Introduction to Econometrics 2: Recitation 9

Seung-hun Lee

Columbia University

April 8th, 2020

Motivation

• The usual linear regression, which has the form

$$y = X\beta + u$$

where E(Xu) = 0 (or more restrictively, E(u|X) = 0)

- ullet This setup is aimed at capturing the conditional mean of y given X.
- However, there is no reason to restrict our attention to just a conditional mean. We might want a conditional median etc.
- Quantile regression aims to capture different values of β depending on the location of the conditional distribution.

Setup

• The quantile regression seeks to estimate the conditional quantile

$$q_{\tau}(y|X) = X\beta_{\tau}$$

where $\tau \in [0,1]$ is the percentile of our choice satisfying $F_{y|X}(X\beta_{\tau}|X) = \tau$.

With

$$F_{y|X}(X\beta_{\tau}|X) = \Pr(y \le X\beta_{\tau}|X) = \tau$$

we can write

$$\tau - \Pr(y \le X \beta_{\tau} | X) = 0$$

Since $\Pr(y \leq X\beta_{\tau}|X)$ is equal to $E[1(y - X\beta_{\tau} \leq 0)] = E[1(u \leq 0)]$, we can obtain the condition

$$E[\tau - 1(y - X\beta_{\tau} \le 0)|X] = 0$$

this also implies $E[(\tau - 1(y - X\beta_{\tau} \le 0))X] = 0$

Setup: Check Function

• The check function can be defined as

$$\rho_{\tau}(u) = u(\tau - 1(u \le 0))$$

• Median: Let $\tau = 1/2$. Then the check function becomes

$$\rho_{1/2}(u) = \begin{cases} -\frac{1}{2}u & (u \le 0) \\ \frac{1}{2}u & (u > 0) \end{cases} = \frac{1}{2}|u| = \frac{1}{2}|y - X\beta_{1/2}|$$

This becomes equivalent to solving the least absolute deviation problem.

• $\tau = 1/3$: Then the check function becomes

$$\rho_{1/3}(u) = \begin{cases} -\frac{2}{3}u & (u \le 0) \\ \frac{1}{3}u & (u > 0) \end{cases}$$

which has a kink at u = 0 and is asymmetric.

Finding the Quantile Estimator

• The minimization problem solved in quantile regression is

$$\min_{\beta} E[\rho_{\tau}(y - X\beta_{\tau})|X]$$

which can be written as

$$E[\rho_{\tau}(y-X_{i}\beta_{\tau})|X] = (\tau-1)\int_{-\infty}^{a}(y-a)f_{Y|X}(y|x)dy + \tau\int_{a}^{\infty}(y-a)f_{Y|X}(y|x)dy$$

where $a = X\beta_{\tau}$

Take the first order condition w.r.t. a to get

$$-(\tau - 1) \int_{-\infty}^{a} f_{Y|X}(y|x) dy - \tau \int_{a}^{\infty} f_{Y|X}(y|x) dy = 0$$

$$\iff -\tau + F(a|X) = 0$$

Finding the Quantile Estimator

• Thus, the β_{τ} that solves

$$X\beta_{\tau} = a = F_{Y|X}^{-1}(\tau|X)$$

is the β_{τ} that we are looking for

We can also solve for

$$\min_{\beta} E[\rho_{\tau}(y - X\beta_{\tau})X]$$

or in a sample analogue

$$\min_{\beta} \frac{1}{n} \sum_{i=1}^{n} \rho_{\tau} (y_i - X_i \beta_{\tau}) X_i$$

For suitable conditions, the resulting estimator is CAN.

Examples

- Levin (2001)
 - In educational production function literature, the effect of class size on various outcomes for the student is controversial
 - Uses quantile regression in estimating educational production
 - Also controls for peer effects turns out that this effect matters more especially for those in the low achievement group
 - Class size does not have as significant effect
- Autor, Houseman, Kerr (2017)
 - Studies effect of direct hire assistance and temporary-help job placement programs in Detroit on distribution of participant's earnings over a 7-quarter period
 - For low-tail, none are effective. For high-tail, direct hire raises earnings but temporary-help does not
 - Autor, Houseman (2010) study the same program without QR and finds on avg that earnings increased

Motivation

- Consider a setting where we observe the data (y_i, x_i) which is i.i.d. and drawn from a DGP $P_0(y|x)$.
- We are interested in backing out the whole or part of the data generating process $P_0(y|x)$ without any modeling assumptions
- This approach is called a nonparametric approach
- We normally use nonparametric approach to
 - Conduct a diagnostic checking of an estimated parametric model,
 - To conveniently display key features of the dataset
 - Conduct an inference under very weak assumptions.

Idea

 For discrete-valued Y and X, this is relatively easy. Just back out the data generating process of interest

$$\hat{P}(y \in A | x \in B) = \frac{n^{-1} \sum_{i=1}^{n} 1(y_i \in A, x_i \in B)}{n^{-1} \sum_{i=1}^{n} 1(x_i \in B)}$$

Provided that $P_0(x \in B) \neq 0$, then the above estimator converges to the true $P_0(y|x)$ as $n \to \infty$.

- For continuous cases, $A \equiv (-\infty, y], B \equiv [x \epsilon, x + \epsilon]$ and use $\lim_{\epsilon \to 0} \hat{P}(A|B)$ to back out the DGP
- ullet This can be problematic when we have too many dimensions of X
- Therefore, the method to conduct nonparametric estimation in this context is kernel density function approach.

Kernels

- Consider the problem of estimating the probability density function f(x) of a random scalar variable X at X = x
- Let $\{X_1, ..., X_n\}$ be a random sample of X. If f is a smooth function, we can approximate f by

$$f(x) \simeq \frac{\int_{x-h}^{x+h} f(u) du}{2h}$$

for a small h

 The numerator on the right hand side can be estimated using a sample analogue of the following form

$$\frac{1}{n} \sum_{i=1}^{n} 1\{x - h \le X_i \le x + h\}$$

Kernels

• Combining the two expressions, we can approximate f(x) with

$$\hat{f}(x) = \frac{n^{-1} \sum_{i=1}^{n} 1[x - h \le X_i \le x + h]}{2h}$$

$$= \frac{1}{2nh} \sum_{i=1}^{n} 1[x - h \le X_i \le x + h]$$

$$= \frac{1}{nh} \sum_{i=1}^{n} \frac{1}{2} 1\left[\left|\frac{x - X_i}{h}\right| \le 1\right]$$

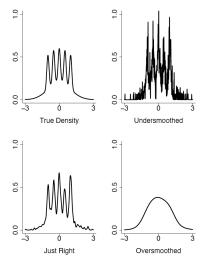
$$= \frac{1}{nh} \sum_{i=1}^{n} K\left(\frac{x - X_i}{h}\right)$$

where $K(u) = \frac{1}{2}1(|u| \le 1)$ - a uniform kernel.

- $K(\cdot)$ is a **kernel density estimator**. It should be a real-to-real function, positive and smooth and integrates to 1 on its support
- Generally type of kernels rarely matter

Bandwidth

 However, bandwidths do matter, as they are involved in the the trade-off between bias and variance



Bandwidth: Characterizing Bias

$$E[\hat{f}(x)] = \frac{1}{h} \int_{-\infty}^{\infty} K\left(\frac{x-s}{h}\right) f(s) ds$$

$$= -\frac{1}{h} \int_{-\infty}^{\infty} K(t) f(x-ht) (-hdt) \left(\because \frac{x-s}{h} = t \text{ transformation}\right)$$

$$= \int_{-\infty}^{\infty} K(t) f(x-ht) dt$$

$$= \int_{-\infty}^{\infty} K(t) \left[f(x) - f'(x) ht + \frac{f''(x) h^2 t^2}{2} + o(h^2) \right] dt$$

$$= f(x) - 0 + \frac{1}{2} \int_{-\infty}^{\infty} K(t) h^2 t^2 f''(x) dt + o(h^2)$$

Where $\int_{-\infty}^{\infty} K(t)dt = 1$ justifies f(x) and $\int_{-\infty}^{\infty} tK(t)dt = 0$ (since kernel is symmetric around 0) justifies second term in the last line being 0

Thus, bias is

$$E[\hat{f}(x)] - f(x) = \frac{1}{2} \int_{-\infty}^{\infty} K(t)h^2 t^2 f''(x) dt$$

Bandwidth: Characterizing Variance

$$Var[\hat{f}(x)] = E\left[\frac{1}{n^2h^2} \left(\sum_{i=1}^n K\left(\frac{x - X_i}{h}\right)\right)^2\right] - (E[\hat{f}(x)])^2$$

$$= E\left[\frac{1}{n^2h^2} \left(\sum_{i=1}^n K^2\left(\frac{x - X_i}{h}\right) + 2\sum_{i < j} K\left(\frac{x - X_i}{h}\right) K\left(\frac{x - X_j}{h}\right)\right)\right] - (E[\hat{f}(x)])^2$$

$$= \frac{1}{nh^2} \int_{-\infty}^{\infty} K^2\left(\frac{x - s}{h}\right) f(s)ds + \frac{n(n-1)}{n^2h^2} \left(\int_{-\infty}^{\infty} K\left(\frac{x - s}{h}\right) f(s)ds\right)^2$$

$$- \frac{1}{h^2} \left(\int_{-\infty}^{\infty} K\left(\frac{x - s}{h}\right) f(s)ds\right)^2$$

Then, use variable transformation and Taylor approximation.

• Thus, the leading term of bias is

$$\frac{1}{nh}\int_{-\infty}^{\infty}K^{2}(t)f(x)dt\simeq O\left(\frac{1}{nh}\right)$$

So low h drops bias at the expense of rising variance

Optimal Bandwidth?

 Optimal h minimizes the loss function, or asymptotic mean integrated squared error (AMISE), defined as

$$\int E(\hat{f}(x) - f(x))^2 dx$$

- We can show that $MSE = Variance + Bias^2$
- From the discussion about the variance and bias,

Variance + Bias² =
$$\frac{1}{nh} \int_{-\infty}^{\infty} K^2(t) f(x) dt + \frac{h^4}{4} (f''(x))^2 \left(\int_{-\infty}^{\infty} K(t) t^2 dt \right)^2$$

Thus, the final version of AMISE can be written as

$$\int (\mathsf{Variance} + \mathsf{Bias}^2) dx = \frac{1}{nh} \int_{-\infty}^{\infty} K^2(t) dt + \frac{h^4}{4} \int_{-\infty}^{\infty} (f''(x))^2 \left(\int_{-\infty}^{\infty} K(t) t^2 dt \right)^2 dx$$

Optimal Bandwidth?

• If $A = \frac{1}{4} \int_{-\infty}^{\infty} (f''(x))^2 \left(\int_{-\infty}^{\infty} K(t) t^2 dt \right)^2 dx$, $B = \int_{-\infty}^{\infty} K^2(t) dt$. Then

$$AMISE = Ah^4 + \frac{B}{nh}$$

Then, the minimization problem becomes min_h AMISE. Therefore, we find h satisfying

$$4Ah^{3} - Bn^{-1}h^{-2} = 0 \iff h^{5} = \frac{B}{4An} \iff h = \left(\frac{B}{4An}\right)^{1/5}$$

- In this framework, the bias and standard errors are both in $n^{-2/5}$ and AMISE will be in $n^{-4/5}$. Therefore, we may not have a CAN estimator at $n^{-1/2}$
- Even bigger problem arises from $\int f''(x)dx$ term in A, as we are not sure of f(x) to begin with, we do not know what f''(x) would be.

Bandwidth Choice in Practice

- Silverman: Use $1.06\sigma n^{-1/5}$ for a normal kernel
- Robust version: $h = 0.9 \min\{s, IQ/1.34\} n^{-1/5}$
- Cross Validation: Use a leave-one-out estimator defined as

$$\hat{f}_{-i}(x) = \frac{1}{nh} \sum_{j \neq i} K\left(\frac{x - x_j}{h}\right)$$

• Local bandwidth: Make h larger in a low density area (decrease variance). In a wiggly region, it is better to take h smaller. (minimize biases).

Curse of Dimensionality

- Now assume that x is not necessarily a scalar, but of dimension d.
- Then we can use a d-dimensional kernel K and estimate f(x) with

$$\hat{f}(x) = \frac{1}{nh^d} \sum_{i=1}^n K\left(\frac{x - x_i}{h}\right)$$

where K can be a d-product of a uni-dimensional kernels

- Not necessarily confined to using a same bandwith for all d kernels.
- We may want to sphericize if the kernel estimators are correlated.
- A bigger concern has to do with the computation cost from using a large d - a curse of dimensionality

Curse of Dimensionality

• Return to calculating $E[\hat{f}(x)^2]$ term in AMISE,

$$E[\hat{f}(x)^{2}] = E\left[\frac{1}{n^{2}h^{2d}}\left(\sum_{i=1}^{n} K\left(\frac{x - X_{i}}{h}\right)\right)^{2}\right]$$

$$= E\left[\frac{1}{n^{2}h^{2d}}\left(\sum_{i=1}^{n} K^{2}\left(\frac{x - X_{i}}{h}\right) + 2\sum_{i < j} K\left(\frac{x - X_{i}}{h}\right) K\left(\frac{x - X_{j}}{h}\right)\right)\right]$$

$$= \frac{1}{nh^{2d}}\int_{-\infty}^{\infty} K^{2}\left(\frac{x - s}{h}\right) f(s)ds + \frac{n(n-1)}{n^{2}h^{2d}}\left(\int_{-\infty}^{\infty} K\left(\frac{x - s}{h}\right) f(s)ds\right)^{2}$$

The leading term is

$$\frac{1}{nh^{2d}}\int_{-\infty}^{\infty}K^{2}\left(\frac{x-s}{h}\right)f(s)ds \simeq \frac{1}{nh^{d}}\int K^{2}(t)f(x-ht)dt = O\left(\frac{1}{nh^{d}}\right)$$

• The optimal h will be in $n^{-\frac{1}{4+d}}$ and convergence occurs in $n^{-\frac{2}{4+d}}$ - at an even slower rate. So more n required to guarantee precision.

Nadaraya-Watson Estimation

- Given the data (y_i, x_i) , we are attempting to capture E[g(y, x)|x] = m(x) for some g(y, x).
- For instance, we can attempt to estimate the conditional expectation by letting g(y,x) = y.
- Note that the conditional expected value can be written as

$$E[y|x] = \int y f_{Y|X}(y|x) dy$$
$$= \int y \frac{f_{Y,X}(y,x)}{f_{X}(x)} dy = \frac{\int y f_{Y,X}(y,x) dy}{\int f_{Y,X}(y,x) dy}$$

• We can obtain the nonparametric estimator for the conditional expected value by replacing $f_{Y,X}$ with its kernel estimator

Nadaraya-Watson Estimation

The numerator becomes

$$\int y \hat{f}(y, x) dy = \int y \frac{1}{nh^2} \sum_{i=1}^{n} K\left(\frac{x - X_i}{h}\right) K\left(\frac{y - Y_i}{h}\right) dy$$

$$= \frac{1}{nh^2} \sum_{i=1}^{n} K\left(\frac{x - X_i}{h}\right) \int y K\left(\frac{y - Y_i}{h}\right) dy$$

$$= \frac{1}{nh^2} \sum_{i=1}^{n} K\left(\frac{x - X_i}{h}\right) \int (Y_i + sh) K(s) (hds) (\because s = \frac{y - Y_i}{h})$$

$$= \frac{1}{nh} \sum_{i=1}^{n} K\left(\frac{x - X_i}{h}\right) Y_i (\because \int K(s) ds = 1, \int sK(s) ds = 0)$$

• The denominator can be written as $\frac{1}{nh}\sum_{i=1}^{n}K\left(\frac{x-X_{i}}{h}\right)$. Thus, the estimator for the conditional expectation becomes

$$\frac{\sum_{i=1}^{n} Y_{i} K\left(\frac{x - X_{i}}{h}\right)}{\sum_{i=1}^{n} K\left(\frac{x - X_{i}}{h}\right)}$$

Nadaraya-Watson Estimation

- Effectively we are putting weight $\frac{K\left(\frac{x-x_i}{h}\right)}{\sum_{i=1}^{n}K\left(\frac{x-X_i}{h}\right)}$ on each observation
- This is also a **local constant estimation** in the sense that when solving the following minimization problem

$$\hat{f}(x) = \arg\min_{a} \frac{1}{nh} \sum_{i=1}^{n} (Y_i - a)^2 K\left(\frac{x - X_i}{h}\right)$$

The first order condition on a yields the following results

$$\sum_{i=1}^{n} Y_{i} K\left(\frac{x - X_{i}}{h}\right) = a \sum_{i=1}^{n} K\left(\frac{x - X_{i}}{h}\right) \implies a = \frac{\sum_{i=1}^{n} Y_{i} K\left(\frac{x - X_{i}}{h}\right)}{\sum_{i=1}^{n} K\left(\frac{x - X_{i}}{h}\right)}$$

- As for the optimal *h*, it is possible to use cross-validation method and minimizing AMISE.
- This method can be unreliable if $f(x) \to 0$

Nadaraya-Watson Estimation

- We can also do something more general. e.g. local linear estimation.
- We regress g(y,x) on a constant (a) and a linear term $(b(x-X_i))$.
- In mathematical expression, we solve

$$\min_{a,b} \frac{1}{nh} \sum_{i=1}^{n} (Y_i - a - b(x - X_i))^2 K\left(\frac{x - X_i}{h}\right)$$

and obtain that $\hat{a} = \hat{g}$ and \hat{b} is an estimate of $\frac{\partial g(x)}{\partial x}$.

- If it happens that the true functional form is linear, then this estimate does not produce a bias.
- In addition, local linear estimation performs better than local constant estimation in the boundaries of the support for X.
- We can do even more with **local polynomial estiation** by regressing g(y,x) on a constant, $x-X_i$, $(x-X_i)^2$ and so on.

Semi-nonparametric Estimation

- Suppose that we are sure that f(x) can be characterized by $f_{m,\sigma}$ where m,σ indexes some properties of the density function f.
- Then, by Weierstrass approximation theorem, we can choose a family of positive functions which increases in complexity $P_{\theta}^1, P_{\theta}^2, \dots$ and maximize over the loglikelihood

$$\sum_{i=1}^{n} \log f_{m,\sigma}(X_i) P_{\theta}^{M}(X_i)$$

- Mixture of normals: Suppose that Y|X is drawn from the two distributions
 - $N_1(m_1(x,\theta),\sigma_1^2(x,\theta))$ with probability $q_1(x,\theta)$
 - $N_2(m_2(x,\theta).\sigma_2^2(x,\theta))$ with probability $q_2(x,\theta)$

Then, we apply a maximum likelihood of the following form

$$\min_{\theta} \sum_{i} \sum_{k} q_k(x_i, \theta) [(y_i - m_k(x_i, \theta))' \sigma_k(x_i, \theta)^{-1} (y_i - m_k(x_i, \theta)) + \log \det \sigma_k(x_i, \theta)]$$

Semi-nonparametric Estimation: Series Estimation

- Let $\{P_k(x_i)|k=1,2...\}$ be the orthonormal basis for a smooth function.
 - $\int P_k(x)^2 dx = 1, \int P_k(x) P_m(x) = 0 \ (k \neq m)$
- These could be polynomials of degree k, sine functions and so on.
- Run a linear regression that has the following form

$$y_i = \sum_{k=1}^M P_k(x_i)\theta_k + \epsilon_i$$

- The $\sum_{k=1}^{M} P_k(x_i)\theta_k$ part is a series approximation to g(x).
- However, depending on the number of M that we choose, the curse of dimensionality can kick in.