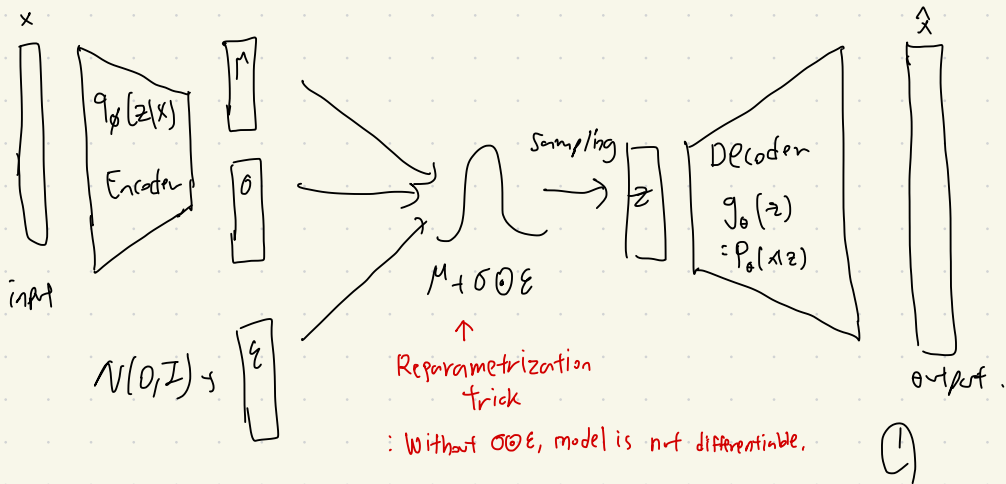
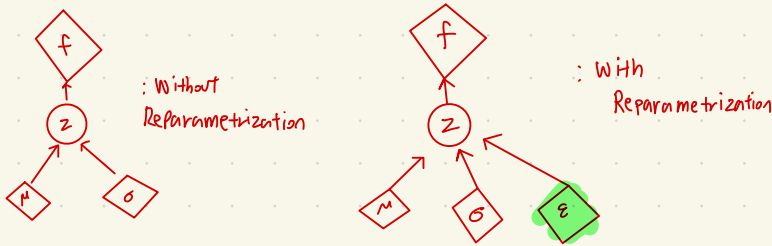


VAE structure:



Visualizing Reparametrization



Objective of VAE: Learn model parameters to maximize likelihood of training data: $P_{\theta}(x)$

$$\text{And, } P_{\theta}(x) = \int P_{\theta}(z) P_{\theta}(x|z) dz$$

$$\text{Why? } \frac{P_{\theta}(x, z)}{P_{\theta}(z)} = P_{\theta}(x|z) \Rightarrow P_{\theta}(x, z) = P_{\theta}(z) P_{\theta}(x|z)$$

$$\text{And } \int P_{\theta}(x, z) dz = P_{\theta}(x)$$

$$\text{Hence, } P_{\theta}(x) = \int P_{\theta}(z) P_{\theta}(x|z) dz$$

However, $\int P_{\theta}(x|z) dz$ is intractable

It implies we would derive a lower bound on the data likelihood, which is tractable

Let's work on log data likelihood

$$\log P_{\theta}(x^{(i)}) = \mathbb{E}_{z \sim q_{\phi}(z|x)} [\log P_{\theta}(x^{(i)})]$$

$$= \mathbb{E}_{z \sim q_{\phi}(z|x)} \left[\log \frac{P_{\theta}(x^{(i)}|z) P_{\theta}(z)}{P_{\theta}(z|x^{(i)})} \right]$$

★ Use Bayes' Rule

$$P(z|x) = \frac{P(x|z)P(z)}{P(x)} \Rightarrow P(x) = \frac{P(x|z)P(z)}{P(z|x)}$$

$$= \mathbb{E}_{z \sim q_{\theta}(z|x)} \left[\log \left(\frac{p_{\theta}(x^{(i)}|z) p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \right) \right]$$

= Multiplying 1

$$= \mathbb{E}_{z \sim q_{\theta}(z|x)} \left[\log \left(p_{\theta}(x^{(i)}|z) \cdot \frac{p_{\theta}(z)}{q_{\theta}(z|x^{(i)})} \cdot \frac{q_{\theta}(z|x^{(i)})}{p_{\theta}(z|x^{(i)})} \right) \right]$$

$$= \mathbb{E}_{z \sim q_{\theta}(z|x)} \left[\log(p_{\theta}(x^{(i)}|z)) - \log\left(\frac{q_{\theta}(z|x^{(i)})}{p_{\theta}(z)}\right) + \log\left(\frac{q_{\theta}(z|x^{(i)})}{p_{\theta}(z|x^{(i)})}\right) \right]$$

$$= \mathbb{E}_z [\log p_{\theta}(x^{(i)}|z)] - \mathbb{E}_z \left[\log \left(\frac{q_{\theta}(z|x^{(i)})}{p_{\theta}(z)} \right) \right] + \mathbb{E}_z \left[\log \left(\frac{q_{\theta}(z|x^{(i)})}{p_{\theta}(z|x^{(i)})} \right) \right]$$

$$= \mathbb{E}_z [\log p_{\theta}(x^{(i)}|z)] - \text{KL}(q_{\theta}(z|x^{(i)}) || p_{\theta}(z)) + \text{KL}(q_{\theta}(z|x^{(i)}) || p_{\theta}(z|x^{(i)}))$$

$$\star \mathbb{E}_{z \sim q_{\theta}(z|x)} \left[\log \frac{q_{\theta}(z|x^{(i)})}{p_{\theta}(z)} \right] = \int q_{\theta}(z|x^{(i)}) \log \left(\frac{q_{\theta}(z|x^{(i)})}{p_{\theta}(z)} \right) dz = \text{KL}(p || q)$$

$$\text{Since } \text{KL}(p || q) = \sum_x p(x) \log \frac{p(x)}{q(x)}$$

However, we know $p_{\theta}(z|x^{(i)})$ is intractable. However KL always ≥ 0 .

Hence,

$$\mathbb{E}_{z \sim q_{\theta}(z|x)} [\log p_{\theta}(x^{(i)}|z)] - \text{KL}(q_{\theta}(z|x^{(i)}) || p_{\theta}(z)) \text{ is our ELBO.}$$

$\mathcal{L}(x^{(i)}, \theta, \phi)$: Tractable lower bound.

Hence, VAE Objective : $\theta^*, \phi^* = \arg \max_{\theta, \phi} \sum_{i=1}^N \mathcal{L}(x^{(i)}, \theta, \phi)$

$$\theta^*, \phi^* = \arg \min_{\theta, \phi} \sum_{i=1}^N \mathcal{L}(x^{(i)}, \theta, \phi) = \sum_{i=1}^N \underbrace{-\log p_{\theta}(x^{(i)}|g_{\phi}(z))}_{\text{Reconstruction Error}} + \underbrace{\text{KL}(q_{\phi}(z|x^{(i)}) || p(z))}_{\text{Regularization}}$$

\downarrow

$p(x|g_{\phi}(z)) = p_{\theta}(x|z)$

where $p(z) = \mathcal{N}(\mathbf{0}, \mathbf{I})$

Regularization :

Assumption 1: $q_{\phi}(z|x^{(i)}) \sim \mathcal{N}(\mu^{(i)}, \sigma^{(i)} \mathbf{I})$

Assumption 2: $p_{\theta}(z) \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

Cause it makes VAE simple and reasonable.

$$D_{KL}(N_0 \| N_1) = \frac{1}{2} \left(\text{tr}(\Sigma_1^{-1} \Sigma_0) + (M_1 - M_0)^T \Sigma_1^{-1} (M_1 - M_0) - k + \ln \left(\frac{\det \Sigma_1}{\det \Sigma_0} \right) \right)$$

Since our $N_i = N(0, I)$, $\Sigma_i = I$, $M_i = 0$

$$\text{Then, } KL(q_\phi(z|x^{(i)}) \| p_\theta(z)) = \frac{1}{2} \sum_{j=1}^J \mu_{i,j}^2 + \sigma_{i,j}^2 - \ln(\sigma_{i,j}^2) - 1$$

Reconstruction Error: MSE or Cross Entropy

MSE: When Decoder uses Gaussian Distribution

Cross-Entropy: When Decoder uses Bernoulli Distribution

Therefore, Goal of VAE is

$$\theta^*, \phi^* = \underset{\theta, \phi}{\operatorname{argmin}} \sum_i \underbrace{\mathbb{E}_{z \sim q_\phi(z|x^{(i)})} [\log(p_\theta(x^{(i)}|z))]}_{\text{Reconstruction Error (MSE or Cross-Entropy)}} + \underbrace{KL(q_\phi(z|x^{(i)}) \| p(z))}_{\text{Regularization}}$$

: Encouraging a structured and well-behaved latent space

β -VAE (Disentangled VAE)

$$\text{Recon || VAE Loss: } L_{VAE} = \underbrace{-\log p_\theta(x|z)}_{\text{improving decoder } z \rightarrow x} + \underbrace{D_{KL}(q_\phi(z|x) \| p_\theta(z))}_{\text{improving encoder (better representation of } z)}$$

Another way of writing VAE objective:

$$\max_{\phi, \theta} \mathbb{E}_{x \sim D} [\mathbb{E}_{z \sim q_\phi(z|x)} \log p_\theta(x|z)]$$

$$\text{s.t. } D_{KL}(q_\phi(z|x) \| p_\theta(z)) < \delta$$

: Maximizing probability of generating real data, while keeping distance between real and approximate posterior distribution ($q_\phi(z|x)$) small. (Under small constant δ)

• VAE maximization objective can then be rewritten as a Lagrangian with a Lagrangian multiplier β under KKT condition.

$$: \mathbb{E}_{z \sim q_\phi(z|x)} \log p_\theta(x|z) - \beta [D_{KL}(q_\phi(z|x) \| p_\theta(z)) - \delta]$$

$$= \mathbb{E}_{z \sim q_\phi(z|x)} \log p_\theta(x|z) - \beta [D_{KL}(q_\phi(z|x) \| p_\theta(z)) + \beta \delta]$$

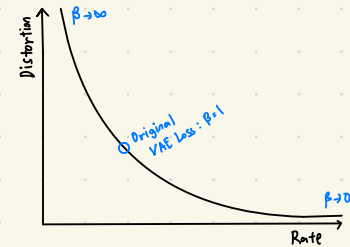
β -VAE Loss hence given by:

$$\mathcal{L}_{\text{beta}}(\phi, \beta) = -\mathbb{E}_{z \sim q_{\phi}(z|x)} [\log p_{\theta}(x|z)] + \beta D_{\text{KL}}(q_{\phi}(z|x) || p_{\theta}(z))$$

- When $\beta=1 \Rightarrow$ Standard VAE
- When $\beta>1 \Rightarrow$ Stronger constraint on latent bottleneck, follow generative process and thus encourage disentanglement
↳ Increasing representation capacity of z . Generally, "stronger disentanglement" means more Gaussian like for most linear definition.
- Disadvantage: Trade-off between disentanglement and reconstruction capability.

* Distortion: $d(x, \hat{x})$ where \hat{x} reconstruction/estimate of x given z . It's a reconstruction loss. e.g. $-\log(p(x|z)) = \text{MSE}[x|z]$

* Rate: Regularization: $\text{KL}(q_{\phi}(z|x) || p_{\theta}(z))$



As $\beta \rightarrow 0$, Optimizer prioritizes minimizing distortion: Rate \uparrow , Distortion \downarrow
 $\beta \rightarrow \infty$, Optimizer prioritizes minimizing rate over maximizing distortion
Rate \downarrow , Distortion \uparrow