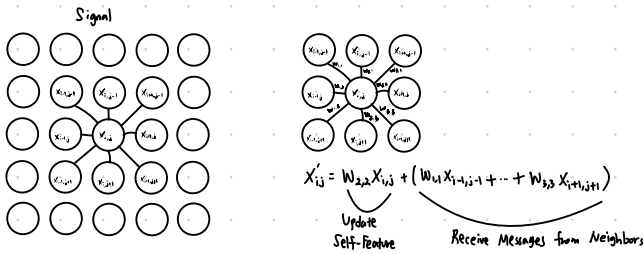
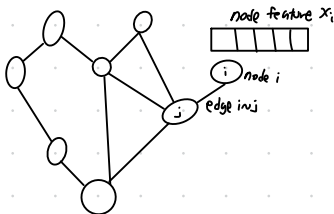


A message Passing View of Convolution



Graphs = Systems of Relations and Interactions

ex) Molecules, Social Networks, ...



Permutations and permutation matrices.

Within linear algebra, each permutation defines a $|V| \times |V|$ matrix.

Such matrices are called permutation matrices (group action $P(g)$)

They have exactly one 1 in every row and column, zeroes elsewhere

Ex)

$$P_{(2,4,1,3)} X = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} -x_1 \\ -x_2 \\ -x_3 \\ -x_4 \end{bmatrix} = \begin{bmatrix} -x_2 \\ -x_4 \\ -x_1 \\ -x_3 \end{bmatrix}$$

Permutation Invariance

$$f\left(\begin{array}{c} \text{graph} \end{array}\right) = y = f\left(\begin{array}{c} \text{permuted graph} \end{array}\right)$$

We need to appropriately permute both rows and columns of A . When applying a permutation matrix P , this amounts to PAP^T .

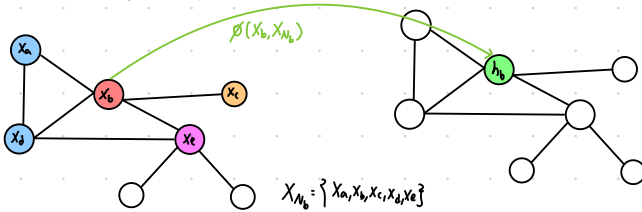
We arrive at updated definitions of suitable functions over graphs:

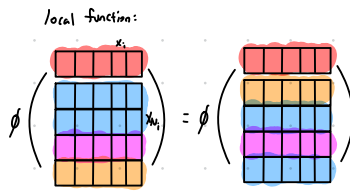
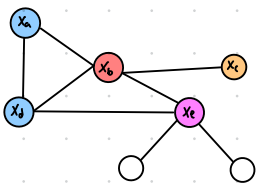
Invariance: $f(PX, PAP^T) = f(X, A)$

★ Why PAP^T to permute A ? : the multiplication of the permutation matrix P and its transpose P^T ensures that both rows and columns are permuted consistently, preserving the connectivity structure of the graph after permuting the nodes.

Equivariance: $f(PX, PAP^T) = Pf(X, A)$

Recipe for graph neural networks, visualized





Message Passing:

Permutation invariant

Permutation-invariant aggregation operator, e.g. Sum

$$f(x_i) = \phi(x_i, \sum_{j \in N_i} \psi(x_i, x_j))$$

New feature of node i

ϕ, ψ : Learnable functions, like MLP

Update rule: $h_i^{(k+1)} = \sigma(h_i^{(k)} W_0^{(k)} + \sum_{j \in N_i} \frac{1}{c_{ij}} h_j^{(k)} W_1^{(k)})$

$\frac{1}{c_{ij}}$: 1st neighbours

$h_i^{(k)}$: itself

$$H^{(k+1)} = \sigma(\hat{A} H^{(k)} W^{(k)})$$

Why PA^T ?

$A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$

$P = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$: Swapping nodes 1 and 3.

$PA^T = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$: This new matrix corresponds to a graph where nodes 1 and 3 have been swapped, while the edges between them are correctly maintained.