

# viterbi

December 19, 2024

## 1 Julia Implementation of Viterbi Algorithm

```
[1]: function Viterbi(states, init, trans, emit, obs)
    # Input:
    # states: Array of hidden states (e.g., [1, 2, ..., S])
    # init: Array of initial probabilities for each state
    # trans:  $S \times S$  transition matrix (transition probabilities between states)
    # emit:  $S \times O$  emission matrix (probabilities of observations given states)
    # obs: Array of  $T$  observations (sequence of observations)

    T = length(obs) # Number of observations
    S = length(states) # Number of states

    # Initialize matrices
    prob = zeros(T, S) #  $T \times S$  matrix for probabilities
    prev = fill(NaN, T, S) #  $T \times S$  matrix for storing previous states

    # Initialization step ( $t = 0$ )
    for s in 1:S
        prob[1, s] = init[s] * emit[s, obs[1]] # Calculate initial
        ↪probabilities
    end

    # Recursion step ( $t = 1$  to  $T-1$ )
    for t in 2:T
        for s in 1:S
            for r in 1:S
                new_prob = prob[t - 1, r] * trans[r, s] * emit[s, obs[t]]
                if new_prob > prob[t, s]
                    prob[t, s] = new_prob
                    prev[t, s] = r # Store the state r that maximized the
                    ↪probability
                end
            end
        end
    end
end
```

```

    # Backtracking to find the most probable path
    path = Vector{Int}(undef, T) # Array to store the path
    path[T] = argmax(prob[T, :]) # Find the state with the highest probability
    ↪at the last time step

    for t in (T - 1):-1:1
        path[t] = prev[t + 1, path[t + 1]] # Follow the back-pointers to
    ↪reconstruct the path
    end

    return path
end

```

[1]: Viterbi (generic function with 1 method)

## 1.1 Explanation

### 1. Inputs:

- **states**: Hidden states (e.g.,  $S_1, S_2, \dots, S_S$ ).
- **init**: Initial probabilities  $P(S_i)$  for each state.
- **trans**: Transition probabilities  $P(S_j|S_i)$  between states.
- **emit**: Emission probabilities  $P(O_k|S_i)$  of observations  $O_k$  given states.
- **obs**: Sequence of observations.

### 2. Initialization:

- At  $t = 0$ , calculate the initial probabilities using  $init[s] \cdot emit[s, obs[1]]$ .

### 3. Recursion:

- For  $t = 1$  to  $T - 1$ , compute probabilities for each state  $s$  by considering all possible previous states  $r$ .
- Track the state  $r$  that maximized the probability.

### 4. Backtracking:

- Start from the state with the maximum probability at the final time step.
- Follow the **prev** matrix to reconstruct the most probable sequence of states.

### 5. Output:

- Returns the most probable sequence of hidden states.

```

[2]: states = [1, 2, 3] # Hidden states
init = [0.5, 0.2, 0.3] # Initial probabilities
trans = [0.7 0.2 0.1; 0.1 0.6 0.3; 0.3 0.3 0.4] # Transition probabilities
emit = [0.9 0.1; 0.2 0.8; 0.1 0.9] # Emission probabilities
obs = [1, 2, 1] # Observation sequence (1-based indexing)

# Run the Viterbi algorithm
most_probable_path = Viterbi(states, init, trans, emit, obs)
println("Most probable path: ", most_probable_path)

```

Most probable path: [1, 1, 1]

## 1.2 Output

For the example above, the algorithm will return the most probable sequence of states corresponding to the observation sequence.

## 2 References

[Viterbi\\_algorithm](#)

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