

## Mathematical Methods for Engineers (MathEng)

### EXAM

11<sup>th</sup> February 2020

Duration: 2 hrs, calculators permitted, no documents

This exam paper contains 7 questions and 40 marks.

ATTEMPT ALL QUESTIONS – ANSWER IN ENGLISH



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1. Via any appropriate method, and by justifying your response, write an expression for the Fourier transform of  $x(t) = \cos w_0 t$ .

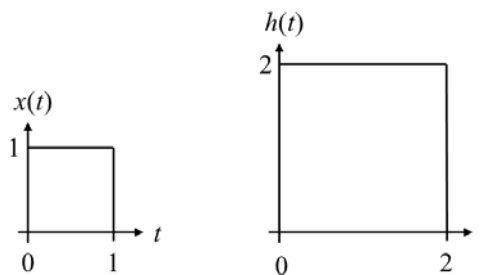
[5 marks]

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2. Sketch the s-plane pole-zero plot for a system with the following transfer function and then sketch the amplitude frequency response.

$$H(s) = \frac{s^2 + 9}{(s^2 + 0.6s + 4.09)}$$

[5marks]

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3. A system with the illustrated transfer function  $h(t)$  is excited by the illustrated input signal  $x(t)$ . Using any appropriate method, **sketch** the output  $y(t) = x(t) * h(t)$ , where  $*$  indicates convolution.



[5 marks]

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4. Using any appropriate technique, derive an expression for the inverse z-transform of:

$$X(z) = \frac{z}{2z^2 - 3z + 1} \quad \text{where} \quad |z| < \frac{1}{2}$$

[6marks]

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5. The joint probability density function for random variables  $x$  and  $y$  is given by:

$$f_{x,y}(x,y) = \begin{cases} 8xy & 0 \leq x \leq 1, 0 \leq y \leq x \\ 0 & \text{otherwise} \end{cases}.$$

Find:

- (a) The marginal probability density function  $f_X(x)$ ;
- (b) The marginal probability density function  $f_Y(y)$ ;
- (c) The conditional probability density function  $f_{X|Y}(x|y)$ ;
- (d) The conditional probability density function  $f_{Y|X}(y|x)$ .

[8 marks]

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6. Determine whether

$$G = \begin{bmatrix} 0 & 0.5 \\ -0.25 & 0.25 \end{bmatrix}$$

is the inverse of any of the following matrices:

$$A = \begin{bmatrix} 4 & -8 \\ 4 & 0 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}, C = \begin{bmatrix} 2 & -4 \\ 2 & 0 \end{bmatrix}, D = \begin{bmatrix} 2 & -4 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

[4 marks]

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7. Use the Gram-Schmidt process to construct an orthogonal set of vectors from the linearly independent set:

$$X_1 = \begin{bmatrix} -4 \\ 3 \\ 6 \end{bmatrix}, X_2 = \begin{bmatrix} 2 \\ -3 \\ 6 \end{bmatrix}, X_3 = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}.$$

[7 marks]

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**Table of selected Laplace transforms**

$$X(s) = \int_{-\infty}^{\infty} x(t) \exp(-st) dt$$

N.B.: lower limit is 0 for one-sided Laplace transform

$$x(t) = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} X(s) \exp(st) ds$$

$x(t) \ (t \geq 0)$	$X(s)$
$\delta(t)$	1
$\delta(t - \alpha)$	$\exp(-\alpha s)$
1 (unit step)	$\frac{1}{s}$
$t$ (unit ramp)	$\frac{1}{s^2}$
$\exp(-\alpha t)$	$\frac{1}{s + \alpha}$
$t \exp(-\alpha t)$	$\frac{1}{(s + \alpha)^2}$
$\sin(\alpha t)$	$\frac{\alpha}{s^2 + \alpha^2}$
$\cos(\alpha t)$	$\frac{s}{s^2 + \alpha^2}$
$e^{-\alpha t} \sin(\omega t)$	$\frac{\omega}{(s + \alpha)^2 + \omega^2}$
$e^{-\alpha t} \cos(\omega t)$	$\frac{s + \alpha}{(s + \alpha)^2 + \omega^2}$

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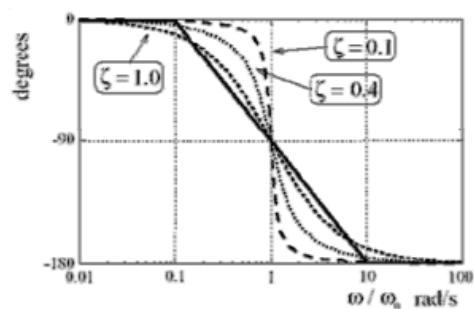
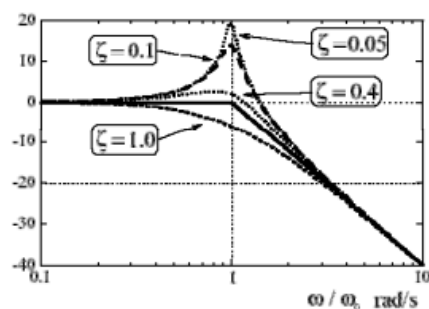
**Bode plots**

Poles or zeros on the real axis:

$$(s + a) = a \left( \frac{s}{a} + 1 \right) = \frac{1}{\tau} (\tau s + 1)$$

Complex conjugate poles (or zeros):

$$(s^2 + As + B) = (s^2 + 2\zeta\omega_0 s + \omega_0^2) = \omega_0^2 ((s/\omega_0)^2 + 2\zeta(s/\omega_0) + 1)$$



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**Table of selected z-transforms**

$$x_c(t) = \sum_{n=0}^{\infty} x(n\Delta t)\delta(t - n\Delta t)$$

$$X_c(s) = \sum_{n=0}^{\infty} x(n\Delta t)\exp(-n\Delta ts)$$

$$X_c(s) = X(z)|_{z=e^{\Delta ts}}$$

$$X_c(\omega) = X_s(s)|_{s=j\omega}$$

$$X(\omega) = X(z)|_{z=\exp(\Delta t j\omega)}$$

$$X(z) = \sum_{n=0}^{\infty} x(n\Delta t)z^{-n}$$

$x(n) \ (n \geq 0)$	$X(z)$
$\delta(n)$ unit pulse	1
$\delta(n-m)$	$z^{-m}$
1 (unit step)	$\frac{z}{z-1}$
$n$ (unit ramp)	$\frac{z}{(z-1)^2}$
$\exp(-\alpha n)$	$\frac{z}{(z-e^{-\alpha})}$
$n \exp(-\alpha n)$	$\frac{e^{-\alpha} z}{(z-e^{-\alpha})^2}$
$\sin(\beta n)$	$\frac{z \sin(\beta)}{z^2 - 2z \cos(\beta) + 1}$
$\cos(\beta n)$	$\frac{z^2 - z \cos(\beta)}{z^2 - 2z \cos(\beta) + 1}$
$e^{-\alpha n} \sin(\beta n)$	$\frac{ze^{-\alpha} \sin(\beta)}{z^2 - 2ze^{-\alpha} \cos(\beta) + e^{-2\alpha}}$
$e^{-\alpha n} \cos(\beta n)$	$\frac{z^2 - ze^{-\alpha} \cos(\beta)}{z^2 - 2ze^{-\alpha} \cos(\beta) + e^{-2\alpha}}$

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**Table of selected Fourier transform pairs**

Function	$x(t)$	$X(\omega)$
Rectangular function of width $\tau$	$\Pi(t/\tau)$	$\tau \operatorname{sinc}(\omega\tau/2)$
Triangular function of width $2\tau$	$\Lambda(t/\tau)$	$\tau \operatorname{sinc}^2(\omega\tau/2)$
Train of impulses every $\Delta t$	$\delta_T(t)$	$2\pi/\Delta t \sum_n \delta(\omega - 2\pi n/\Delta t)$

NB:  $\operatorname{sinc}(x) = \sin(\pi x)/\pi x$

NB:  $\operatorname{sa}(x) = \sin(x)/x$

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**Euler's identity**

$$\exp(j\theta) = \cos \theta + j \sin \theta$$

$$\cos(n\omega_0 t) = \frac{\exp(jn\omega_0 t) + \exp(-jn\omega_0 t)}{2}$$

$$\sin(n\omega_0 t) = \frac{\exp(jn\omega_0 t) - \exp(-jn\omega_0 t)}{2j}$$

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## Fourier series and transforms

### Trigonometric Fourier series

$$x(t) = \frac{A_0}{2} + \sum_{n=1}^{\infty} A_n \cos(n\omega_0 t) + B_n \sin(n\omega_0 t)$$

$$A_n = \frac{2}{T} \int_{-T/2}^{T/2} x(t) \cos(n\omega_0 t) dt$$

$$B_n = \frac{2}{T} \int_{-T/2}^{T/2} x(t) \sin(n\omega_0 t) dt$$

### Complex Fourier series – periodic and continuous in time, discrete in frequency

$$x(t) = \sum_{n=-\infty}^{+\infty} X_n \exp(jn\omega_0 t)$$

$$X_n = \frac{1}{T} \int_{-T/2}^{T/2} x(t) \exp(-jn\omega_0 t) dt$$

### Fourier transform – continuous in time, continuous in frequency

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \exp(j\omega t) d\omega$$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \exp(-j\omega t) dt$$

### Discrete-time Fourier transform – discrete in time, continuous and periodic in frequency

$$x(n\Delta t) = \frac{\Delta t}{2\pi} \int_{-\pi/\Delta t}^{\pi/\Delta t} X(\omega) \exp(jn\Delta t\omega) d\omega$$

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n\Delta t) \exp(-j\omega n\Delta t)$$

### Discrete Fourier transform – discrete and periodic in time and in frequency

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) \exp\left(\frac{jnk2\pi}{N}\right)$$

$$X(k) = \sum_{n=0}^{N-1} x(n) \exp\left(\frac{-jnk2\pi}{N}\right)$$

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**Transformation of random variables**

$$f_Y(y) = \sum_{i=1}^N f_X(x_i) \left| \frac{dx_i}{dy} \right|_{x_i=g_i^{-1}(y)}$$

$$f_{UV}(u, v) = f_{XY}(x, y) \left| \frac{\partial(x, y)}{\partial(u, v)} \right|_{\substack{x=g_1^{-1}(u, v) \\ y=g_2^{-1}(u, v)}}$$

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{bmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{bmatrix}$$