Mathematical Methods for Engineers (MathEng)
EXAM
8th February 2016
Duration: 2 hrs, calculators permitted, no documents
This exam paper contains 7 questions and 60 marks.
ATTEMPT ALL QUESTIONS – ANSWER IN ENGLISH

EURECOM
Sophia Antipolis

---

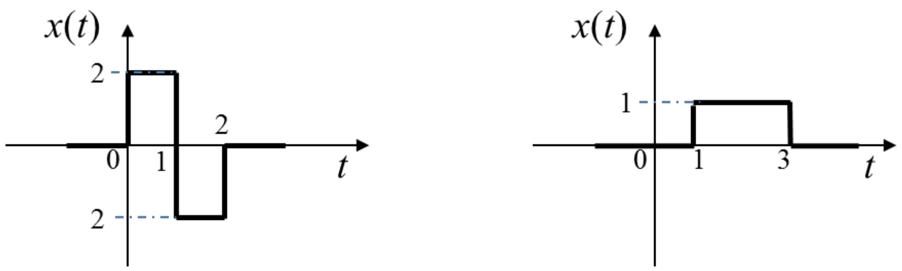
1. Via any appropriate means, determine the complex Fourier series of the following signal $x(t)$:

$$x(t) = 3\cos(5t) + 4\sin(10t)$$

[6 marks]

---

2. The signal illustrated in Figure Q2(a) is applied to the input of a system whose impulse response is illustrated in Figure Q2(b). **Sketch** the system output.



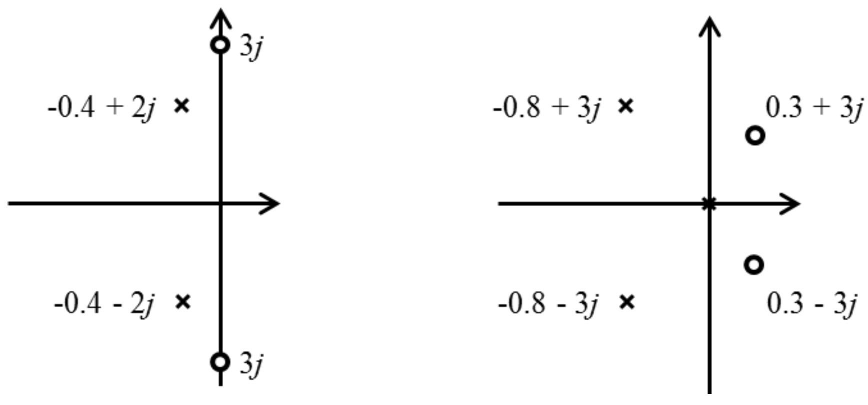
(a) (b)

Figure Q2

[6 marks]

---

3. Sketch the magnitude and phase responses for the two systems whose pole-zero configurations are illustrated in the *s*-planes of Figure Q3(a) and (b).



(a) (b)

Figure Q3

[10 marks]

4. A filter whose difference equation is given by $y(n) = 0.5y(n-1) + x(n)$ is excited by an input signal $x(n) = 0.2^n, n \geq 0$. Use transform techniques to develop an expression for the output $y(n)$.

[10 marks]

---

5. Determine an expression for the DFT, $X(k)$, of the sequence $x(n)$ = 0.25, 0.5, 0.25. Assuming that the sequence $x(n)$ is short interval or frame extracted from a longer duration signal $x'(n)$, explain briefly the purpose and impact on $X(k)$ of the window function w_n.

[10 marks]

---

6. (a) Find the inverse of

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{bmatrix}$$

using the Gauss-Jordan elimination starting with [A I].

(b) Find an orthonormal basis for the column space of the matrix

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 2 & -1 & 1 \\ -2 & 2 & 0 \end{bmatrix}$$

Next, let the vector b be given by

$$b = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}$$

Find the orthogonal projection of this vector, b, onto column space of A.

[10 marks]

---

7. A random variable X has the probability density function

$$f_X(x) = \begin{cases} ae^{-ax}, & x \geq 0 \\ 0, & x < 0 \end{cases}$$

where a is an arbitrary, positive constant.

(a) Determine an expression for the characteristic function $M_x(jv)$

(b) Hence or otherwise, determine $E[X]$ and $E[X^2]$.

[8 marks]

Table of selected Laplace transforms

$$X(s) = \int_{-\infty}^{\infty} x(t)\exp(-st)\,dt$$

N.B.: lower limit is 0 for one-sided Laplace transform

$$x(t) = \frac{1}{2\pi j}\int_{\sigma-j\infty}^{\sigma+j\infty} X(s)\exp(st)\,ds$$

$x(t)\quad (t \geq 0)$	$X(s)$
$\delta(t)$	1
$\delta(t-\alpha)$	$\exp(-\alpha s)$
1 (unit step)	$\frac{1}{s}$
t (unit ramp)	$\frac{1}{s^2}$
$\exp(-\alpha t)$	$\frac{1}{s+\alpha}$
$t\exp(-\alpha t)$	$\frac{1}{(s+\alpha)^2}$
$\sin(\alpha t)$	$\frac{\alpha}{s^2+\alpha^2}$
$\cos(\alpha t)$	$\frac{s}{s^2+\alpha^2}$
$e^{-\alpha t}\sin(\omega t)$	$\frac{\omega}{(s+\alpha)^2+\omega^2}$
$e^{-\alpha t}\cos(\omega t)$	$\frac{s+\alpha}{(s+\alpha)^2+\omega^2}$

Bode plots

Poles or zeros on the real axis:

$$(s+a) = a\left(\frac{s}{a}+1\right) = \frac{1}{\tau}(\tau s+1)$$

Complex conjugate poles (or zeros):

$$(s^2+As+B) = (s^2+2\zeta\omega_0 s+\omega_0^2) = \omega_0^2((s/\omega_0)^2+2\zeta(s/\omega_0)+1)$$

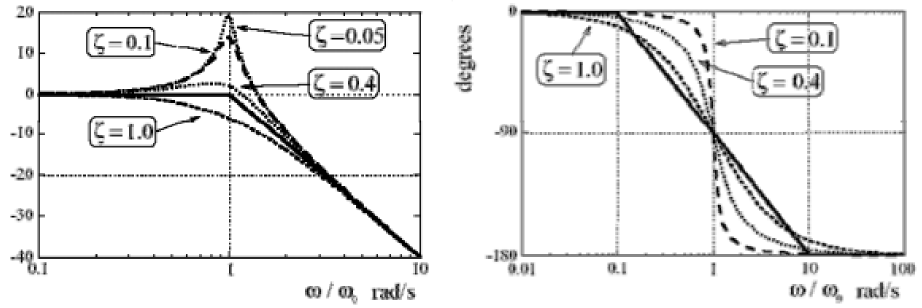


Table of selected z-transforms

$$x_c(t) = \sum_{n=0}^{\infty} x(n\Delta t)\delta(t - n\Delta t)$$

$$X_c(s) = \sum_{n=0}^{\infty} x(n\Delta t)\exp(-n\Delta ts)$$

$$X_c(s) = X(z)|_{z=e^{\Delta ts}}$$

$$X_c(\omega) = X_s(s)|_{s=j\omega}$$

$$X(\omega) = X(z)|_{z=\exp(\Delta tj\omega)}$$

$$X(z) = \sum_{n=0}^{\infty} x(n\Delta t)z^{-n}$$

$x(n) \quad (n \ge 0)$	$X(z)$
$\delta(n)$ unit pulse	1
$\delta(n-m)$	z^{-m}
1 (unit step)	$\dfrac{z}{z-1}$
n (unit ramp)	$\dfrac{z}{(z-1)^2}$
$\exp(-\alpha n)$	$\dfrac{z}{(z-e^{-\alpha})}$
$n\exp(-\alpha n)$	$\dfrac{e^{-\alpha}z}{(z-e^{-\alpha})^2}$
$\sin(\beta n)$	$\dfrac{z\sin(\beta)}{z^2-2z\cos(\beta)+1}$
$\cos(\beta n)$	$\dfrac{z^2-z\cos(\beta)}{z^2-2z\cos(\beta)+1}$
$e^{-\alpha n}\sin(\beta n)$	$\dfrac{ze^{-\alpha}\sin(\beta)}{z^2-2ze^{-\alpha}\cos(\beta)+e^{-2\alpha}}$
$e^{-\alpha n}\cos(\beta n)$	$\dfrac{z^2-ze^{-\alpha}\cos(\beta)}{z^2-2ze^{-\alpha}\cos(\beta)+e^{-2\alpha}}$

Table of selected Fourier transform pairs

Function	$x(t)$	$X(\omega)$
Rectangular function of width τ	$\Pi(t/\tau)$	$\tau\ \mathrm{sinc}(\omega\tau/2)$
Triangular function of width 2τ	$\Lambda(t/\tau)$	$\tau\ \mathrm{sinc}^2(\omega\tau/2)$
Train of impulses every Δt	$\delta_T(t)$	$2\pi/\Delta t\, \Sigma_n \delta(\omega - 2\pi n/\Delta t)$

NB: $\mathrm{sinc}(x) = \sin(\pi x)/\pi x$
NB: $\mathrm{sa}(x) = \sin(x)/x$

Euler's identity

$$\exp(j\theta) = \cos\theta + j\sin\theta$$

$$\cos(n\omega_0 t) = \frac{\exp(jn\omega_0 t) + \exp(-jn\omega_0 t)}{2}$$

$$\sin(n\omega_0 t) = \frac{\exp(jn\omega_0 t) - \exp(-jn\omega_0 t)}{2j}$$

Fourier series and transforms

Trigonometric Fourier series	
$$x(t) = \frac{A_0}{2} + \sum_{n=1}^{\infty} A_n \cos(n\omega_0 t) + B_n \sin(n\omega_0 t)$$ $$A_n = \frac{2}{T}\int_{-T/2}^{T/2} x(t)\cos(n\omega_0\, t)dt$$ $$B_n = \frac{2}{T}\int_{-T/2}^{T/2} x(t)\sin(n\omega_0\, t)dt$$	
Complex Fourier series – periodic and continuous in time, discrete in frequency	
$$x(t) = \sum_{n=-\infty}^{+\infty} X_n \exp(jn\omega_0 t)$$	$$X_n = \frac{1}{T}\int_{-T/2}^{T/2} x(t)\exp(-jn\omega_0 t)\, dt$$
Fourier transform – continuous in time, continuous in frequency	
$$x(t) = \frac{1}{2\pi}\int_{-\infty}^{\infty} X(\omega)\exp(j\omega t)\, d\omega$$	$$X(\omega) = \int_{-\infty}^{\infty} x(t)\exp(-j\omega t)\, dt$$
Discrete-time Fourier transform – discrete in time, continuous and periodic in frequency	
$$x(n\Delta t) = \frac{\Delta t}{2\pi}\int_{-\pi/\Delta t}^{\pi/\Delta t} X(\omega)\exp(jn\Delta t\omega)\, d\omega$$	$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n\Delta t)\exp(-j\omega n\Delta t)$$
Discrete Fourier transform – discrete and periodic in time and in frequency	
$$x(n) = \frac{1}{N}\sum_{k=0}^{N-1} X(k)\exp\left(\frac{jnk2\pi}{N}\right)$$	$$X(k) = \sum_{n=0}^{N-1} x(n)\exp\left(\frac{-jnk2\pi}{N}\right)$$

Transformation of random variables

$$f_Y(y) = \sum_{i=1}^{N} f_X(x_i)\left|\frac{dx_i}{dy}\right|_{x_i=g_i^{-1}(y)}$$

$$f_{UV}(u,v) = f_{XY}(x,y)\left|\frac{\partial(x,y)}{\partial(u,v)}\right|_{\substack{x=g_1^{-1}(u,v)\\ y=g_2^{-1}(u,v)}}$$

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{bmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{bmatrix}$$

 [END OF PAPER]