

Research Interests

Motion and Path Planning, Robotic Decision Making, Multi-agent Systems, Reinforcement Learning

Affiliations

Carnegie Mellon University

Visiting Researcher at Robotics Institute
Supervisor: Sebastian Scherer

Pittsburgh, PA

Aug. 2024 – Present

(Remote: Mar. 2025 – Jul. 2025)

Ulsan National Institute of Science and Technology

M.S. in Artificial Intelligence (GPA: 4.25/4.3)
Advisor: Jeong hwan Jeon

Ulsan, Korea

Aug. 2023 – Aug. 2026 (exp.)

B.S. in Electrical Engineering (CGPA: 3.54/4.3, Major GPA: 3.66/4.3, Advanced GPA: 3.80/4.3)
Graduated Cum Laude

Feb. 2017 – Aug. 2023*

* Including military service, Republic of Korea Army, Feb. 2020 – Sep. 2021

Publications

* indicates equal contributions.

Conferences

1. PIPE Planner: Pathwise Information Gain with Map Predictions for Indoor Robot Exploration

Seungjae Baek*, Brady Moon*, Seungchan Kim*, Muqing Cao, Cherie Ho, Sebastian Scherer, Jeong hwan Jeon
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2025

[Link]

Journals

1. Cooperative Multi-Agent Reinforcement Learning for Multiple Anti-Aircraft Target Surveillance

Kangbeen Lee*, Seungjae Baek*, Philjoon Jung, Tae-Hyun Kim, Jeong hwan Jeon
Journal of the Institute of Control, Robotics and Systems June 2024

[Link]

Preprints & In Preparation

1. Prior-Constrained Explorative Guidance for Generalization in Diffusion Motion Planning

Co-author, Under Review at ICRA 2026

2. Manuscript of Spatio-temporal based attention Rebalancing for eco-friendly fleet control system

Co-first author, Under Review at IJCAI 2026

Research Experiences

Carnegie Mellon University

Robotics Institute, AirLab

Visiting Researcher (Supervisor: Prof. Sebastian Scherer)

Pittsburgh, PA

Aug. 2024 – Present

(Remote: Mar. 2025 – Jul. 2025)

- Led the development of **PIPE Planner**, a predictive exploration framework; achieved **10% higher reconstruction quality** and a **zero-failure rate** in benchmarks by integrating deep learning-based map prediction.
- Leading the system integration of a full-stack aerial platform; **containerized SuperOdometry SLAM** framework to ensure real-time performance on resource-constrained onboard computers.
- Successfully demonstrated autonomous aerial inspection capabilities during a high-profile showcase for the **Pittsburgh Steelers organization**, validating system robustness in real-world settings.
- Developing a simulation environment for multi-drone inspection of unstructured construction sites, formulating implementing metrics for coverage and efficiency.

Ulsan National Institute of Science and Technology
Robotics & Mobility Lab
Graduate Research Assistant (Advisor: Prof. Jeong hwan Jeon)

Ulsan, Korea

Aug. 2023 – Present

- Developed a **CTDE-based cooperative MARL framework** for urban fleet management; achieved scalability from **5 to 100 agents** while substantially reducing **carbon emissions** and maintaining service rates.
- Designed cooperative reinforcement learning algorithms for aerial surveillance, optimizing formation control to **minimize covariance of target estimation up to 50%**.

Undergraduate Research Assistant

Jul. 2022 – Aug. 2023

- Adapted a centralized training with decentralized execution (CTDE) MARL method to video-game simulations and authored a B.S. thesis.
- Engineered an autonomous race car platform as a team leader; addressed real-world sensor noise and drift, winning **1st place** in a course racing competition.

Teaching & Working Experiences

Ulsan National Institute of Science and Technology

Ulsan, Korea

- ITP117: Introduction to AI Programming II, Head Teaching Assistant
- EEE351: Automatic Control, Student Lecturer

Spring 2024
Fall 2022

Clinomics Inc.

Ulsan, Korea

- Project Based Learning (PBL) Teaching Assistant

Feb. 2023 – Jul. 2023

Achievements

Fellowships

- Korean Government Scholarship Program for Study Overseas** (USD 150,000)
Government of the Republic of Korea. Competitive national scholarship intended to support three years of PhD study at selected overseas institutions.
Aug. 2026 – Aug. 2029 (exp.)
- Industrial Innovation Talent Growth Support (Overseas Linkage)** (USD 21,500)
Korea University. Funding for visiting research at Carnegie Mellon University.
Aug. 2025 – Jan. 2026
- AI Excellence Global Innovative Leader Education Program** (USD 40,000 incl. tuition)
Sogang University. Funding for visiting research at Carnegie Mellon University.
Aug. 2024 – Feb. 2025

Scholarships

- Government-funded Graduate Scholarship (Fully funded)**
Ministry of Science and ICT. 2-year, fully funded for Master's degree.
Aug. 2023 – Aug. 2025
- UNIST Academic Performance Scholarship**
Ulsan National Institute of Science and Technology. 4-year, fully funded for undergraduate.
Feb. 2017 – Aug. 2023

Awards & Grants

- IEEE IES SYPA Travel Award (IROS 2025)** (USD 1,500)
IEEE Industrial Electronics Society. Selected for participation in IROS 2025.
Oct. 2025
- Undergraduate Research Excellent Poster Session Award**
Department of Electrical Engineering, Ulsan National Institute of Science and Technology
Jul. 2023

Skills & Services

Languages: Korean – Native, English – Advanced (TOEFL iBT: 106/120)

Programming Languages: C++, Python, MATLAB

Software and Tools: ROS, Gazebo, Git, Docker, CARLA, SUMO, NVIDIA Isaac Sim

Reviewer: IROS (2025), ICRA (2026), RA-L

Misc. & Interests: Marathon, Baseball, General Knowledge (TV Quiz Show Champion)