \sum_{i=1}^n \left( \sum_{j=1}^n x_{ij} - 1 \right)^2 \right)}_{\text{validity: single 1s in each column and row}}$$

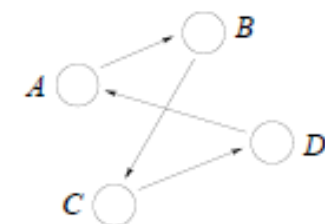
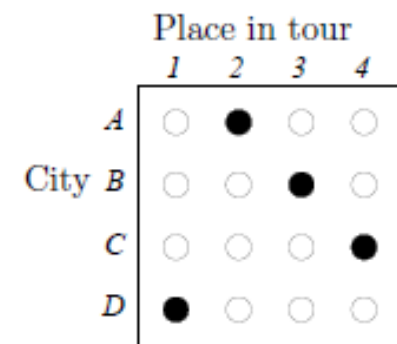
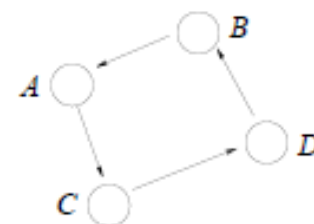
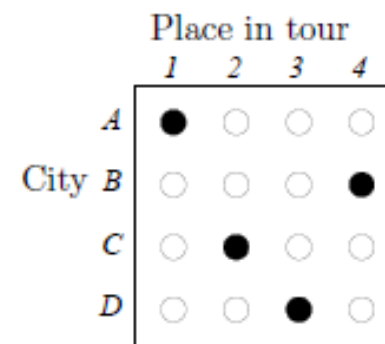
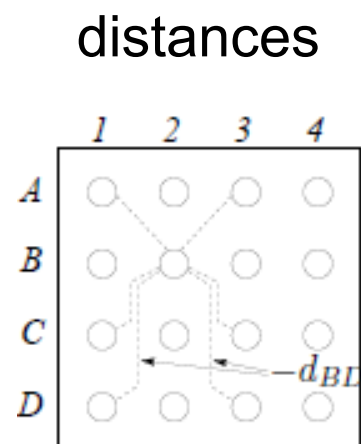
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validity



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# Hopfield networks

## In summary

- Hopfield network is a nice model for memory with biological features including Hebbian learning
- It is a very simple, stable and mathematically tractable model
- It has limited capacity and assumes near orthogonal patterns
- It does not allow for storing time series
- The attractor dynamics is limited to fixed points