# **Essential Mathematical Methods for Engineers** (MathEng)

EXAM

December 2023

Duration: 2 hrs, all documents and calculators permitted ATTEMPT ALL QUESTIONS – ANSWER IN ENGLISH



1. Using Euler's identity (or any other appropriate method), write down an expression for the complex Fourier series of the signal x(t):

$$x(t) = 3\cos(5t) + 4\sin(10t)$$

[5 marks]

2. Develop an expression for the Fourier Transform of the signal x(t) illustrated in Figure Q2 below

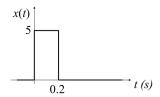


Figure Q2

[6 marks]

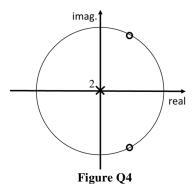
3. A linear, time-invariant system has the following transfer function:

$$H(s) = \frac{10(s+100)}{s^2 + 2s + 100}$$

- (a) Derive an expression for H(s) in the usual, normal form.
- (b) Determine the frequency-invariant gain *K* and the position of any poles and zeros.
- (c) Sketch a Bode plot of the magnitude-frequency response.
- (d) Sketch a Bode plot of the phase-frequency response.

[8 marks]

4. Sketch magnitude and phase responses for a sampled data system with a pair of complex conjugate zeros and two poles at the origin.



[4 marks]

5. A random variable X is uniformly distributed between x = 0 and x = 1. Via any appropriate method, determine the expected value E[Y] of  $Y = \exp(X)$ .

6. Identify the pivots and free variables of the following two matrices A and B. Following the method which we studied in class, find the special solution corresponding to each free variable and, by combining the special solutions, describe every solution to Ax=0 and Bx=0.

$$A = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 1 & 2 & 3 & 6 & 9 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 2 & 4 & 2 \\ 0 & 4 & 4 \\ 0 & 8 & 8 \end{bmatrix}$$

[7 marks]

7. For a projection matrix  $P = A(A^T A)^{-1}A^T$ , show that  $P^2 = P$  and then explain, in terms of the column space of P, why projections Pb and P(Pb) give identical results.

[5 marks]

#### **Table of selected Laplace transforms**

$$X(s) = \int_{-\infty}^{\infty} x(t) \exp(-st) dt$$

N.B.: lower limit is 0 for one-sided Laplace transform

$$x(t) = \frac{1}{2\pi j} \int_{\sigma - j\infty}^{\sigma + j\infty} X(s) \exp(st) \, ds$$

$x(t)  (t \ge 0)$	X(s)
$\delta(t)$	1
$\delta(t-\alpha)$	exp(-\alphas)
1 (unit step)	$\frac{1}{s}$
t (unit ramp)	$\frac{1}{s^2}$
$\exp(-\alpha t)$	$\frac{1}{s+\alpha}$
$t \exp(-\alpha t)$	$\frac{1}{\left(s+\alpha\right)^2}$
sin(ct)	$\frac{\alpha}{s^2 + \alpha^2}$
$\cos(\alpha t)$	$\frac{s}{s^2 + \alpha^2}$
$e^{-\alpha t}\sin(\omega t)$	$\frac{\omega}{(s+\alpha)^2+\omega^2}$
$e^{-\alpha t}\cos(\omega t)$	$\frac{s+\alpha}{(s+\alpha)^2+\omega^2}$

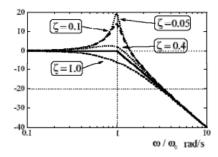
#### **Bode plots**

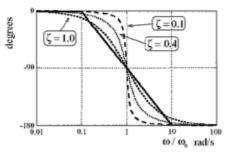
Poles or zeros on the real axis:

$$(s+a) = a\left(\frac{s}{a}+1\right) = \frac{1}{\tau}(\tau s + 1)$$

Complex conjugate poles (or zeros):

$$(s^2 + As + B) = (s^2 + 2\zeta\omega_0 s + \omega_0^2) = \omega_0^2((s/\omega_0)^2 + 2\zeta(s/\omega_0) + 1)$$





#### Table of selected z-transforms

$$x_c(t) = \sum_{n=0}^{\infty} x(n\Delta t)\delta(t - n\Delta t)$$

$$X_c(s) = \sum_{n=0}^{\infty} x(n\Delta t) \exp(-n\Delta t s)$$

$$X_c(s) = X(z)|_{z=e^{\Delta ts}}$$

$$X_c(\omega) = |X_s(s)|_{s=j\omega}$$

$$X(\omega) = X(z)|_{z = \exp(\Delta t j\omega)}$$

$$X(z) = \sum_{n=0}^{\infty} x(n\Delta t)z^{-n}$$

$x(n)  (n \ge 0)$	X(z)		
$\delta(n)$ unit pulse	1		
$\delta(n-m)$	$Z^{-m}$		
1 (unit step)	$\frac{z}{z-1}$		
n (unit ramp)	$\frac{z}{(z-1)^2}$		
$\exp(-\alpha n)$	$\frac{z}{(z-e^{-\alpha})}$		
$n \exp(-\alpha n)$	$\frac{e^{-\alpha}z}{(z-e^{-\alpha})^2}$		
$\sin(\beta n)$	$\frac{z\sin(\beta)}{z^2 - 2z\cos(\beta) + 1}$		
$\cos(\beta n)$	$\frac{z^2 - z\cos(\beta)}{z^2 - 2z\cos(\beta) + 1}$		
$e^{-\alpha n}\sin(\beta n)$	$\frac{ze^{-\alpha}\sin(\beta)}{z^2 - 2ze^{-\alpha}\cos(\beta) + e^{-2\alpha}}$		
$e^{-cn}\cos(\beta n)$	$\frac{z^2 - ze^{-\alpha}\cos(\beta)}{z^2 - 2ze^{-\alpha}\cos(\beta) + e^{-2\alpha}}$		

## **Table of selected Fourier transform pairs**

Function	x(t)	$X(\omega)$
Rectangular function of width $ au$	$\Pi(t/ au)$	$\tau \operatorname{sinc}(\omega \tau/2)$
Triangular function of width $2\tau$	$\Lambda(t/ au)$	$\tau \operatorname{sinc}^2(\omega \tau/2)$
Train of impulses every $\Delta t$	$\delta_T(t)$	$2\pi/\Delta t \Sigma_n \delta(\omega - 2\pi n/\Delta t)$

NB:  $sinc(x) = sin(\pi x)/\pi x$ NB: sa(x) = sin(x)/x

## **Euler's identity**

$$\exp(j\theta) = \cos\theta + j\sin\theta$$

$$\cos(n\omega_0 t) = \frac{\exp(jn\omega_0 t) + \exp(-jn\omega_0 t)}{2}$$

$$\sin(n\omega_0 t) = \frac{\exp(jn\omega_0 t) - \exp(-jn\omega_0 t)}{2j}$$

#### Fourier series and transforms

Trigonometric Fourier series

$$x(t) = \frac{A_0}{2} + \sum_{n=1}^{\infty} A_n \cos(n\omega_0 t) + B_n \sin(n\omega_0 t)$$

$$A_n = \frac{2}{T} \int_{-T/2}^{T/2} x(t) \cos(n\omega_0 t) dt$$

$$B_n = \frac{2}{T} \int_{-T/2}^{T/2} x(t) \sin(n\omega_0 t) dt$$

Complex Fourier series – periodic and continuous in time, discrete in frequency

$$x(t) = \sum_{n=-\infty}^{+\infty} X_n \exp(jn\omega_0 t)$$

$$x(t) = \sum_{n=-\infty}^{+\infty} X_n \exp(jn\omega_0 t)$$
 
$$X_n = \frac{1}{T} \int_{-T/2}^{T/2} x(t) \exp(-jn\omega_0 t) dt$$

Fourier transform – continuous in time, continuous in frequency

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \exp(j\omega t) d\omega \qquad X(\omega) = \int_{-\infty}^{\infty} x(t) \exp(-j\omega t) dt$$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \exp(-j\omega t) dt$$

Discrete-time Fourier transform – discrete in time, continuous and periodic in frequency

$$x(n\Delta t) = \frac{\Delta t}{2\pi} \int_{-\pi/\Delta t}^{\pi/\Delta t} X(\omega) \exp(jn\Delta t\omega) d\omega \qquad X(\omega) = \sum_{n=-\infty}^{\infty} x(n\Delta t) \exp(-j\omega n\Delta t)$$

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n\Delta t) \exp(-j\omega n\Delta t)$$

Discrete Fourier transform – discrete and periodic in time and in frequency

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) \exp\left(\frac{jnk2\pi}{N}\right) \qquad X(k) = \sum_{n=0}^{N-1} x(n) \exp\left(\frac{-jnk2\pi}{N}\right)$$

$$X(k) = \sum_{n=0}^{N-1} x(n) \exp\left(\frac{-jnk2\pi}{N}\right)$$

#### **Transformation of random variables**

$$f_Y(y) = \sum_{i=1}^{N} f_X(x_i) \left| \frac{dx_i}{dy} \right|_{x_i = g_i^{-1}(y)}$$

$$f_{UV}(u,v) = f_{XY}(x,y) \left| \frac{\partial(x,y)}{\partial(u,v)} \right|_{\substack{x=g_1^{-1}(u,v)\\y=g_2^{-1}(u,v)}}$$

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{bmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{bmatrix}$$