

Manoranjani Navamani Kathiresan Kulanthaivel

Brice Setra Robert

## Assignment 1

1. The data-sheet for the JL-55-23 specifies different RX sensitivity levels for different data rates. Additionally, assume that for the correct decoding of the lowest modulation and coding scheme (MCS) a SNR of 0dB is required. What is the maximum allowed receiver noise figure at room temperature (T = 300K) for the given system?

```
In [1]: K_B = 1.38e-23; @show K_B # Boltzmann constant
        T_e = 300; @show T_e; # Average Room Temperature [290 - 300k] Kelvin
```

```
K_B = 1.38e-23
T_e = 300
```

```
In [2]: N_0 = 10 * log10( K_B * T_e ) + 30; @show round( N_0, digits = 0); # Termal Noise -174 dBm

round(N_0, digits = 0) = -174.0
```

```
In [3]: B = 10 * log10(40e6); # B Bandwidth
```

```
In [4]: SNR = 0; @show SNR; # dB

SNR = 0
```

```
In [5]: P_n = N_0 + B; @show round( P_n, digits = 1); # Total RX Noise = -174 dBm + 10log(B) in dB

round(P_n, digits = 1) = -97.8
```

```
In [6]: R_x_s = -97; # MIMO Data Rates & RX-sensitivity (lowest MCS [0 - 15 Mbps] value -97 dB
```

Supported Link rates: in Datasheet JLG-55-23.pdf

MIMO Data Rates & RX-sensitivity	
MCS 15 - 300 Mbps	-74 dBm
MCS 14 - 270 Mbps	-76 dBm
...	...
MCS 1 - 30 Mbps	-94 dBm
MCS 0 - 15 Mbps	-97 dBm

```
In [7]: # Rx Sensitivity
        # R_s = N_0 + F + B + SNR # P_n (dBm) + F (dB) + B (dB) + SNR (dB)
```

```
In [8]: R_v = N_0 + B + SNR; @show R_v;

R_v = -97.80939667551138
```

```
In [9]: F = R_x_s - R_v; @show F; # In dB

F = 0.8093966755113797
```

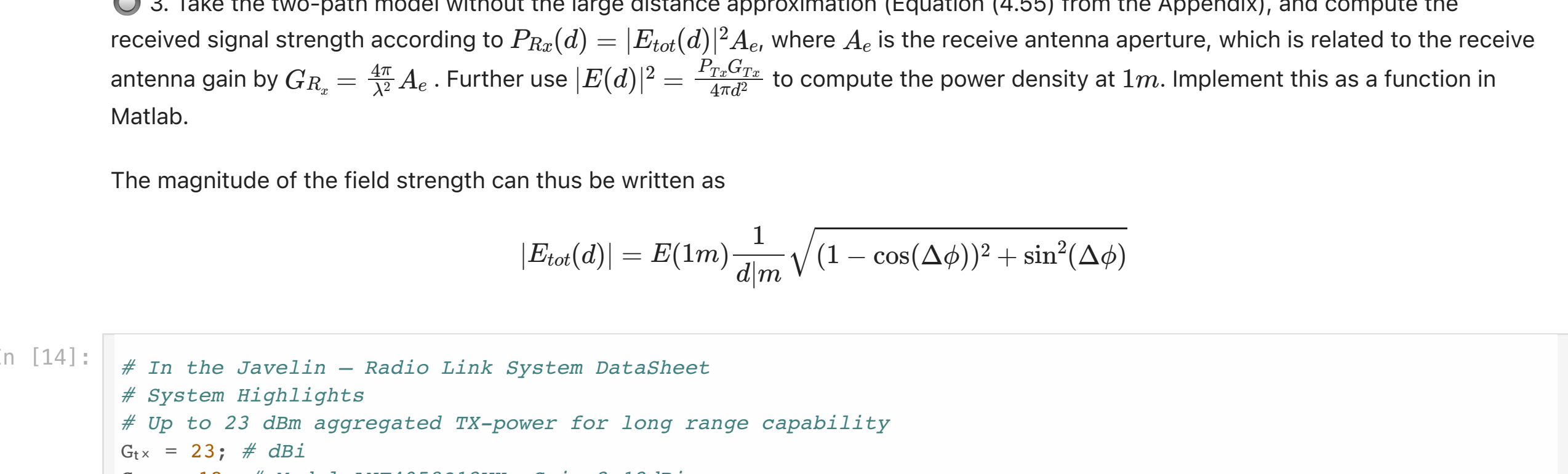
2. Plot the measurement data (RSSI vs distance) for both polarizations. Try to explain where the difference between the two polarizations comes from!

```
In [10]: ## Receive the signal
include("../data/rssi.jl");
```

```
In [11]: # Vectorize the Matlab's data to Julia's format
d1, r_ess1^1 = vec(d1), vec(rssi1);
d2, r_ess1^2 = vec(d2), vec(rssi2);
```

```
In [12]: using Plots, Plots.Measures
```

```
In [13]: plt = plot( d1, r_ess1^1, label = "Horizontal", linewidth = .3)
plt = plot!(d2, r_ess1^2, label = "Vertical", linewidth = .3)
plot(plt
      , xlabel="Distance (km)", ylabel="Received Power (dB)"
      , title="(RSSI vs distance) for both polarizations"
      , size = (800,500)
      , legend = :topright
      , xticks = 0:1:20
      , grid = :true
      , margin = 5mm
      )
```



Try to explain where the difference between the two polarizations comes from!

When analysing polarization for wireless broadband communications between boats on the sea, it may be crucial to consider the typical sea conditions and the specific operational requirements. While vertical polarization seems to be common, its effectiveness may be compromised by large, rough sea waves. We can observe a 10dB difference between the two polarizations and the vertical seems to be unstable.

3. Take the two-path model without the large distance approximation (Equation (4.55) from the Appendix), and compute the received signal strength according to  $P_{Rx}(d) = |E_{tot}(d)|^2 A_e$ , where  $A_e$  is the receive antenna aperture, which is related to the receive antenna gain by  $G_{R_x} = \frac{4\pi}{\lambda^2} A_e$ . Further use  $|E(d)|^2 = \frac{P_T G_T}{4\pi d^2}$  to compute the power density at 1m. Implement this as a function in Matlab.

The magnitude of the field strength can thus be written as

$$|E_{tot}(d)| = E(1m) \frac{1}{d/m} \sqrt{(1 - \cos(\Delta\phi))^2 + \sin^2(\Delta\phi)}$$

```
In [14]: # In the Javelin - Radio Link System DataSheet
# System Highlights
# Up to 23 dBm aggregated TX-power for long range capability
G_tx = 23; # dBi
G_r_x = 12; # Model ANT4958Q12VH Gain 2x12dBi
P_tx = 23; # Up to 23 dBm aggregated TX-power for long range capability
```

```
In [15]: # In linear Values
G_tx_lin = 10^(G_tx/10)
G_r_x_lin = 10^(G_r_x/10)
P_tx_lin = 10^(P_tx/10);
```

```
In [16]: f_c = 5.6e9 # Carrier Frequency in Hz
C = 3e8; # In m/s
```

The formula  $\lambda = C/f$  represents the fundamental relationship between the wavelength  $\lambda$  of a radio wave, the speed of light  $C$ , and the frequency  $f$  of the wave. Then the wavelength calculation would be:  $\lambda = \frac{C}{f} = \frac{3 \times 10^8 \text{ m/s}}{5.6 \text{ GHz}}$

```
In [17]: lambda = C / f_c * 1e-3; @show lambda; # in Km

lambda = 5.357142857142857e-5
```

$$\text{Receiver Antenna: } A_e = \frac{G_{R_x} \lambda^2}{4\pi}$$

```
In [18]: A_e = G_r_x_lin * lambda^2 / 4pi; @show A_e;

A_e = 3.6195667612817716e-9
```

```
In [19]: E_0 = sqrt(( P_tx_lin * G_tx_lin ) / 4pi); @show E_0;

E_0 = 56.285310727541194
```

$$\Delta\phi = 2 \frac{h_{Tx} h_{Rx}}{d} \frac{2\pi f_c}{c}$$

```
In [20]: h_tx = 25 # In meter
h_r_x = 3; # In meter
```

```
In [21]: # For computing linear Values
h_tx_lin = h_tx * 1e-3 # In millimeter
h_r_x_lin = h_r_x * 1e-3; # In millimeter
```

```
In [22]: # Initialize E_tot
E_tot = zeros(length(d1))

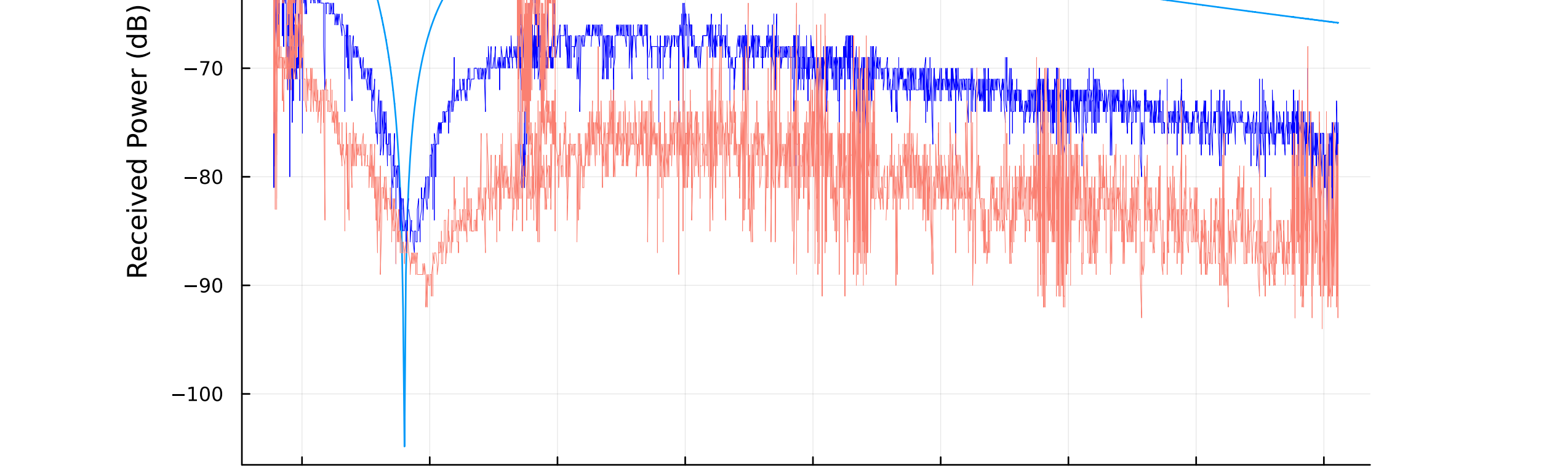
# Compute E_tot for each distance
for (i, d) in enumerate(d1)
    Delta_phi = 2 * (h_tx_lin * h_r_x_lin / d) * (2pi / lambda)
    E_tot[i] = (E_0 / d) * sqrt((1 - cos(Delta_phi))^2 + (sin(Delta_phi))^2)
end
```

```
In [23]: P_r_x = 10 * log10.(E_tot.^2 * A_e); # received power in dB
```

4. Plot the received power based on the previous function on top of the measurement data.

```
In [24]: using LaTeXStrings
```

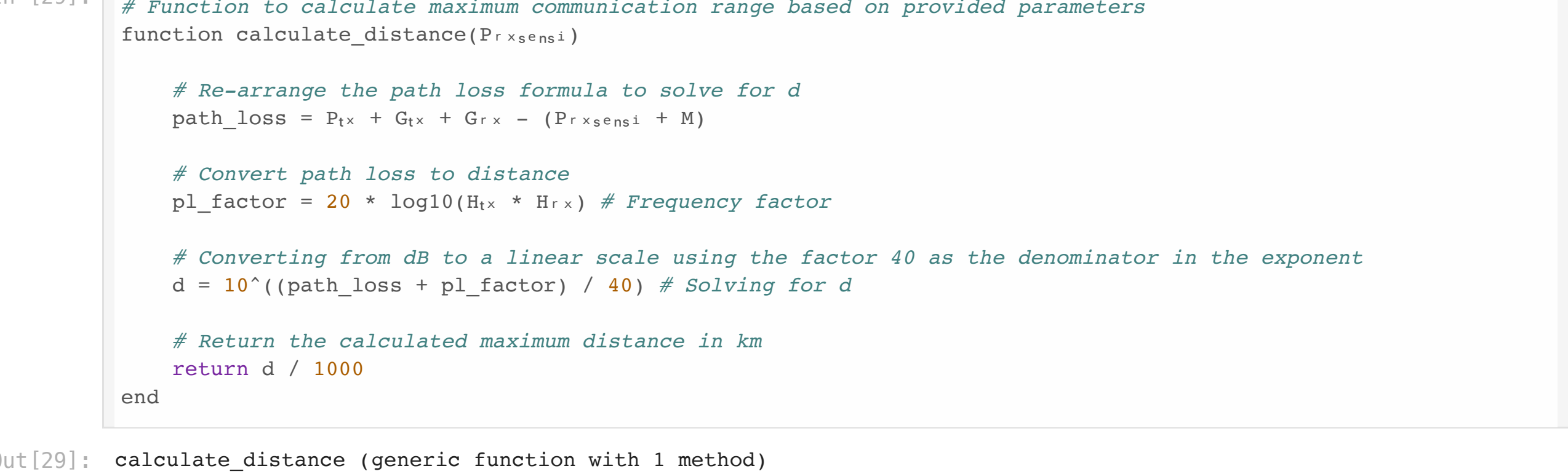
```
In [25]: # Signal Strength vs. Distance on a log scale
p1 = plot(d1, P_r_x
          , #, xaxis=:log
          , xlabel="Distance (km)", ylabel="Received Power (dB)"
          , title=L"P_{Rx}(d) = |E_{tot}(d)|^2 A_e " * " Two-Path Model"
          , size = (800,500)
          , legend=:false
          , xticks = 1:1:10
          , margin = 5mm
          )
plot(p1)
```



Does the model fit the data? Try to explain why or why not!

With the V shape design, then decaying when distance increases, the two-path model follows the same figure as the two polarization plot, albeit higher in height (between -110dB and -50dB). The height may be due to the model's nature of not being affected by white noise.

```
In [26]: p2 = plot(d1, P_r_x
                  #, xaxis=:log
                  , xlabel="Distance (km)", ylabel="Received Power (dB)"
                  , label = "Two-Path Model"
                  , legend=:false
                  )
p2 = plot!( d1, r_ess1^1, label = "Horizontal", linewidth = .3, color=:blue)
p2 = plot!(d2, r_ess1^2, label = "Vertical", linewidth = .3, color=:salmon)
plot(p2
     , xlabel="Distance (km)", ylabel="Received Power (dB)"
     , title="Model Fitting"
     , size = (800,500)
     , xticks = 1:1:10
     , legend = :topright
     , grid = :true
     , margin = 5mm
     )
```



5. Using the path loss approximation for large distances (4.59) from the Appendix, and assuming a fading margin of M = 10 dB, determine the maximum range of one cell for the lowest and the highest MCS.

$$P_{RX}(d) \approx P_{TX} G_{TX} G_{RX} \left( \frac{h_{Tx} h_{Rx}}{d^2} \right)^2 \quad (4.59)$$

```
In [27]: using Printf
```

```
In [28]: M = 10; @show M; # dB Fading Margin
R_sens_low, R_sens_max = -97, -74; @show R_sens_low, R_sens_max; # RX Sensitivity MCS Min and Max

M = 10
(R_sens_low, R_sens_max) = (-97, -74)
```

Calculate Distance

$$d_{(dB)} = P_{TX}(dB) + G_{TX}(dB) + G_{RX}(dB) - (P_{RX\_sens\_range}(dB) + M)$$

$$p_{factor} = 20 \log_{10}(h_{TX} \times h_{RX})$$

Solve d

```
In [29]: # Function to calculate maximum communication range based on provided parameters
function calculate_distance(P_rx_sens_low)

    # Re-arrange the path loss formula to solve for d
    path_loss = P_tx + G_tx + G_rx - (P_rx_sens_low + M)

    # Convert path loss to distance
    pl_factor = 20 * log10(h_tx * h_rx) # Frequency factor

    # Converting from dB to a linear scale using the factor 40 as the denominator in the exponent
    d = 10^((path_loss + pl_factor) / 40) # Solving for d

    # Return the calculated maximum distance in km
    return d / 1000
end
```

```
Out[29]: calculate_distance (generic function with 1 method)
```

```
In [30]: # Calculate distances for the lowest and highest MCS sensitivities
d_max_lowest = calculate_distance(R_sens_low) # Lowest MCS sensitivity
d_max_highest = calculate_distance(R_sens_max) # Highest MCS sensitivity

println("Maximum range for the lowest MCS: $(sprintf("%.2f", d_max_lowest)) km")
println("Maximum range for the highest MCS: $(sprintf("%.2f", d_max_highest)) km")
```

Maximum range for the lowest MCS: 36.52 km

Maximum range for the highest MCS: 9.72 km

```
In [ ]:
```