CECS 456 Machine Learning

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Introduction and Dataset

We chose to do this project because we had an interest in classifying animals and love cute cat pictures.

Our dataset consists of 28,000 medium quality images of 10 different classifications of animals(dog, cat, horse, spyder, butterfly, chicken, sheep, cow, squirrel, elephant).

The different classifications have between 2-5 thousand images each.

There are intentionally some incorrectly classified data in the set, the intent is to simulate real like conditions.

We retrieved our data from https://www.kaggle.com/datasets/alessiocorrado99/animals10

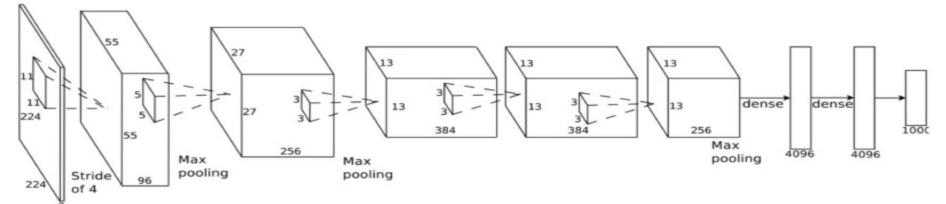
Description and Related Work

On Kaggle's web site there are a lot of related works that use convolutional neural networks as well as other neural network models in order to classify the animal data set. Some import, famous models such as VGG, AlexNet, and ResNet which are all used to classify their images while others build their models from the ground up.

For our project we decided to implement different variations of CNN and see how well they perform.

Definitions

- Convolution Layer
 - o CONV2D:
 - Filter
 - Kernel size
 - Activation
 - padding:
- MaxPool2D
- Flattening
- Dense



Implementation Methodology

- My model was based on the CNN demo we did in class
- I added additional layers and tweaked parameters to see what would improve or worsen accuracy
- A big part of my methodology was testing many different combinations of inputs and layers.
- My model ended with 18 layers as well as 3 drop out layers
- A batch size of 100 and epochs of 5 seemed to be the most consistent. When increasing the epochs I ran into "out of resource errors" This was while the model on my own hardware.
- Activation function Relu
- Total params 1.8m

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 222, 222, 16)	448
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 111, 111, 16)	
conv2d_1 (Conv2D)	(None, 109, 109, 32)	4640
conv2d_2 (Conv2D)	(None, 107, 107, 32)	9248
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 53, 53, 32)	
conv2d_3 (Conv2D)	(None, 51, 51, 64)	18496
conv2d_4 (Conv2D)	(None, 49, 49, 64)	36928
<pre>max_pooling2d_2 (MaxPooling 2D)</pre>	(None, 24, 24, 64)	
conv2d_5 (Conv2D)	(None, 22, 22, 128)	73856
conv2d_6 (Conv2D)	(None, 20, 20, 128)	147584
<pre>max_pooling2d_3 (MaxPooling 2D)</pre>	(None, 10, 10, 128)	
conv2d_7 (Conv2D)	(None, 8, 8, 256)	295168
conv2d_8 (Conv2D)	(None, 6, 6, 256)	590080
<pre>max_pooling2d_4 (MaxPooling 2D)</pre>	(None, 3, 3, 256)	
flatten (Flatten)	(None, 2304)	
dense (Dense)	(None, 256)	590080
dense_1 (Dense)	(None, 128)	32896
dense_2 (Dense)	(None, 128)	16512
dense_3 (Dense)	(None, 10)	1290

Total params: 1,817,226 Trainable params: 1,817,226 Non-trainable params: 0



Results

- Accuracy of 58%
- There is a lot of room for improvement.
- Total loss: 1.23
- Validation loss: 1.32
- Validation accuracy 0.5675

Adrian's Model

Design

I followed the CNN E the foundation for my smaller strides and s amounts and slowly

cnn = tf.keras.models.Sequential() #initi cnn.add(tf.keras.layers.Conv2D(filters=16 cnn.add(tf.keras.layers.Conv2D(filters=16 cnn.add(tf.keras.layers.MaxPool2D(pool si cnn.add(tf.keras.layers.Conv2D(filters=32 cnn.add(tf.keras.layers.Conv2D(filters=32 cnn.add(tf.keras.layers.MaxPool2D(pool si cnn.add(tf.keras.layers.Conv2D(filters=64 cnn.add(tf.keras.layers.Conv2D(filters=64 cnn.add(tf.keras.layers.MaxPool2D(pool si cnn.add(tf.keras.layers.Conv2D(filters=12 cnn.add(tf.keras.layers.Conv2D(filters=12 cnn.add(tf.keras.layers.MaxPool2D(pool si cnn.add(tf.keras.layers.Flatten()) #Flate cnn.add(tf.keras.layers.Dense(units=128, cnn.add(tf.keras.layers.Dense(units=64, a cnn.add(tf.keras.layers.Dense(units=32, cnn.add(tf.keras.layers.Dense(units= 10,

Model: "sequential_2"

Non-trainable params: 0

Layer (type)	Output Shape	Param #
conv2d_16 (Conv2D)	(None, 128, 128, 16)	448
conv2d_17 (Conv2D)	(None, 128, 128, 16)	2320
max_pooling2d_8 (MaxPooling 2D)	(None, 64, 64, 16)	0
conv2d_18 (Conv2D)	(None, 64, 64, 32)	4640
conv2d_19 (Conv2D)	(None, 64, 64, 32)	9248
max_pooling2d_9 (MaxPooling 2D)	(None, 32, 32, 32)	0
conv2d_20 (Conv2D)	(None, 32, 32, 64)	18496
conv2d_21 (Conv2D)	(None, 32, 32, 64)	36928
max_pooling2d_10 (MaxPoolin g2D)	(None, 16, 16, 64)	0
conv2d_22 (Conv2D)	(None, 16, 16, 128)	73856
conv2d_23 (Conv2D)	(None, 16, 16, 128)	147584
max_pooling2d_11 (MaxPoolin g2D)	n (None, 8, 8, 128)	0
flatten_2 (Flatten)	(None, 8192)	ө
dense_7 (Dense)	(None, 128)	1048704
dense_8 (Dense)	(None, 64)	8256
dense_9 (Dense)	(None, 32)	2080
dense_10 (Dense)	(None, 10)	330

he reason behind my decisions was to ave my model slowly acquire arameters while avoiding having too any which i believed would reduce verfitting and decrease training time.

```
rt shape=[128, 128, 3])) #Convolution 1
onvolution 4
onvolution 5
```

Adrian

Training accuracy - 81% Testing accuracy - 66%

```
Epoch 1/10
Epoch 2/10
Epoch 3/10
Epoch 4/10
Epoch 5/10
Epoch 6/10
Epoch 7/10
Epoch 8/10
Epoch 9/10
Epoch 10/10
```

Implementation Methodology

- Based on VGG16
- Extracting data
- Splitting the dataset
- Creating the model
 - 16 layers
 - Activation = relu
 - Batch size = 100
 - Epoch = 20

References:

- https://www.kaggle.com/code/bhupendrakumar/animal-10-vgg16-tf-lr
- h...ps://www.kaggle.com/code/min4tozaki/animal-classification.

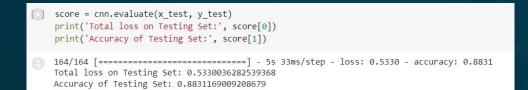
	Epoch 7/20
#ma	210/210 [====================================
cnr	634
#ac	Epoch 8/20
cnr	210/210 [===========] - 62s 295ms/step - loss: 1.0739 - accuracy: 0.6317 - val_loss: 1.2404 - val_accuracy: 0.5
cnr	Epoch 9/20 210/210 [====================================
cnr	949
cnr	Epoch 10/20 210/210 [
cnr	210/210 [====================================
cnr	Epoch 11/20
cnr	210/210 [===========] - 62s 295ms/step - loss: 0.7601 - accuracy: 0.7421 - val_loss: 1.2424 - val_accuracy: 0.6
cnr	Epoch 12/20
cnr	210/210 [============] - 62s 295ms/step - loss: 0.6562 - accuracy: 0.7766 - val_loss: 1.2684 - val_accuracy: 0.6 062
cnr	Epoch 13/20
cnr	210/210 [=============] - 62s 295ms/step - loss: 0.5590 - accuracy: 0.8083 - val_loss: 1.3899 - val_accuracy: 0.6 199
cnr	Epoch 14/20
cnr	210/210 [==================] - 62s 295ms/step - loss; 0.4690 - accuracy; 0.8392 - val_loss; 1.4044 - val_accuracy; 0.5 942 Fooch 15/20
cnr	210/210 [====================================
cnr	117 Epoch 16/20
cnr	210/210 [============] - 62s 295ms/step - loss: 0.3313 - accuracy: 0.8865 - val_loss: 1.7279 - val_accuracy: 0.6 018
cnr	Epoch 17/20
tf.	210/210 [============] - 62s 295ms/step - loss: 0.2756 - accuracy: 0.9064 - val_loss: 2.0465 - val_accuracy: 0.6
	Epoch 18/20
cnr	210/210 [====================================
tf.	942
cnr	Epoch 19/20
tf.	210/210 [=========] - 62s 296ms/step - loss: 0.2104 - accuracy: 0.9269 - val_loss: 2.2097 - val_accuracy: 0.6
cnr	Epoch 20/20
	210/210 [=============] - 62s 296ms/step - loss: 0.1780 - accuracy: 0.9414 - val_loss: 2.0952 - val_accuracy: 0.6 045

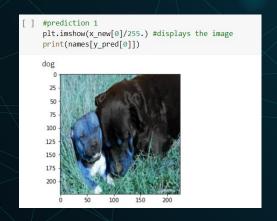
VGG16

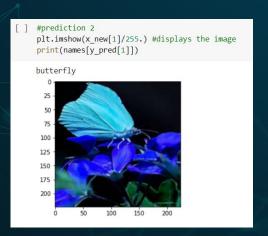
Luke Sunaoka's Model

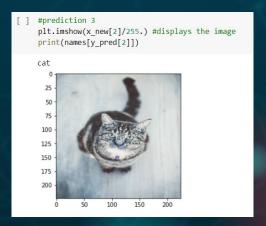
Luke Sunaoka's Model

- Total Loss on Testing Set: 0.533
- Accuracy of Testing Set: 0.883
- Did surprisingly well!
- May be due to implementation









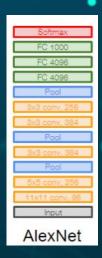
Model: AlexNet

Reasoning

- Achieves better results for image classification
 - Relu activation function is used

$$f(x) = max(0, x)$$

- Standardization
 - Dropout method prevents overfitting
- Data Enhancement
 - Dropout method: randomly setting output of some neurons= 0



Implementation Methodology

```
alexnet.add(Conv2D(96, (11, 11), input_shape=(100, 100, 3), padding='same', kernel_regularizer=12(0)))
alexnet.add(BatchNormalization())
alexnet.add(Activation('relu'))
alexnet.add(MaxPooling2D(pool_size=(2, 2)))
alexnet.add(Conv2D(256, (5, 5), padding='same'))
alexnet.add(BatchNormalization())
alexnet.add(Activation('relu'))
alexnet.add(MaxPooling2D(pool size=(2, 2)))
# Layer 3
alexnet.add(ZeroPadding2D((1, 1)))
alexnet.add(Conv2D(512, (3, 3), padding='same'))
alexnet.add(BatchNormalization())
alexnet.add(Activation('relu'))
alexnet.add(MaxPooling2D(pool_size=(2, 2)))
alexnet.add(ZeroPadding2D((1, 1)))
alexnet.add(Conv2D(1024, (3, 3), padding='same'))
alexnet.add(BatchNormalization())
alexnet.add(Activation('relu'))
Il Layer 5
alexnet.add(ZeroPadding2D((1, 1)))
alexnet.add(Conv2D(1024, (3, 3), padding='same'))
alexnet.add(BatchNormalization())
alexnet.add(Activation('relu'))
alexnet.add(MaxPooling2D(pool_size=(2, 2)))
II Layer 6
alexnet.add(Flatten())
alexnet.add(Dense(3072))
alexnet.add(BatchNormalization())
alexnet.add(Activation('relu'))
alexnet.add(Dropout(0.5))
# Laver 7
alexnet.add(Dense(4096))
alexnet.add(BatchNormalization())
alexnet.add(Activation('relu'))
alexnet.add(Dropout(0.5))
# Layer 8
alexnet.add(Dense(10))
alexnet.add(BatchNormalization())
alexnet.add(Activation('softmax'))
```

Design

- Based on AlexNet
- Data extraction
- Split data into Training and Testing datasets
 - Training: 20,858
 - Testing: 5,320
- Training parameters:
 - 8 layers (5 convolutional, 3 fully connected)
 - Activation func = relu
 - Batch size = 53
 - Epoch = 69

Results

```
Epoch 1/69
Epoch 2/69
Epoch 3/69
Epoch 4/69
Epoch 5/69
Epoch 6/69
53/53 [============= ] - 14s 269ms/step - loss: 1.4388 - accuracy: 0.5173 - val loss: 2.8521 - val accuracy: 0.1889
   Epoch 64/69
   53/53 [========] - 16s 295ms/step - loss: 0.4615 - accuracy: 0.9306 - val loss: 1.0443 - val accuracy: 0.7256
   53/53 [===========] - 16s 295ms/step - loss: 0.4727 - accuracy: 0.9206 - val loss: 1.0382 - val accuracy: 0.7310
   53/53 [============] - 16s 295ms/step - loss: 0.4807 - accuracy: 0.9206 - val loss: 1.1581 - val accuracy: 0.6562
   Epoch 67/69
   Epoch 68/69
   53/53 [===========] - 16s 295ms/step - loss: 0.4468 - accuracy: 0.9292 - val_loss: 1.0275 - val accuracy: 0.7261
   Epoch 69/69
   53/53 [===========] - 16s 296ms/step - loss: 0.4307 - accuracy: 0.9349 - val loss: 1.0156 - val accuracy: 0.7530
```

Epoch 69/69

Accuracy: 0.9349

• Loss: 0.4307

Validation accuracy: 0.7530

Validation loss: 1.0156

Total params: 229,985,586

Trainable params: 229,965,406

Non-trainable params: 20,180

<pre>max_pooling2d_10 (MaxPoolin g2D)</pre>	(None, 13, 13, 512)	
zero_padding2d_7 (ZeroPaddi ng2D)	(None, 15, 15, 512)	
conv2d_13 (Conv2D)	(None, 15, 15, 1024)	4719616
batch_normalization_19 (Bat chNormalization)	(None, 15, 15, 1024)	4896
activation_19 (Activation)	(None, 15, 15, 1024)	
zero_padding2d_8 (ZeroPaddi ng2D)	(None, 17, 17, 1024)	
conv2d_14 (Conv2D)	(None, 17, 17, 1024)	9438208
batch_normalization_20 (Bat chNormalization)	(None, 17, 17, 1024)	4096
activation_20 (Activation)	(None, 17, 17, 1024)	
<pre>max_pooling2d_11 (MaxPoolin g2D)</pre>	(None, 8, 8, 1024)	
flatten_2 (Flatten)	(None, 65536)	
dense_6 (Dense)	(None, 3072)	201329664
batch_normalization_21 (Bat chNormalization)	(None, 3072)	12288
activation_21 (Activation)	(None, 3072)	
dropout_4 (Dropout)	(None, 3072)	
dense_7 (Dense)	(None, 4096)	12587008
batch_normalization_22 (Bat chNormalization)	(None, 4096)	16384
activation_22 (Activation)	(None, 4096)	
dropout_5 (Dropout)	(None, 4096)	
dense_8 (Dense)	(None, 10)	40970
batch_normalization_23 (Bat chNormalization)	(None, 10)	48
activation_23 (Activation)	(None, 10)	

Total params: 229,985,586 Trainable params: 229,965,406 Non-trainable params: 20,180

Kelly Duangrudeeswat

Results, Analysis, and Conclusion

- Kelly (69) and Luke(20) used a higher number of epoch while Matt(5) and Adrian(10) used a lower number of epochs
- Accuracy scores were as follows:

Matthew: 0.58

Adrian:0.65

Luke: 0.88

Kelly: 0.93

- Although VGG should be having a higher accuracy, because Kelly had higher number of epochs with her AlexNet model, her accuracy had the highest
- Furthermore, Matt and Adrian implemented their own CNN which maybe why its performance is limited in accuracy and results.
- The project was overall an accumulation of everything we've learned and it was great to see it being applied.

