

# MATH 689 - Physics for Mathematicians

Seth Hoisington

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**Theorem 1** (Equivalence of E-L equation and Hamiltonian system). *The curve  $q(t)$  in  $M$  is a solution of the E-L equation  $\frac{d}{dt} \frac{\partial L}{\partial \dot{q}}(q(t), \dot{q}(t)) = \frac{\partial L}{\partial q}(q(t), \dot{q}(t))$  if and only if the curve  $(p(t), q(t))$  in  $T^*M$ , with  $p(t) = \frac{\partial L}{\partial \dot{q}}(q(t), \dot{q}(t))$  is the solution to the following system:*

$$\begin{cases} \dot{q}_i(t) = \frac{\partial H}{\partial p_i}(p(t), q(t)) \\ \dot{p}_i(t) = -\frac{\partial H}{\partial q_i}(p(t), q(t)) \end{cases}$$

where  $(p_1, \dots, p_n, q^1, \dots, q^n)$  are the canonical coordinates on  $T^*M$  near  $q \in M$ , and where  $H$  is related to  $L$  via the Legendre transform:

$$H(p, q) = \max_{v \in T_q M} (p(v) - L(q, v))$$

*Proof.* By strong convexity of  $v \mapsto L(q, v)$  for all  $q$ , the maximum of  $v \mapsto h(p, q, v)$ , if attained is attained at a unique  $v := v(p, q)$  and  $H(p, q) = h(p, q, v(p, q))$ . For  $v = v(p, q)$ :

$$\begin{aligned} 0 &= \frac{\partial}{\partial v^i} h(p, q, v) \Big|_{v=v(p, q)} \\ &= \frac{\partial}{\partial v^i} (p_i v^i - L(q, v)) \Big|_{v=v(p, q)} \\ &= p_i - \frac{\partial}{\partial v^i} L(q, v) \Big|_{v=v(p, q)} \\ \Leftrightarrow p_i &= \frac{\partial}{\partial v^i} L(q, v) \Big|_{v=v(p, q)} \end{aligned} \tag{1}$$

Hence by the uniqueness of  $v(p, q)$ , we find that  $v(p(t), q(t)) = \dot{q}(t)$  since

$$\frac{\partial L}{\partial v} \Big|_{(q, v)=(q(t), \dot{q}(t))} = p(t) = \frac{\partial L}{\partial v} \Big|_{(q, v)=(q(t), v(p(t), q(t)))}$$

Therefore,  $H(p(t), q(t)) = h(p(t), q(t), \dot{q}(t))$ , we see that

$$\begin{aligned}\frac{\partial H}{\partial p_i}(p(t), q(t)) &= \frac{\partial}{\partial p_i} h(p, q, v(p, q)) \Big|_{(p,q)=(p(t),q(t))} \\ &= \frac{\partial}{\partial p_i} h(p, q, v) \Big|_{(p,q,v)=(p(t),q(t),v(p(t),q(t)))} \\ &\quad + \frac{\partial}{\partial v} h(p, q, v) \Big|_{(p,q,v)=(p(t),q(t),v(p(t),q(t)))} \frac{\partial}{\partial p_i} v(p, q) \Big|_{(p,q)=(p(t),q(t))}\end{aligned}$$

Since  $\frac{\partial h}{\partial v} = 0$  at  $(p, q, v) = (p, q, v(p, q))$ , in local coordinates, we have

$$\begin{aligned}\frac{\partial H}{\partial p_i}(p(t), q(t)) &= \frac{\partial}{\partial p_i} h(p, q, v) \Big|_{(p,q,v)=(p(t),q(t),v(p(t),q(t)))} \\ &= \frac{\partial}{\partial p_i} \left( \sum_{i=1}^n p_i v^i - L(q, v) \right) \Big|_{(p,q,v)=(p(t),q(t),v(p(t),q(t)))} \\ &= v^i \Big|_{(p,q,v)=(p(t),q(t),v(p(t),q(t)))} \\ &= \dot{q}^i(t)\end{aligned}$$

Therefore, we have that, for all  $i$ ,

$$\dot{q}^i(t) = \frac{\partial H}{\partial p^i}(p(t), q(t)).$$

Now, we will verify the second set of equations:

$$\begin{aligned}\frac{\partial H}{\partial q^i}(p(t), q(t)) &= \frac{\partial}{\partial q^i} h(p, q, v(p, q)) \Big|_{(p,q)=(p(t),q(t))} \\ &= \frac{\partial}{\partial q^i} h(p, q, v) \Big|_{(p,q,v)=(p(t),q(t),v(p(t),q(t)))} \\ &\quad + \frac{\partial h}{\partial v} \Big|_{(p(t),q(t),v(p(t),q(t)))} \frac{\partial}{\partial q^i} v(p, q) \Big|_{(p(t),q(t))} \\ &= \frac{\partial}{\partial q^i} h(p, q, v) \Big|_{(p,q,v)=(p(t),q(t),v(p(t),q(t)))} + 0 \frac{\partial v}{\partial q^i} \Big|_{(p(t),q(t))} \\ &= \frac{\partial}{\partial q^i} \left( \sum_i p_i v^i - L(q, v) \right) \Big|_{(p,q,v)=(p(t),q(t),\dot{q}(t))} \\ &= - \frac{\partial L}{\partial q^i} \Big|_{(p,q,v)=(p(t),q(t),\dot{q}(t))} \\ &= - \frac{\partial L}{\partial q^i} \Big|_{(q,v)=(q(t),\dot{q}(t))}\end{aligned}$$

By Euler-Lagrange, we have that

$$\begin{aligned}\dot{p}(t) &= \frac{d}{dt} \frac{\partial L}{\partial \dot{q}}(q(t), \dot{q}(t)) \\ &= \frac{\partial L}{\partial q}(q(t), \dot{q}(t)) \\ &= -\frac{\partial H}{\partial q^i}(p(t), q(t))\end{aligned}$$

Therefore,  $H$  is a solution to the Hamiltonian system.  $\square$

## 1 Canonical Symplectic Structure and Coordinate-free Construction of Hamiltonian vector fields in $T^*M$

### 1.1 The tautological (Liouville) 1-form on $T^*M$

Let  $\lambda = (p, q) \in T^*M$  where  $q \in M, p \in T_q^*M$ . Then let  $\pi : T^*M \rightarrow M$  be the canonical projection:  $\pi(p, q) = q$ . We want to define a 1-form on  $T^*M$  (which is a manifold itself). For some  $w \in T_\lambda(T^*M)$ . We define

$$S(\lambda)(w) = p(\pi_{*,\lambda}(w))$$

Note that  $\pi_{*,\lambda} : T_\lambda(T^*M) \rightarrow T_qM$ , so  $p$  indeed acts upon  $\pi_{*,\lambda}(w)$ .

**Lemma 1.** *In canonical coordinates  $(p_1, \dots, p_n, q^1, \dots, q^n) \in T^*M$ ,*

$$S = p^1 dq^1 + \dots + p_n dq^n.$$

*Proof.* In our coordinates,  $\pi(p_1, \dots, p_n, q^1, \dots, q^n) = (q^1, \dots, q^n)$ . Let  $w = v^1 \frac{\partial}{\partial q^1} + \dots + v^n \frac{\partial}{\partial q^n}$ . Then,

$$\begin{aligned}s(w) &= p(d\pi(w)) \\ &= \sum_i p_i dq^i \left( \sum_j v^j \frac{\partial}{\partial q^j} \right) \\ &= \sum_i p_i v^i\end{aligned}$$

On the other hand,

$$\sum_i p_i dq^i(w) = \sum_i p_i dq^i \left( \sum_j v^j \frac{\partial}{\partial q^j} + \sum_j \xi_j \frac{\partial}{\partial p_j} \right) = \sum_i p_i v^i$$

$\square$

Let  $\sigma = ds$  (the exterior derivative of the Liouville form).

**Properties of  $\sigma$ :**

- $\sigma$  is exact (and thus closed)
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**Lemma 2.**  $\sigma$  is a nondegenerate 2-form. (For every  $\lambda \in T^*M$ , if for some  $w \in T_\lambda(T^*M)$  we have  $\iota_w \sigma(\lambda) = 0$ , then  $w = 0$ .)

*Proof.* By Lemma 1, in canonical coordinates,  $s = p_1 dq^1 + \cdots + p_n dq^n$ , so

$$ds = dp_1 \wedge dq^1 + \cdots + dp_n \wedge dq^n.$$

In the basis  $\left(\frac{\partial}{\partial p_1}, \dots, \frac{\partial}{\partial p_n}, \frac{\partial}{\partial q^1}, \dots, \frac{\partial}{\partial q^n}\right)$  of  $T_\lambda(T^*M)$ , this form corresponds to the matrix

$$\left(\begin{array}{c|c} 0 & I \\ \hline -I & 0 \end{array}\right)$$

since  $\sigma(\frac{\partial}{\partial p_i}, \frac{\partial}{\partial p_j}) = 0$ ,  $\sigma(\frac{\partial}{\partial p_i}, \frac{\partial}{\partial q^j}) = \delta_{ij}$ , and  $\sigma(\frac{\partial}{\partial q^i}, \frac{\partial}{\partial q^j}) = 0$ . Since this matrix is nonsingular, the form is nondegenerate (reference?)  $\square$

**Definition 1.** A closed, non-degenerate 2-form  $\omega$  on a manifold  $M$  is called a symplectic form (or symplectic structure). If such a form exists on  $M$ , then the pair  $(M, \omega)$  is a symplectic manifold. For any such symplectic manifold, it can be shown that  $\dim(M)$  is even.

Therefore, we have just shown that the manifold  $(T^*M, \sigma)$  is a symplectic manifold.

Any smooth function  $H : T^*M \rightarrow \mathbb{R}$  is called an (autonomous) Hamiltonian.

**Lemma 3.** For any Hamiltonian  $H : T^*M \rightarrow \mathbb{R}$ , there exists a unique vector field, denoted by  $\vec{H}$  such that  $\iota_{\vec{H}} \sigma = -dH$ . Moreover, in the canonical coordinates  $(p_1, \dots, p_n, q^1, \dots, q^n) \in T^*M$ ,

$$\vec{H} = \frac{\partial H}{\partial p_1} \frac{\partial}{\partial q^1} + \cdots + \frac{\partial H}{\partial p_n} \frac{\partial}{\partial q^n} - p \text{dof} H q^1 \frac{\partial}{\partial p_1} + \cdots + \frac{\partial H}{\partial q^n} \frac{\partial}{\partial p_n} = \sum_i \frac{\partial H}{\partial p_i} \frac{\partial}{\partial q^i} - p \text{dof} H q^i \frac{\partial}{\partial p_i}.$$

Thus, a curve  $\lambda(t)$  in  $T^*M$  satisfies  $\lambda(t) = \vec{H}(\lambda(t))$  if and only if

$$\begin{cases} \dot{q}^i(t) = \frac{\partial H}{\partial p_i}(p(t), q(t)) \\ \dot{p}^i(t) = -\frac{\partial H}{\partial q^i}(p(t), q(t)) \end{cases}$$

*Proof.* The existence and uniqueness of  $\vec{H}$  follows from nondegeneracy.  $\square$